

## Raspberry Pi Wide-Angle Camera use tutorial

1. You need to connect camera to Raspberry Pi board.
2. You must to install a new operating system before use camera, which can identify if the camera module is connected. The simplest method is download Raspbian system from Raspberry Pi website, and install it to new SD card.

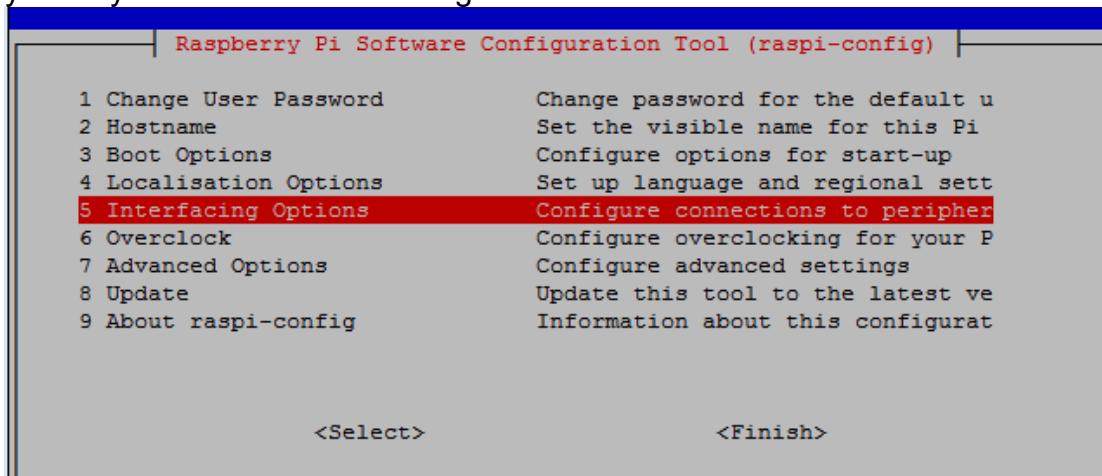
Regardless of the version of the Raspbian system you are using, I recommend that you update the system with the following command:

**sudo apt-get update**  
**sudo apt-get upgrade**

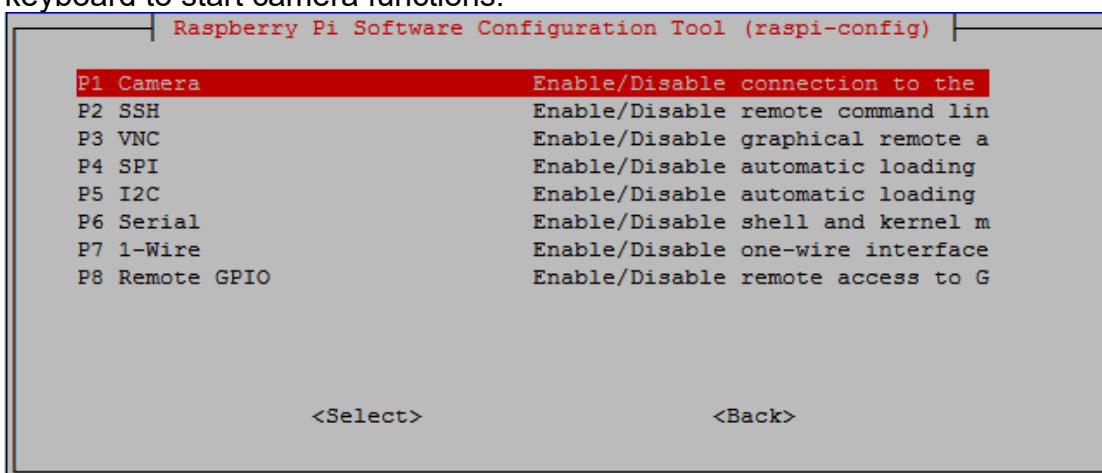
3. Enable camera options

3.1) You need to input: **sudo raspi-config** to enter the following interface:

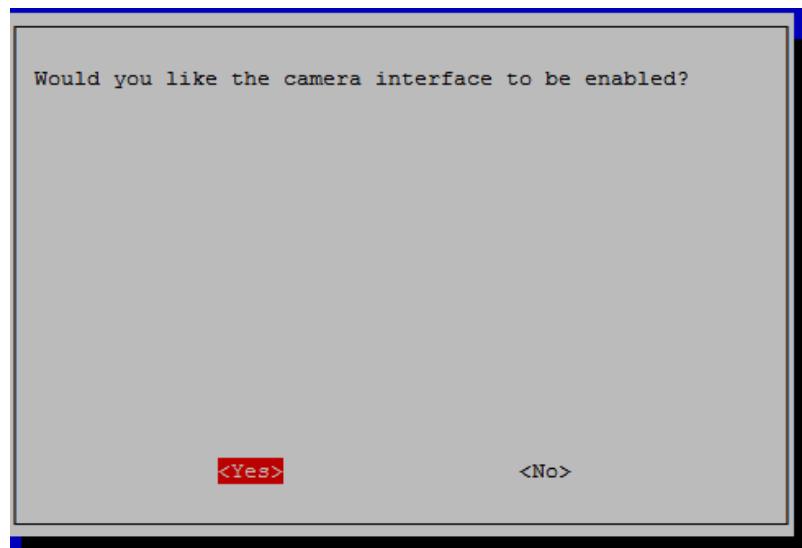
3.2) You need to choose “Interfacing Options”, press the “Enter” key of your keyboard to enter the configuration.



3.3) You need to choose “P1 Camera”, press the “Enter” key of your keyboard to start camera functions.



3.4) You need to choose “Yes”.



After the above steps, the camera function of Raspberry Pi has been turned on.

#### 4. Use camera

##### We recommend using method 1

**Method 1:** You can use Raspberry Pi official original camera by system command

**raspistill -----**This command is to get the static image

The picture below shows the parameter information about the command displayed directly by the command raspistill.

```

root@raspberrypi:/home/pi# raspistill
raspistill Camera App v1.3.11

Runs camera for specific time, and take JPG capture at end if requested

usage: raspistill [options]

Image parameter commands

-?, --help      : This help information
-w, --width    : Set image width <size>
-h, --height   : Set image height <size>
-q, --quality  : Set jpeg quality <0 to 100>
-r, --raw       : Add raw bayer data to jpeg metadata
-o, --output   : Output filename <filename> (to write to stdout, use '-o -'). If not specified, no file is saved
-l, --latest    : Link latest complete image to filename <filename>
-v, --verbose   : Output verbose information during run
-t, --timeout   : Time (in ms) before takes picture and shuts down (if not specified, set to 5s)
-th, --thumb    : Set thumbnail parameters (x:y:quality) or none
-d, --demo      : Run a demo mode (cycle through range of camera options, no capture)
-e, --encoding  : Encoding to use for output file (jpg, bmp, gif, png)
-x, --exif     : EXIF tag to apply to captures (format as 'key=value') or none
-tl, --timelapse : Timelapse mode. Takes a picture every <t>ms. %d == frame number (Try: -o img_%04d.jpg)
-fp, --fullpreview : Run the preview using the still capture resolution (may reduce preview fps)
-k, --keypress   : Wait between captures for a ENTER, X then ENTER to exit
-s, --signal    : Wait between captures for a SIGUSR1 or SIGUSR2 from another process
-g, --gl        : Draw preview to texture instead of using video render component
-gc, --glcapture : Capture the GL frame-buffer instead of the camera image
-set, --settings : Retrieve camera settings and write to stdout
-cs, --camselect : Select camera <number>. Default 0
-bm, --burst    : Enable 'burst capture mode'
-md, --mode     : Force sensor mode. 0:auto. See docs for other modes available
-dt, --datetime  : Replace output pattern (%d) with DateTime (MonthDayHourMinSec)
-ts, --timestamp : Replace output pattern (%d) with unix timestamp (seconds since 1970)
-fs, --framestart : Starting frame number in output pattern(%d)
-rs, --restart   : JPEG Restart interval (default of 0 for none)

Preview parameter commands

-p, --preview   : Preview window settings <'x,y,w,h'>
-f, --fullscreen : Fullscreen preview mode
-op, --opacity   : Preview window opacity (0-255)
-n, --nopreview : Do not display a preview window

```

### **raspivid -----This command is to get the video information**

```

root@raspberrypi:/home/pi# raspivid
raspivid Camera App v1.3.12

Display camera output to display, and optionally saves an H264 capture at requested bitrate

usage: raspivid [options]

Image parameter commands

-?, --help      : This help information
-w, --width    : Set image width <size>. Default 1920
-h, --height   : Set image height <size>. Default 1080
-b, --bitrate  : Set bitrate. Use bits per second (e.g. 10MBits/s would be -b 10000000)
-o, --output   : Output filename <filename> (to write to stdout, use '-o -').
                  Connect to a remote IPv4 host (e.g. tcp://192.168.1.2:1234, udp://192.168.1.2:1234)
                  To listen on a TCP port (IPv4) and wait for an incoming connection use -l
                  (e.g. raspivid -l -o tcp://0.0.0.0:3333 -> bind to all network interfaces, raspivid -l -o tcp://192.168.1.1:3333 -> bind to a certain local IPv4)
-v, --verbose   : Output verbose information during run
-t, --timeout   : Time (in ms) to capture for. If not specified, set to 5s. Zero to disable
-d, --demo      : Run a demo mode (cycle through range of camera options, no capture)
-fps, --framerate : Specify the frames per second to record
-e, --penc     : Display preview image *after* encoding (shows compression artifacts)
-g, --intra    : Specify the intra refresh period (key frame rate/GoP size). Zero to produce an initial I-frame and then just P-frames.
-pf, --profile : Specify H264 profile to use for encoding
-td, --timed   : Cycle between capture and pause. -cycle on,off where on is record time and off is pause time in ms
-s, --signal   : Cycle between capture and pause on Signal
-k, --keypress  : Cycle between capture and pause on ENTER
-i, --initial  : Initial state. Use 'record' or 'pause'. Default 'record'
-qp, --qp      : Quantisation parameter. Use approximately 10-40. Default 0 (off)
-ih, --inline   : Insert inline headers (SPS, PPS) to stream
-sg, --segment  : Segment output file in to multiple files at specified interval <ms>
-wr, --wrap     : In segment mode, wrap any numbered filename back to 1 when reach number
-sn, --start    : In segment mode, start with specified segment number
-sp, --split    : In wait mode, create new output file for each start event
-c, --circular : Run encoded data through circular buffer until triggered then save
-x, --vectors   : Output filename <filename> for inline motion vectors
-cs, --camselect : Select camera <number>. Default 0

```

### Raspistill related commands:

1. After a delay of 1.1 seconds (in milliseconds), take a photo and name it image.jpg

**raspistill -t 1000 -o image.jpg**

2. Take a photo of custom size and frame rate

**raspistill -t 1000 -o image.jpg -w 640 -h 480 -q 5**

3. Set embossed style image effects

**raspistill -t 1000 -o image.jpg -ifx emboss**

4. Get a photo and send it to a standard output device (such as a monitor)

**raspistill -t 1000 -o**

### Raspiivid related commands:

1. Shoot a video: The default is video length is 5s, resolution is 1920\*1080, frame rate: 17

**raspivid -o myvideo.h264**

2. Take a video: resolution is 640\*480, time is 10s

**raspivid -o myvideo.h264 -t 10000 -w 640 -h 480**

Note: raspivid outputs an uncompressed H.264 video stream. In order to allow our normal video player to play, you need to install the gpac package.

**apt-get install -y gpac**

Then use the MP4Box application in the gpac package to convert the H.264 format video stream to 10 frames per second MP4 format video.

**MP4Box -fps 10 -add myvideo.h264 myvideo.mp4**

**Method 2:** You can transfer the video which captured by the Raspberry Pi to the web page.

4.1) You need to log into Raspberry Pi system and give home folder permissions to copy drive folders to this directory. This operation can only be performed by root users.

4.2) You should input: #su

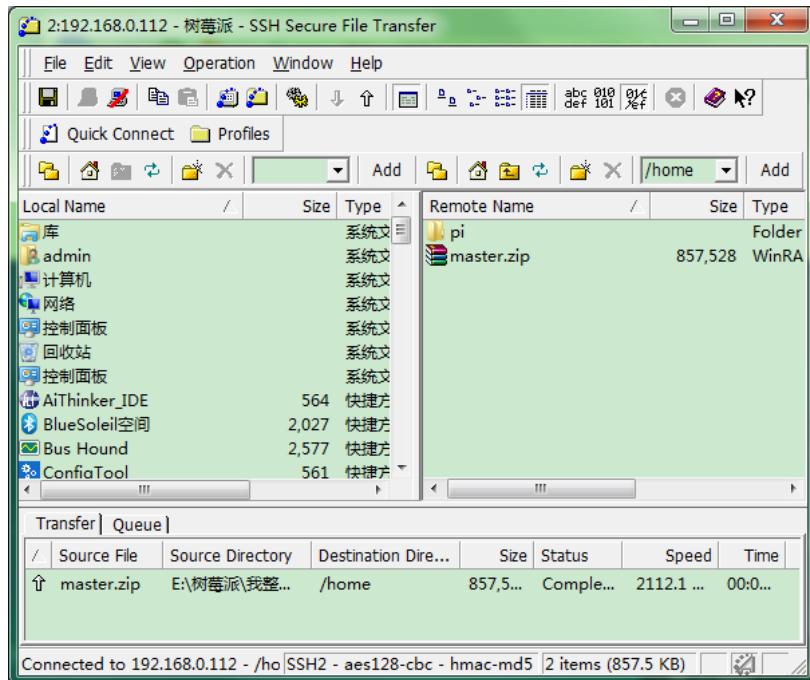
(This command to make you enter root user)

4.3) Then input your password of root permissions

4.4) You should input: #chmod 777 /home

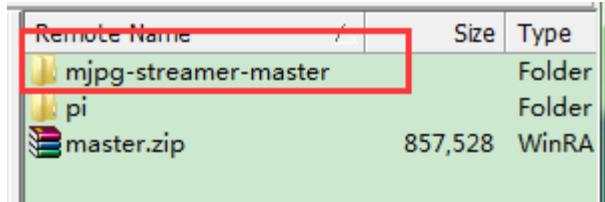
(This command to give home folder permissions to RWX.)

4.5) You need to copy “**master.zip**” to home directory. As shown in the figure below.



4.6) You should input: **#unzip master.zip**  
 (This command to unzip master.zip)

After complete unzip, you can see **mjpg-streamer-master** folder. As shown in the figure below.



4.7) Compiling this project requires cmake: perform the following command to install download.

(apt-get is a networked installation, so you need make Raspberry Pi successfully connect to the network.)

You should input:

**#sudo apt-get install cmake**

A prompt will appear when installing, you need to enter Y.

After completion, As shown in the figure below.

```

Suggested packages:
  codeblocks eclipse ninja-build
The following NEW packages will be installed:
  cmake cmake-data
0 upgraded, 2 newly installed, 0 to remove and 6 not upgraded.
Need to get 2,845 kB of archives.
After this operation, 14.6 MB of additional disk space will be used.
Do you want to continue? [Y/n] Y
Get:1 http://mirrordirector.raspbian.org/raspbian/ jessie/main cmake-data all 3.0.2-1+deb8u1 [929 kB]
Get:2 http://mirrordirector.raspbian.org/raspbian/ jessie/main cmake armhf 3.0.2-1+deb8u1 [1,915 kB]
Fetched 2,845 kB in 3s (861 kB/s)
Selecting previously unselected package cmake-data.
(Reading database ... 124054 files and directories currently installed.)
Preparing to unpack .../cmake-data_3.0.2-1+deb8u1_all.deb ...
Unpacking cmake-data (3.0.2-1+deb8u1) ...
Selecting previously unselected package cmake.
Preparing to unpack .../cmake_3.0.2-1+deb8u1_armhf.deb ...
Unpacking cmake (3.0.2-1+deb8u1) ...
Processing triggers for man-db (2.7.0.2-5) ...
Setting up cmake-data (3.0.2-1+deb8u1) ...
Setting up cmake (3.0.2-1+deb8u1) ...
root@raspberrypi:/home#
Connected to 192.168.0.112           SSH2 - aes128-cbc - hmac-md5 | 80x24 | ☰

```

## 5. You need to install library

You should input:

**#sudo apt-get install libjpeg8-dev**

After completion, As shown in the figure below.

```

root@raspberrypi:/home# sudo apt-get install libjpeg8-dev
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following NEW packages will be installed:
  libjpeg8-dev
0 upgraded, 1 newly installed, 0 to remove and 6 not upgraded.
Need to get 205 kB of archives.
After this operation, 436 kB of additional disk space will be used.
Get:1 http://mirrordirector.raspbian.org/raspbian/ jessie/main libjpeg8-dev armhf 8d1-2 [205 kB]
Fetched 205 kB in 1s (150 kB/s)
Selecting previously unselected package libjpeg8-dev:armhf.
(Reading database ... 125733 files and directories currently installed.)
Preparing to unpack .../libjpeg8-dev_8d1-2_armhf.deb ...
Unpacking libjpeg8-dev:armhf (8d1-2) ...
Setting up libjpeg8-dev:armhf (8d1-2) ...
root@raspberrypi:/home#

```

## 6. Compiling

You need to enter: /home/pi/mjpg-streamer-master/mjpg-streamer-experimental/

And you need to run the following command directly

**#make clean all**

You can wait for the compilation to complete, you can see the interface shown below.

```

1:192.168.0.112 - 树莓派 - SSH Secure Shell
File Edit View Window Help
Quick Connect Profiles
Linking C shared library output_http.so
make[3]: Leaving directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
[ 87%] Built target output_http
make[3]: Entering directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
Scanning dependencies of target output_rtsp
make[3]: Leaving directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
make[3]: Entering directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
[ 93%] Building C object plugins/output_rtsp/CMakeFiles/output_rtsp.dir/output_rtsp.c.o
Linking C shared library output_rtsp.so
make[3]: Leaving directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
[ 93%] Built target output_rtsp
make[3]: Entering directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
Scanning dependencies of target output_udp
make[3]: Leaving directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
make[3]: Entering directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
[100%] Building C object plugins/output_udp/CMakeFiles/output_udp.dir/output_udp.c.o
Linking C shared library output_udp.so
make[3]: Leaving directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
[100%] Built target output_udp
make[2]: Leaving directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
make[1]: Leaving directory '/home/mjpg-streamer-master/mjpg-streamer-experimental/_build'
root@raspberrypi:/home/mjpg-streamer-master/mjpg-streamer-experimental#
Connected to 192.168.0.112           SSH2 - aes128-cbc - hmac-md5 | 77x35

```

## 7. Restart system

You need to input: **reboot** to reboot system

Plug in the camera and restart the system.

## 8. After rebooting, enter the system.

You need to enter the **mjpg-streamer-experimental** directory by command.  
And use the following command to start the Raspberry Pi Official Original Camera:

**#./mjpg\_streamer -i "./input\_raspicam.so" -o "./output\_http.so -w ./www"**

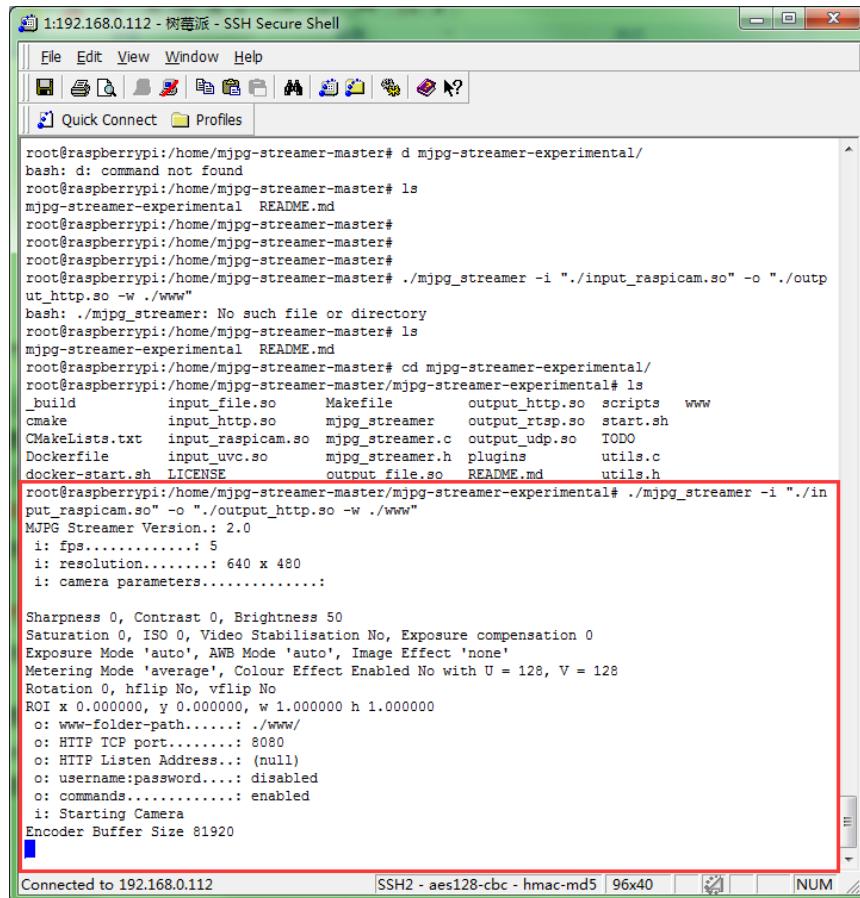
(Note: Raspberry Pi special camera includes: Raspberry Pi night vision camera, Raspberry Pi official original camera, Raspberry pie wide-angle camera)

If you want to modify the resolution of the captured video, you need to input the following command:

**#./mjpg\_streamer -i "./input\_raspicam.so -w 320 -h 240 -fps 10" -o "./output\_http.so -w ./www"**

Some cameras will report an error when executing this command. If they do not return to the command prompt and display "Starting Camera", it means success.

As shown in the figure below, the camera is successfully turned on:



```

1:192.168.0.112 - 树莓派 - SSH Secure Shell
File Edit View Window Help
Quick Connect Profiles
root@raspberrypi:/home/mjpg-streamer-master# d mjpg-streamer-experimental/
bash: d: command not found
root@raspberrypi:/home/mjpg-streamer-master# ls
mjpg-streamer-experimental README.md
root@raspberrypi:/home/mjpg-streamer-master#
root@raspberrypi:/home/mjpg-streamer-master#
root@raspberrypi:/home/mjpg-streamer-master# ./mjpg_streamer -i "./input_raspicam.so" -o "./output_http.so -w ./www"
bash: ./mjpg_streamer: No such file or directory
root@raspberrypi:/home/mjpg-streamer-master# ls
mjpg-streamer-experimental README.md
root@raspberrypi:/home/mjpg-streamer-master# cd mjpg-streamer-experimental/
root@raspberrypi:/home/mjpg-streamer-master/mjpg-streamer-experimental# ls
_build      input_file.so      Makefile      output_http.so  scripts   www
cmake       input_http.so     mjpg_streamer  output_rtp.so   start.sh
CMakeLists.txt  input_raspicam.so  mjpg_streamer.c  output_udp.so  TODO
Dockerfile   input_uvc.so     mjpg_streamer.h  plugins     utils.c
docker-start.sh  LICENSE      output_file.so  README.md    utils.h
root@raspberrypi:/home/mjpg-streamer-master/mjpg-streamer-experimental# ./mjpg_streamer -i "./input_raspicam.so" -o "./output_http.so -w ./www"
MJPEG Streamer Version.: 2.0
i: fps.....: 5
i: resolution.....: 640 x 480
i: camera parameters.....:

Sharpness 0, Contrast 0, Brightness 50
Saturation 0, ISO 0, Video Stabilisation No, Exposure compensation 0
Exposure Mode 'auto', AWB Mode 'auto', Image Effect 'none'
Metering Mode 'average', Colour Effect Enabled No with U = 128, V = 128
Rotation 0, hflip No, vflip No
ROI x 0.000000, y 0.000000, w 1.000000 h 1.000000
o: www-folder-path.....: ./www/
o: HTTP TCP port.....: 8080
o: HTTP Listen Address.: (null)
o: username:password....: disabled
o: commands.....: enabled
i: Starting Camera
Encoder Buffer Size 81920

```

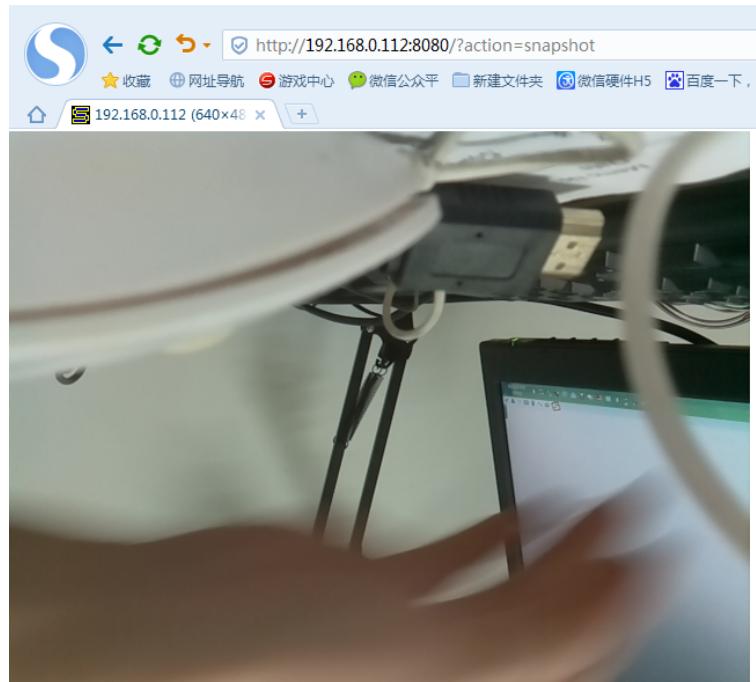
Connected to 192.168.0.112    SSH2 - aes128-cbc - hmac-md5 | 96x40 | NUM

## 9. Test results

View the image, open the browser on the PC side, you need to enter the following URL to see the static screenshot:

**<http://<RaspberryPi IP>:8080/?action=snapshot>**

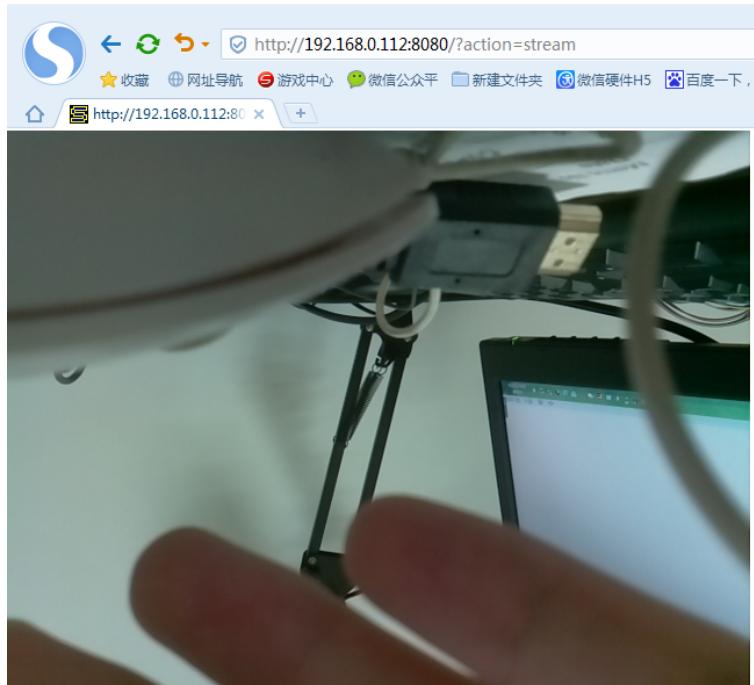
My URL is: <http://192.168.0.112:8080/?action=snapshot>



You should input the following URL to see the dynamic image:

**http://<RaspberryPi IP>:8080/?action=stream**

My URL is: <http://192.168.0.112:8080/?action=stream>



You can also use the following URL:

**http://<RaspberryPi IP>:8080/javascript\_simple.html**

PS: When using the RaspiCamera dedicated camera, the dynamic image screen will have a transmission delay, about 1.4 frames / sec. It is recommended to use static capture.