

Using MIPI camera

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- Configure camera
 - Use camera
 - Preview camera
 - Photograph
 - rpicam-still
 - Video
 - rpicam-vid
 - Error resolution

The Raspberry Pi 5 combines the previous CSI and DSI interfaces into two dual-purpose CSI/DSI (MIPI) ports.

Configure camera

When using a Raspberry Pi camera or a third-party camera, you can modify the camera configuration according to the following table:

Camera module	File located at: /boot/firmware/config.txt
V1 Camera (OV5647)	dtoverlay=ov5647
V2 camera (IMX219)	dtoverlay=imx219
HQ Camera (IMX477)	dtoverlay=imx477
GS camera (IMX296)	dtoverlay=imx296
Camera module 3 (IMX708)	dtoverlay=imx708
IMX290 and IMX327	dtoverlay=imx290,clock-frequency=74250000 or (both modules share the IMX290 kernel driver; for the correct frequency, see the module vendor's instructions) dtoverlay=imx290,clock-frequency=37125000
IMX378 type	dtoverlay=imx378
OV9281 series	dtoverlay=ov9281

If you are not using the official Raspberry Pi camera, you can modify the config.txt file as shown in the table and add the dtoverlay content to the /boot/firmware/config.txt file.

```
Disable camera on startup: camera_auto_detect=0
```

For example: Raspberry Pi uses IMX219 camera, connect the camera to the Raspberry Pi J4 interface, and then modify the /boot/firmware/config.txt file:

```
GNU nano 7.2                                config.txt *
auto_initramfs=1

# Enable DRM VC4 V3D driver
dtoverlay=vc4-kms-v3d
max_framebuffers=2

# Don't have the firmware create an initial video= setting in cmdline.txt.
# Use the kernel's default instead.
disable_fw_kms_setup=1

# Run in 64-bit mode
arm_64bit=1

# Disable compensation for displays with overscan
disable_overscan=1

# Run as fast as firmware / board allows
arm_boost=1

[cm4]
# Enable host mode on the 2711 built-in XHCI USB controller.
# This line should be removed if the legacy DWC2 controller is required
# (e.g. for USB device mode) or if USB support is not required.
otg_mode=1

[all]
dtoverlay=imx219

^G Help      ^O Write Out  ^W Where Is   ^K Cut        ^T Execute    ^C Location
^X Exit      ^R Read File  ^\ Replace    ^U Paste      ^J Justify    ^_ Go To Line
```

To use the IMX219 camera, it needs to be connected to the J4 interface of Raspberry Pi 5 for recognition!

Modify the configuration file and restart to take effect!

Use camera

Preview camera

-rpicam-hello

Entering this command in the terminal will display the preview window for about 5 seconds.

- `rpicam-hello -t 0`

Running this command in the terminal will always display the preview window. You can use the window close button and Ctrl+C to exit!

Photograph

- `rpicam-jpeg -o test.jpg`

Display a preview for 5 seconds, then capture the image and save it as a test.jpg file

- `rpicam-jpeg -o test.jpg -t 2000 --width 640 --height 480`

Show a preview for 2 seconds, then capture and save the image as a test.jpg file, with the image having a width of 640 pixels and a height of 480 pixels.

rpicam-still

This command can be used to save files in different formats:

```
rpicam-still -e png -o test.png
rpicam-still -e bmp -o test.bmp
rpicam-still -e rgb -o test.data
rpicam-still -e yuv420 -o test.data
```

- Raw image capture

```
rpicam-still -r -o test.jpg
```

- Time-lapse shooting

Capture images continuously at intervals of 2 seconds for a total capture duration of 30 seconds, and save each image as a file name similar to image0001.jpg:

```
rpicam-still -t 30000 --timelapse 2000 -o image%04d.jpg
```

Video

rpicam-vid

Commands for video recording using the camera module on the Raspberry Pi.

Example: Record 10 seconds of video and write to test.h264 file

```
rpicam-vid -t 10000 -o test.h264
```

play video

```
vlc test.h264
```

Note: If the test.h264 file cannot be played and an error occurs, please try the following method to solve it.

Error resolution

Modify the frame rate of H264 playback per second



