## 6. Face detection

**File path:**/home/pi/Yahboom\_Project/1.OpenCV course/04 advanced tutorial/face\_detaction.ipynb

The test code is as follows:

```
#bgr8 to jpeg format
import enum
import cv2

def bgr8_to_jpeg(value, quality=75):
    return bytes(cv2.imencode('.jpg', value)[1])
```

```
#Camera display component
import cv2
import ipywidgets.widgets as widgets
import threading
import time
importsys

image_widget = widgets.Image(format='jpeg', width=320, height=240)
display(image_widget)
```

```
image = cv2.VideoCapture(0)

image.set(3,320)

image.set(4,240)

ret, frame = image.read()

image_widget.value = bgr8_to_jpeg(frame)
```

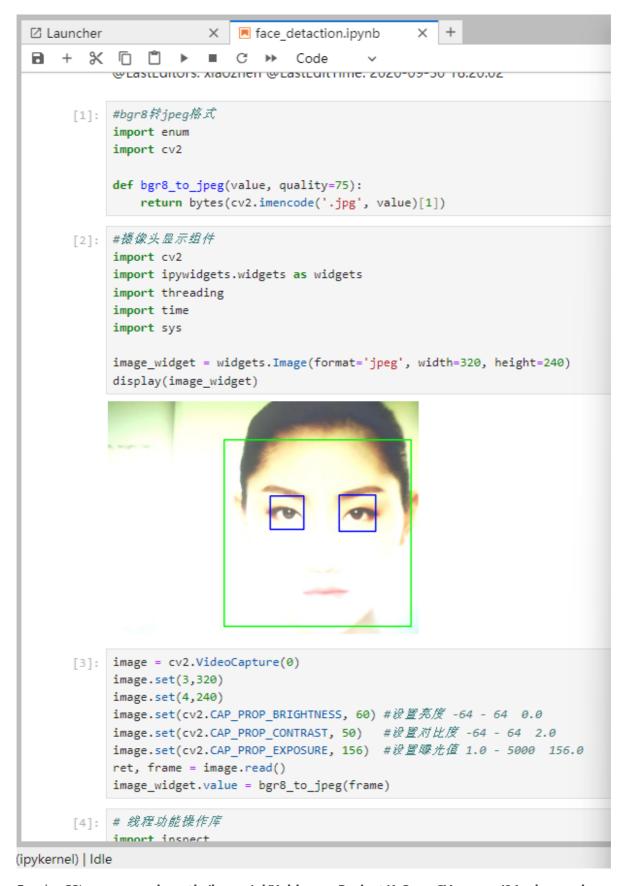
```
# Thread function operation library
import inspect
```

```
import ctypes
def _async_raise(tid, exctype):
     """raises the exception, performs cleanup if needed"""
    tid = ctypes.c_long(tid)
    if not inspect.isclass(exctype):
        exctype = type(exctype)
     res = ctypes.pythonapi.PyThreadState_SetAsyncExc(tid,
ctypes.py_object(exctype))
    if res == 0:
         raise ValueError("invalid thread id")
     elif res != 1:
         # """if it returns a number greater than one, you're in trouble,
         # and you should call it again with exc=NULL to revert the effect"""
         ctypes.pythonapi.PyThreadState_SetAsyncExc(tid, None)
def stop_thread(thread):
    _async_raise(thread.ident, SystemExit)
```

```
# bodies = body_haar.detectMultiScale(gray_img, 1.3, 5)
# for body_x,body_y,body_w,body_h in bodies:
# cv2.rectangle(frame, (body_x, body_y), (body_x+body_w, body_y+body_h),
(0,255,0), 2)
         faces = face_haar.detectMultiScale(gray_img, 1.1, 3)
         for face_x,face_y,face_w,face_h in faces:
             cv2.rectangle(frame, (face_x, face_y), (face_x+face_w,
face_y+face_h), (0,255,0), 2)
         eyes = eye_haar.detectMultiScale(gray_img, 1.1, 3)
         for eye_x,eye_y,eye_w,eye_h in eyes:
            cv2.rectangle(frame, (eye_x,eye_y), (eye_x+eye_w, eye_y+eye_h),
(255,0,0), 2)
# eyes = eye_haar.detectMultiScale(gray_img, 1.3, 5)
# for eye_x,eye_y,eye_w,eye_h in eyes:
# cv2.rectangle(frame, (eye_x,eye_y), (eye_x+eye_w, eye_y+eye_h), (255,0,0), 2)
         image_widget.value = bgr8_to_jpeg(frame)
         time.sleep(0.010)
#Start thread
thread1 = threading.Thread(target=Camera_display)
thread1.setDaemon(True)
thread1.start()
#End the process and release the camera. Execute when needed.
stop_thread(thread1)
```

image.release()

After running, we can see the picture displayed by the camera below the display camera component and frame the person's face and eyes. Note that light may affect the experimental results.



For the CSI camera, **code path:/home/pi/Yahboom\_Project/1.OpenCV course/04 advanced tutorial/face\_detection\_CSI.py** 

Operation mode

```
python3 face_detection_CSI.py
```

## **Precautions**

When running this routine using the CSI camera, if you encounter the following error message:

```
t, apa.plugin: C<mark>ould not</mark> load the Qt platform plugin "xcb" in "/home/pi/.local/lib/python3.11/site-packages/cv2/qt/plugins" even though it was found.
This application failed to start because no Qt platform plugin could be initialized. Reinstalling the application may fix this problem.
```

The following operations need to be done

```
cd /home/pi/.local/lib/python3.11/site-packages/cv2/qt/plugins/platforms rm -rf libqxcb.so
```

```
pi@raspberrypi:~ $ cd /home/pi/.local/lib/python3.11/site-packages/cv2/qt/plugins/platforms
pi@raspberrypi:~/.local/lib/python3.11/site-packages/cv2/qt/plugins/platforms $ ls
libqxcb.so
pi@raspberrypi:~/.local/lib/python3.11/site-packages/cv2/qt/plugins/platforms $ rm -rf libqxcb.so
```