

3.1.5 QR code recognition

Introduction to QR Code

QR code uses a certain geometric figure to record data symbol information in a black and white pattern distributed on a plane (two-dimensional direction) according to a certain rule.

Code path:

/home/pi/Yahboom Project/3.AI Visual course/05.QR code recognition.ipynb

```
#bgr8 to jpeg format
import enum
import cv2
def bgr8 to jpeg(value, quality=75):
    return bytes(cv2.imencode('.jpg', value)[1])
       # Import library and show camera display component
# import the necessary packages
#import simple_barcode_detection
import cv2
import numpy as np
import pyzbar.pyzbar as pyzbar
from PIL import Image
import ipywidgets.widgets as widgets
image widget = widgets.Image(format='jpeg', width=320, height=240)
display(image widget)
                                     # Display camera component
# Define the parse QR code interface
def decodeDisplay(image):
    barcodes = pyzbar.decode(image)
    for barcode in barcodes:
         # Extract the position of the bounding box of the QR code
  # Draw the bounding box of the barcode in the image
         (x, y, w, h) = barcode.rect
         cv2.rectangle(image, (x, y), (x + w, y + h), (225, 225, 225), 2)
         # Extract the QR code data as a byte object, so if we want to output the
image, you need to convert it to a string
         barcodeData = barcode.data.decode("utf-8")
         barcodeType = barcode.type
         # Draws the data and barcode type of the barcode on the image
         text = "{} ({})".format(barcodeData, barcodeType)
         cv2.putText(image, text, (x, y - 10), cv2.FONT HERSHEY SIMPLEX,0.5, (225,
225, 225), 2)
         # Print the data and barcode type of the barcode on the terminal
```



```
print("[INFO] Found {} barcode: {}".format(barcodeType, barcodeData))
    return image
def detect():
    camera = cv2.VideoCapture(0)
    camera.set(3, 320)
    camera.set(4, 240)
    camera.set(5, 120) # Set frame rate
    # fourcc = cv2.VideoWriter fourcc(*"MPEG")
    camera.set(cv2.CAP PROP FOURCC, cv2.VideoWriter.fourcc('M', 'J', 'P', 'G'))
    camera.set(cv2.CAP PROP BRIGHTNESS, 40) #Set brightness -64 - 64 0.0
    camera.set(cv2.CAP_PROP_CONTRAST, 50) #Set contrast -64 - 64 2.0
    camera.set(cv2.CAP PROP EXPOSURE, 156) #Set exposure 1.0 - 5000 156.0
    ret, frame = camera.read()
    image widget.value = bgr8 to jpeg(frame)
    while True:
         # Read frame currently
         ret, frame = camera.read()
         # To Grayscale image
         gray = cv2.cvtColor(frame, cv2.COLOR BGR2GRAY)
         im = decodeDisplay(gray)
         cv2.waitKey(5)
         image_widget.value = bgr8_to_jpeg(im)
         # If you press q, you will be out of the loop
         if cv2.waitKey(10) \& 0xFF == ord('q'):
              break
    camera.release()
    cv2.destroyAllWindows()
while 1:
    detect()
```

After run above program, put a QR code front the camera, it will be recognized.





```
[*]: while 1:
    detect()

[INFO] Found QRCODE barcode: Yahboom
```

We can click the pause button to stop the process. As shown below.

```
# Draws the acta and barcode type of the barcode on the image
text = "{} ({})".format(barcodeData, barcodeType)

cv2.putText(image, text, (x, y - 10), cv2.FONT HERSHEY SIMPLEX.0.5, (225.
```