

2.2.1 Drive buzzer

The hardware part is not shown in detail. The following is an introduction to API functions:

```
Buzzer_control (1) #Buzzer on  
Buzzer_control (0) #Buzzer off
```

Code path:

/home/pi/Yahboom_Project/2Hardware_Control_course/1_Buzzer.ipynb

```
# Import Raspblock Drive library
```

```
from Raspblock import Raspblock
```

```
robot = Raspblock()      # get object
```

```
robot.Buzzer_control(1)  # buzzer on
```

```
robot.Buzzer_control(0)  # buzzer off
```

```
del robot                # The object needs to be released after use, otherwise, when  
the next program needs to use this object module, it will be occupied and will  
become unusable
```