

QR code recognition

Introduction to QR Code

QR code uses a certain geometric figure to record data symbol information in a black and white pattern distributed on a plane (two-dimensional direction) according to a certain rule.

Code path:

/home/pi/Yahboom_Project/Raspbot/3.AI Vision course/06.QR code recognition/QR code recognition.ipynb

```
#bgr8 to jpeg format
import enum
import cv2

def bgr8_to_jpeg(value, quality=75):
    return bytes(cv2.imencode('.jpg', value)[1])

    # Import library and show camera display component
# import the necessary packages
#import simple_barcode_detection
import cv2
import numpy as np
import pyzbar.pyzbar as pyzbar
from PIL import Image
import ipywidgets.widgets as widgets

image_widget = widgets.Image(format='jpeg', width=320, height=240)
display(image_widget) # Display camera component

# Define the parse QR code interface
def decodeDisplay(image):
    barcodes = pyzbar.decode(image)
    for barcode in barcodes:
        # Extract the position of the bounding box of the QR code
        # Draw the bounding box of the barcode in the image
        (x, y, w, h) = barcode.rect
        cv2.rectangle(image, (x, y), (x + w, y + h), (225, 225, 225), 2)
        # Extract the QR code data as a byte object, so if we want to output the
        image, you need to convert it to a string
        barcodeData = barcode.data.decode("utf-8")
        barcodeType = barcode.type

        # Draws the data and barcode type of the barcode on the image
        text = "{} {}".format(barcodeData, barcodeType)
        cv2.putText(image, text, (x, y - 10), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (225, 225, 225), 2)
```

```

        # Print the data and barcode type of the barcode on the terminal
        print("[INFO] Found {} barcode: {}".format(barcodeType, barcodeData))
    return image

def detect():
    camera = cv2.VideoCapture(0)
    camera.set(3, 320)
    camera.set(4, 240)
    camera.set(5, 120) # Set frame rate
    # fourcc = cv2.VideoWriter_fourcc(*"MPEG")
    camera.set(cv2.CAP_PROP_FOURCC, cv2.VideoWriter.fourcc('M', 'J', 'P', 'G'))
    camera.set(cv2.CAP_PROP_BRIGHTNESS, 40) #Set brightness -64 - 64 0.0
    camera.set(cv2.CAP_PROP_CONTRAST, 50) #Set contrast -64 - 64 2.0
    camera.set(cv2.CAP_PROP_EXPOSURE, 156) #Set exposure 1.0 - 5000 156.0
    ret, frame = camera.read()
    image_widget.value = bgr8_to_jpeg(frame)
    while True:
        # Read frame currently
        ret, frame = camera.read()
        # To Grayscale image
        gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
        im = decodeDisplay(gray)

        cv2.waitKey(5)
        image_widget.value = bgr8_to_jpeg(im)
        # If you press q, you will be out of the loop
        if cv2.waitKey(10) & 0xFF == ord('q'):
            break
    camera.release()
    cv2.destroyAllWindows()

while 1:
    detect()

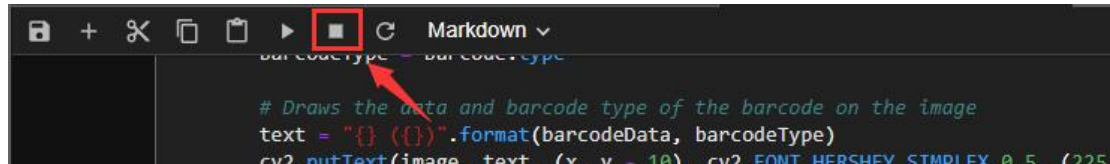
```

After run above program, put a QR code front the camera, it will be recognized.



```
[*]: while 1:  
    detect()  
  
[INFO] Found QRCODE barcode: Yahboom  
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```

We can click the pause button to stop the process. As shown below.



The screenshot shows a code editor interface. In the top toolbar, the pause button (a square icon) is highlighted with a red square. A red arrow points from the text below to this button. The code editor displays the following Python code:

```
barcodeType = barcodeType  
  
# Draws the data and barcode type of the barcode on the image  
text = "{} ({}).format(barcodeData, barcodeType)  
cv2.putText(image, text, (x, y - 10), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (225,
```