

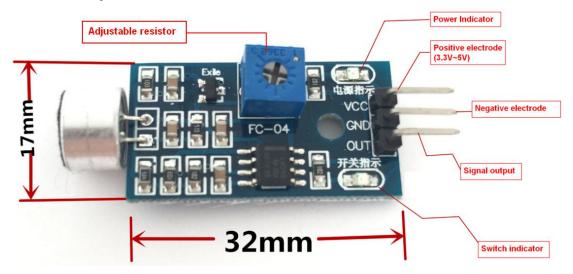
Course 25 ----Sound sensor

The purpose of the experiment:

In this course we mainly study the use of Sound sensors.

Introduction of Sound sensors:

The actual object is shown below.



List of components required for the experiment:

Arduino UNO board *1

USB cable *1

DC motor with mini fan *1

ULN2003 *1

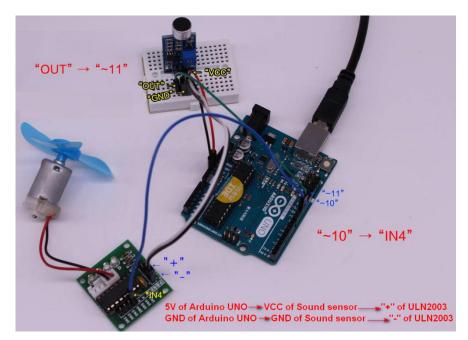
Sound sensor *1

Dupont line *1 bunch

Actual object connection diagram:

We need to connect the circuit as shown in the figure below.





Experimental code analysis:

int motor = 10; //The negative pole of the motor is connected to the drive plate in4, and the in4 is connected to the port 10 of Arduino UNO int voice = 11;

```
void setup()
{
    pinMode(motor, OUTPUT);
    pinMode(voice, INPUT);
}

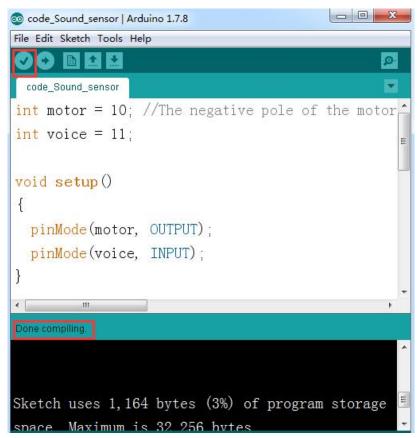
void loop()
{
    if (!digitalRead(voice)) //Determines whether the received data values conform to the range
    {
        digitalWrite(motor, HIGH);
        delay(10);
    }
    else
    {
        digitalWrite(motor, LOW);
    }
}
```

Experimental steps:

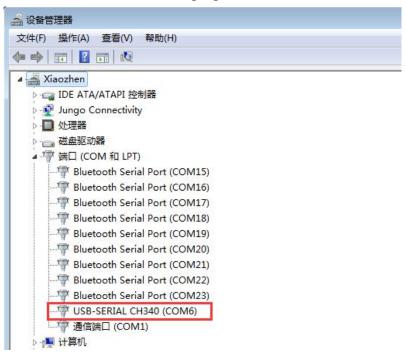
1. We need to open the program for this experiment:



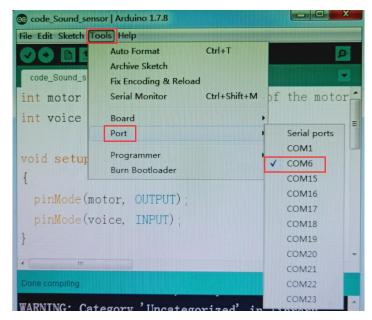
code_Sound_sensor.ino, click " $\sqrt{}$ "under the menu bar, compile the program, and wait for the words of **Done compiling** in the lower left corner, as shown in the following figure.



2. In the menu bar of Arduino IDE, you need to select the Tools J--- Port J--- select the port that the serial number displayed by the device manager just now.for example: COM6, as shown in the following figure.







3. After the selection is completed, you need to click "→"under the menu bar,and upload the program to the Arduino UNO board, when appears to **Done uploading** on the lower left corner, that means that the program has been successfully uploaded to the Arduino UNO board, as shown in the following figure.

```
© code_Sound_sensor | Arduino 1.7.8

File Edit Sketch Tools Help

code_Sound_sensor | Int motor = 10; //The negative pole of the motor int voice = 11;

void setup()
{
    pinMode(motor, OUTPUT);
    pinMode(voice, INPUT);
}

One uploading.

memory, leaving 2,035 bytes for local variables. Maximum is 2,048 bytes.
```

4. After the program is uploaded, the small fan will turn when we make a sound to the sound sensor.

(Note: You need to rotate the adjustable resistor on the sound sensor to change the sensitivity of the sound sensor for better experimental results)