

Spider advance

Learning goals:

In this lesson, we mainly learn how to control block motor by micro:bit and super:bit expansion board.

Code:

! Note:

Due to the problem of the building block structure, if you want the spider to move forward, the direction of the building block motor needs to be set backward.

```
1 from microbit import *
2 import superbit
3
4 display.show(Image.HEART)
5
6
7 while True:
8     superbit.motor_control(superbit.M1, -255, 0)
9     superbit.motor_control(superbit.M3, -255, 0)
10
11
```

import superbit library;

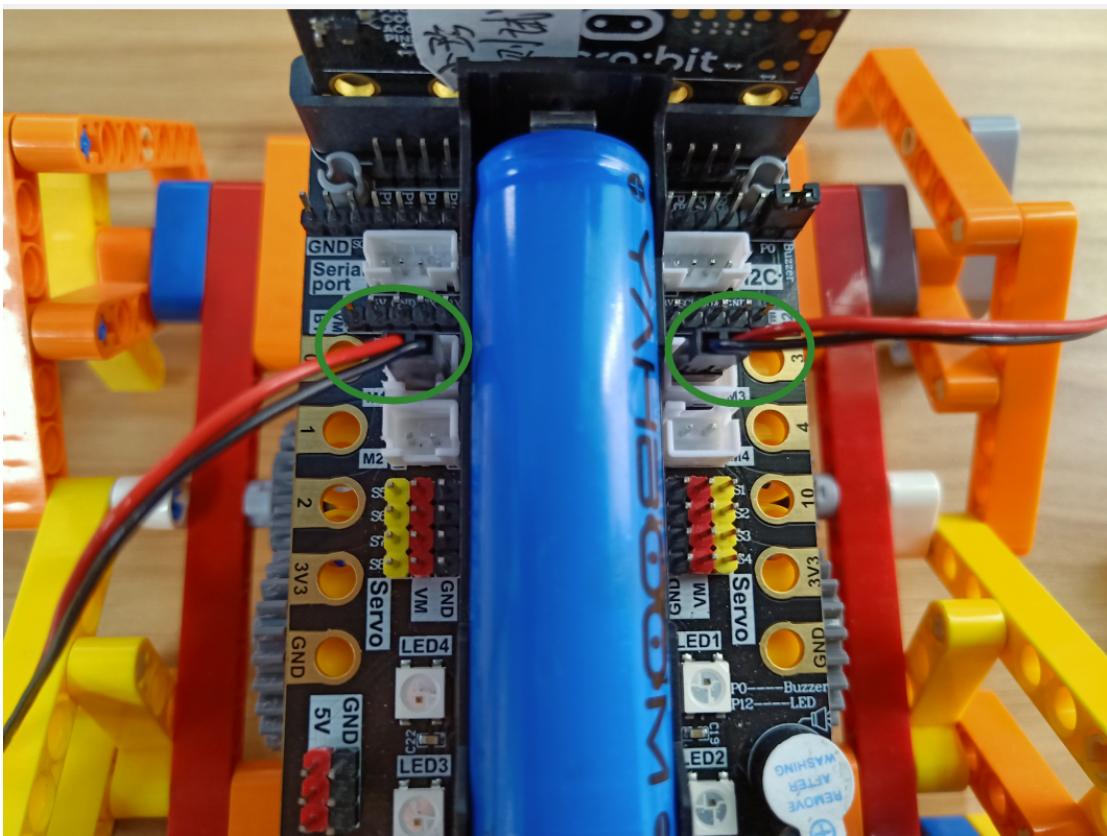
display.show (Image.HAPPY): Micro:bit dot matrix display smile pattern;

superbit.motor_control (superbit.M1, 255, 0): M1 is the interface on the super:bit board, speed is 255.

About wiring:

We need to connect two building block motors to the M1 and M3 interfaces of the Super:bit expansion board.

The black wiring of the motor is near the battery side. As shown below.



Programming and downloading:

1. You should open the Mu software, and enter the code in the edit window, , as shown below.

Note! All English and symbols should be entered in English, and the last line must be a space.

```

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2 import superbit
3
4 display.show(Image.HEART)
5
6 while True:
7     superbit.motor_control(superbit.M1, -255, 0)
8     superbit.motor_control(superbit.M3, -255, 0)
9
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```

2. You can click the “Check” button to check if our code has an error. If a line appears with a cursor or an underscore, the program indicating this line is wrong.

Mu 1.0.3 - Spider advance.py

```

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2 import superbit
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4 display.show(Image.HEART)
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7 while True:
8     superbit.motor_control(superbit.M1, -255, 0)
9     superbit.motor_control(superbit.M3, -255, 0)
10
11

```

Well done! No problems here.

3.Click the 'REPL' button to check whether the super:bit library has been downloaded. If not, please refer to the [1.preparation before class] ---> [2.How to import Yahboom superbit library] import super:bit library tutorial.

```

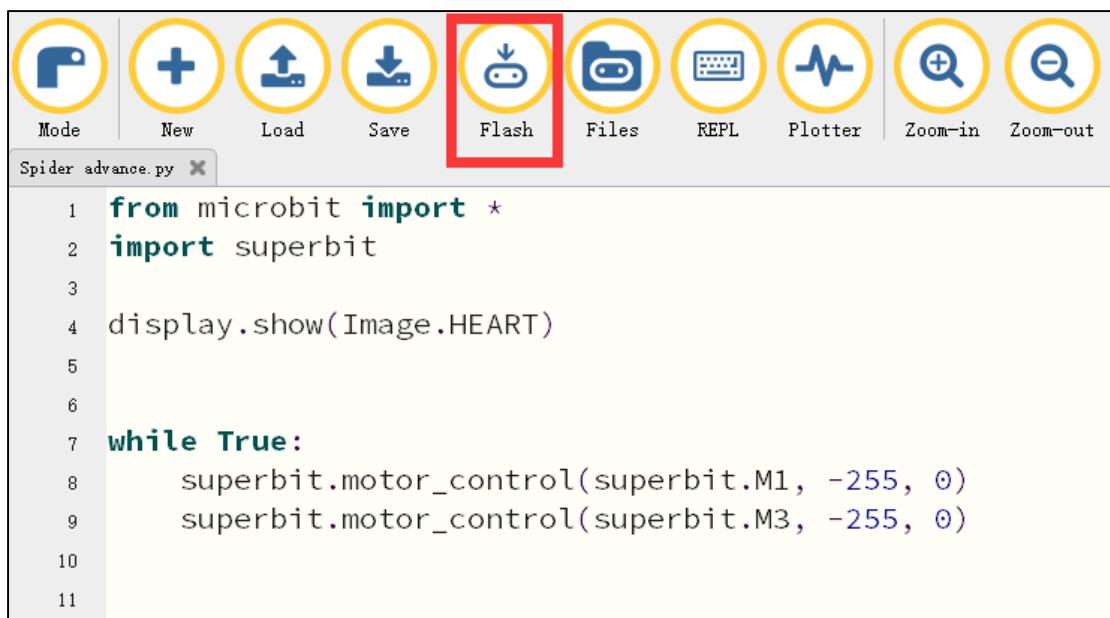
1 from microbit import *
2 import superbit
3
4 display.show(Image.HEART)
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9     superbit.motor_control(superbit.M3, -255, 0)
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11

```

BBC micro:bit REPL

MicroPython for Super:bit V1.1 modified by Yahboom Team
Type "help()" for more information.
>>>

4.After writing the code, please click the 'Flash' button to download the program to the micro:bit board.



```
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2 import superbit
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7 while True:
8     superbit.motor_control(superbit.M1, -255, 0)
9     superbit.motor_control(superbit.M3, -255, 0)
10
11
```

If the program is wrong or the experimental phenomenon is wrong after downloading, please confirm whether you have downloaded the superbit library hex file we provided to the micro: bit board.

For the specific method of adding library files, please refer to [【Preparation before class】](#) --- [【How to import Yahboom superbit library】](#)

6. After downloading the program, we can see micro:bit dot matrix will display “Heart” pattern and spider will advance.

If you need to start over, press the reset button on the back of the micro:bit board.