

## Gyroscope

### 1.Learning goals

In this lesson, we mainly learn how to control motor by micro:bit and Super:bit expansion board.

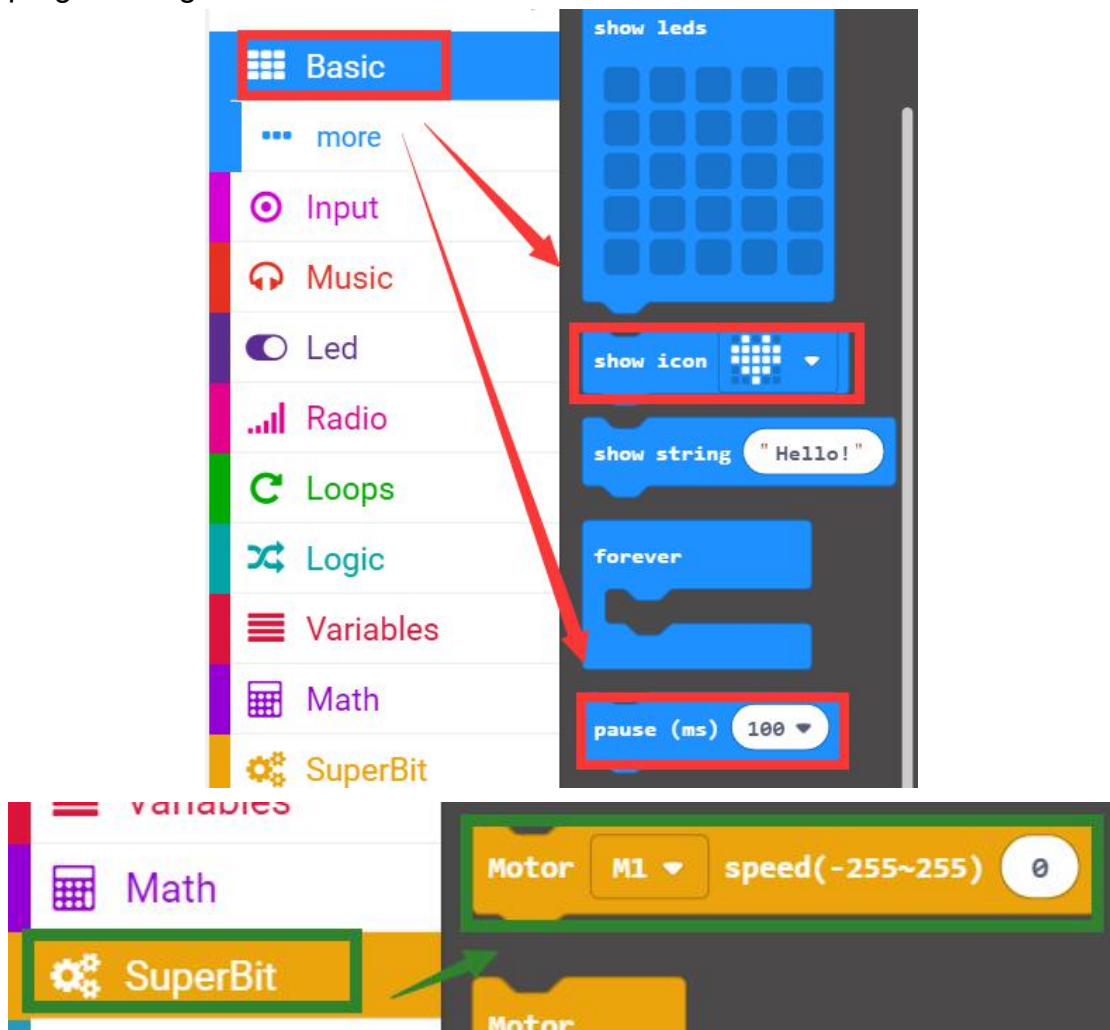
### 2.Programming method

**Mode 1 online programming:** First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: <http://microbit.org/> to enter the programming interface. Add the Yahboom package <https://github.com/lzty634158/SuperBit> to program.

**Mode 2 offline programming:** We need to open the offline programming software. After the installation is complete, enter the programming interface, click **【New Project】**, add Yahboom package: <https://github.com/lzty634158/SuperBit>, you can program.

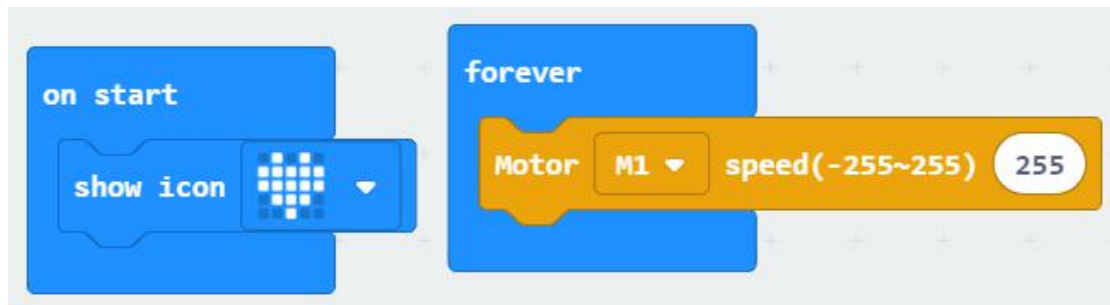
### 3.Looking for blocks

The following is the location of the building blocks required for this programming.



#### 4.Combine building block

The summary program is shown below:



#### 5.Assembly steps

Please refer to the [Gyroscope assembly steps](#) folder in the [Assembly instructions](#) folder for building blocks assembly steps.

#### 6.About wiring

We need to connect two building block motors to the **M1** interfaces of the Super:bit expansion board.

#### 7. Experimental phenomena

After the program is successfully downloaded, open the power, the micro:bit dot matrix will display the “heart” pattern, Motor will forward, the speed is 255.

If you need to restart, please press the reset button on the micro: bit board.