

Ferris wheel Rotate

1.Learning goals

In this lesson, we mainly learn how to control motor by micro:bit and Super:bit expansion board.

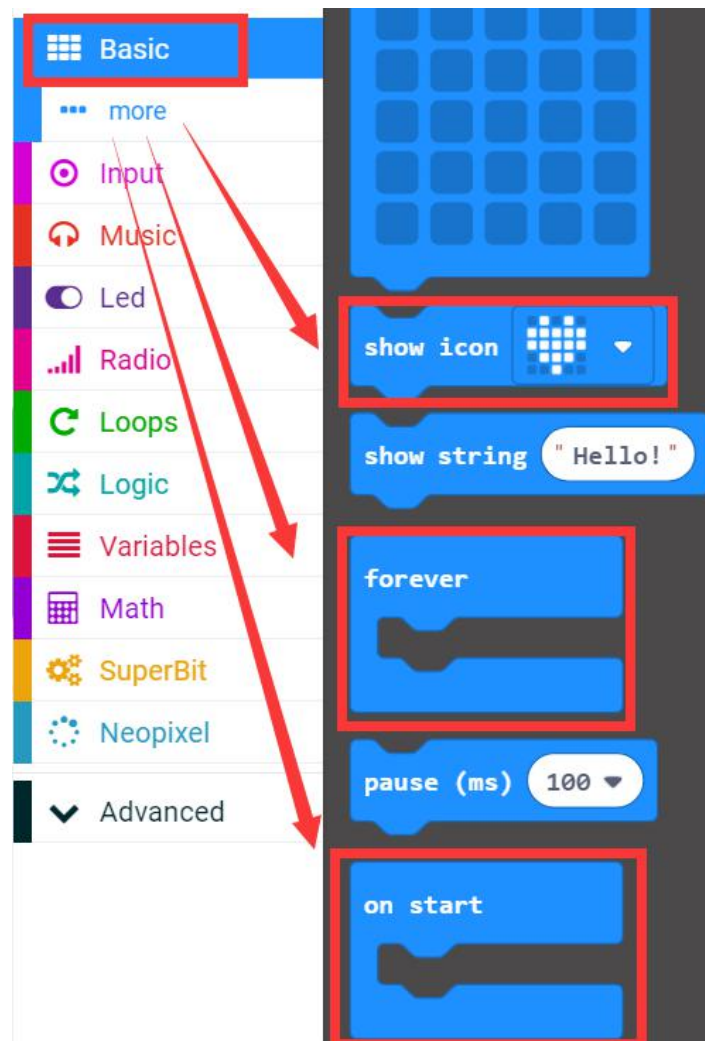
2.Programming method

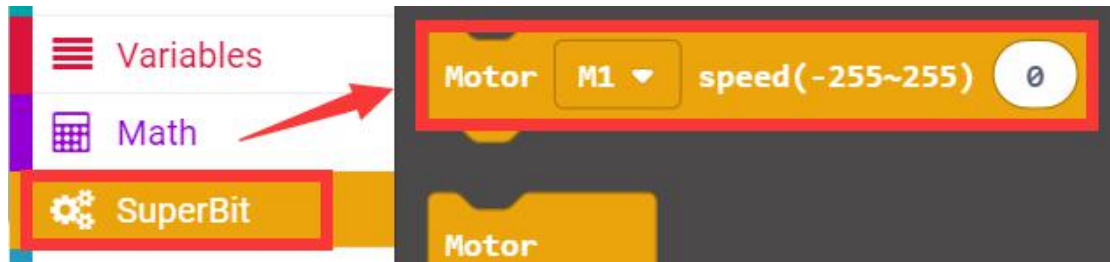
Mode 1 online programming: First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: <http://microbit.org/> to enter the programming interface. Add the Yahboom package <https://github.com/lzty634158/SuperBit> to program.

Mode 2 offline programming: We need to open the offline programming software. After the installation is complete, enter the programming interface, click **【New Project】**, add Yahboom package: <https://github.com/lzty634158/SuperBit>, you can program.

3.Looking for blocks

The following is the location of the building blocks required for this programming.





4.Combine building block

For details of the program, please import the [microbit-Ferris-wheel-rotate.hex](#) file into the MakeCode editor for viewing.



5.Assembly steps

Please refer to the [Ferris wheel assembly steps folder](#) in the [Assembly instructions](#) folder for building blocks assembly steps.

6.About wiring

We need to connect two building block motors to the **M1** interfaces of the Super:bit expansion board.

7. Experimental phenomena

After the program is successfully downloaded, open the power, the micro:bit dot matrix will display the “heart” pattern, and the motor will forward with 255 speed.

If you need to restart, please press the reset button on the micro: bit board.