

1. Instructions before use

1.1. Source code description

We provide two sets of function package source code, one is the function package source code that only drives radar and handheld radar mapping, and the other is the function package source code of our car tutorial case including mapping navigation and radar gameplay (**Note that this is It needs to be used with a car. Only the source code is provided here for learning**).

ydlidar_ws.tar.xz: This is a function package for driving radar and handheld radar mapping.

oradar_ws_src.tar.xz: Here is the function package source code of the car tutorial case. **This needs to be used with the car and is provided here for learning purposes.**

Generally, you can install the ydlidar_ws function package on your own motherboard. The function package installation shown in other cases requires some dependencies, and errors may occur during installation and compilation. The ** source code here is for reference only and will not actually run. **, but our company's robot products can achieve this, please be advised.

There is also a set called ros_ws_src.tar.xz, which contains codes related to the ROS1 basic tutorial.