15. Optical flow detection algorithm

1. Use

Code path: ~/yahboomcar_ws/src/opencv_apps/launch

• Start the camera

roslaunch yahboomcar_visual opencv_apps.launch img_flip:=false

• img_flip parameters: Whether the image needs to be flipped horizontally, the default is false.

[usb_cam-test.launch] file opens the [web_video_server] node by default, and you can directly use the [IP:8080] web page to view images in real time.

• Start the corner detection function of Opencv_apps

roslaunch opencv_apps fback_flow.launch # Optical flow detection algorithm

The debug_view for some functions is disabled, and there is no screen appearing. You can view the effect in the following two ways.

The reason for closing debug_view is that it will generate errors on the terminal, but the actual effect has not been affected!

Local View Screen

Enter the following command and select the corresponding topic to see the effect:

rqt_image_view

LAN viewing screen

(Same as under LAN) Enter IP+port in the browser, for example:

192.168.2.150:8080 # IP is the IP of the host computer

2. Effect display

Move the screen and observe the phenomenon.

