

LCD Display (SPI)

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1. Learning Objectives

1. Learn the basic knowledge of SPI communication.
2. Read the data in the flash and display it on the onboard LCD screen.

SPI Protocol

The SPI protocol (Serial Peripheral Interface) is a commonly used synchronous serial communication protocol designed for high-speed, short-distance communication between microcontrollers and external devices. It supports full-duplex communication, that is, data can be sent and received between the master and slave devices at the same time, and is commonly used in devices such as memory chips, sensors, display drivers, and wireless modules.

SPI Hardware Interface

The SPI protocol usually uses four lines for data transmission:

- **SCLK (Serial Clock):** The clock signal generated by the master device is used for synchronous communication.
- **MOSI (Master Output Slave Input):** The master device sends data to the slave device.
- **MISO (Master Input Slave Output):** The slave device sends data to the master device.
- **SS/CS (Slave Select):** The master device activates the target slave device through the chip select signal.

SPI Advantages

- Fast communication speed, suitable for high-bandwidth applications.
- Support full-duplex transmission, improve efficiency.
- Simple hardware implementation, direct interface.
- Support multiple slave device connections.

SPI Determinism

- Lack of standardized error detection mechanism.
- The number of master device pins increases with the number of slave devices.
- The communication distance is limited and is usually used for on-board communication.

2. Hardware Construction

W25Q32 is a common serial flash memory device that uses the SPI (Serial Peripheral Interface) interface protocol. It has high-speed read, write and erase functions and is widely used in high-performance electronic devices such as embedded systems, storage devices, routers, etc. The capacity of W25Q32 is 32 Mbit (ie 4 MB), and the numbers in the model represent different capacity options, such as W25Q16, W25Q64, W25Q128, etc., to meet the needs of different application scenarios.

The memory of the W25Q32 chip is allocated by sector (Sector) and block (Block). Specifically:

- **Sector:** Each sector is 4KB in size.
- **Block:** Each block contains 16 sectors, i.e., a block is 64KB in size.

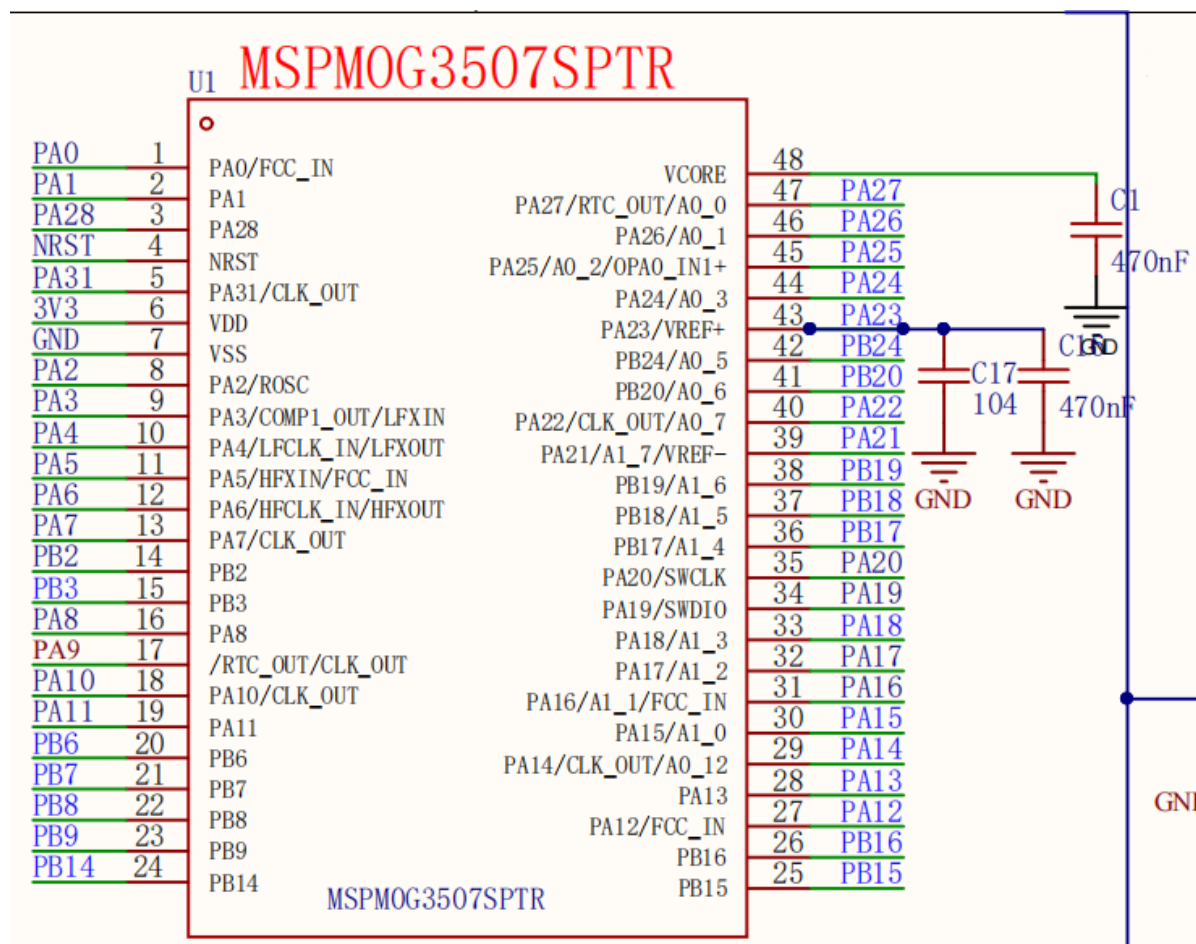
These storage unit structures make data management and storage operations more flexible, and are particularly suitable for embedded systems and storage applications that require frequent read and write operations.

We use the hardware SPI method to drive W25Q32, so we need to determine whether the pin we set has a hardware SPI peripheral interface. In the data sheet, PB14~PB17 can be multiplexed as 4 communication lines of SPI1.

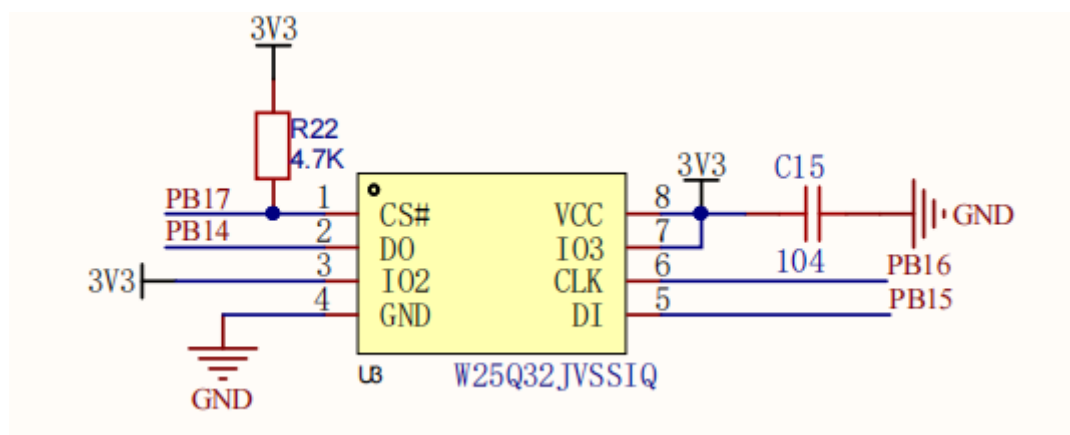
31	PB14		SPI1_CS3 [2] / SPI1_POCI [3] / SPI0_CS3 [4] / TIMG12_C1 [5] / TIMG8_IDX [6] / TIMA0_C0 [7]	2	24	-	-
32	PB15		UART2_TX [2] / SPI1_PICO [3] / UART3_CTS [4] / TIMG8_C0 [5] / TIMG7_C0 [6]	3	25	-	-
33	PB16		UART2_RX [2] / SPI1_SCK [3] / UART3_RTS [4] / TIMG8_C1 [5] / TIMG7_C1 [6]	4	26	-	-
43	PB17	A1_4 / COMP1_IN2-	UART2_TX [2] / SPI0_PICO [3] / SPI1_CS1 [4] / TIMA1_C0 [5] / TIMA0_C2 [6]	14	36	-	-

This course does not require additional hardware equipment, and can directly use the onboard LCD screen and external storage flash on the MSPM0G3507 motherboard.

MSPM0G3507 main control diagram:

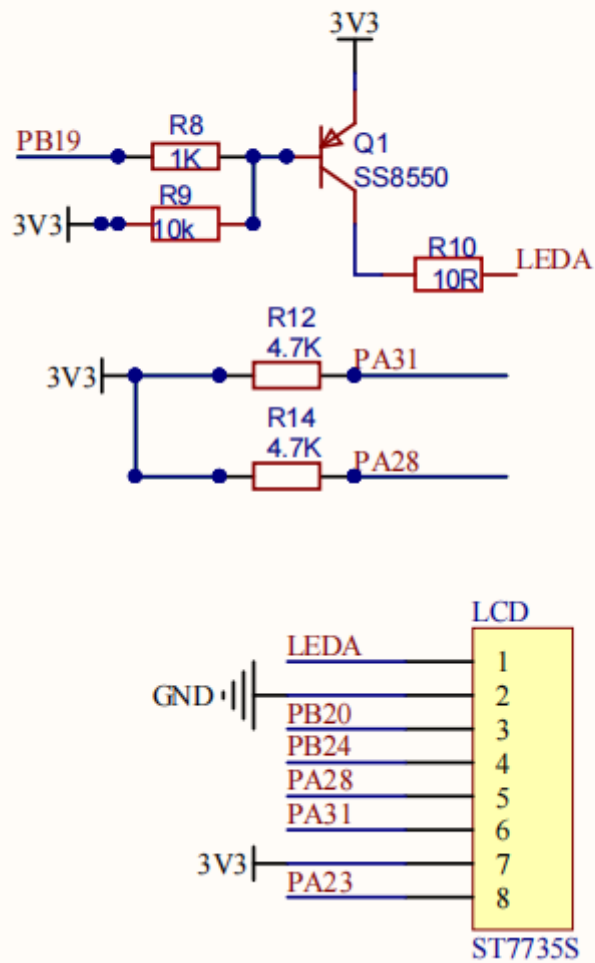


W25Q32 partial schematic diagram:



LCD screen partial schematic diagram:

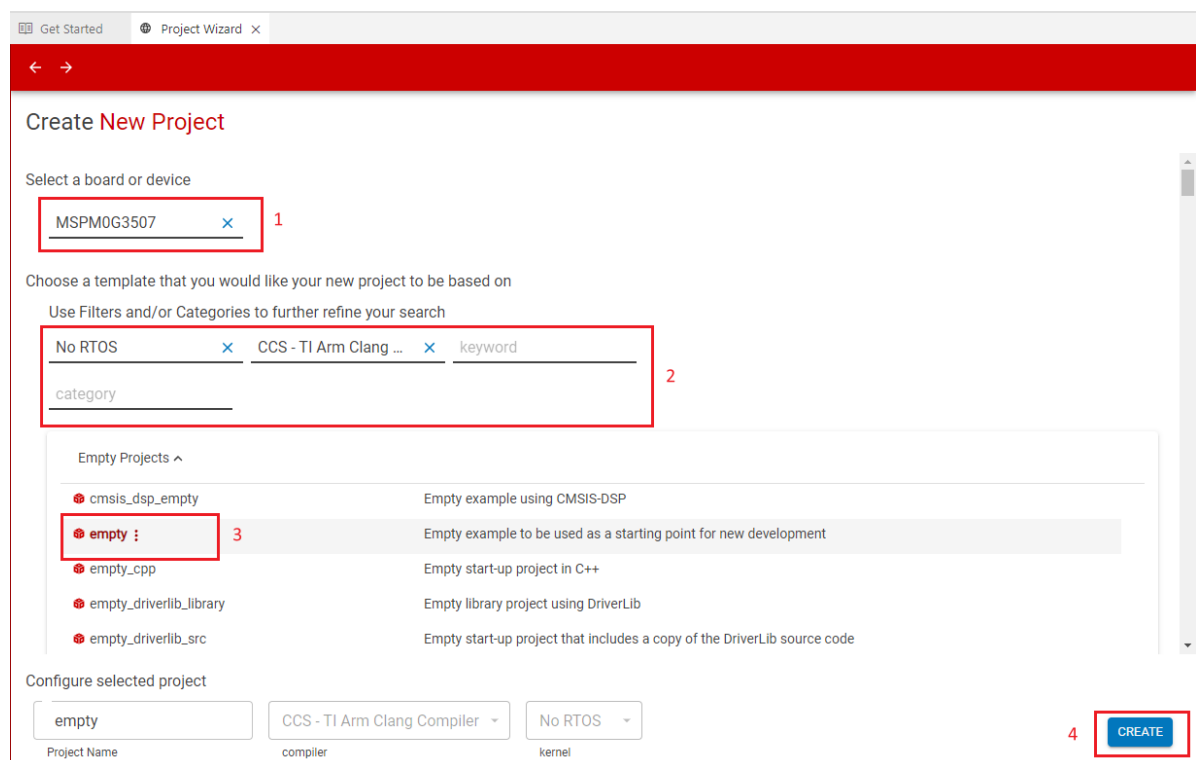
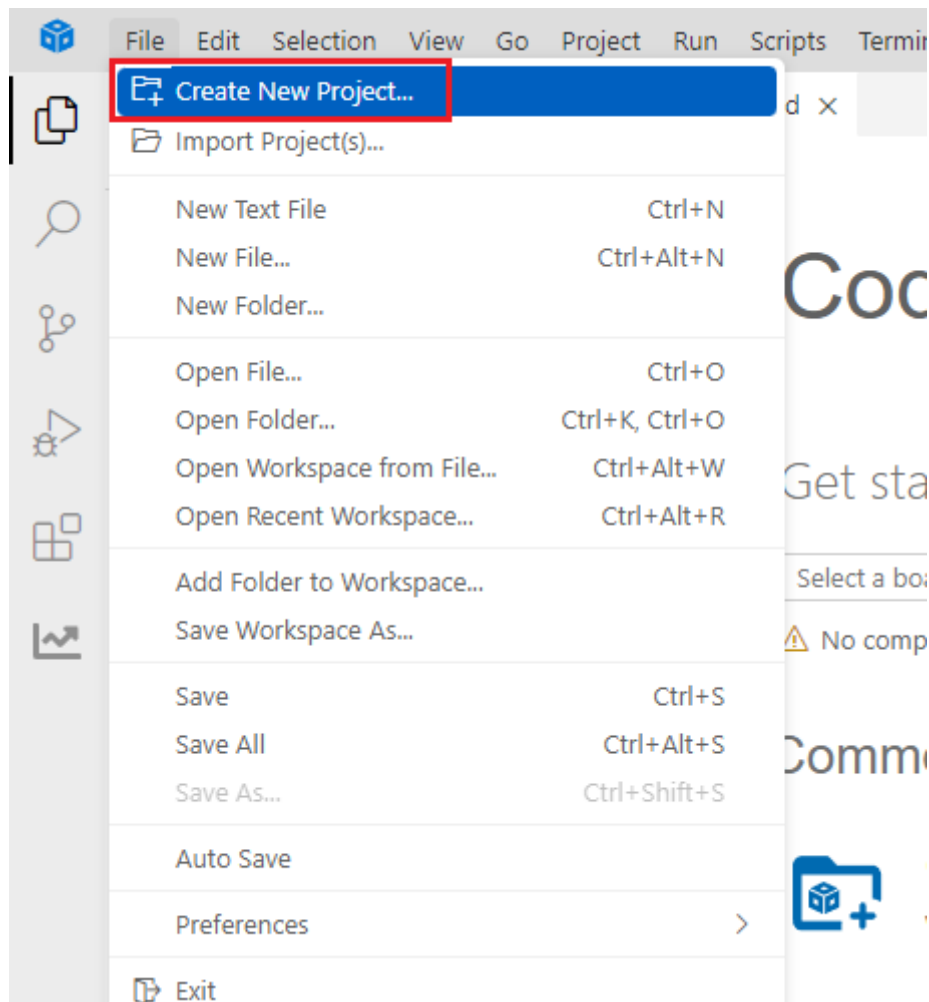
LCD Display



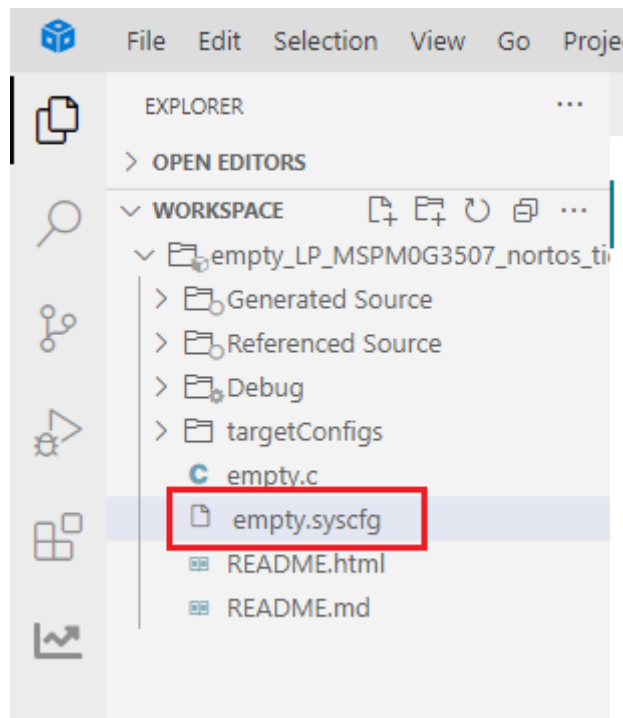
3. Experimental steps

1. Open the SYSCONFIG configuration tool

Create a blank project empty in CCS.



Find and open the empty.syscfg file in the left workspace of CCS.



2. SPI parameter configuration

Find the SPI column on the left, click to enter, and add SPI peripherals.

The interface shows the 'SPI (0 of 2 Added)' configuration page. The left pane lists the following categories and items:

- PROJECT CONFIGURATION (1)
 - Project Configur... 1/1 ✓ (+)
- MSPM0 DRIVER LIBRARY (7)
 - SYSTEM (9)
 - Board 1/1 ✓ (+)
 - Configuration NVM (+)
 - DMA (+)
 - GPIO 1 ✓ (+)
 - MATHACL (+)
 - RTC (+)
 - SYSCTL 1/1 ✓ (+)
 - SYSTICK (+)
 - WWDT (+)
 - ANALOG (6)
 - ADC12 (+)
 - COMP (+)
 - DAC12 (+)
 - GPAMP (+)
 - OPA (+)
 - VREF (+)
 - COMMUNICATIONS (6)
 - I2C (+)
 - I2C - SMBUS (+)
 - MCAN (+)
 - SPI** (+) (highlighted)
 - UART (+)
 - UART - LIN (+)
 - TIMERS (6)

The right pane shows the 'SPI (0 of 2 Added)' configuration page. It includes a description of the SPI module, configuration options for Basic and Advanced users, and a functional block diagram. The 'ADD' button is highlighted with a red rectangle.

Description

The **SPI module** provides an interface for synchronous serial communication with peripheral devices and other controllers.

Under *Basic Configuration* users can:

- Enable and configure SPI initialization parameters:
 - Mode select
 - Clock configuration
 - Frame configuration
 - Chip select

Under *Advanced Configuration* users can:

- Enable/configure parity mode
- Configure TX/RX FIFO thresholds
- Enable command data mode and/or internal loopback
- Configure sampling parameters

SPI Functional Block Diagram:

The diagram shows the SPI Control block receiving inputs from SYSCLK, MFCLK, and LFCLK. It contains a Clock Control block with CLKSEL and CLKDIV. The output is the SPI Clock.

Click the **Add** button to add a SPI to your design

SPI (1 of 2 Added) ⓘ

+ ADD
= REMOVE ALL

✓
SPI

📄
🗑️

i Peripheral does not retain register contents in STOP or STANDBY modes. User should take care to save and restore register configuration in application. See Retention Configuration section for more details.

Name
SPI

Selected Peripheral
SPI1

Quick Profiles
^

SPI Profiles
Custom ▾

Basic Configuration
^

SPI Initialization Configuration
^

Mode Select
Controller ▾

Clock Configuration
▾

Target Bit Rate (Hz)
16000000

Calculated Bit Rate
16000000.00 ▾

Calculated Error (%)
0

Frame Format
Motorola 3-wire ▾

Clock Polarity
Low ▾

Phase
Data captured on first clock edge ▾

Frame Size (bits)
8 ▾

Bit Order
MSB ▾

Advanced Configuration
^

Parity
Disabled ▾

RX FIFO Threshold Level
RX FIFO contains >= 2 entries ▾

TX FIFO Threshold Level
TX FIFO contains <= 2 entries ▾

Communication Direction
PICO and POCI ▾

Enable Packing
☐

In most SPI protocols, the chip select is always pulled low during the entire timing when sending and receiving, and the chip select of the SPI peripheral will be pulled high after each frame is sent and received, so the CS chip select line needs to be independently controlled by the MCU's IO port, and there is no way to use the CS pin of the SPI peripheral. **Here, the GPIO method (software method) is used to control the output of the CS pin.**

PinMux Peripheral and Pin Configuration
^

SPI Peripheral
SPI1 ▾
🔒

SPI SCLK (Clock)
PB16/4 ▾
🔒

SPI PICO (Peripheral In, Controller Out)
PB15/3 ▾
🔒

SPI POCI (Peripheral Out, Controller In)
PB14/2 ▾
🔒

3. Pin parameter configuration

LCD screen

Backlight **BLK**:

GPIO (6 Added) ?

✓ BLK

✓ CS

✓ DC

✓ RES

✓ MOSI

✓ SCLK

+

ADD

REMOVE ALL

Name

BLK

Port

PORTB

Port Segment

Any

Group Pins

^

1 added

+

ADD

REMOVE ALL

✓ PIN_19

Name

PIN_19

Direction

Output

Initial Value

Set

IO Structure

Any

Digital IOMUX Features

▼

Assigned Port

PORTB

Assigned Port Segment

Any

Assigned Pin

19

Interrupts/Events

▼

CS, DC, RES, MOSI, SCLK are as follows:

GPIO (6 Added) ⓘ

ADD REMOVE ALL

BLK

CS

DC

RES

MOSI

SCLK

Name

CS

Port

PORTA

Port Segment

Any

Group Pins

1 added

ADD REMOVE ALL

PIN_23

Name

PIN_23

Direction

Output

Initial Value

Cleared

IO Structure

Any

Digital IOMUX Features

Assigned Port

PORTA

Assigned Port Segment

Any

Assigned Pin

23

Interrupts/Events

GPIO (6 Added) ⓘ

ADD REMOVE ALL

BLK

CS

DC

RES

MOSI

SCLK

Name

DC

Port

PORTB

Port Segment

Any

Group Pins

1 added

ADD REMOVE ALL

PIN_24

Name

PIN_24

Direction

Output

Initial Value

Cleared

IO Structure

Any

Digital IOMUX Features

Assigned Port

PORTB

Assigned Port Segment

Any

Assigned Pin

24

Interrupts/Events

GPIO (6 Added) ⓘ

ADD REMOVE ALL

BLK

CS

DC

RES

MOSI

SCLK

Name

RES

Port

PORTB

Port Segment

Any

Group Pins

1 added

ADD REMOVE ALL

PIN_20

Name

PIN_20

Direction

Output

Initial Value

Cleared

IO Structure

Any

Digital IOMUX Features

Assigned Port

PORTB

Assigned Port Segment

Any

Assigned Pin

20

Interrupts/Events

GPIO (6 Added) ⓘ

ADD REMOVE ALL

BLK

CS

DC

RES

MOSI

SCLK

Name

SCLK

Port

PORTA

Port Segment

Any

Group Pins

1 added

ADD REMOVE ALL

PIN_31

Name

PIN_31

Direction

Output

Initial Value

Cleared

IO Structure

Any

Digital IOMUX Features

Assigned Port

PORTA

Assigned Port Segment

Any

Assigned Pin

31

Interrupts/Events

GPIO (6 Added) ⓘ

ADD REMOVE ALL

BLK

CS

DC

RES

MOSI

SCLK

Name

MOSI

Port

PORTA

Port Segment

Any

Group Pins

1 added

ADD REMOVE ALL

PIN_28

Name

PIN_28

Direction

Output

Initial Value

Cleared

IO Structure

Any

Digital IOMUX Features

Assigned Port

PORTA

Assigned Port Segment

Any

Assigned Pin

28

Interrupts/Events

External Flash

CS1:

CS1

Name	CS1
Port	Any
Port Segment	Any

Group Pins

1 added

+

 ADD

REMOVE ALL

✓ PIN_17

Name	PIN_17
Direction	Output
Initial Value	Cleared
IO Structure	Any

Digital IOMUX Features

Assigned Port	PORTB
Assigned Port Segment	Any
Assigned Pin	17

Interrupts/Events

LaunchPad-Specific Pin	No Shortcut Used
------------------------	------------------

PinMux Peripheral and Pin Configuration

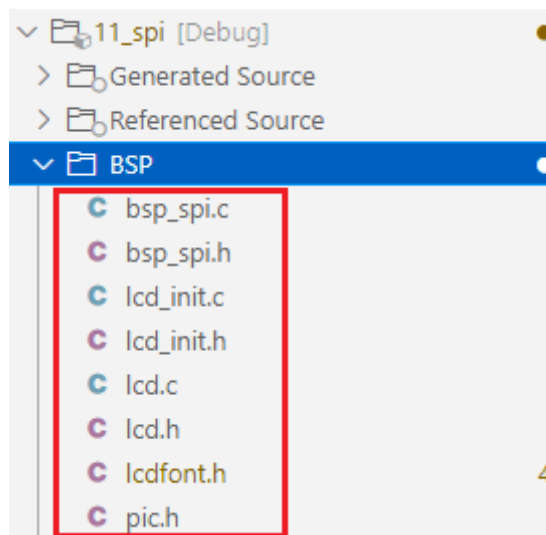
PIN_17

Any(PB17/14)

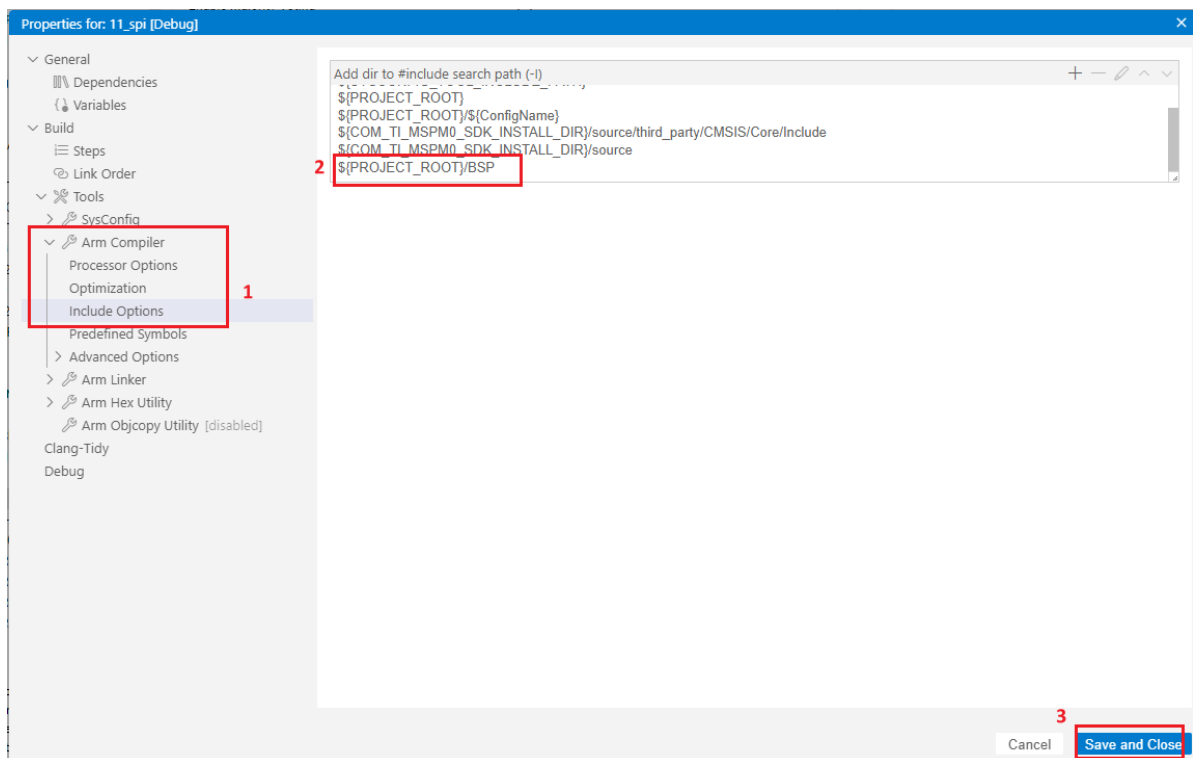
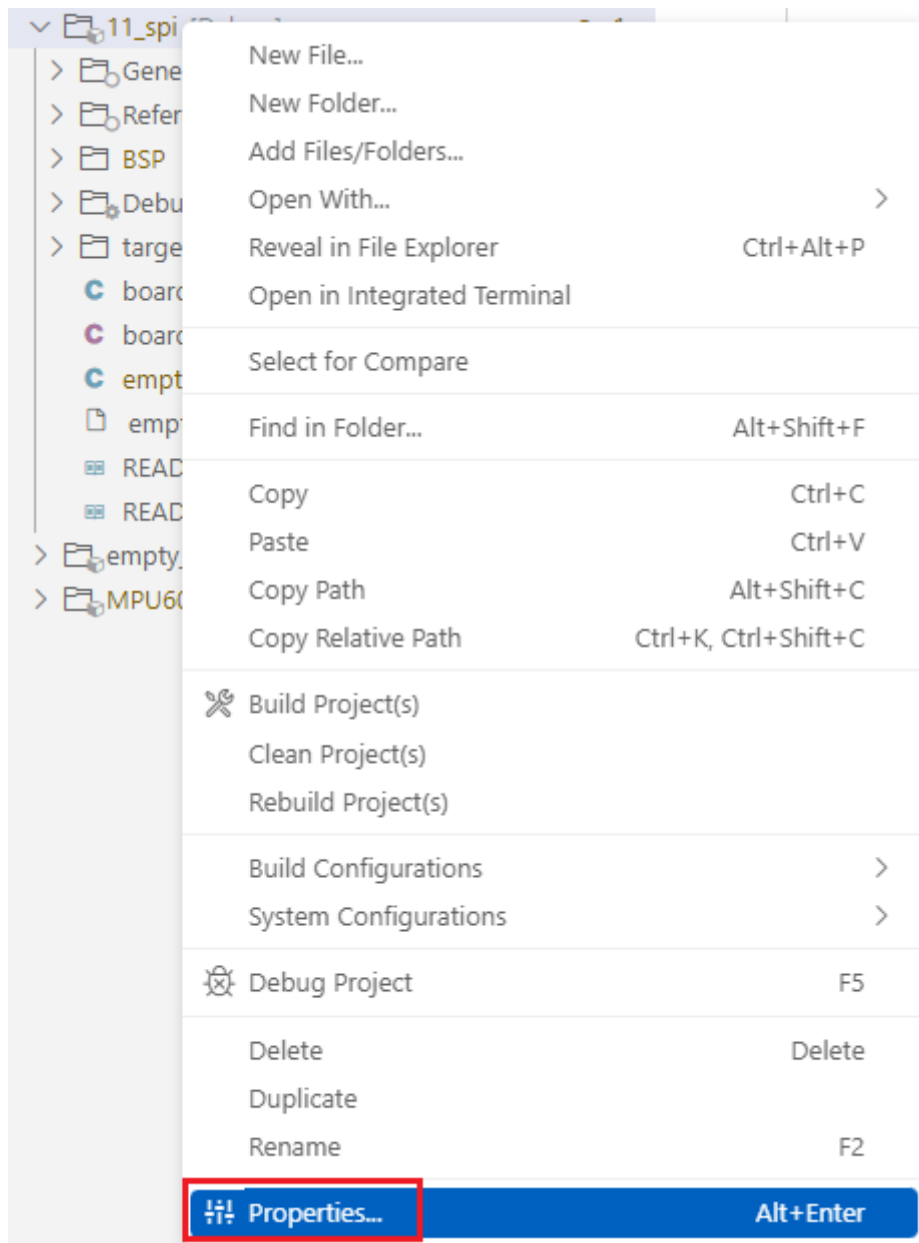
4. Use of SPI protocol

We create a new folder under the project folder: `BSP`. Create four more files under the BSP folder, namely `lcd.c`, `lcd.h`, `bsp_spi.c` and `bsp_spi.h`.

Include the following LCD display drivers and fonts, and put them in the BSP folder



Update the header file path and right-click the project folder.



5. Write program

Define the operation interface and related functions of the LCD display

lcd.h

```
#ifndef __LCD_H
#define __LCD_H
#include <stdint.h>

void LCD_Fill(uint16_t xsta,uint16_t ysta,uint16_t xend,uint16_t yend,uint16_t
color);//指定区域填充颜色 Specify area fill color
void LCD_DrawPoint(uint16_t x,uint16_t y,uint16_t color);//在指定位置画一个点 Draw a
point at the specified location
void LCD_DrawLine(uint16_t x1,uint16_t y1,uint16_t x2,uint16_t y2,uint16_t
color);//在指定位置画一条线 Draw a line at the specified position
void LCD_DrawRectangle(uint16_t x1, uint16_t y1, uint16_t x2, uint16_t
y2,uint16_t color);//在指定位置画一个矩形 Draw a rectangle at the specified location
void Draw_Circle(uint16_t x0,uint16_t y0,uint8_t r,uint16_t color);//在指定位置画一
个圆 Draw a circle at the specified location

void LCD_ShowChinese(uint16_t x,uint16_t y,uint8_t *s,uint16_t fc,uint16_t
bc,uint8_t sizey,uint8_t mode);//显示汉字串 Display Chinese character string
void LCD_ShowChinese12x12(uint16_t x,uint16_t y,uint8_t *s,uint16_t fc,uint16_t
bc,uint8_t sizey,uint8_t mode);//显示单个12x12汉字 Display a single 12x12 Chinese
character
void LCD_ShowChinese16x16(uint16_t x,uint16_t y,uint8_t *s,uint16_t fc,uint16_t
bc,uint8_t sizey,uint8_t mode);//显示单个16x16汉字 Display a single 16x16 Chinese
character
void LCD_ShowChinese24x24(uint16_t x,uint16_t y,uint8_t *s,uint16_t fc,uint16_t
bc,uint8_t sizey,uint8_t mode);//显示单个24x24汉字 Display a single 24x24 Chinese
character
void LCD_ShowChinese32x32(uint16_t x,uint16_t y,uint8_t *s,uint16_t fc,uint16_t
bc,uint8_t sizey,uint8_t mode);//显示单个32x32汉字 Display a single 32x32 Chinese
character

void LCD_ShowChar(uint16_t x,uint16_t y,uint8_t num,uint16_t fc,uint16_t
bc,uint8_t sizey,uint8_t mode);//显示一个字符 Display a character
void LCD_ShowString(uint16_t x,uint16_t y,const uint8_t *p,uint16_t fc,uint16_t
bc,uint8_t sizey,uint8_t mode);//显示字符串 Display String
uint32_t mypow(uint8_t m,uint8_t n);//求幂 Power
void LCD_ShowIntNum(uint16_t x,uint16_t y,uint16_t num,uint8_t len,uint16_t
fc,uint16_t bc,uint8_t sizey);//显示整数变量 Display integer variables
void LCD_ShowFloatNum1(uint16_t x,uint16_t y,float num,uint8_t len,uint16_t
fc,uint16_t bc,uint8_t sizey);//显示两位小数变量 Display variables with two decimal
places

void LCD_ShowPicture(uint16_t x,uint16_t y,uint16_t length,uint16_t width,const
uint8_t pic[]);//显示图片 Show image

//画笔颜色 Brush Color
#define WHITE          0xFFFF
#define BLACK          0x0000
#define BLUE           0x001F
#define BRED           0XF81F
```

```

#define GRED          0xFFE0
#define GBLUE         0x07FF
#define RED           0xF800
#define MAGENTA       0xF81F
#define GREEN         0x07E0
#define CYAN          0x7FFF
#define YELLOW        0xFFE0
#define BROWN         0xBC40 //棕色 Brown
#define BRRED         0xFC07 //棕红色 Brown red
#define GRAY          0x8430 //灰色 Gray
#define DARKBLUE      0x01CF //深蓝色 Dark blue
#define LIGHTBLUE     0x7D7C //浅蓝色 Light blue
#define GRAYBLUE      0x5458 //灰蓝色 Gray blue
#define LIGHTGREEN     0x841F //浅绿色 Light green
#define LGRAY         0xC618 //浅灰色(PANNEL),窗体背景色 Light gray (PANNEL),
window background color
#define LGRAYBLUE     0xA651 //浅灰蓝色(中间层颜色) Light gray blue (middle layer
color)
#define LBBLUE        0x2B12 //浅棕蓝色(选择条目的反色) Light brown blue
(inverted color of selected item)

#endif

```

Next is the LCD display driver

lcd.c (only part of it is captured here, please check the project source code for details)

```

#include "lcd.h"
#include "lcd_init.h"
#include "lcdfont.h"
#include "board.h"

/*****
    函数说明：在指定区域填充颜色
    入口数据：xsta,ysta    起始坐标
                xend,yend    终止坐标
                color        要填充的颜色
    返回值：    无
    Function description: Fill the specified area with color
    Input data: xsta, ysta starting coordinates
                xend, yend ending coordinates
                color the color to be filled
    Return value: None
*****/
void LCD_Fill(uint16_t xsta,uint16_t ysta,uint16_t xend,uint16_t yend,uint16_t
color)
{
    uint16_t i,j;
    LCD_Address_Set(xsta,ysta,xend-1,yend-1);//设置显示范围 Set the display range
    for(i=ysta;i<yend;i++)
    {
        for(j=xsta;j<xend;j++)
        {
            LCD_WR_DATA(color);
        }
    }
}

```

```

}

/*****
    函数说明：在指定位置画点
    入口数据：x,y 画点坐标
               color 点的颜色
    返回值： 无
    Function description: Draw a point at the specified position
    Input data: x, y coordinates of the point
               color color of the point
    Return value: None
*****/
void LCD_DrawPoint(uint16_t x,uint16_t y,uint16_t color)
{
    LCD_Address_Set(x,y,x,y);//设置光标位置 Set the cursor position
    LCD_WR_DATA(color);
}
...

```

bsp_spi.h

```

#ifndef _BSP_SPI_H__
#define _BSP_SPI_H__

#include "board.h"

//CS引脚的输出控制
//x=0时输出低电平
//x=1时输出高电平
//CS pin output control
//x=0 when output is low level
//x=1 when output is high level
#define SPI_CS(x) ( (x) ? DL_GPIO_SetPins(CS1_PORT,CS1_PIN_17_PIN) :
DL_GPIO_ClearPins(CS1_PORT,CS1_PIN_17_PIN) )

uint16_t w25q32_readID(void);//读取w25q32的ID Read the ID of w25q32
void w25q32_write(uint8_t* buffer, uint32_t addr, uint16_t numbyte);
//w25q32写数据 w25q32 write data
void w25q32_read(uint8_t* buffer,uint32_t read_addr,uint16_t
read_length);//w25q32读数据 w25q32 Read Data
#endif

```

The initialization of SPI has been configured in SYSCONFIG, but we still need to prepare the SPI read and write steps. To ensure the success of sending and receiving data, when sending, you need to ensure that the data in the send buffer is sent, that is, the send buffer is empty, before the next data can be sent; when receiving, you need to ensure that there is data in the receive buffer before receiving.

bsp_spi.c (only part of it is intercepted here, please refer to the project source code for details)

```

#include "bsp_spi.h"

uint8_t spi_read_write_byte(uint8_t dat)
{
    uint8_t data = 0;

```

```

        //发送数据 Sending Data
        DL_SPI_transmitData8(SPI_INST,dat);
        //等待SPI总线空闲 Wait for the SPI bus to be idle
        while(DL_SPI_isBusy(SPI_INST));
        //接收数据 Receiving Data
        data = DL_SPI_receiveData8(SPI_INST);
        //等待SPI总线空闲 Wait for the SPI bus to be idle
        while(DL_SPI_isBusy(SPI_INST));

        return data;
    }
    ...

```

Then write the following code in the empty.c file

```

#include "ti_msp_dl_config.h"
#include "board.h"
#include "lcd_init.h"
#include "lcd.h"
#include "pic.h"
#include "bsp_spi.h"
#include <stdint.h>
#include <stdio.h>

int main(void)
{
    unsigned char buff[10] = {0};

    //开发板初始化 Development board initialization
    board_init();

    delay_ms(100); //等待部署 waiting for deployment

    //读取W25Q32的ID Read the ID of W25Q32
    printf("ID = %X\r\n",W25Q32_readID());

    //读取0地址的5个字节数据到buff Read 5 bytes of data from address 0 to buff
    W25Q32_read(buff, 0, 7);

    //串口输出读取的数据 Serial port outputs the read data
    printf("buff = %s\r\n",buff);

    //往0地址写入5个字节长度的数据 ABCD Write 5 bytes of data ABCD to address 0
    W25Q32_write("Yahboom", 0, 7);
    delay_ms(100);

    //读取0地址的5个字节数据到buff Read 5 bytes of data from address 0 to buff
    W25Q32_read(buff, 0, 7);

    //串口输出读取的数据 Serial port outputs the read data
    // printf("buff = %s\r\n",buff);

    SYSCFG_DL_init();

    LCD_Init(); //LCD初始化 LCD Initialization

```

```

LCD_Fill(0,0,LCD_W,LCD_H,WHITE);
LCD_ShowPicture(20,45,120,29,gImage_pic1);
LCD_ShowString(10,0,"Hello!",BLACK,WHITE,16,0);
// LCD_ShowChinese(50,20,"亚博智能",BLACK,WHITE,16,0);

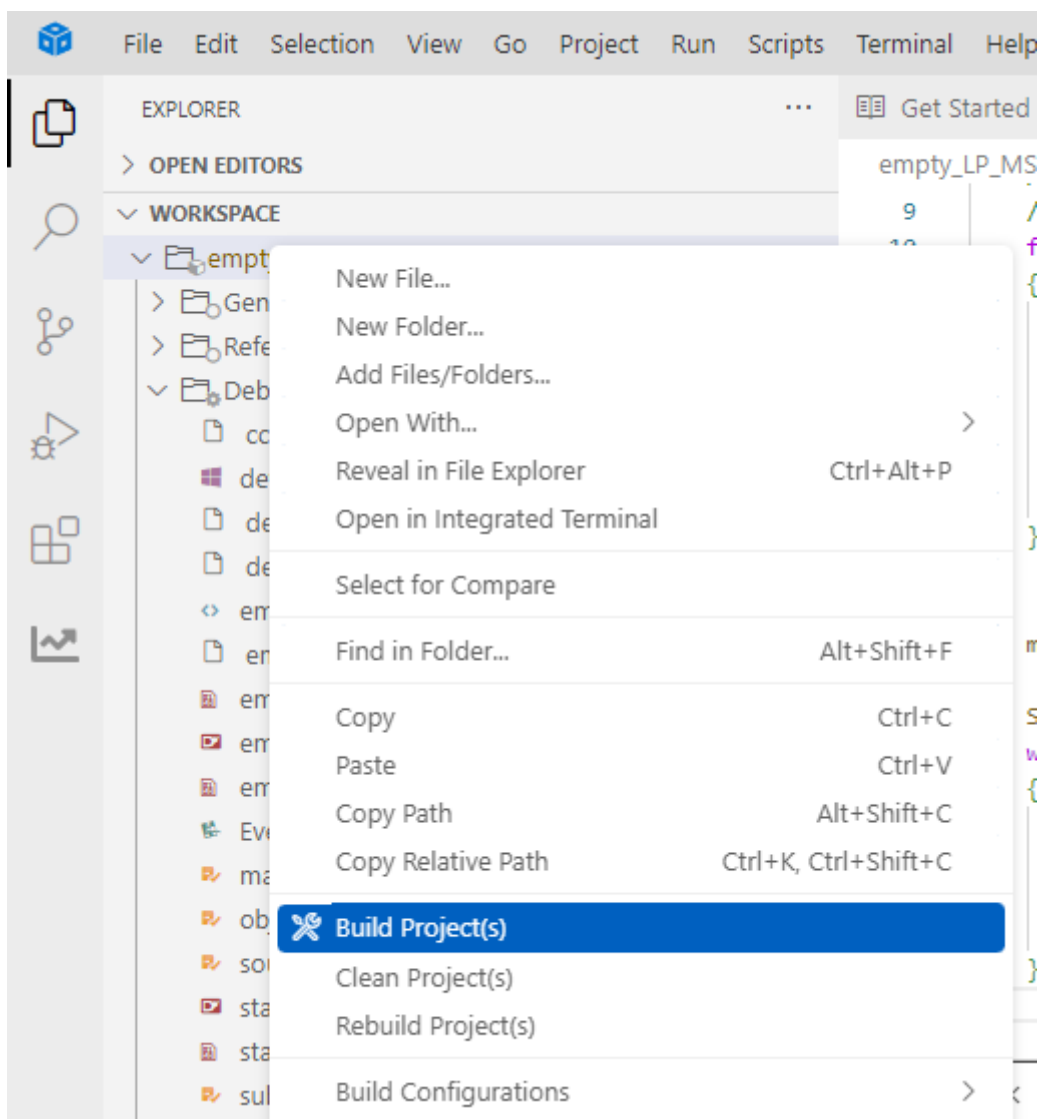
// 显示 buff 中的内容在同一行上 Display the contents of buff on the same line
int x = 54; // 起始 x 坐标 Starting x coordinate
for (int i = 0; i < 7; i++)
{
    char str[2] = {buff[i], '\0'}; // 每次取一个字符 Take one character at a
time
    LCD_ShowString(x, 25, str,BLACK, WHITE, 16, 0); // 显示字符 Display
Characters
    x += 8; // 每个字符的宽度为 8, x 坐标向右偏移 Each character is 8 wide and
has an x-coordinate offset to the right.
}

while (1)
{

}
}

```

6. Compile



Once the compilation is successful, you can download the program to the development board.

4. Program Analysis

- lcd.c

```
432 /*****
433 函数说明: 显示图片
434 入口数据: x,y起点坐标
435          length 图片长度
436          width 图片宽度
437          pic[] 图片数组
438 返回值: 无
439 Function description: Display image
440 Input data: x, y starting point coordinates
441          length Image length
442          width Image width
443          pic[] Image array
444 Return value: None
445 *****/
446 void LCD_ShowPicture(uint16_t x,uint16_t y,uint16_t length,uint16_t width,const uint8_t pic[])
447 {
448     uint16_t i,j;
449     uint32_t k=0;
450     LCD_Address_Set(x,y,x+length-1,y+width-1);
451     for(i=0;i<length;i++)
452     {
453         for(j=0;j<width;j++)
454         {
455             LCD_WR_DATA8(pic[k*2]);
456             LCD_WR_DATA8(pic[k*2+1]);
457             k++;
458         }
459     }
460 }
```

The `LCD_ShowPicture` function draws the picture at the specified starting point `(x, y)`, sets the display area according to the given length and width, and writes the color data of each pixel to the LCD by traversing the picture array to complete the picture display.

```
309 /*****
310 函数说明: 显示字符串
311 入口数据: x,y显示坐标
312          *p 要显示的字符串
313          fc 字的颜色
314          bc 字的背景色
315          sizey 字号
316          mode: 0非叠加模式 1叠加模式
317 返回值: 无
318 Function description: Display string
319 Input data: x, y display coordinates
320          *p string to be displayed
321          fc color of the word
322          bc background color of the word
323          sizey font size
324          mode: 0 non-overlay mode 1 overlay mode
325 Return value: None
326 *****/
327 void LCD_ShowString(uint16_t x,uint16_t y,const uint8_t *p,uint16_t fc,uint16_t bc,uint8_t sizey,uint8_t mode)
328 {
329     while(*p!='\0')
330     {
331         LCD_ShowChar(x,y,*p,fc,bc,sizey,mode);
332         x+=sizey/2;
333         p++;
334     }
335 }
```

The `LCD_ShowString` function is used to display a string at the specified coordinates `(x, y)`, and calls the `LCD_ShowChar` function in sequence to draw each character in the string. At the same time, the character spacing is adjusted according to the font size. Both overlay mode and non-overlay mode display are supported.

```

152 /*****
153 函数说明: 显示字符串
154 入口数据: x,y显示坐标
155          *s 要显示的字符串
156          fc 字的颜色
157          bc 字的背景色
158          sizey 字号 可选 16 24 32
159          mode: 0非叠加模式 1叠加模式
160 返回值: 无
161 Function description: Display Chinese character string
162 Input data: x, y display coordinates
163          *s Chinese character string to be displayed
164          fc character color
165          bc character background color
166          sizey font size optional 16 24 32
167          mode: 0 non-overlay mode 1 overlay mode
168 Return value: None
169 *****/
170 void LCD_ShowChinese(uint16_t x,uint16_t y,uint8_t *s,uint16_t fc,uint16_t bc,uint8_t sizey,uint8_t mode)
171 {
172     while(*s!=0)
173     {
174         LCD_ShowChinese16x16(x,y,s,fc,bc,sizey,mode);
175         s+=2;
176         x+=sizey;
177     }
178 }

```

The `LCD_ShowChinese` function is used to display a Chinese character string at the specified coordinates (x, y). It draws each Chinese character by calling the `LCD_ShowChinese16x16` function one by one and adjusts the display position of the next Chinese character according to the font size. It supports both overlay mode and non-overlay mode display.

- bsp_spi.c

```

172 /*****
173 * 函数名称: W25Q32_read
174 * 函数功能: 读取W25Q32的数据
175 * 传入参数: buffer=读出数据的保存地址 read_addr=读取地址 read_length=读去长度
176 * 函数返回: 无
177 * 作者: LC
178 * 备注: 无
179 * Function name: W25Q32_read
180 * Function function: Read W25Q32 data
181 * Input parameters: buffer = storage address of read data read_addr = read address read_length = read length
182 * Function return: None
183 * Author: LC
184 * Notes: None
185 *****/
186 void W25Q32_read(uint8_t* buffer,uint32_t read_addr,uint16_t read_length)
187 {
188     uint16_t i;
189     //拉低CS端为低电平 Pull the CS end to a low level
190     SPI_CS(0);
191     //发送指令03h Send instruction 03h
192     spi_read_write_byte(0x03);
193     //发送24位读取数据地址的高8位
194     // Send the high 8 bits of the 24-bit read data address
195     spi_read_write_byte((uint8_t)((read_addr)>>16));
196     //发送24位读取数据地址的中8位
197     // Send the middle 8 bits of the 24-bit read data address
198     spi_read_write_byte((uint8_t)((read_addr)>>8));
199     //发送24位读取数据地址的低8位
200     // Send the low 8 bits of the 24-bit read data address
201     spi_read_write_byte((uint8_t)read_addr);
202     //根据读取长度读取地址保存到buffer中
203     // Read the address according to the read length and save it in the buffer
204     for(i=0;i<read_length;i++)
205     {
206         buffer[i]= spi_read_write_byte(0xFF);
207     }
208     //恢复CS端为高电平 Restore the CS end to a high level
209     SPI_CS(1);
210 }

```

The `w25q32_read` function is used to read data from the W25Q32 flash chip. The function first starts SPI communication by pulling the CS pin low, then sends the read command (0x03) and the high, middle, and low bytes of the read address. Next, the data is read byte by byte and stored in the provided buffer (`buffer`) according to the specified read length. Finally, the function restores the CS pin to a high level to end the data transfer. This process ensures that the specified length of data is read from the specified address.

```

123  /*****
124  * 函数名称: W25Q32_write
125  * 函数功能: 写数据到W25Q32进行保存
126  * 传入参数: buffer=写入的数据内容      addr=写入地址      numbyte=写入数据的长度
127  * 函数返回: 无
128  * 作者: LC
129  * 备注: 无
130  * Function name: W25Q32_write
131  * Function function: Write data to W25Q32 for storage
132  * Input parameters: buffer = data content to be written addr = write address numbyte = length of written data
133  * Function return: None
134  * Author: LC
135  * Notes: None
136  *****/
137  void W25Q32_write(uint8_t* buffer, uint32_t addr, uint16_t numbyte)
138  {
139      unsigned int i = 0;
140      //擦除扇区数据 Erase sector data
141      W25Q32_erase_sector(addr/4096);
142      //写使能 Write enable
143      W25Q32_write_enable();
144      //忙检测 Busy detection
145      W25Q32_wait_busy();
146      //写入数据 Write data
147      //拉低CS端为低电平 Pull CS to low level
148      SPI_CS(0);
149      //发送指令02h Send instruction 02h
150      spi_read_write_byte(0x02);
151      //发送写入的24位地址中的高8位
152      // Send the high 8 bits of the 24-bit address to be written
153      spi_read_write_byte((uint8_t)((addr)>>16));
154      //发送写入的24位地址中的中8位
155      // Send the middle 8 bits of the 24-bit address to be written
156      spi_read_write_byte((uint8_t)((addr)>>8));
157      //发送写入的24位地址中的低8位
158      // Send the low 8 bits of the 24-bit address to be written
159      spi_read_write_byte((uint8_t)addr);
160      //根据写入的字节长度连续写入数据buffer
161      // Continuously write data buffer according to the length of the written byte
162      for(i=0;i<numbyte;i++)
163      {
164          spi_read_write_byte(buffer[i]);
165      }
166      //恢复CS端为高电平 Restore CS end to high level
167      SPI_CS(1);
168      //忙检测 Busy detection
169      W25Q32_wait_busy();
170  }

```

The `w25q32_write` function is used to write data to the W25Q32 flash chip. First, the function erases the sector data at the target address. Then, it enables the write operation and checks if the chip is busy. Next, the function sends a write command (0x02) and a data address (24-bit address) to the chip through the SPI interface, and writes the data byte by byte according to the specified write length. Finally, the function waits for the write operation to complete and restores the CS pin to a high level to ensure that the data is written correctly and the chip is in an idle state.

- empty.c

```

11 int main(void)
12 {
13     unsigned char buff[10] = {0};
14
15     //开发板初始化 Development board initialization
16     board_init();
17
18     delay_ms(100); //等待部署 Waiting for deployment
19
20     //读取W25Q32的ID Read the ID of W25Q32
21     printf("ID = %X\r\n", W25Q32_readID());
22
23     //读取0地址的5个字节数据到buff Read 5 bytes of data from address 0 to buff
24     W25Q32_read(buff, 0, 7);
25
26     //串口输出读取的数据 Serial port outputs the read data
27     printf("buff = %s\r\n", buff);
28
29     //往0地址写入5个字节长度的数据 ABCD Write 5 bytes of data ABCD to address 0
30     W25Q32_write("Yahboom", 0, 7);
31     delay_ms(100);
32
33     //读取0地址的5个字节数据到buff Read 5 bytes of data from address 0 to buff
34     W25Q32_read(buff, 0, 7);
35
36     //串口输出读取的数据 Serial port outputs the read data
37     // printf("buff = %s\r\n", buff);
38
39     SYSCFG_DL_init();
40
41     LCD_Init(); //LCD初始化 LCD Initialization
42     LCD_Fill(0, 0, LCD_W, LCD_H, WHITE);
43     LCD_ShowPicture(20, 45, 120, 29, gImage_pic1);
44     LCD_ShowString(10, 0, "Hello!", BLACK, WHITE, 16, 0);
45     // LCD_ShowChinese(50, 20, "亚博智能", BLACK, WHITE, 16, 0);
46
47     // 显示 buff 中的内容在同一行上 Display the contents of buff on the same line
48     int x = 54; // 起始 x 坐标 Starting x coordinate
49     for (int i = 0; i < 7; i++)
50     {
51         char str[2] = {buff[i], '\0'}; // 每次取一个字符 Take one character at a time
52         LCD_ShowString(x, 25, str, BLACK, WHITE, 16, 0); // 显示字符 Display Characters
53         x += 8; // 每个字符的宽度为 8, x 坐标向右偏移 Each character is 8 wide and has an x-coordinate offset to the right.
54     }
55
56     while (1)
57     {
58     }
59 }
60 }

```

The main functions of this program are to initialize the development board, read and write data from the W25Q32 flash chip, and display the read content through the LCD. First, the program initializes the development board and related hardware. Then, it reads the chip ID of the W25Q32 and outputs it through the serial port. Next, the program reads 7 bytes of data from the starting address (address 0) of the flash memory to the `buff` array and outputs this data through the serial port. Next, it writes the string "Yahboom" to address 0 of the flash memory and reads and displays this data again. Finally, the program initializes the LCD screen, displays a welcome message and a picture, and displays the read `buff` data character by character on the same line on the screen.

5. Experimental phenomenon

After the program is downloaded, the text "Hello!", the data in the flash, and the logo of Yabo Smart will be displayed in lines on the LCD display.

