

Wristbit control Basic version hellobot car

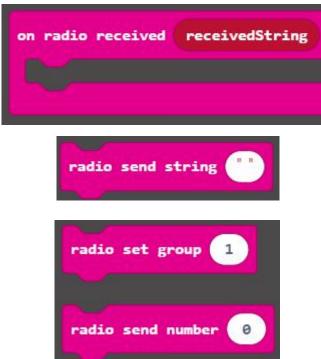
1. Learning goals

In this lesson, we will learn to use Wrist:bit control Basic version hellobot car.

2. Working principle

This course mainly uses the networking function of micro:bit to realize communication between two micro:bit motherboards. The two microbits need to be set in the same group, and the receivedStrings of the two receive the characters from the other to communicate.

In this course, we mainly use the building blocks shown in the figure below.



3. Programming method

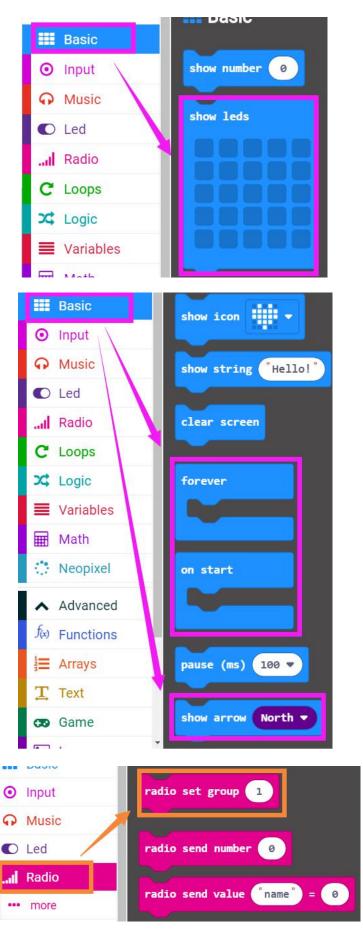
Mode 1 online programming: First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: http://microbit.org/ to enter the programming interface to program.

Mode 2 offline programming: We need to open the offline programming software. After the installation is complete, enter the programming interface, click \(\bigcup \) New Project \(\bigcup \) , you can program.

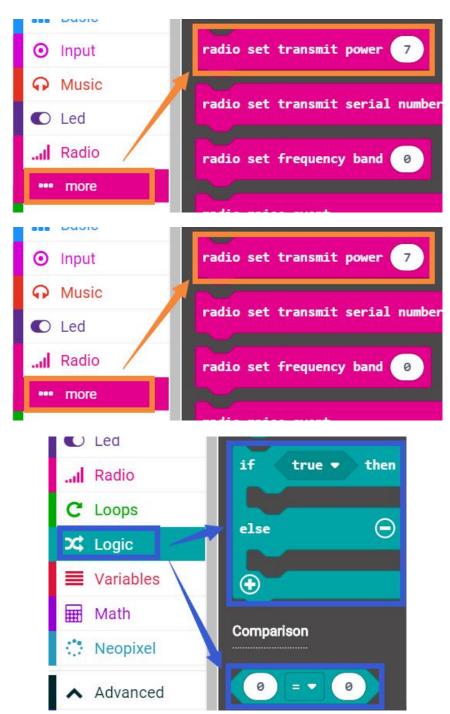
4. Looking for blocks

The following is the location of the building blocks required for this programming.

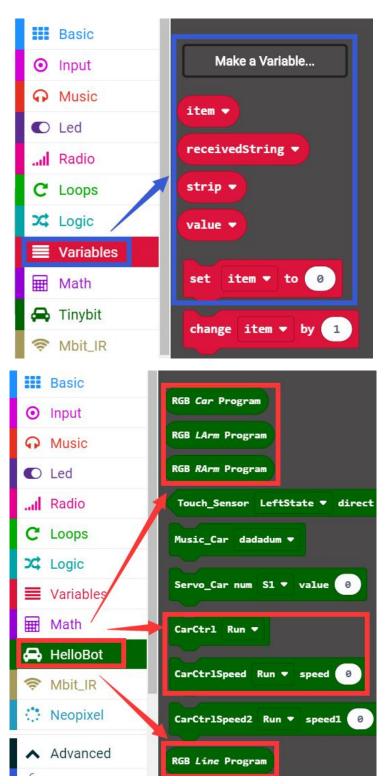




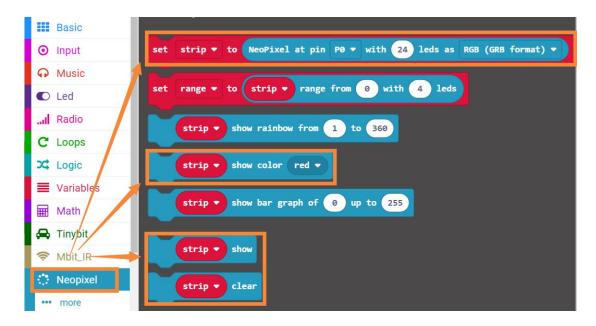












5. Combine block

Basic Hellobot car code as shown below.

```
show icon

Servo_Car num S1 ▼ value 90

Servo_Car num S2 ▼ value 90

set flag1 ▼ to 0

set flag2 ▼ to 0

radio set group 1

radio set transmit power 7
```



```
on radio received receivedString
 set value ▼ to receivedString
         compare (value ▼ ) to ("A")
                                  = - 0
                                               then
  CarCtrlSpeed Run ▼ speed 150
           compare value ▼ to "B"
 else if
                                                  then 😑
  CarCtrlSpeed Back ▼ speed 150
            compare value ▼ to "C" = ▼ 0
                                                  then 🖃
  CarCtrlSpeed SpinLeft ▼ speed 100
           compare value ▼ to ("D") = ▼ (0)
 else if
                                                  then 😑
  CarCtrlSpeed SpinRight ▼ speed 100
 else if
           compare value ▼ to ("I") = ▼ 0
                                                  then 🕣
       RGB Car Program show color black ▼
        RGB LArm Program | show color | black ▼
        RGB RArm Program show color black ▼
        RGB Line Program | show color | black ▼
        RGB Car Program show
        RGB LArm Program | show
```

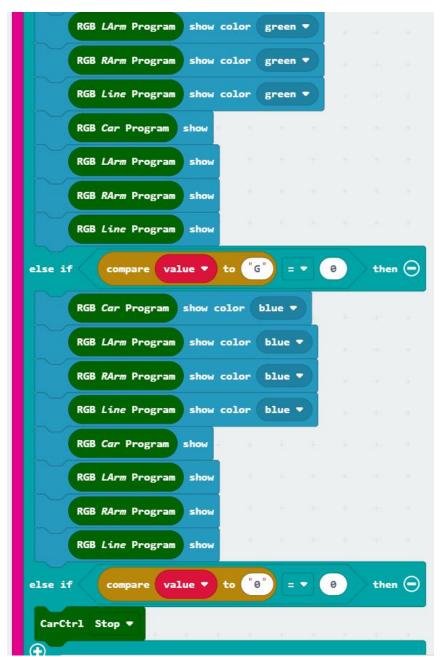


```
RGB RArm Program show
      RGB Line Program show
                                                 then 🕣
          compare value ▼ to "E"
else if
         flag1 ▼ = ▼ 0
                            then
   Servo_Car num S1 ▼ value 80
   change flag1 ▼ by 1
                    = - 1
                                 then 😑
           flag1 ▼
   Servo_Car num S1 ▼ value 120
   change flag1 ▼ by 1
                                     \Theta
 else
   Servo_Car num S1 ▼ value 180
   set flag1 ▼ to 0
 (
      RGB Car Program show color red ▼
      RGB LArm Program show color red ▼
      RGB RArm Program show color red ▼
      RGB Line Program show color red ▼
      RGB Car Program show
```



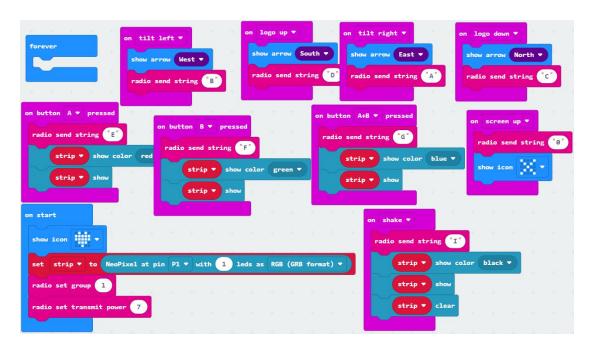
```
RGB LArm Program show
      RGB RArm Program show
      RGB Line Program show
else if
                                                 then 😑
                 = - 0
   Servo_Car num S2 ▼ value 100
   change flag2 ▼ by 1
                                 then 😑
                     = - 1
 else if
            flag2 ▼
   Servo_Car num S2 ▼ value 60
                                      \Theta
 else
   Servo_Car num S2 ▼ value 0
   set flag2 ▼ to 0
 (
      RGB Car Program show color green ▼
      RGB LArm Program show color green ▼
      RGB RArm Program show color green ▼
      RGB Line Program show color green ▼
```





Wrist:bit code code as shown below.

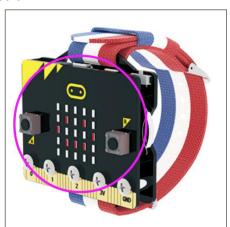




6. Experimental phenomena

We need to download microbit-Basic-Hellobot-code.hex file into micro:bit board of Hellobot car.

We need to download microbit-Wristbit-code.hex file into micro:bit board of Wristbit.





After the program is successfully downloaded. Take wrist:bit on your left wrist as shown below.





Basic Hellobot car dot matrix of will display a heart and two servo will rotate to 90°. Wrist:bit dot matrix will display a heart pattern.

if the wrist:bit is facing upward, car will stop;

if the micro:bit tilt left, the micro:bit dot matrix display arrow points to west, car will back;

if the micro:bit tilt right, the micro:bit dot matrix display arrow points to the east, car will advance;

If the micro:bit logo up, micro:bit dot matrix display points to the south, car will spin left;

if the micro:bit logo down, micro:bit dot matrix display points to the north, car will spin right;

if we press the button A, the RGB lights of the Wrist:bit and the car will become red. When we press button B, the RGB lights of the Wrist:bit and the car will become green.

if we press the A and B buttons at the same time, the RGB lights of the Wrist:bit and the car will become blue.

if we shaking the Wrist:bit, the RGB lights of Wrist:bit and the car will off.