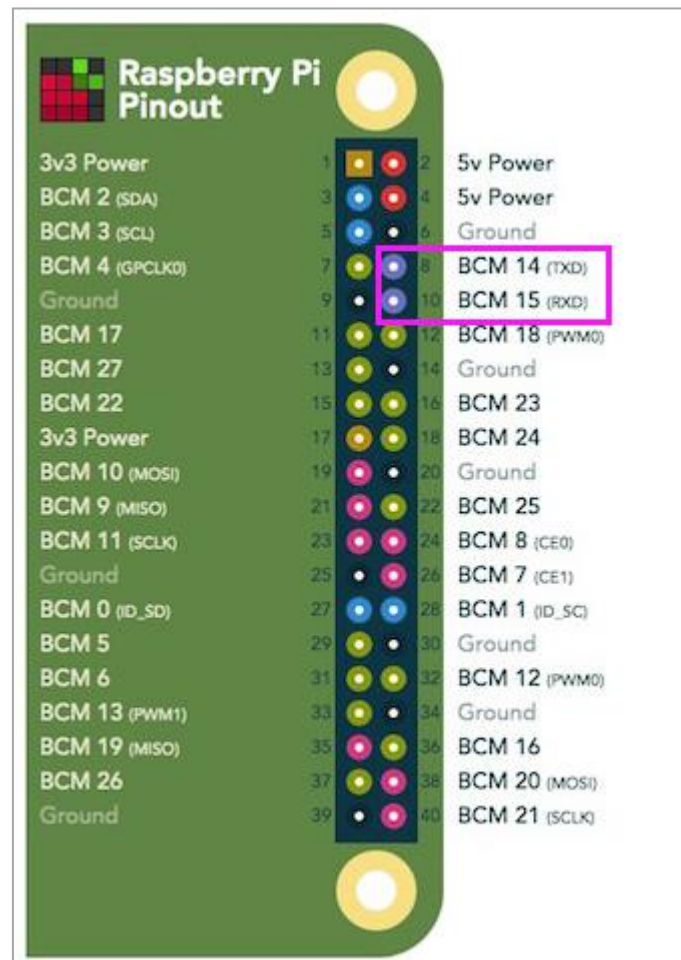


1. About wiring

TTL interface on drive board	Development board interface
5V	VCC
GND	GND
TX	RX(Pin 10)
RX	TX(Pin 8)



2. About code

Transfer the `raspberrypi_bus_servo.py` file in the data to the Raspberry Pi system via winscp, then open the Raspberry Pi system terminal to enter the corresponding directory, and run the following code:

```
sudo python3 raspberrypi_bus_servo.py
```

3. Experimental phenomena

The servo will rotate to two angles and keep this state in loop.