

## 1. Bus servo installation and interface



servo front



servo back



Steering wheel and bearing



## Installation diagram:



## Bus servo interface:



The 15kg bus servo possess two interfaces, and the functions of these two interfaces are exactly the same, and multiple steering gears can form a multi-level combination.

Product name: YB-SD15M serial bus intelligent servo

Brand: Yahboom

Product size: 44.37\*23.06\*35.12mm Locked-rotor torque: ≥15kgf.cm at 7.4V Rotation range: 300°±15°(96~4000) No-load current: ≤310mA at 7.4V Locked rotor current: ≤3.2A at 7.4V

Servo accuracy: ≤1°

Rotation speed: ≤0.30 Sec/60° at 7.4V Control angle range: 300°±15°(96~4000)

Applicable scenarios: Bionic robot joints of robotic arms and manipulators

Readback function: support to read back information such as servo position and status

Product weight: 50±1g Working voltage: 6.0~7.4V

Control method: UART serial command Communication baud rate: 115200

Storage: Servo settings are automatically saved when power off

Servo ID: 1~250, the default is 1

Protection: locked rotor 3 seconds into protection Parameter feedback: abnormal feedback, position

Gear type: Metal gear set Matching line length: 20cm Interface model: PH2.0-3Pin



