Micro:bit handle control

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1. Learning objectives

In this course, we mainly learn how to use MakeCode graphical programming to control the oscillating fan with the microbit handle.

2. Building blocks

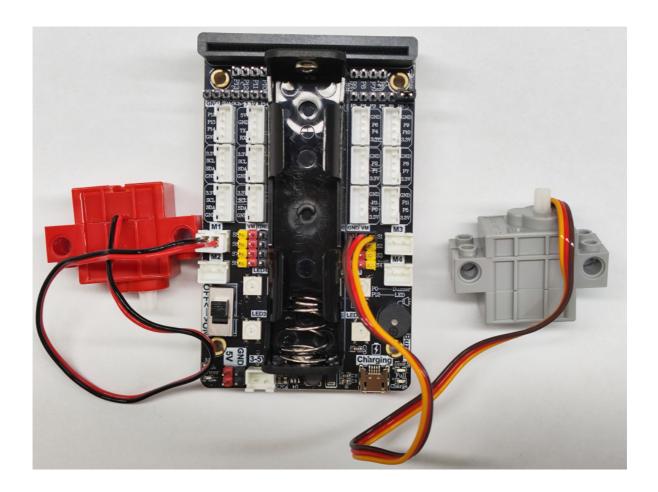
For the building blocks steps, please refer to the installation drawings of **[Assembly Course]-- [Oscillating fan]** in the materials or the building blocks installation brochure.

3. Motor wiring

The building blocks motor wiring is inserted into the M1 interface of the Super:bit expansion board, and the black wiring is inserted into the side close to the battery.

The building blocks servo wiring is inserted into the S1 interface of the Super:bit expansion board, and the orange servo wiring is inserted into the yellow pin of S1.

As shown below:



4. Programming

Method 1 Online Programming:

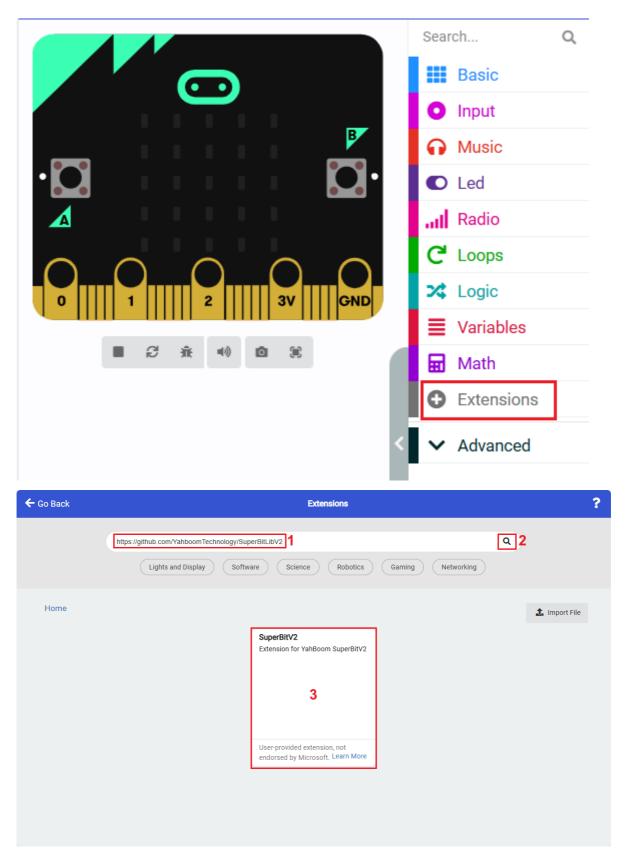
First, connect micro:bit to the computer via a USB data cable. A USB flash drive will pop up on the computer. Click the URL in the USB flash drive: https://makecode.microbit.org/ to enter the programming interface. Then, add the Yahboom software package to start programming.

Method 2 Offline Programming:

Open the offline programming software MakeCode and enter the programming interface. Click [New] and add the Yahboom software package to start programming.

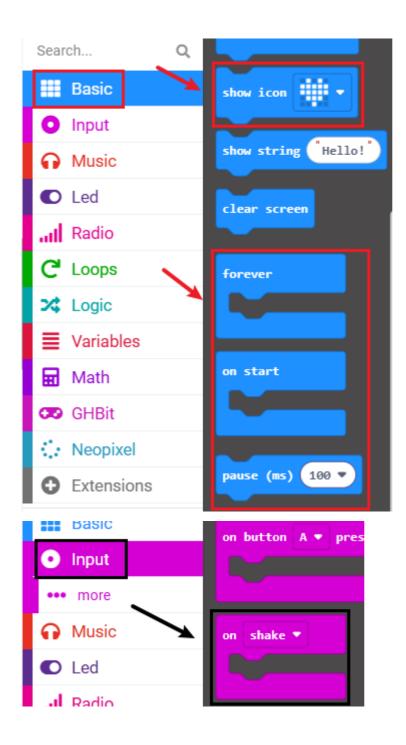
superbit kit expansion package: https://github.com/YahboomTechnology/SuperBitLibV2 handle expansion package: https://github.com/YahboomTechnology/GHBitLib

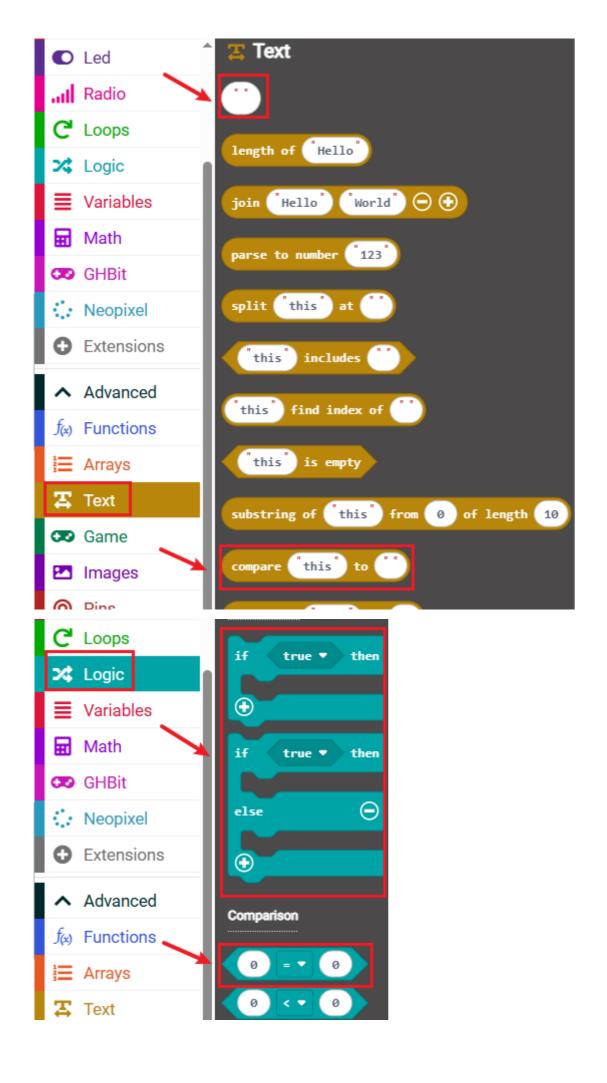
4.1 Add expansion package

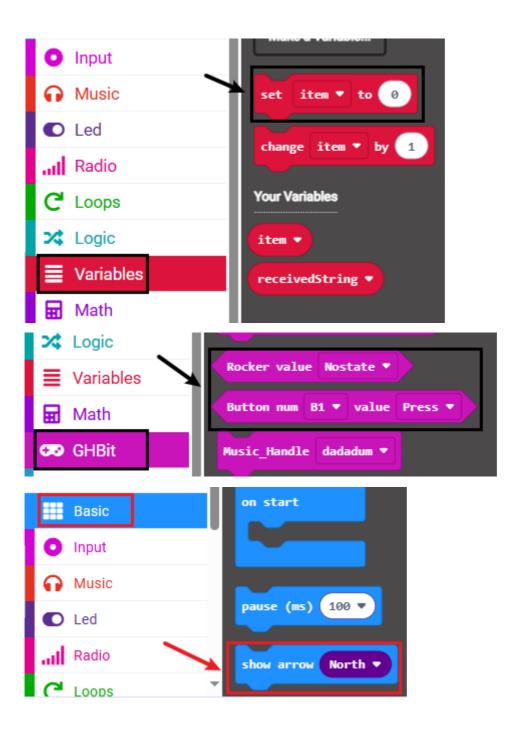


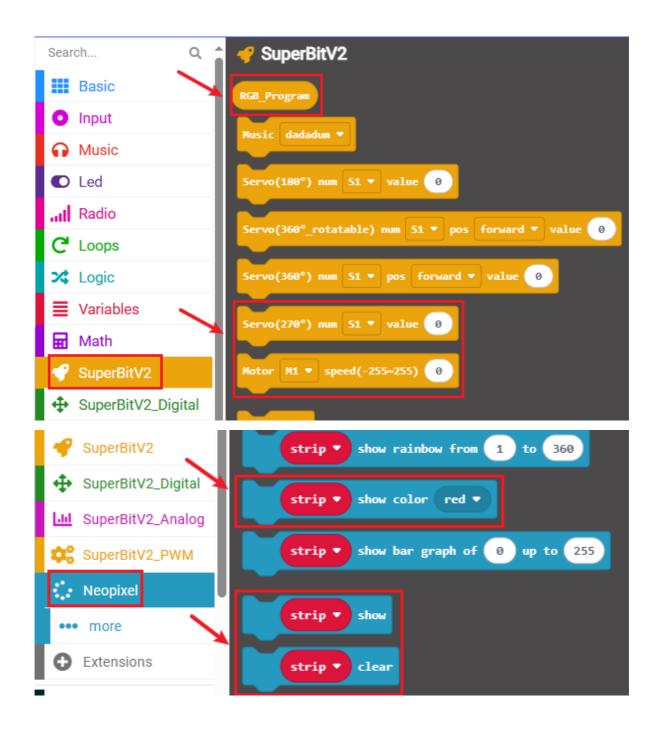
4.2 Blocks used

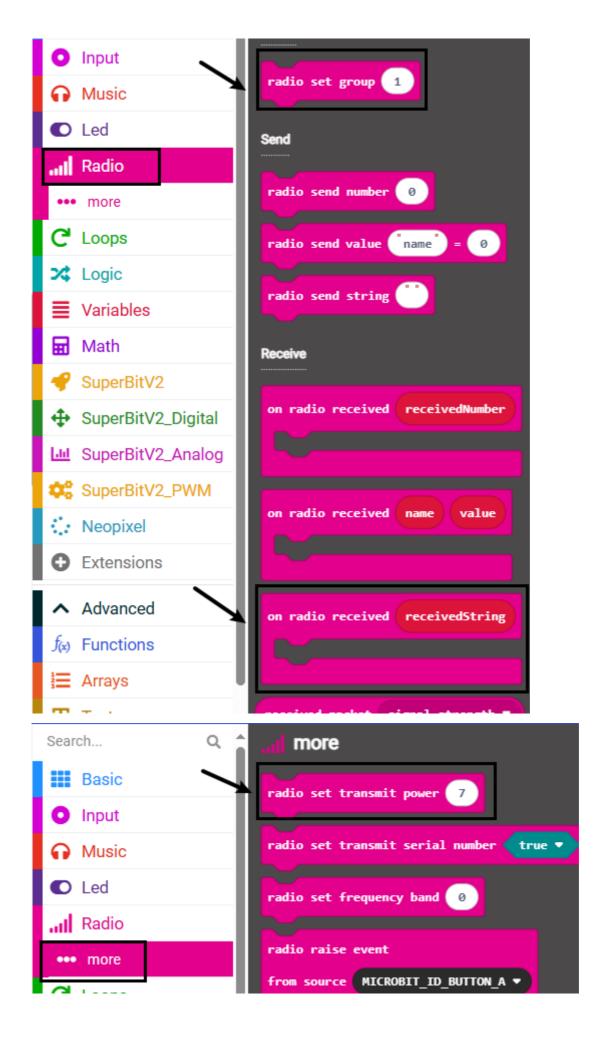
The location of the blocks required for this programming is shown in the figure below.





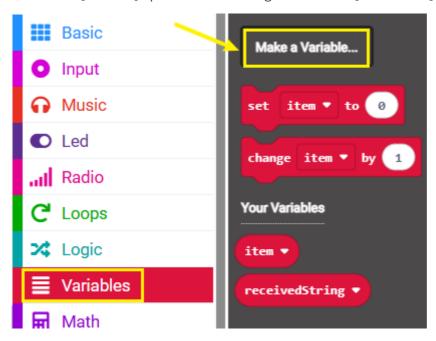






4.3 Add new variables

 $\ensuremath{\textcircled{1}}$ Find the [Variable] option in the building block bar ---- [Set variable]



② Enter the variable name to complete the new variable.



4.4 Combined blocks

The microbit summary program on the **Oscillating fan** is shown in the figure below

```
on start
                                        on radio received receivedString ▼
                                         set item ▼ to receivedString ▼
 radio set group 1
 radio set transmit power 7
                                                 compare item ▼ to ("E") = ▼ (0
 show icon ▼
                                                RGB_Program show color red ▼
 set angle ▼ to 135
 Servo(270°) num S1 ▼ value angle ▼
                                           Servo(270°) num S1 ▼ value 0
 Motor M1 ▼ speed(-255~255) 0
                                                  compare item ▼ to ("F")
                                                RGB_Program show color green ▼
                                           Servo(270°) num | S1 ▼ | value | 135
                                                  compare item ▼ to ("G") = ▼ 0
                                                RGB_Program show color blue 🕶
                                                RGB_Program show
                                                    compare item ▼ to "H"
                                                                                          then 😑
                                                RGB_Program show color yellow ▼
                                           Servo(270°) num | 51 ▼ | value | 270
                                                  compare item ▼ to A
                                                                                          then 😑
                                                  compare item ▼ to "B"
                                                                                          then 🖃
                                           Motor M1 ▼ speed(-255~255) (-255
                                                   compare item ▼ to "I"
                                                RGB_Program clear
                                                                                              \Theta
                                           Motor M1 ▼ speed(-255~255) 0
```

The **handle rocker control** program is as follows

```
on start
 show icon
 radio set group 1
 radio set transmit power 7
      Rocker value Up ▼
  radio send string "A"
                                                       radio send string "E"
  show arrow North ▼
 else if Rocker value Down ▼
  radio send string B
                                                           Button num B2 ▼ value Press ▼  then
  show arrow South ▼
                                                       radio send string "F"
 else if Rocker value Left ▼ then
                                      \Theta
  radio send string (C)
  show arrow West ▼
 else if Rocker value Right ▼ then
                                                           Button num B3 ▼ value Press ▼
  radio send string D
                                                       radio send string "G"
  show arrow East ▼
 else if Rocker value Press ▼ then
  radio send string I
                                                           Button num B4 ▼ value Press ▼
  show icon
                                                       radio send string H
 else if Rocker value Nostate ▼ then 🖨
                                                      \oplus
  radio send string 0
  show icon
 ①
```

The handle gravity control program is as follows

```
on start

show icon

radio send string constant show arrow west radio send string and send string and show arrow south radio send strin
```

You can also directly open the **microbit-handle-control-Oscillating-fan.hex**、 **microbit-Handle-rocker-control.hex**、 **microbit-Handle-gravity-control.hex** Drag the file into the browser that opens the URL, and the program diagram of the source code of this project will be automatically opened

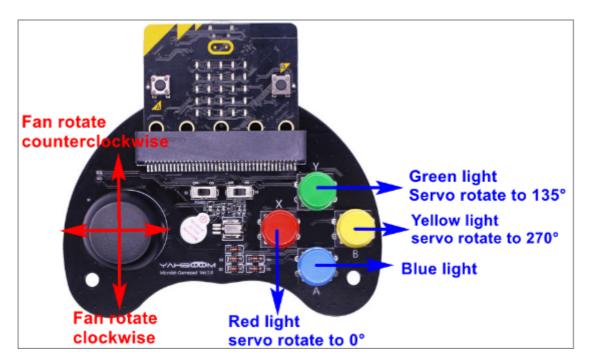
5. Experimental phenomenon

We need to download the Oscillating fan program to the micro:bit mainboard of the Oscillating fan, turn on the power switch of the Oscillating fan, and we can see a heart pattern displayed on the micro:bit dot matrix;

Download the handle remote control program to the micro:bit mainboard of the handle, turn on the power switch of the handle, and we can see that the micro:bit dot matrix will be initialized to display a heart pattern, and then an "X" pattern will be displayed, indicating that the handle is in the default state and no data is sent.

The two will automatically complete the pairing, and then we can start to remotely control the Oscillating fan.

The handle functions are as follows.



!Note: When the rocker is used for control, pressing the rocker will turn off the RGB light. This function does not exist when the handle is controlled by gravity.