# **Obstacle detection**

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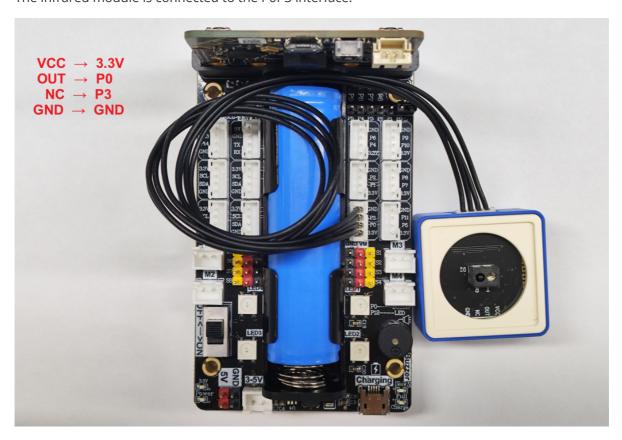
- 1. Learning Objectives
- 2. Sensor Wiring
- 3. Code Analysis
- 4. Write and download the program
- 5. Experimental phenomenon

## 1. Learning Objectives

In this course, we mainly learn how to implement obstacle detection through python programming.

## 2. Sensor Wiring

The infrared module is connected to the POP3 interface.



# 3. Code Analysis

For the program of this course, please see the **Obstacle-detection.py** file.

```
from microbit import *
import WOM_Sensor_Kit
```

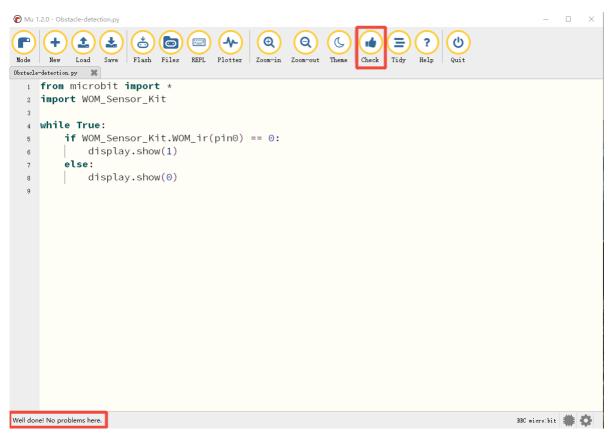
First, import the library needed for this lesson from microbit: WOM\_Sensor\_Kit library is used for sensors.

```
while True:
if WOM_Sensor_Kit.WOM_ir(pin0) == 0:
display.show(1)
else:
display.show(0)
```

In an infinite loop, read the state of the infrared sensor connected to pin0 and display the corresponding number on the micro:bit screen. When infrared rays are detected (the sensor return value is 0), the number 1 is displayed, otherwise, the number 0 is displayed, indicating that infrared rays are not detected

### 4. Write and download the program

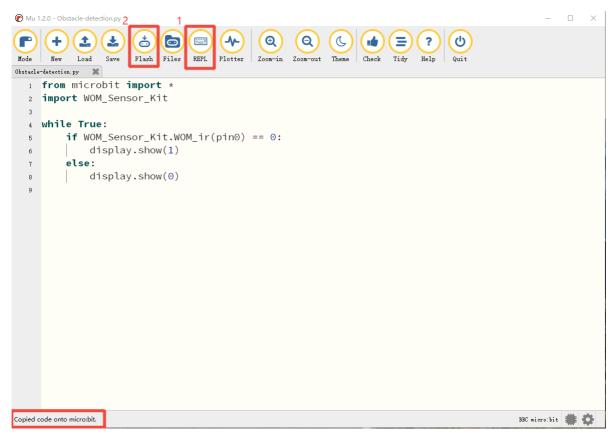
- 1. Open the Mu software and enter the code in the editing window. **Note! All English and** symbols should be entered in English mode, use the Tab key for indentation, and the last line ends with a blank program.
- 2. Click the thumb 'Check' button to check if there are any errors in our code. If a cursor or underline appears in a line, it means a syntax error. Please check and modify it. If there is no error, the lower left corner will prompt that there is no problem with the detection.



3. Click the 'REPL' button to check whether the Superbit library has been downloaded. If not, please refer to [Preparation before class] --> [2.4 Python Programming Guide].

```
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                      Obstacle-detection.py
  1 from microbit import *
  import WOM_Sensor_Kit
  4 while True:
          if WOM_Sensor_Kit.WOM_ir(pin0) == 0:
  5
             display.show(1)
            display.show(0)
  8
 BBC micro:bit REPL
MicroPython v1.15-64-g1e2f0d280 on 2025-06-26; SuperbitV2 and Sensor v3.0.0 with modified by Yahboom Team
     "help()" for more information.
>>>
                                                                                            BBC micro:bit 👛 💍
```

4. After the program is written, connect the computer and the microbit mainboard with a microUSB data cable, and click the 'Flash' button to download the program to the micro:bit mainboard. (You need to click the 'REPL' button again to turn off the import library file function before you can download the program normally).



5. If the download fails, please confirm whether the microbit is properly connected to the computer via the microUSB data cable and the Superbit Python library has been imported.

### 5. Experimental phenomenon

displays 1, otherwise it displays 0.			

After the program runs successfully, when an obstacle is detected, the microbit dot matrix