

2.Close APP control process

The image system that comes with the robotic arm at the factory can automatically run APP control process when it is turned on.

In order to avoid resource occupation, please enter the command to end the APP remote control process before running other programs.

1. Close the APP remote control process temporarily.

Input following command:

sh ~/Dofbot/kill_YahboomArm.sh

```
jetson@jetson-desktop:~$ sh ~/Dofbot/kill_YahboomArm.sh
Number of processes=2
Yahboom_Arm.py is running, and kill it:
5668 5704
jetson@jetson-desktop:~$
```

2. Close the APP remote control process permanently.

Input following command:

sudo systemctl stop yb-bigProgram.service

sudo systemctl disable yb-bigProgram.service

```
dofbot@Dofbot:~$ sudo systemctl stop yb-bigProgram.service
[sudo] password for dofbot:
dofbot@Dofbot:~$ sudo systemctl disable yb-bigProgram.service
Removed /etc/systemd/system/multi-user.target.wants/yb-bigProgram.service.
```

3. If you need to restart the factory program to start automatically after booting.

Input following command:

sudo systemctl restart yb-bigProgram.service

sudo systemctl enable yb-bigProgram.service