Joint control

1 Single joint control

```
send_angle

description:set the angle of a specified joint
parameters:
1.id, the number corresponding to a joint; for six axes, it is within 1-6; for
four axes, it is within 1-4
2.degree: joint angle value to be set
3.speed: 0-100, the speed at which the joint moves to a specified angle to
complete instructions
returned value: none
```

2 Multi joint control

```
send_angles

description:set the angles of six axes
parameters:
1.degrees: including the angles of all joints, and having a length of 6
2.speed: 0~100, the speed at which the joint moves to a specified angle to
complete instructions
returned value: none
```