

IO Control

```
<!-- initialize the program -->
const mycobot = require('mycobot')

const obj = mycobot.connect('COM15',115200)

<!-- set the color of ATOM indicator lamp-->
<!-- Note: set three parameters to 0-255 -->
obj.write(mycobot.setColor(125,11,9))

<!-- set the angle and coordinate of the current robot arm to the running start
point of the robot arm -->
obj.write(mycobot.setGripperInit())
```