

# Setting All Arms to Starting Point

M5Stack series: Make sure robot is connected with PC

Other series: Make sure the robot is in normal status.

## Purpose for this section

This section introduces instructions for setting all arms to starting point.

### Introduction to API

- `Set Angle ()`
- Applicable to six-axis robots (myCobot 280 series, mechArm series and myCobot 320 series)



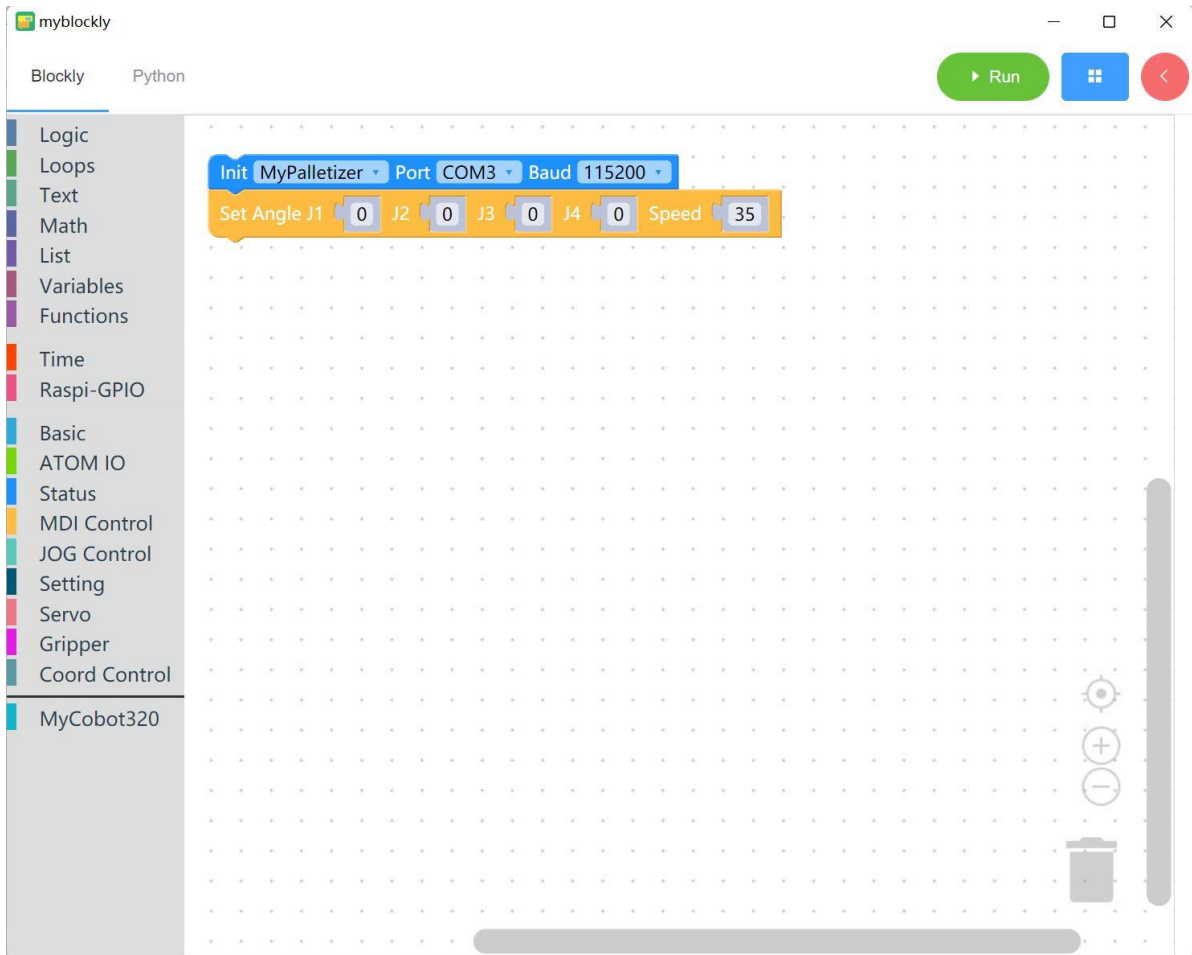
- Applicable to four-axis robots (myPalletizer series)



- Parameters:
  - Joint angle: if arms are set to starting point, set parameters of angles as `0`
  - Speed: set it within its due range according to your needs.
- Function: Set all arms to the starting point (Angle `0`)

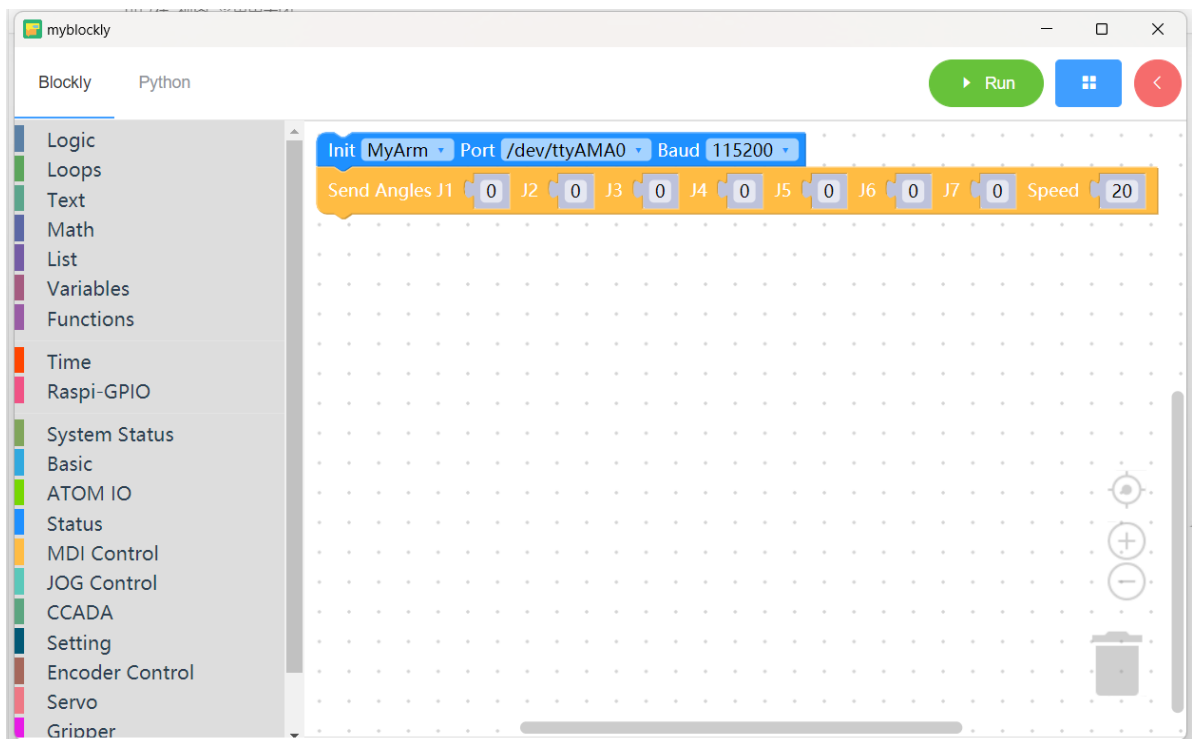
### MyPalletizer

#### Simple demo



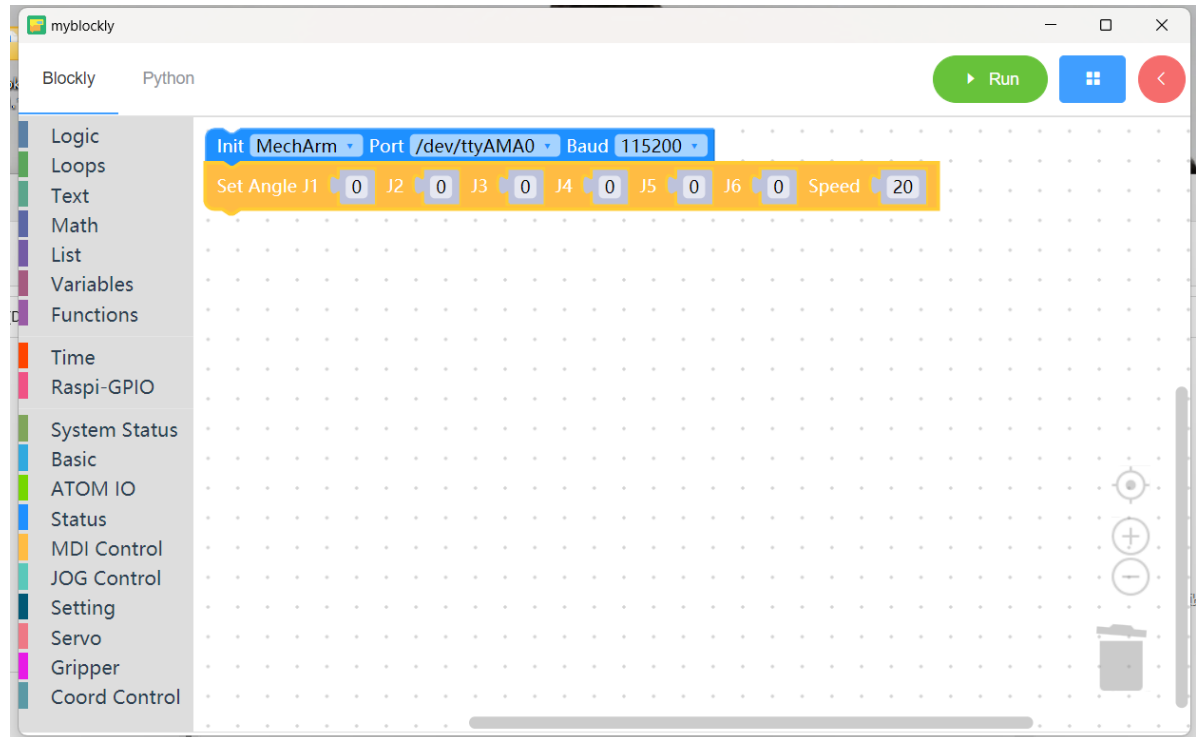
## MyArm

### Simple demo



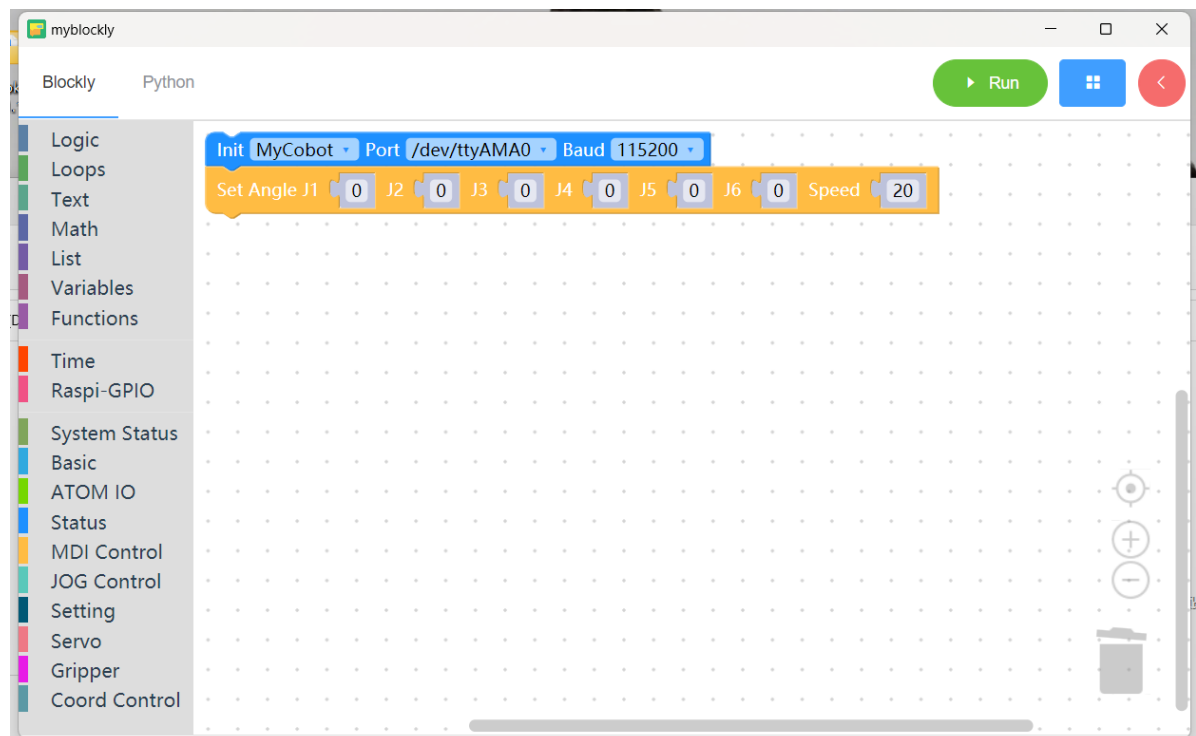
# MechArm

## Simple demo



# MyCobot

## Simple demo



- Motion:Six  
All arms move to its starting point in 35 seconds.

