







EGYPFWD Initiative

Advanced Embedded Systems Nanodegree,
Embedded Software Design Masterclass by SPRINTS Egypt.

Automotive Door Control System Dynamic Design

A Graduation Project submitted in partial Fulfillment of Embedded Software Design Masterclass.

Prepared by

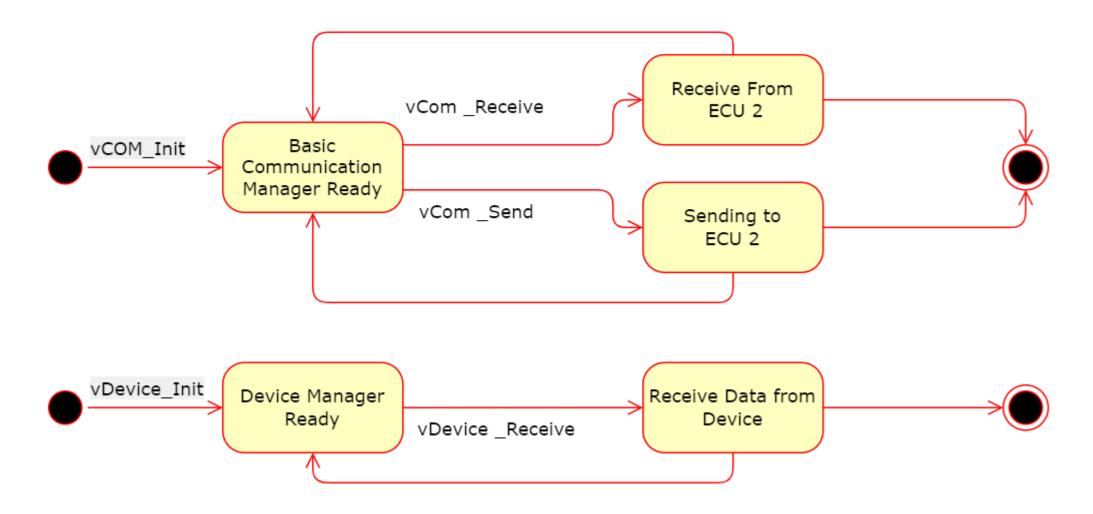
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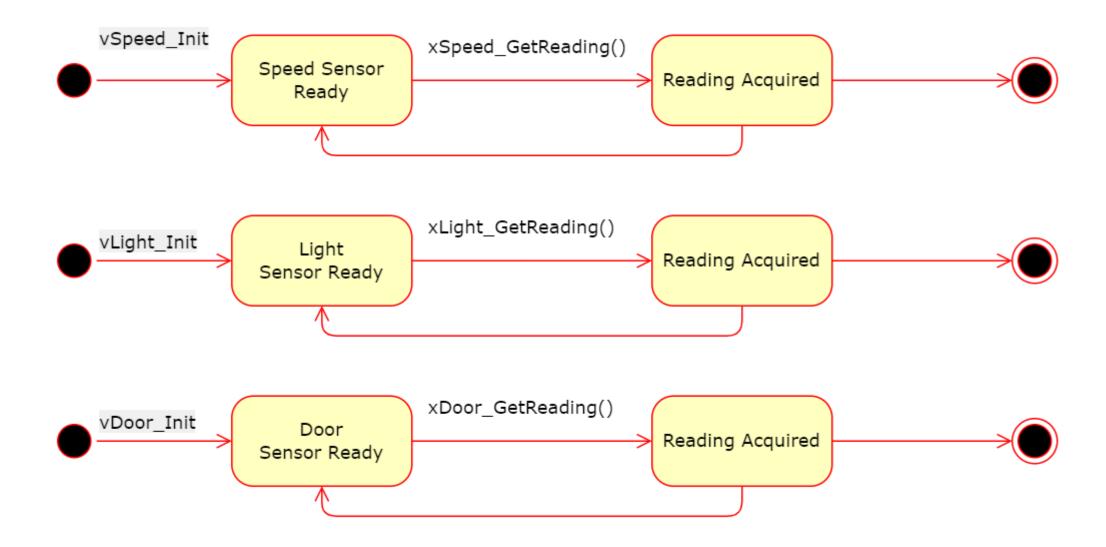
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<u>Github</u>

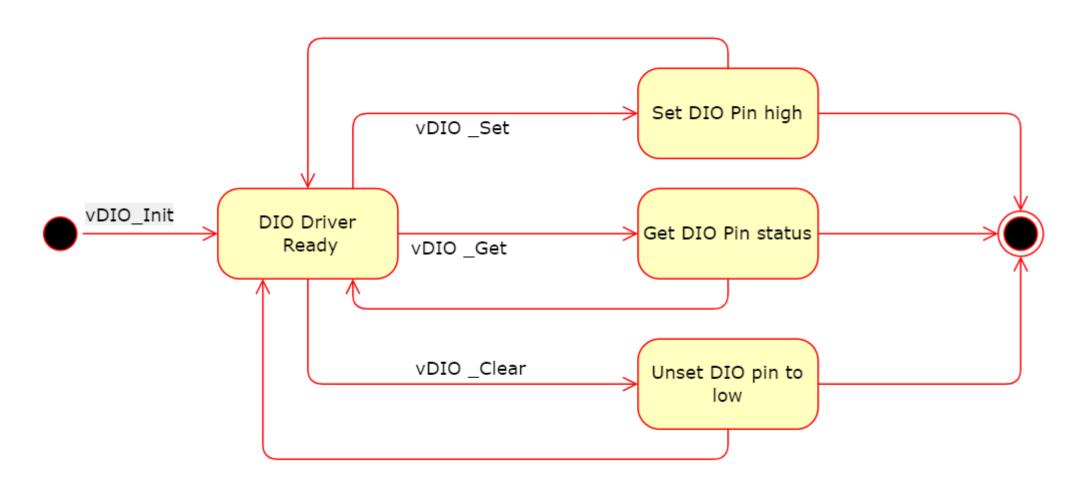
ECU 1: Manager Modules State Diagrams



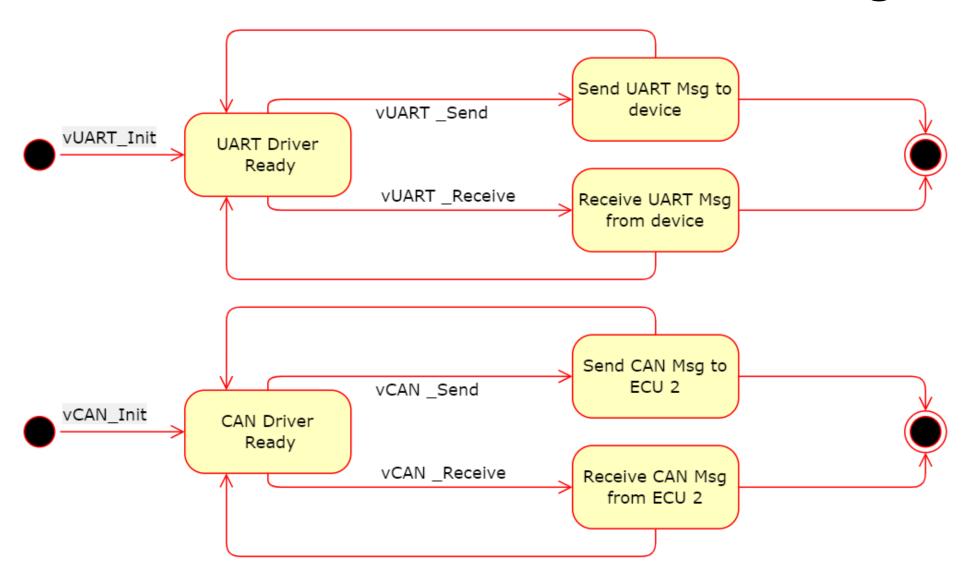
ECU 1: Sensor Modules State Diagrams



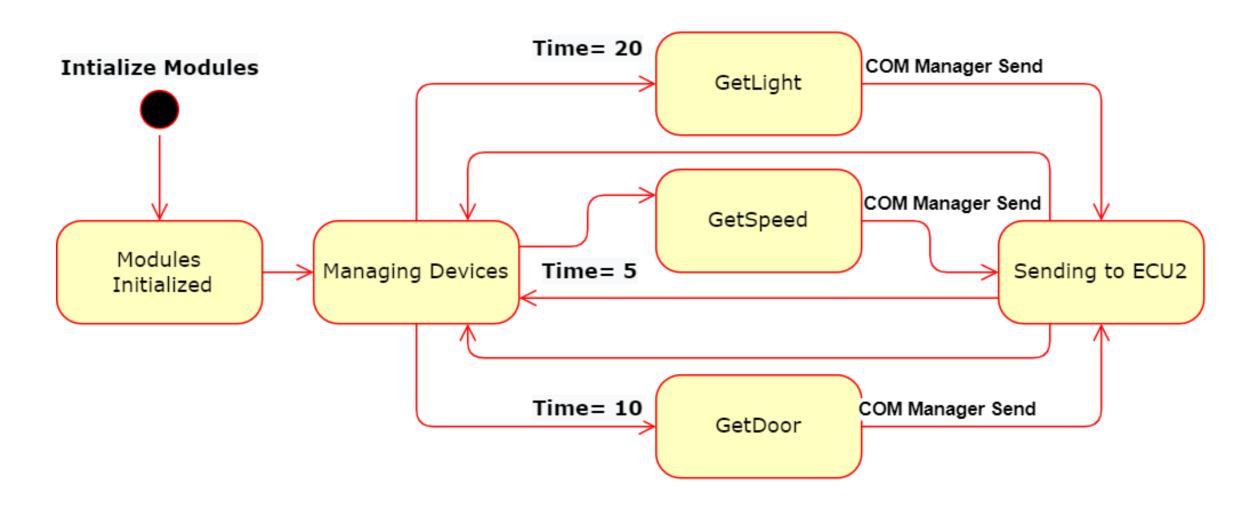
ECU 1 MCAL: DIO State Diagram



ECU 1 MCAL: COM Drivers State Diagram



ECU 1 : State Diagram



ECU 1: CPU LOAD

• Calculation of HyperPeriod

Assumptions: Tick time = 1 ms; Task periodicities : 5, 10, 20 ms; Execution times = 1,2,4 ms

$$HyperPeriod = LCM(Periodicities) = LCM(5,10,20)$$

$$HyperPeriod = 20$$

• CPU Load Calculations

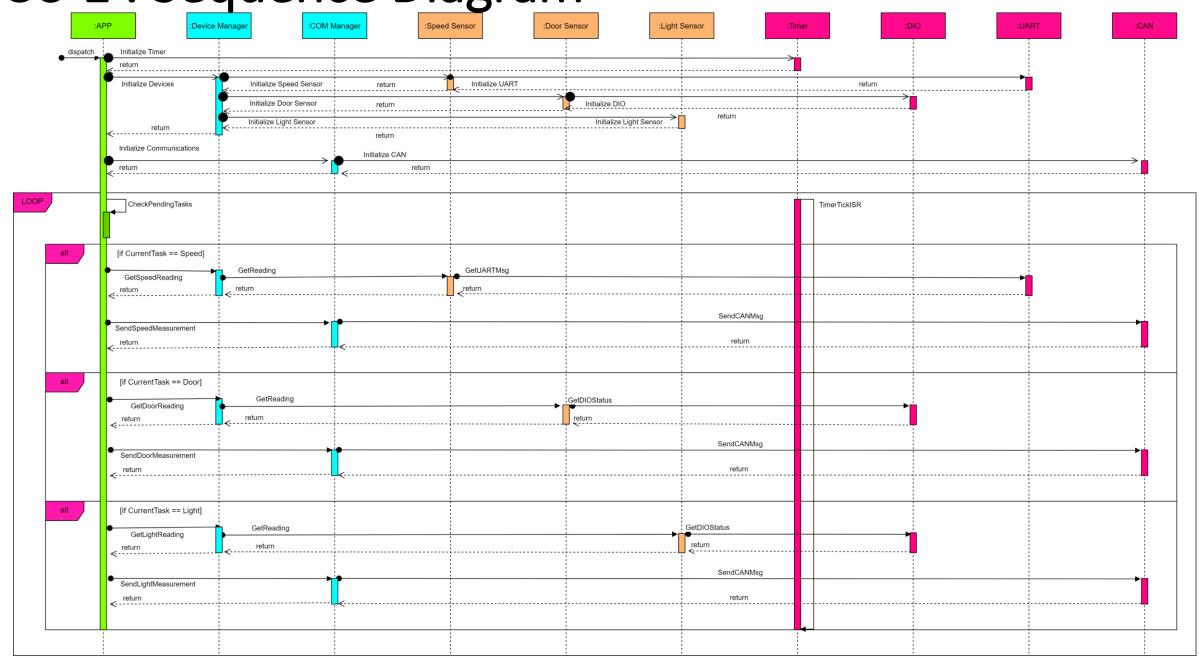
$$CPU LOAD = \frac{Total Time}{HyperPeriod} * 100$$

$$Total\ Time = \sum_{i=1}^{6} ExecutionTime_{i} * Num\ of\ Calls\ In\ HyperPeriod_{i}$$

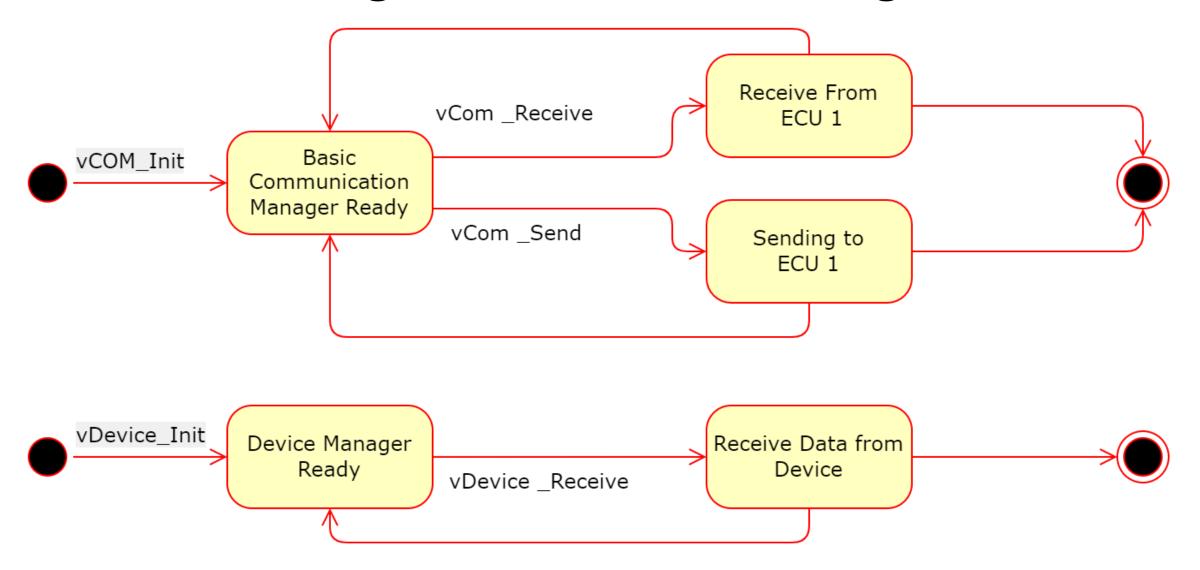
$$Total\ Time = 1 * 5 + 2 * 2 + 4 * 1 = 13ms$$

$$Utilization = CPU LOAD = \frac{13}{20} * 100 = 65\%$$

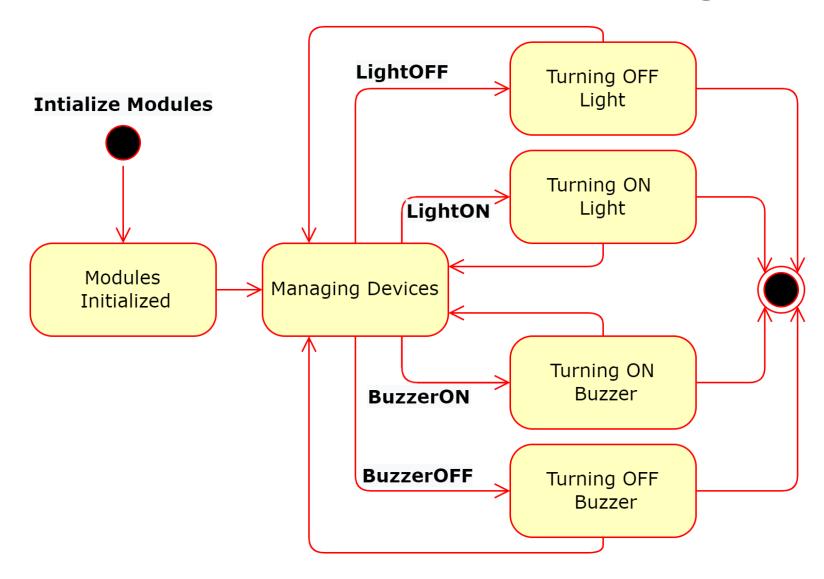
ECU 1: Sequence Diagram



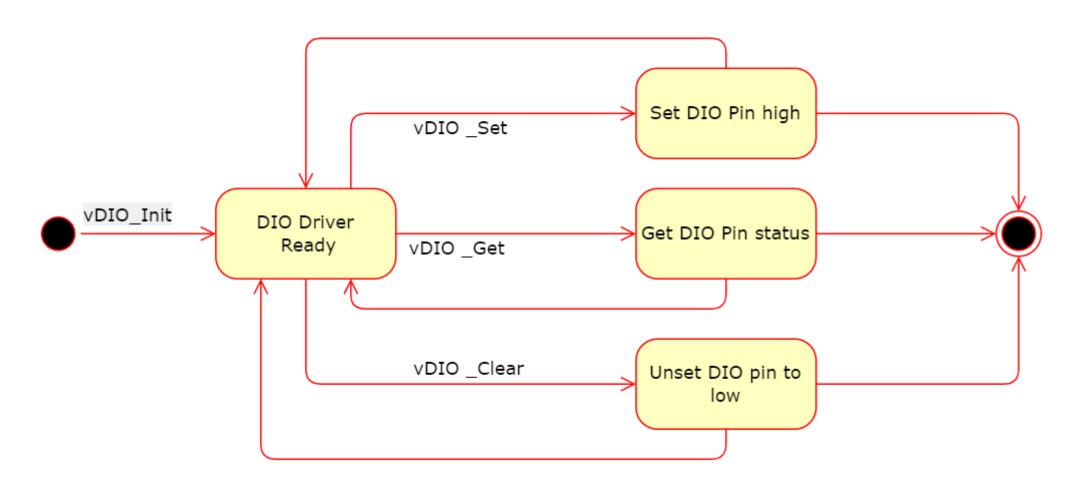
ECU 2: Manager Modules State Diagrams



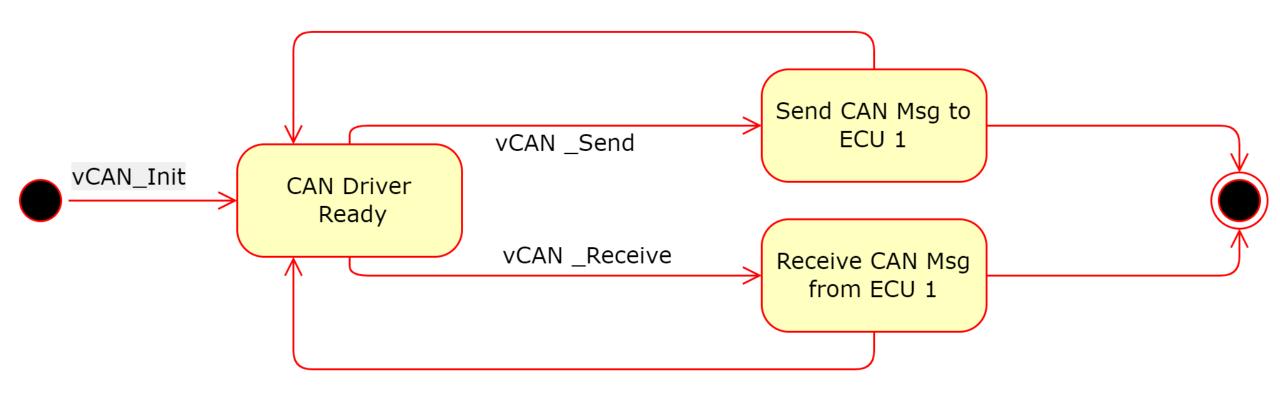
ECU 2 : Actuator Modules State Diagrams



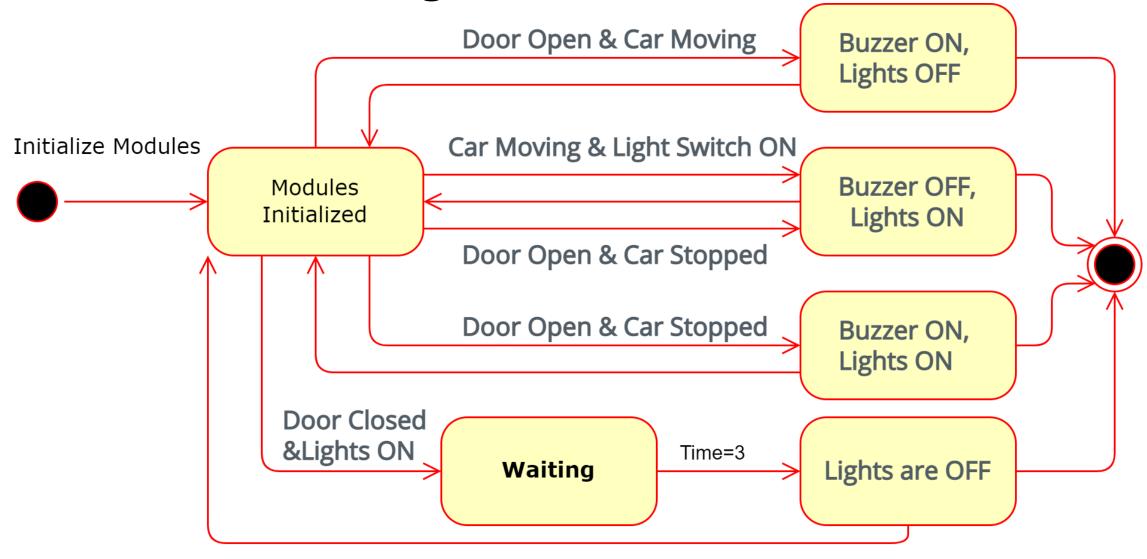
ECU 2 MCAL: DIO State Diagram



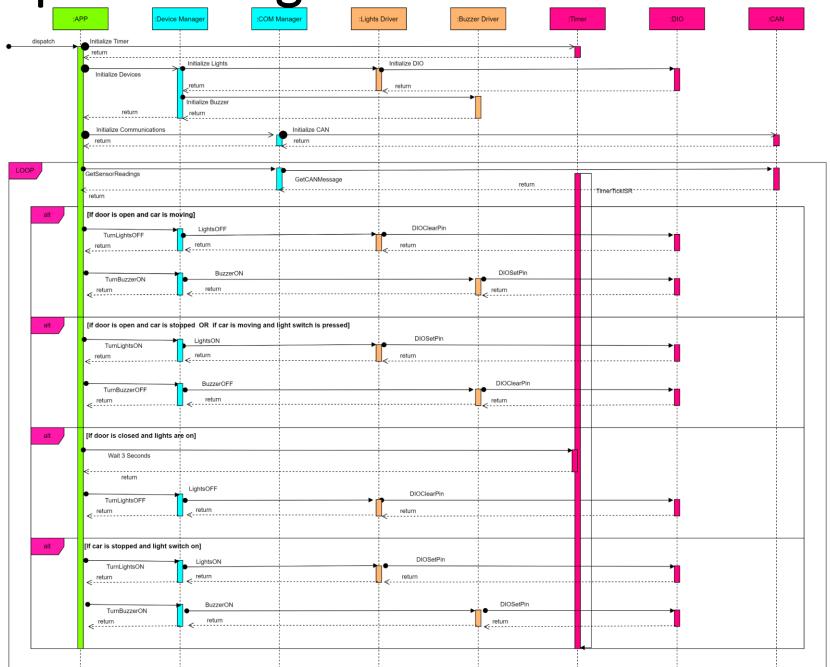
ECU 2 MCAL: COM Drivers State Diagram



ECU 2 : State Diagram



ECU 1: Sequence Diagram



ECU 2: CPU LOAD

• Calculation of HyperPeriod

Assumptions: Tick time = 1 ms; Task periodicities : 5, 10 ms; Execution times = 2, 3 ms

$$HyperPeriod = LCM(Periodicities) = LCM(5,10)$$

$$HyperPeriod = 10$$

CPU Load Calculations

$$CPU LOAD = \frac{Total Time}{HyperPeriod} * 100$$

$$Total\ Time = \sum_{i=1}^{6} ExecutionTime_{i} * Num\ of\ Calls\ In\ HyperPeriod_{i}$$

$$Total\ Time = 2 * 2 + 3 * 1 = 7ms$$

$$Utilization = CPU LOAD = \frac{7}{10} * 100 = 70\%$$