

# Yaliang Wang

925 Dempster Apt. 2W  
Evanston, IL, 60201  
United States

Phone: 1 (224) 420 - 2689  
Email: yaliangwang2015@u.northwestern.edu  
Website: <http://career.yaliang-wang.tk>

## Education

M.S. Computer Science, Department of Electrical Engineering and Computer Science, Northwestern University, 2014 - present.

B.E. Automation(Control), Department of Control Science and Engineering, Zhejiang University, 2009 - 2013.

## Project

### Mobile Management and Development

**Product Manager and Software Developer**, Social Networking Application, *December, 2014 - March, 2015*  
Hybrid App Builds on HTML5, jQuery, PhoneGap™Build & Parse.com .

### Computer Vision

Detection, Tracking of Particles and Bubbles in IV Bags, *December, 2014 - present.*

### Machine Learning

Handwritten Digit Recognition

*December, 2014 - March, 2015*

2-Layer Neural Network, 1000 hidden neurons

MNIST Dataset, 60k for training, 10k for testing

Error Rate: 3.27 % on testing

[Github](#) [Video\(3 mins\)](#)

Reinforcement Learning in Bipedal Walking Simulation

*December, 2014 - March, 2015*

### Control

Balance Maintenance for Humanoid Robots Subjected to External Disturbance, *December, 2012 - June, 2014.*

## Awards

Best Student Application Paper Award, IFAC ICONS 2013, 2013.

Zhejiang University 2013 Session Excellent Bachelor Thesis Award, Zhejiang University, 2013.

## Publications

**Yaliang Wang**, Rong Xiong, Qiuguo Zhu, and Jian Chu, "Compliance Control for Standing Maintenance of Humanoid Robots under Unknown External Disturbances", *2014 IEEE International Conference on Robotics and Automation (ICRA 2014)*, pp. 2297-2304 Hong Kong, China, May 31 - June 5, 2014.

**Yaliang Wang**, Qiuguo Zhu, Rong Xiong, and Jian Chu, "Standing Balance Control for Position Control-Based Humanoid Robot", *3rd IFAC International Conference on Intelligent Control and Automation Science (IFAC ICONS 2013)*, pp.429-436, Chengdu, China, September 2-4, 2013.

Chao Li, Rong Xiong, Qiuguo Zhu, Jun Wu, **Yaliang Wang**, Yiming Huang, "Push recovery for the standing under-actuated bipedal robot using the hip strategy", *Journal of Zhejiang University-SCIENCE*, 2014.

## Exchange Experience

Vancouver Summer Business Program, SAUDER School of Business, The University of British Columbia, *July, 2012 - August, 2012.*