From m_0 m_1 $f(k_1) + f(b) + f(m_1) = 0$ $k_1(q_1, q_2) + b(\dot{q}_1 - \dot{q}_2) + m\dot{q}_1 = 0$ $m\dot{q}_1 = -k_1(q_1, q_2) - b(\dot{q}_1 - \dot{q}_2) = 0$ for mass m_2 $f(bump) = f(m_1) + f(k_1) + f(b) + f(k_2)$ $f(bump) = m_1\dot{q}_2 + k_1(q_2 - \dot{q}_1) + k_2\dot{q}_2$ $m_1\dot{q}_2 = f(bump) - Y_1(q_2 - \dot{q}_1) - b(\dot{q}_2 - \dot{q}_1) + k_2\dot{q}_2$ Therefore of $f(a_1, a_2, a_3) + b(\dot{q}_2 - \dot{q}_1) + b(\dot{q}_2 - \dot{q}_1) + k_2\dot{q}_2$ $m_1\dot{q}_2 = k_1(q_2 - q_1) + b(\dot{q}_2 - \dot{q}_1) - k_2\dot{q}_2$ $m_2\dot{q}_2 = f(bump) - k_1(q_2 - \dot{q}_1) - b(\dot{q}_2 - \dot{q}_1) - k_2\dot{q}_2$