Modele1debug

November 17, 2025

[2412]:
```
import sys
import numpy as np
import matplotlib.pyplot as plt

np.random.seed(0)
```

[2413]:
```
def extract_features_full(img):
    """
    Version COMPLÈTE: 337 features optimisées
    Pour rétinopathie diabétique sur images 28x28x3
    """
    features = []

    # Convert to float
    img = img.astype(np.float32)

    # Grayscale
    gray = img.mean(axis=2)


    for c in range(3):
        channel = img[:, :, c]
        # Percentiles groupés pour performance
        percs = np.percentile(channel, [10, 25, 50, 75, 90])
        features.extend([
            channel.mean(),
            channel.std(),
            percs[0],  # p10
            percs[1],  # p25
            percs[2],  # p50 (médiane)
            percs[3],  # p75
            percs[4],  # p90
        ])

    gray_percs = np.percentile(gray, [10, 25, 50, 75, 90])
    features.extend([
        gray.mean(),
        gray.std(),
```

```
        gray.min(),
        gray.max(),
        gray_percs[0],  # p10
        gray_percs[1],  # p25
        gray_percs[2],
        gray_percs[3],  # p75
        gray_percs[4],  # p90
    ])

    H, W = gray.shape
    h2, w2 = H//2, W//2

    quadrants = [
        gray[:h2, :w2],   # Top-left
        gray[:h2, w2:],   # Top-right
        gray[h2:, :w2],   # Bottom-left
        gray[h2:, w2:]    # Bottom-right
    ]

    for quad in quadrants:
        features.extend([
            quad.mean(),
            quad.std(),
            quad.min(),
            quad.max()
        ])

    features.append(gray.max() - gray.min())

    features.append(gray.std() / (gray.mean() + 1e-8))

    hist_entr, _ = np.histogram(gray.ravel(), bins=64, range=(0, 256))
    hist_entr = hist_entr / (hist_entr.sum() + 1e-8)
    entropy = -np.sum(hist_entr * np.log2(hist_entr + 1e-8))
    features.append(entropy)

    skew = ((gray - gray.mean())**3).mean() / (gray.std()**3 + 1e-8)
    features.append(skew)


    means = img.mean(axis=(0, 1))
    stds = img.std(axis=(0, 1))

    features.extend([
        means[0] / (means[1] + 1e-8),  # R/G ratio
        means[0] / (means[2] + 1e-8),  # R/B ratio
        means[1] / (means[2] + 1e-8),  # G/B ratio
```

```
        stds[0] / (stds[1] + 1e-8),    # R_std/G_std
        stds[0] / (stds[2] + 1e-8),    # R_std/B_std
        stds[1] / (stds[2] + 1e-8),    # G_std/B_std
    ])

    H, W = gray.shape
    padded = np.pad(gray, 1, mode="edge")
    lbp_img = np.zeros((H, W), dtype=np.uint8)

    offsets = [(-1,-1), (-1,0), (-1,1), (0,-1), (0,1), (1,-1), (1,0), (1,1)]

    for idx, (dy, dx) in enumerate(offsets):
        neigh = padded[1+dy:H+1+dy, 1+dx:W+1+dx]
        lbp_img |= ((neigh >= gray).astype(np.uint8) << idx)

    hist_lbp, _ = np.histogram(lbp_img, bins=256, range=(0, 256))
    features.extend(hist_lbp.tolist())

    hist_intensity, _ = np.histogram(gray, bins=16, range=(0, 256))
    features.extend(hist_intensity.tolist())

    return np.array(features, dtype=np.float32)
```

[2414]:
```
import numpy as np

def extract_features(img):
    """
    Version légère: ~100 features au lieu de 337
    Garde les plus importantes
    """
    features = []
    img = img.astype(np.float32)
    gray = img.mean(axis=2)

    # 1. RGB stats (18)
    for c in range(3):
        channel = img[:, :, c]
        features.append(channel.mean())
        features.append(channel.std())
        features.append(np.percentile(channel, 10))
        features.append(np.percentile(channel, 50))
        features.append(np.percentile(channel, 90))
        features.append(channel.max())

    # 2. Grayscale (6)
    features.append(gray.mean())
    features.append(gray.std())
```

```
    features.append(np.percentile(gray, 25))
    features.append(np.percentile(gray, 75))
    features.append(gray.min())
    features.append(gray.max())

    # 3. Edges (3)
    gx = np.abs(gray[:, 1:] - gray[:, :-1]).mean()
    gy = np.abs(gray[1:, :] - gray[:-1, :]).mean()
    features.extend([gx, gy, np.sqrt(gx**2 + gy**2)])

    # 4. Quadrants (8)
    H, W = gray.shape
    h2, w2 = H//2, W//2
    for quad in [gray[:h2, :w2], gray[:h2, w2:], gray[h2:, :w2], gray[h2:, w2:
↪]]:
        features.append(quad.mean())
        features.append(quad.std())

    # 5. Color ratios (3)
    R, G, B = img[:,:,0], img[:,:,1], img[:,:,2]
    features.append(R.mean() / (G.mean() + 1e-8))
    features.append(R.mean() / (B.mean() + 1e-8))
    features.append(G.mean() / (B.mean() + 1e-8))

    # 6. LBP (64 bins au lieu de 256)
    def lbp(gray):
        H, W = gray.shape
        padded = np.pad(gray, ((1, 1), (1, 1)), mode="edge")
        lbp_img = np.zeros((H, W), dtype=np.uint8)
        offsets = [(-1,-1),(-1,0),(-1,1),(0,-1),(0,1),(1,-1),(1,0),(1,1)]
        for idx, (dy, dx) in enumerate(offsets):
            neigh = padded[1+dy:H+1+dy, 1+dx:W+1+dx]
            bit = (neigh >= gray).astype(np.uint8)
            lbp_img |= (bit << idx)
        return lbp_img

    lbp_img = lbp(gray)
    hist_lbp = np.histogram(lbp_img, bins=64, range=(0, 256))[0]
    features.extend(hist_lbp.tolist())


    return np.array(features, dtype=np.float32)
```

[2415]:
```
import numpy as np
import itertools

def polynomial_expansion_degree3(X):
```

```
    N, d = X.shape
    features = []

    # Degree 1
    features.append(X)

    # Degree 2
    for i, j in itertools.combinations_with_replacement(range(d), 2):
        features.append((X[:, i] * X[:, j]).reshape(N, 1))

    # Degree 3
    for i, j, k in itertools.combinations_with_replacement(range(d), 3):
        features.append((X[:, i] * X[:, j] * X[:, k]).reshape(N, 1))

    return np.hstack(features)
```

[2416]:
```
class StandardScaler:
    def fit(self, X):
        self.mu = X.mean(axis=0)
        self.sigma = X.std(axis=0) + 1e-8
    def transform(self, X):
        return (X - self.mu) / self.sigma
    def fit_transform(self, X):
        self.fit(X)
        return self.transform(X)
```

[2417]:
```
class SoftmaxClassifier:
    def __init__(self, input_dim, num_classes, reg=0.0, seed=None):

        if seed is not None:
            np.random.seed(seed)

        self.W = 0.01 * np.random.randn(input_dim, num_classes).astype(np.
 ↪float32)
        self.reg = reg  # L2
        self.b = np.zeros(num_classes)
        self.seed = seed

    def _softmax(self, scores):
        # scores: (N, K)
        scores = scores - scores.max(axis=1, keepdims=True)
        exp_scores = np.exp(scores)
        return exp_scores / exp_scores.sum(axis=1, keepdims=True)

    def loss(self, X, y, sample_weights=None):
        N = X.shape[0]
```

```
        scores = X @ self.W + self.b
        probs = self._softmax(scores)

        correct_logprobs = -np.log(probs[np.arange(N), y] + 1e-12)

        if sample_weights is None:
            sample_weights = np.ones(N)

        loss = np.sum(sample_weights * correct_logprobs) / N
        loss += 0.5 * self.reg * np.sum(self.W**2)

        return loss, probs

    def grad(self, X, y, probs, sample_weights=None):
        N = X.shape[0]

        if sample_weights is None:
            sample_weights = np.ones(N)

        dscores = probs.copy()
        dscores[np.arange(N), y] -= 1
        dscores *= sample_weights[:, None]
        dscores /= N

        dW = X.T @ dscores + self.reg * self.W
        db = dscores.sum(axis=0)
        return dW, db


    def fit(self, X, y, lr=1e-4, n_steps=1000, sample_weights=None,␣
↪verbose=True):
        losses = []
        for step in range(n_steps):

            loss, probs = self.loss(X, y, sample_weights)
            dW, db = self.grad(X, y, probs, sample_weights)

            self.W -= lr * dW
            self.b -= lr * db

            losses.append(loss)

            if verbose and step % 100 == 0:
                print(f"Step {step}, loss = {loss:.4f}")

        return losses
```

```
    def predict_proba(self, X):
        scores = X @ self.W
        probs = self._softmax(scores)
        return probs

    def predict(self, X):
        probs = self.predict_proba(X)
        return probs.argmax(axis=1)
```

[2418]:
```
def accuracy(y_true, y_pred):
    y_true = np.asarray(y_true)
    y_pred = np.asarray(y_pred)
    return np.mean(y_true == y_pred)
```

[2419]:
```
def confusion_matrix_np(y_true, y_pred, num_classes=None):
    y_true = np.asarray(y_true).astype(int)
    y_pred = np.asarray(y_pred).astype(int)

    if num_classes is None:
        num_classes = max(y_true.max(), y_pred.max()) + 1

    cm = np.zeros((num_classes, num_classes), dtype=int)
    for t, p in zip(y_true, y_pred):
        cm[t, p] += 1
    return cm
```

[2420]:
```
def balanced_accuracy(y_true, y_pred):
    cm = confusion_matrix_np(y_true, y_pred)
    TP = np.diag(cm)
    real_pos = cm.sum(axis=1)
    recall = np.where(real_pos > 0, TP / real_pos, 0.0)
    return recall.mean()
```

[2421]:
```
def recall_per_class(cm):
    """
    cm : matrice de confusion (numpy array KxK)
    retourne un vecteur de recall par classe
    """
    TP = np.diag(cm)
    real_pos = cm.sum(axis=1)   # total de vrais échantillons par classe

    # recall par classe (évite division par zéro)
    recall = np.where(real_pos > 0, TP / real_pos, 0.0)
    return recall
```

[2422]:
```python
import numpy as np

def random_flip(img):
    return np.fliplr(img)

def random_brightness(img):
    factor = 0.5 + np.random.rand()  # between 0.5 and 1.5
    return np.clip(img * factor, 0, 255).astype(np.uint8)

def random_noise(img):
    noise = np.random.normal(0, 10, img.shape)
    return np.clip(img + noise, 0, 255).astype(np.uint8)

def random_shift(img, max_shift=2):
    """Shift image by a few pixels using NumPy roll."""
    dx = np.random.randint(-max_shift, max_shift+1)
    dy = np.random.randint(-max_shift, max_shift+1)
    shifted = np.roll(img, dx, axis=0)
    shifted = np.roll(shifted, dy, axis=1)
    return shifted

def augment_image(img):
    """Apply one random augmentation with pure NumPy."""
    ops = [random_flip, random_brightness, random_noise, random_shift]
    op = np.random.choice(ops)
    return op(img)
```

[2423]:
```python
import numpy as np

def rbf_kernel(x, X, sigma=1.0):
    # ||x - X||^2 = sum( (x_i - X_i)^2 )
    dists = np.sum((X - x)**2, axis=1)
    return np.exp(-dists / (2 * sigma**2))


class KernelPerceptron:
    def __init__(self, kernel_fn, n_classes, sigma=1.0):
        self.kernel_fn = kernel_fn
        self.n_classes = n_classes
        self.sigma = sigma


    def fit(self, X, y, max_epochs=10):
        """
        Entraînement multiclasse One-vs-Rest
        """
        N = X.shape[0]
```

```
        self.X = X
        self.classes = np.unique(y)
        self.train_y = y
        #np.random.seed(0)

        # On crée  pour chaque classe
        self.alpha = np.zeros((self.n_classes, N))

        # Precompute Gram matrix
        print("Computing Gram matrix...")
        self.K = np.zeros((N, N))
        for i in range(N):
            self.K[i] = self.kernel_fn(X[i], X, self.sigma)

        for c in self.classes:
            print(f"Training classifier for class {c}...")
            y_bin = np.where(y == c, 1, -1)

            count = 0
            i = 0
            n_iter = 0
            n_iter_max = max_epochs * N

            while count < N and n_iter < n_iter_max:
                pred = np.sign(np.sum(self.alpha[c] * y_bin * self.K[i]))

                if pred != y_bin[i]:
                    self.alpha[c][i] += 1
                    count = 0
                else:
                    count += 1

                i = (i + 1) % N
                n_iter += 1

        print("Training done.")

    def predict(self, X_test):
        """
        Retourne la classe prédite pour chaque x_test
        """
        outputs = []
        for x in X_test:
            # compute kernel K(x, X_train)
            k = self.kernel_fn(x, self.X, self.sigma)

            # score pour chaque classe
```

```
            scores = []
            for c in self.classes:
                y_bin = np.where(self.train_y == c, 1, -1)
                score = np.sum(self.alpha[c] * y_bin * k)
                scores.append(score)

            # classe la plus probable
            outputs.append(np.argmax(scores))

        return np.array(outputs)
```

[2424]:
```
def rbf_kernel_svm(X,Y, sigma):
    dists = np.sum(X**2, axis=1)[:,None] + np.sum(Y**2, axis=1)[None, :] - 2 *␣
 ↪X @ Y.T
    return np.exp(-dists / (2*sigma**2))

class SVM:
    def __init__(self, sigma=1.0, max_iter=5, sample_weights=None):
        self.sigma = sigma
        self.max_iter = max_iter
        self.sample_weights = sample_weights

    def fit(self, X, y):
        self.X = X
        self.y = y
        self.classes = np.unique(y)
        self.K = rbf_kernel_svm(X,X,self.sigma)

        N = X.shape[0]

        self.alpha = {}

        for c in self.classes:
            print(f"train class {c} vs rest")
            y_bin = np.where(y == c, 1, -1)
            alpha_c = np.zeros(N)

            for it in range(self.max_iter):
                for i in range(N):
                    f = np.sum(alpha_c * y_bin * self.K[:, i])
                    if y_bin[i] * f <= 0:
                        alpha_c[i] += self.sample_weights[i]

            self.alpha[c] = alpha_c

    def decision_function(self, X_test):
        K_test = rbf_kernel_svm(X_test, self.X, self.sigma)
```

```
        scores = []
        for c in self.classes:
            y_bin = np.where(self.y == c,1,-1)
            s = K_test @ (self.alpha[c]*y_bin)
            scores.append(s)

        return np.vstack(scores).T

    def predict(self, X_test):
        scores = self.decision_function(X_test)
        return self.classes[np.argmax(scores, axis=1)]
```

[2425]:
```
def PCA_(X, k=30):

    X_centered = X - X.mean(axis=0)
    C = np.cov(X_centered, rowvar=False)
    eigvals, eigvecs = np.linalg.eigh(C)
    idx = np.argsort(eigvals)[::-1]
    eigvecs = eigvecs[idx][:k]  # k = 30 par ex.
    X_reduced = X_centered @ eigvecs.T
    return X_reduced
```

[2426]:
```
import tensorflow as tf
print(tf.__version__)
```

```
2.20.0
```

[2427]:
```
def train_test_split(*arrays, test_size=0.2, train_size=None, random_state=0,␣
 ↪shuffle=True):
    if len(arrays) == 0
        raise ValueError("aucun array")

    n_samples = arrays[0].shape[0]
    for array in arrays:
        if array.shape[0] != n_samples:
            raise ValueError("Array de taille diff")

    if train_size is not None:
        if train_size + test_size > 1.0:
            raise ValueError("train_size + test_size ne peut depasser 1.0")
        n_train = int(n_samples * train_size)
    else:
        n_train = int(n_samples * train_size)

    if random_state is not None:
        np.random.seed(random_state)
```

```
    idx = np.arange(n_samples)

    if shuffle:
        np.random.shuffle(idx)

    train_idx = idx[:n_train]
    test_idx = idx[n_train:]

    result = []

    for array in arrays:
        result.append(array[train_idx])
        result.append(array[test_idx])

    return result
```

```
  Cell In[2427], line 2
    if len(arrays) == 0
                      ^
SyntaxError: expected ':'
```

[ ]:
```
import pickle
import numpy as np
#from sklearn.preprocessing import StandardScaler
#from sklearn.model_selection import train_test_split
import tensorflow as tf

# --- Load training data ---
path_to_data = 'ift-3395-6390-kaggle-2-competition-fall-2025/train_data.pkl'
with open(path_to_data, "rb") as f:
    train_data = pickle.load(f)

X_imgs = train_data["images"].astype(np.float32)
y = train_data["labels"].reshape(-1)

X_imgs = X_imgs.astype(np.float32)
X_imgs = (X_imgs - X_imgs.min()) / (X_imgs.max() - X_imgs.min() + 1e-6)

X_imgs = (X_imgs - X_imgs.mean()) / (X_imgs.std() + 1e-6)
```

[ ]:
```
def fft2_image(img):
    F = np.fft.fft2(img.mean(axis=2))
    F = np.fft.fftshift(F)
    mag = np.log1p(np.abs(F))
```

```
    return mag
```

[ ]:
```
def radial_profile(img):
    h, w = img.shape
    cy, cx = h//2, w//2

    y, x = np.ogrid[:h, :w]
    r = np.sqrt((x-cx)**2 + (y-cy)**2).astype(int)

    radial_mean = np.bincount(r.ravel(), img.ravel()) / np.bincount(r.ravel())
    return radial_mean
```

[ ]:
```
def extract_simple_stats(img):
    gray = img.mean(axis=2)
    return np.array([gray.mean(), gray.std(), gray.min(), gray.max()], dtype=np.
 ↪float32)
```

[ ]:
```
def simple_augment(images):
    # flip horizontal + ajout bruit très léger
    flips = images[:, :, ::-1, :]   # inversion horizontale
    noise = images + 0.01*np.random.randn(*images.shape)
    return np.concatenate([images, flips, noise], axis=0)

X_imgs = simple_augment(X_imgs)
y = np.concatenate([y, y, y])      # labels doublés aussi
```

[ ]:
```
def fft_features_batch(images):
    # Convert to grayscale BEFORE FFT
    gray = images.mean(axis=3)   # (N, 28, 28)

    F = np.fft.fft2(gray, axes=(1,2))
    F_shift = np.fft.fftshift(F, axes=(1,2))
    mag = np.abs(F_shift)        # (N, 28, 28)

    return mag


fft_mag = fft_features_batch(X_imgs)
X_fft = np.array([radial_profile(img) for img in fft_mag], dtype=np.float32)
X_stats = np.array([extract_simple_stats(img) for img in X_imgs], dtype=np.
 ↪float32)
X = np.hstack([X_fft, X_stats])
```

[ ]:
```
scaler = StandardScaler()
X = scaler.fit_transform(X)
```

[ ]:
```
X_train, X_test, y_train, y_test = train_test_split(
    X, y, test_size=0.2, random_state=0
)
```

[ ]:
```
class_counts = np.bincount(y_train)
class_weights = (1.0 / class_counts)
class_weights /= class_weights.sum()
sample_weights = class_weights[y_train]
```

[ ]:
```
"""
model = SVM(sigma=, max_iter=15, sample_weights=sample_weights)
model.fit(X_train, y_train)
"""
```

[ ]:
```
'\nmodel = SVM(sigma=, max_iter=15,
sample_weights=sample_weights)\nmodel.fit(X_train, y_train)\n'
```

[ ]:
```
model = KernelPerceptron(kernel_fn=rbf_kernel, n_classes=5, sigma=2)
model.fit(X_train, y_train, max_epochs=5)
```

```
Computing Gram matrix…
Training classifier for class 0…
Training classifier for class 1…
Training classifier for class 2…
Training classifier for class 3…
Training classifier for class 4…
Training done.
```

[ ]:
```
"""
model = SoftmaxClassifier(input_dim=X.shape[1], num_classes=num_classes, reg=0.
↪05, seed=0)
model.fit(X_train, y_train, lr=2, n_steps=5000, sample_weights=sample_weights)
"""
```

[ ]:
```
'\nmodel = SoftmaxClassifier(input_dim=X.shape[1], num_classes=num_classes,
reg=0.05, seed=0)\nmodel.fit(X_train, y_train, lr=2, n_steps=5000,
sample_weights=sample_weights)\n'
```

[ ]:
```
y_pred = model.predict(X_test)
acc = (y_pred == y_test).mean()
print("Test accuracy =", acc)

cm = confusion_matrix_np(y_test, y_pred)
bal_acc = balanced_accuracy(y_test, y_pred)
rec = recall_per_class(cm)

print("Balanced acc :", bal_acc)
print("Recall par classe :", rec)
```

```
print("Recall moyen :", rec.mean())
```

```
Test accuracy = 0.6620370370370371
Balanced acc : 0.5947081040889166
Recall par classe : [0.86941581 0.32467532 0.43548387 0.56896552 0.775     ]
Recall moyen : 0.5947081040889166
```

[ ]:
```
pickle.dump((model, scaler), open("model_fft.pkl", "wb"))
```

[ ]:
```
import pickle
import numpy as np
import pandas as pd

# --------------------------
# 1. Charger le modèle entraîné
# --------------------------
model, scaler = pickle.load(open("model_fft.pkl", "rb"))

# --------------------------
# 2. Charger le test_data.pkl
# --------------------------
with open("ift-3395-6390-kaggle-2-competition-fall-2025/test_data.pkl", "rb")␣
 ↪as f:
    test_data = pickle.load(f)

X_test_imgs = test_data["images"]


# Apply to test set
X_test_feats = np.array([extract_features(img) for img in X_test_imgs],␣
 ↪dtype=np.float32)

# --------------------------
# 4. Normaliser avec les stats du train
# --------------------------
X_test_norm = scaler.transform(X_test_feats)

# --------------------------
# 5. Prédire
# --------------------------
y_pred = model.predict(X_test_norm).astype(int)

# --------------------------
# 6. Générer le CSV Kaggle
# --------------------------
df = pd.DataFrame({
    "ID": np.arange(1, len(y_pred)+1),
```

```
    "Label": y_pred
})

df.to_csv("ift3395_YamirPoldoSilvaV10.csv", index=False)

print("Fichier 'submission.csv' généré !")
```

```
---------------------------------------------------------------------------
ValueError                                Traceback (most recent call last)
Cell In[2395], line 25
     20 X_test_feats = np.array([extract_features(img) for img in X_test_imgs],
 ↪dtype=np.float32)
     22 # --------------------------
     23 # 4. Normaliser avec les stats du train
     24 # --------------------------
---> 25 X_test_norm = scaler.transform(X_test_feats)
     27 # --------------------------
     28 # 5. Prédire
     29 # --------------------------
     30 y_pred = model.predict(X_test_norm).astype(int)

Cell In[2370], line 6, in StandardScaler.transform(self, X)
      5 def transform(self, X):
----> 6     return (X - self.mu) / self.sigma

ValueError: operands could not be broadcast together with shapes (400,102) (24,
```