

# Chapter 1: Introduction

Chao Wang

SUSTech

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# Information of This Course

# Basic Information

- **Lecturer:** Dr. Chao Wang
  - Email: wangc6@sustech.edu.cn
  - Office: School of Business Building 333
  - Office hours: Tuesday 16:00 – 18:00 or by appointment
- **Tutors:**
  - Mr. Junjie Yu (Email: 12132909@mail.sustech.edu.cn)
  - ...
- **Lecture Hours:**
  - Tuesday 14:00 – 15:50
  - Friday (only odd week) 10:20 – 12:10
- **Venue:** the Three Teaching Building, Room 104
- **QQ group:** 935969266

- MA107 Advanced Linear Algebra I or MA107A Linear Algebra A

**Note:**

- It is strongly recommended that sophomores postpone taking this course to the 4th semester or after. This course will also be arranged in the 2023 spring semester.

# References

- Main references:

- [1] Slides for this course - This course will follow closely with the lecture slides which can be downloaded from the course website.
- [2] Lily Pan, Operations Research, The Chinese University of Hong Kong (lecture note) 2021.
- [3] Haoyan Liu, Jiang Hu, Yongfeng Li, Zaiwen Wen. Optimization: Modeling, algorithm and theory, (chinese), 2021.

- Other references

- [5] Luenberger, D. G., & Ye, Y. Linear and nonlinear programming (3rd Edition). Reading, MA: Addison-wesley. 2008.
- [6] Baomin Chen. Optimization theory and algorithm, Tsinghua university press (chinese)
- [7] Juraj Stacho Introduction to operations research, Columbia University, lecture notes ([link](#))
- [8] Fred S. Hillier, Gerald J. Lieberman, Introduction to Operations Research, 10th Edition, McFraw-Hill Education, 2015.

# Main contents

- Chapter 1. Introduction  
(ref: [ch1,2] & [ch1&ch3,3])
- Chapter 2. Basic Concepts  
(ref: [ch2,2] & [ch2,3])
- Chapter 3. Canonical Problem Forms  
(ref: [ch4,3])
- Chapter 4. Linear Programming & Simplex Method  
(ref: [ch1&ch4&ch5,2])
- Chapter 5. Duality & Sensitivity Analysis  
(ref: [ch7&ch8,2])
- Chapter 6. Optimality Condition  
(ref: [ch5,3])
- Chapter 7. Gradient-based Algorithms  
(ref: [ch6,3])

- A project presentation (10%)
- Six assignments (20%)
- A two-hour written midterm examination (20%)
- A two-hour written final examination (50%)

Remark: The assignment is due by 00:00 am on the due date. Partially or wholly copied assignments will be penalized and/or reported as plagiarism.



# Teaching hours

- **Lectures:** The lectures will be held on Tuesdays and Fridays. The lectures will be used to introduce concepts and develop theories and algorithms.
- **Tutorials:** To facilitate the understanding of the course content, there will be 10 tutorials scheduled in this term starting from the next week. Recitations will cover problems that are similar to the ones on the current problem set. You will be asked to work out solutions to the problems.
- **Midterm:** There will be one quiz (Midterm test). The tentative date for the test is Nov. 1st. If in any doubt, check with the instructor.
- **Final:** There will be one final exam arranged by the university. The tentative date will be arranged in January.

# Tentative Teaching Plan

L=Lecture, T=Tutorial, P=Project presentation date, HW= Homework due date

Week	Date	Content	Date	Content
1	Sep. 6	L1+L2	Sep. 9	L3+T1
2	Sep. 13	L4+L5		
3	Sep. 20	L6+ T2	Sep. 23	L7+L8
4	Sep. 27	L9+T3+HW1		
5	Oct. 11	L10+L11	Oct.14	L12+T4
6	Oct. 18	L13+L14+HW2		
7	Oct. 25	L15+T5	Oct.28	L16+L17
8	Nov.1	Midterm+ HW3		
9	Nov.8	L18+T6	Nov.11	L19+L20
10	Nov.15	L21+T7+HW4		
11	Nov. 22	L22+L23	Nov.25	L24+T8
12	Nov. 29	L25+ L26+HW5		
13	Dec.6	L27+T9	Dec.9	L28+L29
14	Dec.13	L30+L31+HW6		
15	Dec.20	L32+T10	Dec. 23	P
16	Dec. 27	P		

# Overview of OR & Optimization

# What is OR?

- **Operations research (OR)** is an analytical method of **problem-solving** and **decision-making** that is useful in the management of organizations.
- In operations research, problems are broken down into **basic components** and then solved in defined steps by mathematical analysis.
- OR=Operational Research = Operations Research  
     $\approx$  Management Science  $\approx$  Industrial Engineering
- **Example:** Assignment problem, transportation problem, network problem, game theory, **linear programming**...

# What is Optimization?

- **Optimization** models the goal of solving a problem in the **optimal way**.
- Optimization is an **essential tool** in life, business, and engineer.
- In general, it can be formulated as

$$\begin{array}{ll}\min & f_0(x) \\ \text{s.t.}, & f_i(x) \leq b_i, i = 1, \dots, m.\end{array}$$

- $x = (x_1, \dots, x_n)$  : optimization variables
- $f_0 : \mathbb{R}^n \rightarrow \mathbb{R}$  : objective function
- $f_i : \mathbb{R}^n \rightarrow \mathbb{R}, i = 1, \dots, m$  : constraint functions
- **Example:** linear/nonlinear optimization, **convex**/non-convex optimization

# Optimization problem

- The general form of optimization:

$$\begin{array}{ll}\text{Min} & f(x) \\ \text{Subject to} & x \in \Omega\end{array}$$

- Suppose  $x \in \mathbb{R}^n$ ,  $\Omega$  is called the **feasible set**.
- If  $\Omega = \mathbb{R}^n$ , then the problem is called **unconstrained**.
- Otherwise, the problem is called **constrained**.
- We can write any **constrained** problem in the unconstrained form

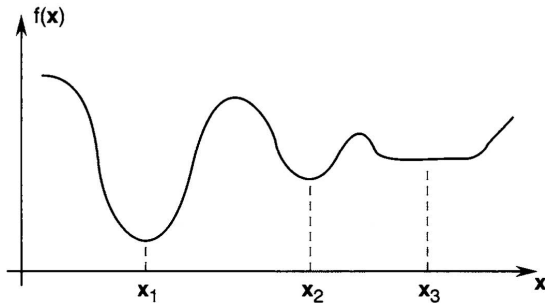
$$\min f(x) + \iota_{\Omega}(x),$$

where the **indicator function**

$$\iota_{\Omega}(x) = \begin{cases} 0, & x \in \Omega, \\ \infty, & x \notin \Omega. \end{cases}$$

# Types of solutions

- $x^*$  is a **local minimizer** if there is  $\epsilon > 0$  such that  $f(x) \geq f(x^*)$  for all  $x \in \Omega \setminus \{x^*\}$  and  $\|x - x^*\| < \epsilon$ .
- $x^*$  is a **global minimizer** if  $f(x) \geq f(x^*)$  for all  $x \in \Omega \setminus \{x^*\}$
- If " $\geq$ " is replaced with " $>$ ", then they are **strict local minimizer** and **strict global minimizer**, respectively.



$x_1$ : strict global minimizer;  $x_2$ : strict local minimizer;  $x_3$ : local minimizer

# Type of Problems — Linear Programming

$$\begin{array}{ll}\text{Max/Min} & z = \sum_{j=1}^n c_j x_j \\ \text{Subject to} & \sum_{j=1}^n a_{ij} x_j \begin{pmatrix} \geq \\ \leq \\ = \end{pmatrix} b_i, \quad i = 1, 2, \dots, m \\ & x_j \begin{pmatrix} \geq 0 \\ \leq 0 \\ \text{unrestricted} \end{pmatrix}, \quad j = 1, 2, \dots, n.\end{array}$$

## Terminology

- **objective function**:  $\sum_{j=1}^n c_j x_j$
- **decision variables**:  $x_1, x_2, \dots, x_i, \dots$
- **constraint**: e.g.:  $\sum_{j=1}^n a_{ij} x_j \leq b_i$
- **variable domains**: e.g.:  $x_j \geq 0$



# Type of problems — Linear programming

**Example:** A production problem

A firm produces  $n$  different goods using  $m$  different raw materials. Let  $b_i$ ,  $i = 1, 2, \dots, m$ , be the available amount of the  $i$ th raw material. The  $j$ th good,  $j = 1, \dots, n$ , requires  $a_{ij}$  units of the  $i$ th material and results in a revenue of  $c_j$  per unit produced. The firm faces the problem of deciding how much of each good to produce in order to maximize its total revenue.

**Formulation:**

Let  $x_j$ ,  $j = 1, \dots, n$ , be the amount of  $j$ th good.

$$\begin{array}{ll} \text{Maximize} & c_1x_1 + \cdots + c_nx_n \\ \text{subject to} & a_{i1}x_1 + \cdots + a_{in}x_n \leq b_i, \quad i = 1, \dots, m, \\ & x_j \geq 0, \quad j = 1, \dots, n. \end{array} \quad (1)$$

# Type of problems — Linear programming

**Example:** A diet problem

There are  $m$  different types of food,  $F_1, \dots, F_m$ , that supply varying quantities of the  $n$  nutrients,  $N_1, \dots, N_n$ , that are essential to good health. Let  $c_j$  be the minimum daily requirement of nutrient,  $N_j$ . Let  $b_i$  be the price per unit of good,  $F_i$ . Let  $a_{ij}$  be the amount of nutrient  $N_j$  contained in one unit of food  $F_i$ . The problem is to supply the required nutrients at minimum cost.

**Formulation:**

Let  $x_i$  be the number of units of good  $F_i$  to be purchased per day. The problem can be formulated as follows:

$$\begin{array}{ll} \text{Minimize} & b_1x_1 + \dots + b_mx_m \\ \text{subject to} & a_{1j}x_1 + \dots + a_{mj}x_m \geq c_j, \quad j = 1, \dots, n, \\ & x_i \geq 0, \quad i = 1, \dots, m. \end{array} \quad (2)$$

# Type of problems — Linear programming

## Example: A Transportation Problem

There are  $I$  ports, or production plants,  $P_1, \dots, P_I$ , that supply a certain commodity, and there are  $J$  markets,  $M_1, \dots, M_J$ , to which this commodity must be shipped. Port  $P_i$  possesses an amount  $s_i$  of the commodity ( $i = 1, 2, \dots, I$ ), and market  $M_j$  must receive the amount of  $r_j$  of the commodity ( $j = 1, \dots, J$ ). Let  $b_{ij}$  be the cost of transporting one unit of the commodity from port  $P_i$  to market  $M_j$ . The problem is to meet the market requirements at minimum transportation cost.

## Formulation:

Let  $x_{ij}$  be the quantity of the commodity shipped from port  $P_i$  to market  $M_j$ . The problem can be formulated as follows:

$$\begin{aligned} \text{Minimize} \quad & \sum_{i=1}^I \sum_{j=1}^J x_{ij} b_{ij} \\ \text{subject to} \quad & \sum_{j=1}^J x_{ij} \leq s_i, \quad i = 1, \dots, I, \\ & \sum_{i=1}^I x_{ij} \geq r_j, \quad j = 1, \dots, J, \\ & x_{ij} \geq 0, \quad i = 1, \dots, I \text{ and } j = 1, \dots, J. \end{aligned} \tag{3}$$

# Properties of Linear Programming

- ① There is a **unique** objective function.
- ② The objective function is **linear** and all constraints are **linear** equalities or inequalities.
- ③ The coefficients of the decision variables in the objective function and each constraint are **constant**.
- ④ The decision variables are permitted to assume fractional as well as integer values.

# Type of Problems — Nonlinear programming

- **multiobjective or goal programs**: Problems with more than one objective function.
- **nonlinear program**: Any optimization problem that fails to satisfy Property 2
- **dynamic program**: the coefficients is time dependent. And the problem is defined in a certain class
- **stochastic program**: the coefficients are not constant but instead are probabilistic
- **integer program or a mixed-integer program**: one or more of the decision variables are restricted to integer values

## Type of problems — Integer Programming

**Example:** A local manufacturing plant runs 24 hours a day, 7 days a week. During various times throughout the day, different numbers of workers are needed to run the various machines. Below are the minimum number of people needed to safely run the plant during various times.

Times	Employees Needed
12 AM - 4 AM	8
4 AM - 8 AM	9
8 AM - 12 PM	15
12 PM - 4PM	14
4 PM - 8 PM	13
8 PM - 12 AM	11

A worker can only start working at the start of each 4-hour period, and should work for 8 hours straight. What is the minimum number of people required daily to safely run the plant?



# Type of Problems — Least squares

## Example: Polynomial Fitting

- Suppose the observed data is  $y_i \in \mathbb{R}$  for each time point  $t_i, i = 1, 2, \dots, N$ , respectively. The underlying assumption it is that there is some function of time  $f : \mathbb{R} \rightarrow \mathbb{R}$  such that  $y_i = f(t_i), i = 1, 2, \dots, N$ .
- How to estimate it by a polynomial of a fixed degree, say  $n$  :  
$$p(t) = x_0 + x_1 t + x_2 t^2 + \dots + x_n t^n.$$
- How to determine the coefficients that "best" fit the data? - If were possible to exactly fit the data, then there would exist a value for the coefficient.
- If  $n \ll N$ , it cannot expect to fit the data perfectly and so there will be errors. It is wish to minimize the sum of the squares of the errors in the fit:



# Type of Problems — Least squares

## Example: Polynomial Fitting

This minimization problem has the form  $\min_x \frac{1}{2} \|Vx - y\|_2^2$ , where

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix}, x = \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix} \text{ and } V = \begin{bmatrix} 1 & t_1 & t_1^2 & \cdots & t_1^n \\ 1 & t_2 & t_2^2 & \cdots & t_2^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & t_N & t_N^2 & \cdots & t_N^n \end{bmatrix}.$$

- **least squares**: a standard approach in regression analysis to approximate the solution of **overdetermined** systems (sets of equations in which there are more equations than unknowns)

# Type of Problems — Variants of least squares

## Example: Structured Optimization

$\ell_1$  norm regularized linear regression

$$\min_x \frac{1}{2} \|Ax - b\|_2^2 + \tau \|x\|_1$$

- $\|x\|_1 = \sum_i |x_i|$  approaching  $\|x\|_0$  (number of nonzero entries)
- $\tau$  is a fixed constant called regularization parameter.
- this is called LASSO in statistics, Compressed sensing in signal processing
- a non-smoothed problem but **convex** (will explain in the next chapter)

# Type of Problems — Variants of least squares

- Ridge regression/Tikhonov regularization

$$\min_x \frac{1}{2} \|Ax - b\|_2^2 + \mu \|x\|_2^2$$

- sparse regularization

$$\min_x \frac{1}{2} \|Ax - b\|_2^2 + \mu \|x\|_1$$

- Lasso/Basis pursuit

$$\min_x \|x\|_1, \text{ s.t. } \|Ax - b\|_2 \leq \epsilon$$

or

$$\min_x \|Ax - b\|_2, \text{ s.t. } \|x\|_1 \leq \sigma$$

or even under a different norm

$$\min_x \|Ax - b\|_1, \text{ s.t. } \|x\|_1 \leq \sigma$$

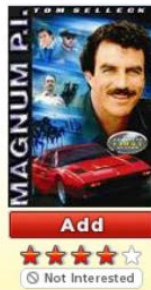
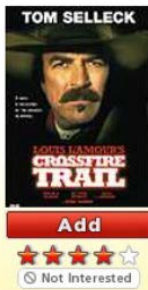
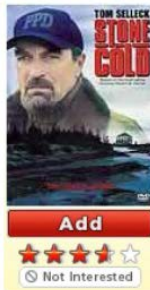
# Some applications — recommendation

## Example: Recommendation System: Netflix

- Rating Movies



- Get recommendations



# Some applications — recommendation

## Example: Recommendation System: Netflix Prize

- 480,189 users rate 17,770 movies
- over 100 million ratings (1.2%)
- Data: incomplete rating matrix
- Decision: predict the missing ratings
- 1 million dollar prize



# Some applications — recommendation

## Example: Recommendation System: Netflix Prize

	Movie				
User	?	9	5	6	8
	8	8	4	9	?
	1	3	?	5	4
	8	?	10	4	1

- Rating matrix is believed to be low rank



$$\min_X \text{rank}(X) \quad \text{s.t.} \quad X_{ij} = M_{ij}, \forall (i,j) \in \Omega$$
$$\text{Or} \quad \min_X \|X\|_* \quad \text{s.t.} \quad X_{ij} = M_{ij}, \forall (i,j) \in \Omega$$

where  $\|X\|_* := \sum \sigma_i(X)$  is the nuclear norm of matrix  $X$ , and  $\sigma_i(X)$  is the  $i$ -th singular value of  $X$

# Some applications — machine learning

Many problems in ML can be written as

- linear regression:  $\min_{x \in \mathcal{W}} \sum_{i=1}^N \frac{1}{2} \|a_i^\top x - b_i\|_2^2 + \mu \|x\|_1$
  - logistic regression:  $\min_{x \in \mathcal{W}} \frac{1}{N} \sum_{i=1}^N \log(1 + \exp(-b_i a_i^\top x)) + \mu \|x\|_1$
  - general formulation:  $\min_{w \in \mathcal{W}} \sum_{i=1}^N \ell(h(x, a_i), b_i) + \mu r(x)$
- 
- The pairs  $(a_i, b_i)$  are given data,  $b_i$  is the label of the data point  $a_i$
  - $\ell(\cdot)$  : measures how model fit for data points (avoids under-fitting)
  - $r(x)$  : regularization term (avoids over-fitting)
  - $h(x, a)$ : linear function or models constructed from deep neural networks

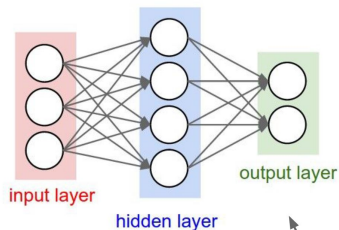
# Some applications — machine learning

Given:

- Some dataset of  $(x, y)$
- a score function:
  - Linear:  $s = f(x; W) \stackrel{\text{e.g.}}{=} Wx$
  - 2-layer neural network:  $s = f(x; W) \stackrel{\text{e.g.}}{=} W_2 \max(0, W_1 x)$
- a loss function:
  - Softmax:  $L_i = -\log \left( \frac{e^{s_{y_i}}}{\sum_j e^{s_j}} \right)$
  - SVM  $L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + 1)$
  - Full loss:  $L = \frac{1}{N} \sum_{i=1}^N L_i + R(W)$

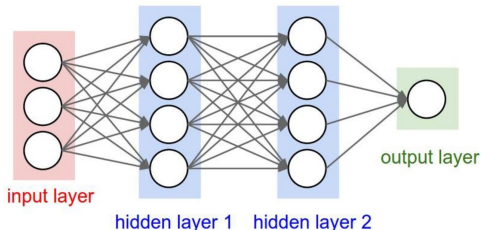


## Neural networks: Architectures



"2-layer Neural Net", or  
"1-hidden-layer Neural Net"

**"Fully-connected" layers**



"3-layer Neural Net", or  
"2-hidden-layer Neural Net"

## Convolutional network (AlexNet)

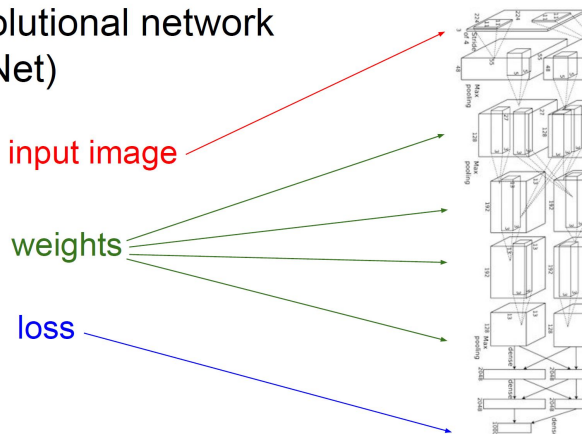


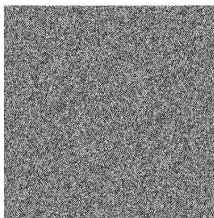
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# Some applications — image reconstruction

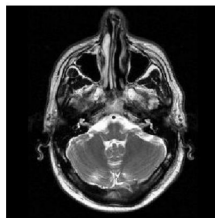
## Example: MRI: Magnetic Resonance Imaging



(a) MRI Scan



(b) Fourier Coefficients



(c) Image

Is it possible to cut the scan time into half?

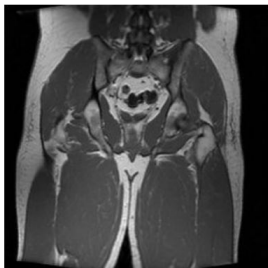
# Some applications — image reconstruction

## Example: MRI: Magnetic Resonance Imaging

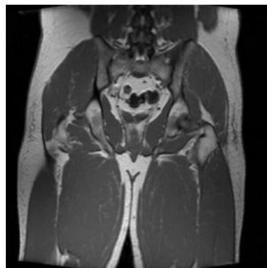
- MR images often have sparse representations under some wavelet transform  $\Phi$
- Solve

$$\min_u \|\Phi u\|_1 + \frac{\mu}{2} \|Ru - b\|^2$$

$R$  : partial discrete Fourier transform



(a) full sampling



(b) 39% sampling,

# Summary

- Optimization problems underlie nearly everything we do in Machine Learning and Statistics. In other courses, you learn how to:

translate



*Conceptual idea*

into  $P : \min_{x \in D} f(x)$

*Optimization problem*

- This course:
  - **Model**: How to simplify  $P$  into a simpler form?
  - **Algorithm**: How to solve  $P$ ?
  - **Analysis**: why this is a good skill to have

# Recall: Main contents

- Chapter 1. Introduction (overview)
- Chapter 2. Basic Concepts (warm-up)
- Chapter 3. Canonical Problem Forms (warm-up)
- Chapter 4. Linear Programming & Simplex Method (model & algorithm)
- Chapter 5. Duality & Sensitivity Analysis (analysis)
- Chapter 6. Optimality Condition (analysis)
- Chapter 7. Gradient-based Algorithms (algorithm)