

# CS 341: Algorithms

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- 1 Course Information
- 2 Introduction
- 3 Divide-and-Conquer Algorithms
- 4 Greedy Algorithms
- 5 Dynamic Programming Algorithms
- 6 Graph Algorithms
- 7 Intractability and Undecidability

# Table of Contents

## 7 Intractability and Undecidability

- Decision Problems
- The Complexity Class P
- Decision, Optimal Value and Optimization Problems
- The Complexity Class NP
- Reductions
- NP-completeness and NP-complete Problems
- Undecidability

# Decision Problems

**Decision Problem:** Given a problem instance  $I$ , answer a certain question “yes” or “no”.

**Problem Instance:** Input for the specified problem.

**Problem Solution:** Correct answer (“yes” or “no”) for the specified problem instance.  $I$  is a **yes-instance** if the correct answer for the instance  $I$  is “yes”.  $I$  is a **no-instance** if the correct answer for the instance  $I$  is “no”.

**Size of a problem instance:**  $Size(I)$  is the number of bits required to specify (or encode) the instance  $I$ .

# The Complexity Class P

**Algorithm Solving a Decision Problem:** An algorithm  $A$  is said to **solve** a decision problem  $\Pi$  provided that  $A$  finds the correct answer (“yes” or “no”) for every instance  $I$  of  $\Pi$  in finite time.

**Polynomial-time Algorithm:** An algorithm  $A$  for a decision problem  $\Pi$  is said to be a **polynomial-time algorithm** provided that the complexity of  $A$  is  $O(n^k)$ , where  $k$  is a positive integer and  $n = \text{Size}(I)$ .

**The Complexity Class P** denotes the set of all decision problems that have polynomial-time algorithms solving them. We write  $\Pi \in P$  if the decision problem  $\Pi$  is in the complexity class  $P$ .

# Cycles in Graphs

## Problem

### Cycle

**Instance:** *An undirected graph  $G = (V, E)$ .*

**Question:** *Does  $G$  contain a cycle?*

## Problem

### Hamiltonian Cycle

**Instance:** *An undirected graph  $G = (V, E)$ .*

**Question:** *Does  $G$  contain a hamiltonian cycle?*

A **hamiltonian cycle** is a cycle that passes through every vertex in  $V$  exactly once.

# Knapsack Problems

## Problem

### 0-1 Knapsack-Dec

**Instance:** a list of **profits**,  $P = [p_1, \dots, p_n]$ ; a list of **weights**,  $W = [w_1, \dots, w_n]$ ; a **capacity**,  $M$ ; and a **target profit**,  $T$ .

**Question:** Is there an  $n$ -tuple  $[x_1, x_2, \dots, x_n] \in \{0, 1\}^n$  such that  $\sum w_i x_i \leq M$  and  $\sum p_i x_i \geq T$ ?

## Problem

### Rational Knapsack-Dec

**Instance:** a list of **profits**,  $P = [p_1, \dots, p_n]$ ; a list of **weights**,  $W = [w_1, \dots, w_n]$ ; a **capacity**,  $M$ ; and a **target profit**,  $T$ .

**Question:** Is there an  $n$ -tuple  $[x_1, x_2, \dots, x_n] \in [0, 1]^n$  such that  $\sum w_i x_i \leq M$  and  $\sum p_i x_i \geq T$ ?

# Polynomial-time Turing Reductions

Suppose  $\Pi_1$  and  $\Pi_2$  are problems (not necessarily decision problems). A (hypothetical) algorithm  $A_2$  to solve  $\Pi_2$  is called an **oracle** for  $\Pi_2$ .

Suppose that  $A$  is an algorithm that solves  $\Pi_1$ , assuming the existence of an oracle  $A_2$  for  $\Pi_2$ . ( $A_2$  is used as a subroutine within the algorithm  $A$ .)

Then we say that  $A$  is a **Turing reduction** from  $\Pi_1$  to  $\Pi_2$ , denoted  $\Pi_1 \leq^T \Pi_2$ .

A Turing reduction  $A$  is a **polynomial-time Turing reduction** if the running time of  $A$  is polynomial, under the assumption that the oracle  $A_2$  has **unit cost** running time.

If there is a polynomial-time Turing reduction from  $\Pi_1$  to  $\Pi_2$ , we write  $\Pi_1 \leq_P^T \Pi_2$ .

Informally: **Existence of a polynomial-time Turing reduction means that if we can solve  $\Pi_2$  in polynomial time, then we can solve  $\Pi_1$  in polynomial time.**



# Travelling Salesperson Problems

## Problem

### TSP-Optimization

**Instance:** A graph  $G$  and edge weights  $w : E \rightarrow \mathbb{Z}^+$ .

**Find:** A hamiltonian cycle  $H$  in  $G$  such that  $w(H) = \sum_{e \in H} w(e)$  is minimized.

## Problem

### TSP-Optimal Value

**Instance:** A graph  $G$  and edge weights  $w : E \rightarrow \mathbb{Z}^+$ .

**Find:** The minimum  $T$  such that there exists a hamiltonian cycle  $H$  in  $G$  with  $w(H) = T$ .

## Problem

### TSP-Decision

**Instance:** A graph  $G$ , edge weights  $w : E \rightarrow \mathbb{Z}^+$ , and a target  $T$ .

**Question:** Does there exist a hamiltonian cycle  $H$  in  $G$  with  $w(H) \leq T$ ?

# TSP-Optimal Value $\leq_P^T$ TSP-Dec

**Algorithm:** *TSP-OptimalValue-Solver*( $G, w$ )

**external** *TSP-Dec-Solver*

$hi \leftarrow \sum_{e \in E} w(e)$

$lo \leftarrow 0$

**if not** *TSP-Dec-Solver*( $G, w, hi$ ) **then return** ( $\infty$ )

**while**  $hi > lo$

**do**  $\begin{cases} mid \leftarrow \lfloor \frac{hi+lo}{2} \rfloor \\ \text{if } \textit{TSP-Dec-Solver}(G, w, mid) \\ \quad \text{then } hi \leftarrow mid \\ \quad \text{else } lo \leftarrow mid + 1 \end{cases}$

**return** ( $hi$ )

# TSP-Optimization $\leq_P^T$ TSP-Dec

**Algorithm:** *TSP-Optimization-Solver*( $G = (V, E), w$ )  
external *TSP-OptimalValue-Solver*, *TSP-Dec-Solver*  
 $T^* \leftarrow \textit{TSP-OptimalValue-Solver}(G, w)$   
**if**  $T^* = \infty$  **then return** ("no hamiltonian cycle exists")  
 $w_0 \leftarrow w$   
 $H \leftarrow \emptyset$   
**for all**  $e \in E$   
    **do**  $\begin{cases} w_0[e] \leftarrow \infty \\ \textbf{if not } \textit{TSP-Dec-Solver}(G, w_0, T^*) \\ \quad \textbf{then } \begin{cases} w_0[e] \leftarrow w[e] \\ H \leftarrow H \cup \{e\} \end{cases} \end{cases}$   
**return** ( $H$ )

# Certificates

**Certificate:** Informally, a certificate for a yes-instance  $I$  is some “extra information”  $C$  which makes it easy to **verify** that  $I$  is a yes-instance.

**Certificate Verification Algorithm:** Suppose that  $Ver$  is an algorithm that verifies certificates for yes-instances. Then  $Ver(I, C)$  outputs “yes” if  $I$  is a yes-instance and  $C$  is a valid certificate for  $I$ . If  $Ver(I, C)$  outputs “no”, then either  $I$  is a no-instance, or  $I$  is a yes-instance and  $C$  is an invalid certificate.

**Polynomial-time Certificate Verification Algorithm:** A certificate verification algorithm  $Ver$  is a polynomial-time certificate verification algorithm if the complexity of  $Ver$  is  $O(n^k)$ , where  $k$  is a positive integer and  $n = Size(I)$ .

# The Complexity Class NP

**Certificate Verification Algorithm for a Decision Problem:** A certificate verification algorithm  $Ver$  is said to **solve** a decision problem  $\Pi$  provided that

- **for every** yes-instance  $I$ , **there exists** a certificate  $C$  such that  $Ver(I, C)$  outputs “yes”.
- **for every** no-instance  $I$  and **for every** certificate  $C$ ,  $Ver(I, C)$  outputs “no”.

**The Complexity Class NP** denotes the set of all decision problems that have polynomial-time certificate verification algorithms solving them. We write  $\Pi \in NP$  if the decision problem  $\Pi$  is in the complexity class  $NP$ .

**Finding Certificates vs Verifying Certificates:** It is **not required** to be able to **find** a certificate  $C$  for a yes-instance in polynomial time in order to say that a decision problem  $\Pi \in NP$ .

# Certificate Verification Algorithm for Hamiltonian Cycle

A certificate consists of an  $n$ -tuple,  $X = [x_1, \dots, x_n]$ , that might be a hamiltonian cycle for a given graph  $G = (V, E)$  (where  $n = |V|$ ).

**Algorithm:** *Hamiltonian Cycle Certificate Verification*( $G, X$ )

$flag \leftarrow \text{true}$

$Used \leftarrow \{x_1\}$

$j \leftarrow 2$

**while** ( $j \leq n$ ) **and**  $flag$

**do**  $\begin{cases} flag \leftarrow (x_j \notin Used) \text{ and } (\{x_{j-1}, x_j\} \in E) \\ \text{if } (j = n) \text{ then } flag \leftarrow flag \text{ and } (\{x_n, x_1\} \in E) \\ Used \leftarrow Used \cup \{x_j\} \end{cases}$

**return** ( $flag$ )

# Polynomial-time Reductions

For a decision problem  $\Pi$ , let  $\mathcal{I}(\Pi)$  denote the set of all instances of  $\Pi$ . Let  $\mathcal{I}_{\text{yes}}(\Pi)$  and  $\mathcal{I}_{\text{no}}(\Pi)$  denote the set of all yes-instances and no-instances (respectively) of  $\Pi$ .

Suppose that  $\Pi_1$  and  $\Pi_2$  are decision problems. We say that there is a **polynomial-time reduction** (AKA **polynomial transformation**) from  $\Pi_1$  to  $\Pi_2$  (denoted  $\Pi_1 \leq_P \Pi_2$ ) if there exists a function  $f : \mathcal{I}(\Pi_1) \rightarrow \mathcal{I}(\Pi_2)$  such that the following properties are satisfied:

- $f(I)$  is computable in polynomial time (as a function of *size*( $I$ ), where  $I \in \mathcal{I}(\Pi_1)$ )
- if  $I \in \mathcal{I}_{\text{yes}}(\Pi_1)$ , then  $f(I) \in \mathcal{I}_{\text{yes}}(\Pi_2)$
- if  $I \in \mathcal{I}_{\text{no}}(\Pi_1)$ , then  $f(I) \in \mathcal{I}_{\text{no}}(\Pi_2)$

# Two Graph Theory Decision Problems

## Problem

### Clique

**Instance:** An undirected graph  $G = (V, E)$  and an integer  $k$ , where  $1 \leq k \leq |V|$ .

**Question:** Does  $G$  contain a clique of size  $\geq k$ ? (A **clique** is a subset of vertices  $W \subseteq V$  such that  $uv \in E$  for all  $u, v \in W$ ,  $u \neq v$ .)

## Problem

### Vertex Cover

**Instance:** An undirected graph  $G = (V, E)$  and an integer  $k$ , where  $1 \leq k \leq |V|$ .

**Question:** Does  $G$  contain a vertex cover of size  $\leq k$ ? (A **vertex cover** is a subset of vertices  $W \subseteq V$  such that  $\{u, v\} \cap W \neq \emptyset$  for all edges  $uv \in E$ .)



# Clique $\leq_P$ Vertex-Cover

Suppose that  $I = (G, k)$  is an instance of **Clique**, where  $G = (V, E)$ ,  $V = \{v_1, \dots, v_n\}$  and  $1 \leq k \leq n$ .

Construct an instance  $f(I) = (H, \ell)$  of **Vertex Cover**, where  $H = (V, F)$ ,  $\ell = n - k$  and

$$v_i v_j \in F \Leftrightarrow v_i v_j \notin E.$$

$H$  is called the **complement** of  $G$ , because every edge of  $G$  is a non-edge of  $H$  and every non-edge of  $G$  is an edge of  $H$ .

# Properties of Polynomial-time Reductions

Suppose that  $\Pi_1, \Pi_2, \dots$  are decision problems.

## Theorem

*If  $\Pi_1 \leq_P \Pi_2$  and  $\Pi_2 \in P$ , then  $\Pi_1 \in P$ .*

## Theorem

*$\Pi_1 \leq_P \Pi_2$  and  $\Pi_2 \leq_P \Pi_3$ , then  $\Pi_1 \leq_P \Pi_3$ .*

# The Complexity Class $\text{NPC}$

The complexity class  $\text{NPC}$  denotes the set of all decision problems  $\Pi$  that satisfy the following two properties:

- $\Pi \in \text{NP}$
- For all  $\Pi' \in \text{NP}$ ,  $\Pi' \leq_P \Pi$ .

$\text{NPC}$  is an abbreviation for  $\text{NP-complete}$ .

## Theorem

If  $P \cap \text{NPC} \neq \emptyset$ , then  $P = \text{NP}$ .

# Satisfiability and the Cook-Levin Theorem

## Problem

### CNF-Satisfiability

**Instance:** A boolean formula  $F$  in  $n$  boolean variables  $x_1, \dots, x_n$ , such that  $F$  is the **conjunction** (logical “and”) of  $m$  **clauses**, where each clause is the **disjunction** (logical “or”) of literals. (A **literal** is a boolean variable or its negation.)

**Question:** Is there a truth assignment such that  $F$  evaluates to **true**?

## Theorem

**CNF-Satisfiability**  $\in$  **NPC**.

# Proving Problems NP-complete

Now, given any NP-complete problem, say  $\Pi_1$ , other problems in **NP** can be proven to be NP-complete via polynomial reductions **from**  $\Pi_1$ , as stated in the following theorem:

## Theorem

*Suppose that the following conditions are satisfied:*

- $\Pi_1 \in \text{NPC}$ ,
- $\Pi_1 \leq_P \Pi_2$ , and
- $\Pi_2 \in \text{NP}$ .

*Then  $\Pi_2 \in \text{NPC}$ .*

# More Satisfiability Problems

## Problem

### 3-CNF-Satisfiability

**Instance:** A boolean formula  $F$  in  $n$  boolean variables, such that  $F$  is the conjunction of  $m$  clauses, where each clause is the disjunction of exactly **three** literals.

**Question:** Is there a truth assignment such that  $F$  evaluates to **true**?

## Problem

### 2-CNF-Satisfiability

**Instance:** A boolean formula  $F$  in  $n$  boolean variables, such that  $F$  is the conjunction of  $m$  clauses, where each clause is the disjunction of exactly **two** literals.

**Question:** Is there a truth assignment such that  $F$  evaluates to **true**?

**3-CNF-Satisfiability**  $\in$  **NP**, while **2-CNF-Satisfiability**  $\in$  **P**.

## CNF-Satisfiability $\leq_P$ 3-CNF-Satisfiability

Suppose that  $(X, \mathcal{C})$  is an instance of **CNF-SAT**, where  $X = \{x_1, \dots, x_n\}$  and  $\mathcal{C} = \{C_1, \dots, C_m\}$ . For each  $C_j$ , do the following:

**case 1** If  $|C_j| = 1$ , say  $C_j = \{z\}$ , construct four clauses

$$\{z, a, b\}, \{z, a, \bar{b}\}, \{z, \bar{a}, b\}, \{z, \bar{a}, \bar{b}\}.$$

**case 2** If  $|C_j| = 2$ , say  $C_j = \{z_1, z_2\}$ , construct two clauses

$$\{z_1, z_2, c\}, \{z_1, z_2, \bar{c}\}.$$

**case 3** If  $|C_j| = 3$ , then leave  $C_j$  unchanged.

**case 4** If  $|C_j| \geq 4$ , say  $C_j = \{z_1, z_2, \dots, z_k\}$ , then construct  $k - 2$  new clauses

$$\{z_1, z_2, d_1\}, \{\bar{d}_1, z_3, d_2\}, \{\bar{d}_2, z_4, d_3\}, \dots, \\ \{\bar{d}_{k-4}, z_{k-2}, d_{k-3}\}, \{\bar{d}_{k-3}, z_{k-1}, z_k\}.$$

### 3-CNF-Satisfiability $\leq_P$ Clique

Let  $I$  be the instance of **3-CNF-SAT** consisting of  $n$  variables,  $x_1, \dots, x_n$ , and  $m$  clauses,  $C_1, \dots, C_m$ . Let  $C_i = \{z_1^i, z_2^i, z_3^i\}$ ,  $1 \leq i \leq m$ .

Define  $f(I) = (G, k)$ , where  $G = (V, E)$  according to the following rules:

- $V = \{v_j^i : 1 \leq i \leq m, 1 \leq j \leq n\}$ ,
- $v_j^i v_{j'}^{i'} \in E$  if and only if  $i \neq i'$  and  $z_j^i \neq \overline{z_{j'}^{i'}}$ , and
- $k = m$ .



# Subset Sum

## Problem

### Subset Sum

**Instance:** A list of **sizes**  $S = [s_1, \dots, s_n]$ ; and a **target sum**,  $T$ . These are all positive integers.

**Question:** Does there exist a subset  $J \subseteq \{1, \dots, n\}$  such that  $\sum_{i \in J} s_i = T$ ?

## Vertex Cover $\leq_P$ Subset Sum

Suppose  $I = (G, k)$ , where  $G = (V, E)$ ,  $|V| = n$ ,  $|E| = m$  and  $1 \leq k \leq n$ .

Suppose  $V = \{v_1, \dots, v_n\}$  and  $E = \{e_0, \dots, e_{m-1}\}$ . For  $1 \leq i \leq n$ ,  $0 \leq j \leq m-1$ , let

$$c_{ij} = \begin{cases} 1 & \text{if } e_j \text{ is incident with } v_i \\ 0 & \text{otherwise.} \end{cases}$$

Define  $n + m$  sizes and a target sum  $W$  as follows:

$$a_i = 10^m + \sum_{j=0}^{m-1} c_{ij} 10^j \quad (1 \leq i \leq n)$$

$$b_j = 10^j \quad (0 \leq j \leq m-1)$$

$$W = k \cdot 10^m + \sum_{j=0}^{m-1} 2 \cdot 10^j$$

Then define  $f(I) = (a_1, \dots, a_n, b_0, \dots, b_{m-1}, W)$ .

# Reductions among NP-complete Problems (summary)



In the above diagram, arrows denote polynomial reductions.

# Undecidable Problems

A decision problem  $\Pi$  is **undecidable** if there does not exist an algorithm that solves  $\Pi$ .

If  $\Pi$  is undecidable, then for every algorithm  $A$ , there exists at least one instance  $I \in \mathcal{I}(\Pi)$  such that  $A(I)$  does not find the correct answer (“yes” or “no”) in finite time.

## Problem

### Halting

**Instance:** *A computer program  $A$  and input  $x$  for the program  $A$ .*

**Question:** *When program  $A$  is executed with input  $x$ , will it halt in finite time?*

# Undecidability of the Halting Problem

Suppose that *Halt* is a program that solves the **Halting Problem**. Consider the following algorithm *Strange*.

**Algorithm:** *Strange*(*A*)  
  external *Halt*  
  **if not** *Halt*(*A*, *A*)  
    **then return** (!)  
  **else**  $\begin{cases} i \leftarrow 1 \\ \textbf{while } i \neq 0 \textbf{ do } i \leftarrow i + 1 \end{cases}$

What happens when we run *Strange*(*Strange*)?