

Routing Protocols

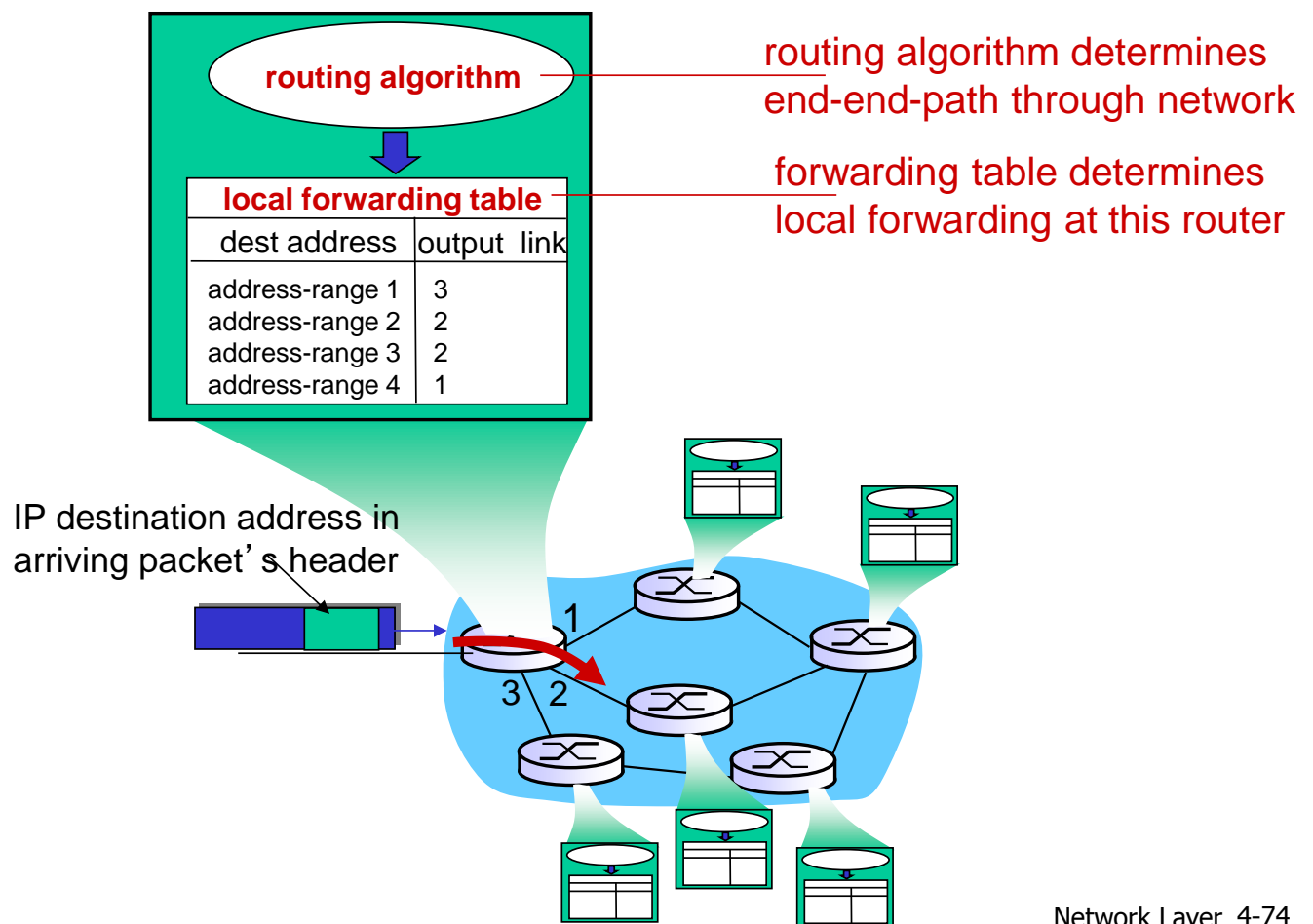
- How is routing/forwarding table established?
- Unfortunately, your textbook has nothing on this.
- Therefore, I resort to 4.5-4.7 of:

Computer networking : a top-down approach, 6th ed., Kurose and Ross

- On 3-hour reserve at DC Library
- You may find the slides to be detailed enough.

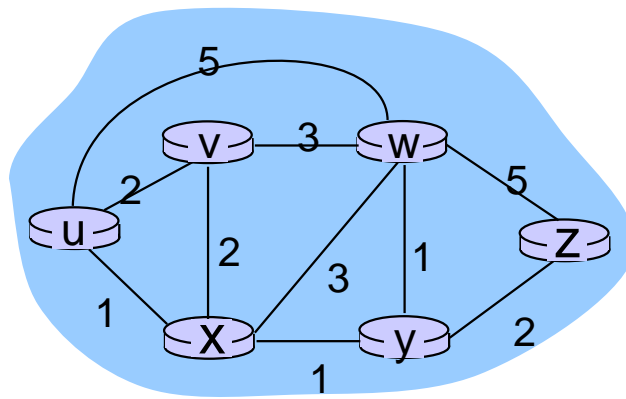
Often manual configuration of routes is not practical (they can be super complicated and dynamic). Thus we get routing protocols. There is nothing in the current textbook for this so you need to look at the older textbook.

Interplay between routing, forwarding



The whole point of a routing protocol is to figure out what the forwarding table should look like. Basically where the packets should go next.

Graph abstraction



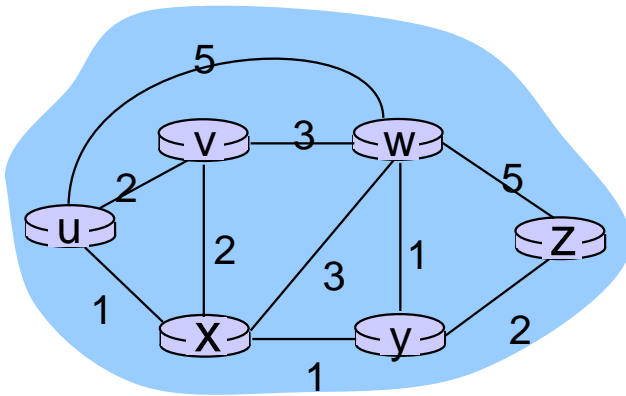
graph: $G = (N, E)$

N = set of routers = $\{ u, v, w, x, y, z \}$

E = set of links = $\{ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) \}$

aside: graph abstraction is useful in other network contexts, e.g., P2P, where N is set of peers and E is set of TCP connections

Graph abstraction: costs



$c(x, x') = \text{cost of link } (x, x')$

e.g., $c(w, z) = 5$

cost could always be 1, or
inversely related to bandwidth,
or inversely related to
congestion

cost of path $(x_1, x_2, x_3, \dots, x_p) = c(x_1, x_2) + c(x_2, x_3) + \dots + c(x_{p-1}, x_p)$

key question: what is the least-cost path between u and z ?

routing algorithm: algorithm that finds that least cost path

We abstract this out to a graph. We have nodes and weighted edges (often the nodes are routers or devices). Often the cost is multidimensional which can make things complicated. We want to try to find the cheapest path through this graph.

Routing algorithm classification

Q: global or decentralized information?

global:

- ❖ all routers have complete topology, link cost info
- ❖ “link state” algorithms

decentralized:

- ❖ router knows physically-connected neighbors, link costs to neighbors
- ❖ iterative process of computation, exchange of info with neighbors
- ❖ “distance vector” algorithms

Q: static or dynamic?

static:

- ❖ routes change slowly over time

dynamic:

- ❖ routes change more quickly
 - periodic update
 - in response to link cost changes

A Link-State Routing Algorithm

Dijkstra's algorithm

- ❖ net topology, link costs known to all nodes
 - accomplished via “link state broadcast”
 - all nodes have same info
- ❖ computes least cost paths from one node (‘source’) to all other nodes
 - gives *forwarding table* for that node
- ❖ iterative: after k iterations, know least cost path to k dest.’s

notation:

- ❖ $c(x,y)$: link cost from node x to y; $= \infty$ if not direct neighbors
- ❖ $D(v)$: current value of cost of path from source to dest. v
- ❖ $p(v)$: predecessor node along path from source to v
- ❖ N' : set of nodes whose least cost path definitively known

Dijkstra's Algorithm

1 **Initialization:**

2 $N' = \{u\}$

3 for all nodes v

4 if v adjacent to u

5 then $D(v) = c(u,v)$

6 else $D(v) = \infty$

7

8 **Loop**

9 find w not in N' such that $D(w)$ is a minimum

10 add w to N'

11 update $D(v)$ for all v adjacent to w and not in N' :

12 **$D(v) = \min(D(v), D(w) + c(w,v))$**

13 /* new cost to v is either old cost to v or known

14 shortest path cost to w plus cost from w to v */

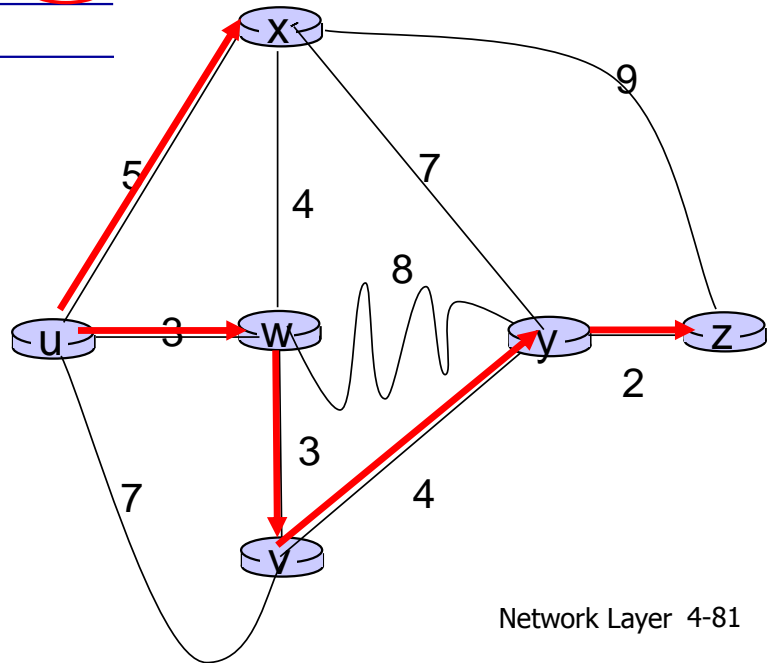
15 **until all nodes in N'**

Dijkstra's algorithm: example

Step	N'	D(v) p(v)	D(w) p(w)	D(x) p(x)	D(y) p(y)	D(z) p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					

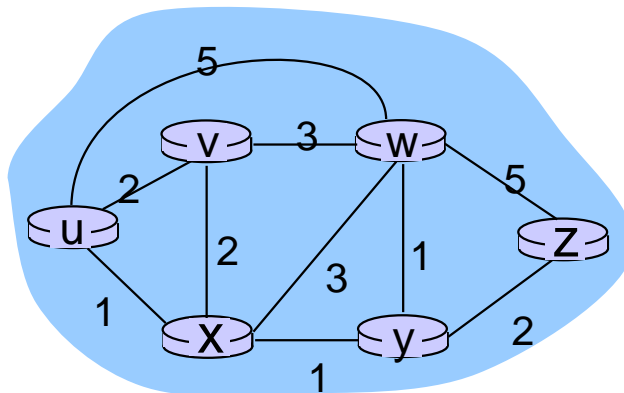
notes:

- ❖ construct shortest path tree by tracing predecessor nodes
- ❖ ties can exist (can be broken arbitrarily)



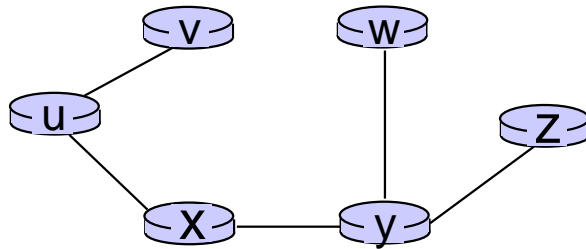
Dijkstra's algorithm: another example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					



Dijkstra's algorithm: example (2)

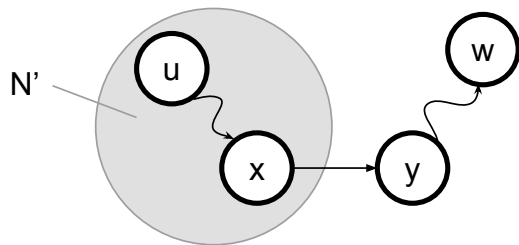
resulting shortest-path tree from u:



resulting forwarding table in u:

destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

Dijkstra's - correctness (Cormen et al.)



- Let $\delta(a)$ denote shortest distance from u to a
- Let w be first vertex added in loop such that:
 $D(w) > \delta(w)$
- A shortest path from u to w can be decomposed into $u \rightsquigarrow x \rightarrow y \rightsquigarrow w$, where $u, x \in N'$ and $y, w \notin N'$

- Because $u \rightsquigarrow w$ is a shortest path, so is $u \rightsquigarrow y$. Therefore, just before we choose w in the loop, $D(y) = \delta(y)$. And $\delta(y) = D(y) \leq \delta(w) < D(w)$.
- But we chose w over y in the loop. So, $\delta(w) < D(w) \leq D(y) = \delta(y)$.
- Contradiction. Therefore, $\delta(w) = D(w) = D(y) = \delta(y)$.

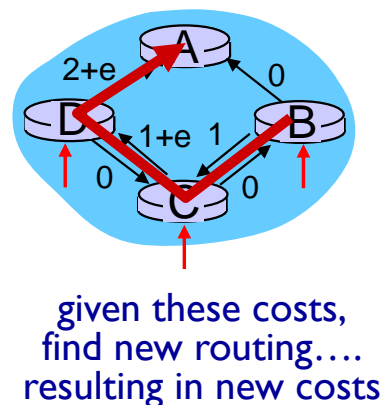
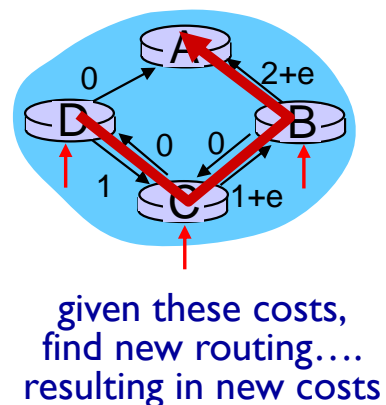
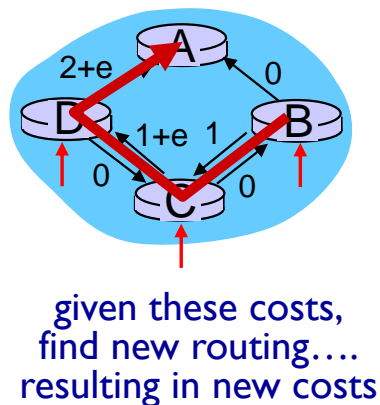
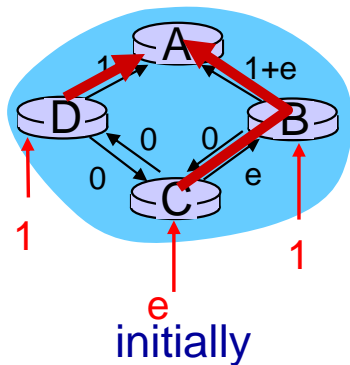
Dijkstra's algorithm, discussion

algorithm complexity: n nodes

- ❖ each iteration: need to check all nodes, w , not in N
- ❖ $n(n+1)/2$ comparisons: $O(n^2)$
- ❖ more efficient implementations possible: $O(n \log n)$

oscillations possible:

- ❖ e.g., support link cost equals amount of carried traffic:



Chapter 4: outline

4.1 introduction

4.2 virtual circuit and datagram networks

4.3 what's inside a router

4.4 IP: Internet Protocol

- datagram format
- IPv4 addressing
- ICMP
- IPv6

4.5 routing algorithms

- link state
- distance vector
- hierarchical routing

4.6 routing in the Internet

- RIP
- OSPF
- BGP

4.7 broadcast and multicast routing

Distance vector algorithm

Bellman-Ford equation (dynamic programming)

let

$d_x(y) :=$ cost of least-cost path from x to y

then

$$d_x(y) = \min_v \{ c(x,v) + d_v(y) \}$$

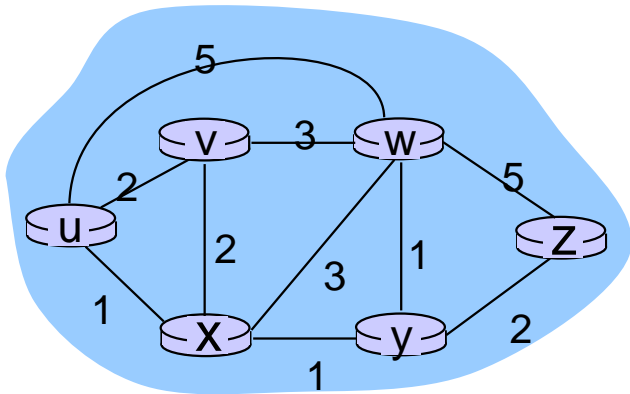
cost from neighbor v to destination y

cost to neighbor v

\min taken over all neighbors v of x

Dijkstra's algorithm shit.

Bellman-Ford example



clearly, $d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$\begin{aligned} d_u(z) &= \min \{ c(u,v) + d_v(z), \\ &\quad c(u,x) + d_x(z), \\ &\quad c(u,w) + d_w(z) \} \\ &= \min \{ 2 + 5, \\ &\quad 1 + 3, \\ &\quad 5 + 3 \} = 4 \end{aligned}$$

node achieving minimum is next
hop in shortest path, used in forwarding table

Distance vector algorithm

- ❖ $D_x(y)$ = estimate of least cost from x to y
 - x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- ❖ node x :
 - knows cost to each neighbor v : $c(x,v)$
 - maintains its neighbors' distance vectors. For each neighbor v , x maintains $\mathbf{D}_v = [D_v(y): y \in N]$

Distance vector algorithm

key idea:

- ❖ from time-to-time, each node sends its own distance vector estimate to neighbors
- ❖ when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v \{c(x,v) + D_v(y)\} \text{ for each node } y \in N$$

- ❖ under minor, natural conditions, the estimate $D_x(y)$ converge to the actual least cost $d_x(y)$

Distance vector algorithm

iterative, asynchronous:

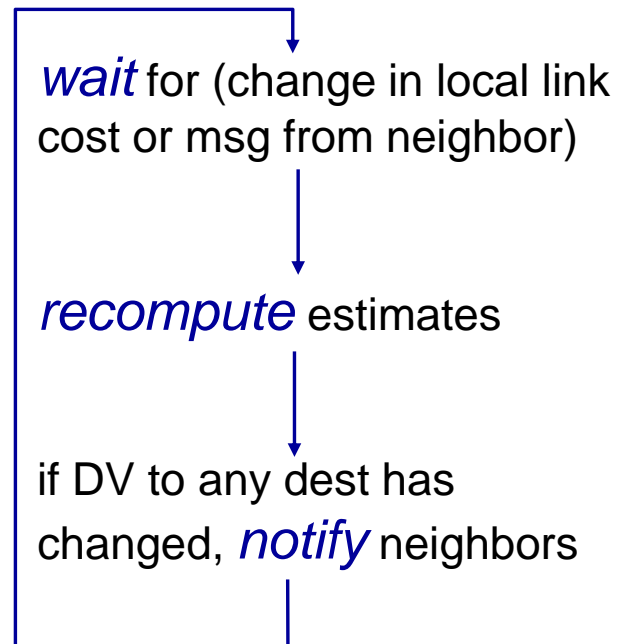
each local iteration
caused by:

- ❖ local link cost change
- ❖ DV update message from neighbor

distributed:

- ❖ each node notifies neighbors *only* when its DV changes
 - neighbors then notify their neighbors if necessary

each node:



$$D_x(y) = \min\{c(x,y) + D_y(y), c(x,z) + D_z(y)\} \\ = \min\{2+0, 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z), c(x,z) + D_z(z)\} \\ = \min\{2+1, 7+0\} = 3$$

**node x
table**

		cost to		
		x	y	z
from	x	0	2	7
	y	∞	∞	∞
	z	∞	∞	∞

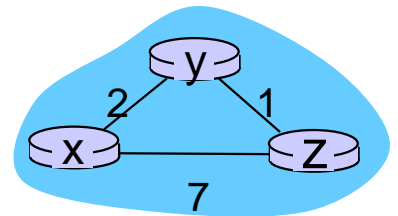
		cost to		
		x	y	z
from	x	0	2	3
	y	2	0	1
	z	7	1	0

**node y
table**

		cost to		
		x	y	z
from	x	∞	∞	∞
	y	2	0	1
	z	∞	∞	∞

**node z
table**

		cost to		
		x	y	z
from	x	∞	∞	∞
	y	∞	∞	∞
	z	7	1	0



time

$$D_x(y) = \min\{c(x,y) + D_y(y), c(x,z) + D_z(y)\} \\ = \min\{2+0, 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z), c(x,z) + D_z(z)\} \\ = \min\{2+1, 7+0\} = 3$$

node x
table

		cost to		
		x	y	z
from	x	0	2	7
	y	∞	∞	∞
	z	∞	∞	∞

node y
table

		cost to		
		x	y	z
from	x	∞	∞	∞
	y	2	0	1
	z	∞	∞	∞

node z
table

		cost to		
		x	y	z
from	x	∞	∞	∞
	y	∞	∞	∞
	z	7	1	0

		cost to		
		x	y	z
from	x	0	2	3
	y	2	0	1
	z	7	1	0

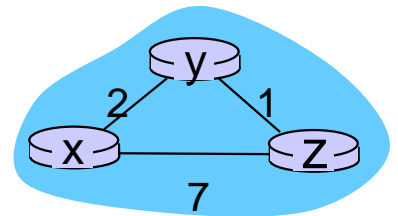
		cost to		
		x	y	z
from	x	0	2	7
	y	2	0	1
	z	7	1	0

		cost to		
		x	y	z
from	x	0	2	7
	y	2	0	1
	z	3	1	0

		cost to		
		x	y	z
from	x	0	2	3
	y	2	0	1
	z	3	1	0

		cost to		
		x	y	z
from	x	0	2	3
	y	2	0	1
	z	3	1	0

		cost to		
		x	y	z
from	x	0	2	3
	y	2	0	1
	z	3	1	0

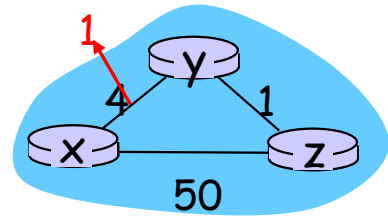


time

Distance vector: link cost changes

link cost changes:

- ❖ node detects local link cost change
- ❖ updates routing info, recalculates distance vector
- ❖ if DV changes, notify neighbors



“good
news
travels
fast”

t_0 : y detects link-cost change, updates its DV, informs its neighbors.

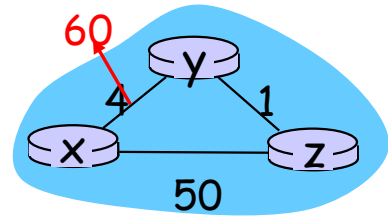
t_1 : z receives update from y , updates its table, computes new least cost to x , sends its neighbors its DV.

t_2 : y receives z 's update, updates its distance table. y 's least costs do *not* change, so y does *not* send a message to z .

Distance vector: link cost changes

link cost changes:

- ❖ node detects local link cost change
- ❖ *bad news travels slow* - “count to infinity” problem!
- ❖ 44 iterations before algorithm stabilizes: see text



poisoned reverse:

- ❖ If Z routes through Y to get to X :
 - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- ❖ will this completely solve count to infinity problem?

We can keep track of distance vector tables that say the total cost of the path to another node and the next hop in the path. These values are calculated using djikstra's algorithm. You keep updating it by adding and taking mins as you go. Basically nodes keep each other in sync by sending their distance tables to each other and if a better path occurs updating to match it.

When the distance between two nodes updates shit gets a bit crazy. Basically the nodes that notices the change will update its table to reflect it. If the path is now shorter it moves very quickly sending it around. If the path increases it moves incredibly slowly. We can get loops because the tables don't all update at the same time so one table can think that one way is the optimal math while a table with fresher data knows that another path is optimal. This results in data moving around a ton.

Counting to infinity Say Y notices the update first. It sees that to get to X costs 60 so it looks for a faster route. Z says that it can get to X with a cost of 5 so Y wants to use Z. Once this is done Y broadcasts its change and Z decides to update. Then Z updates its self. It does the same logic where it sees that Y can reach X with a cost of six so it wants to go through there. Then Z broadcasts it change. This goes back and forth for a while until it gets its shit together.

poisoned reverse: with this Z advertises to Y that it has a cost of infinity to get anywhere. This makes Y go directly to X and broadcasts the update to Z. This puts an infinity to get to Z. Now Z has to update itself. It updates its routing table to now use the direct connects to X and Y (because these are the cheapest known paths). This is how we get around the counting to infinity problem. Poisoned reverse is not always sufficient. He gives a good example for this, see supplementary notes on it. There is going to be a question about this on the exam

Comparison of LS and DV algorithms

message complexity

- ❖ **LS:** with n nodes, E links, $O(nE)$ msgs sent
- ❖ **DV:** exchange between neighbors only
 - convergence time varies

speed of convergence

- ❖ **LS:** $O(n^2)$ algorithm requires $O(nE)$ msgs
 - may have oscillations
- ❖ **DV:** convergence time varies
 - may be routing loops
 - count-to-infinity problem

robustness: what happens if router malfunctions?

LS:

- node can advertise incorrect *link* cost
- each node computes only its own table

DV:

- DV node can advertise incorrect *path* cost
- each node's table used by others
 - error propagate thru network

LOOK THIS UP IN THE TEXTBOOK

Hierarchical routing

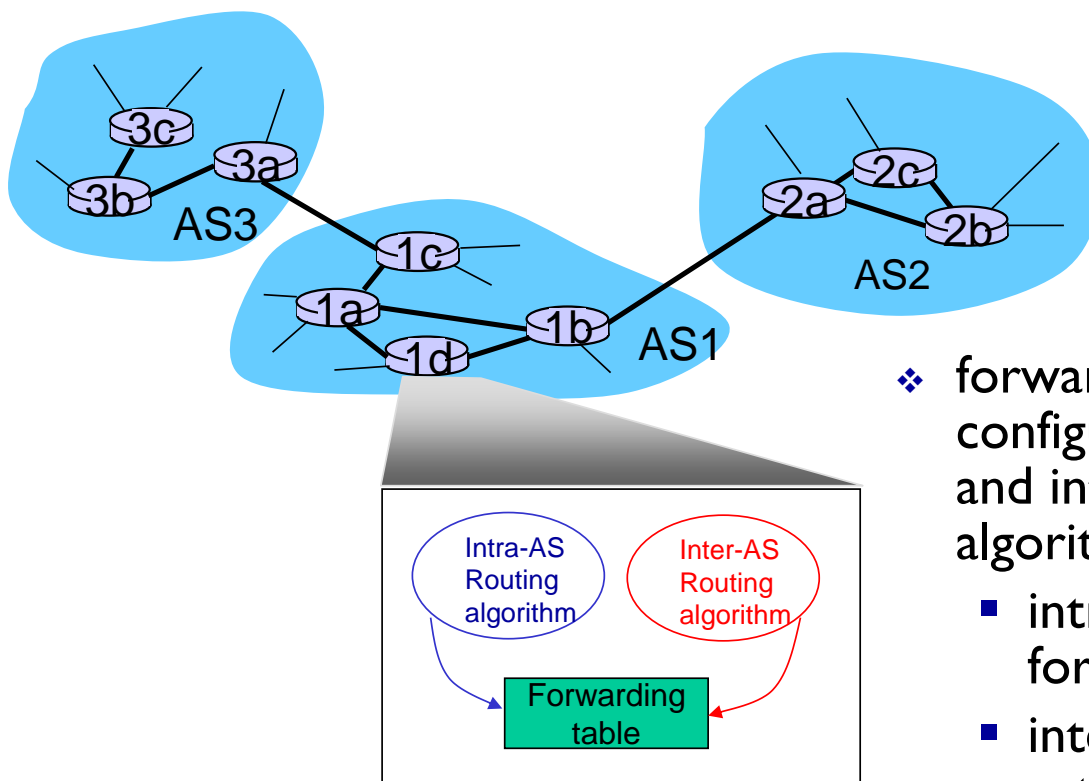
- ❖ aggregate routers into regions, “**autonomous systems**” (AS)
- ❖ routers in same AS run same routing protocol
 - “**intra-AS**” routing protocol
 - routers in different AS can run different intra-AS routing protocol

gateway router:

- ❖ at “edge” of its own AS
- ❖ has link to router in another AS

Every system figures out which routing protocol works for them so a gateway router is needed to talk between them. This allows us to categorize routers by the routing protocol that they follow.

Interconnected ASes



- ❖ forwarding table configured by both intra- and inter-AS routing algorithm
 - intra-AS sets entries for internal dests
 - inter-AS & intra-AS sets entries for external dests

There's an intra routing algorithm and inter and these could be different and are categorized by AS.

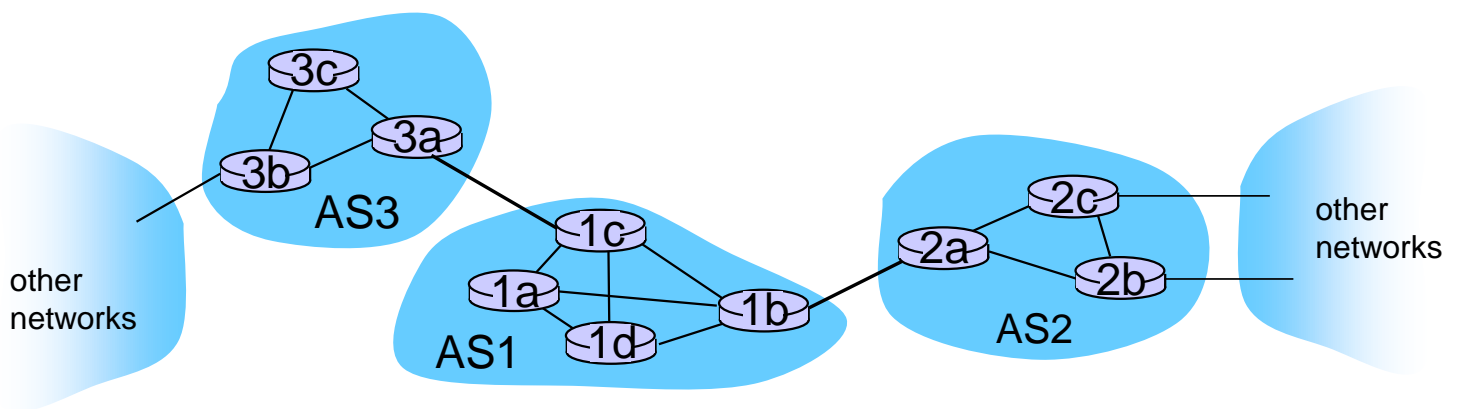
Inter-AS tasks

- ❖ suppose router in AS1 receives datagram destined outside of AS1:
 - router should forward packet to gateway router, but which one?

AS1 must:

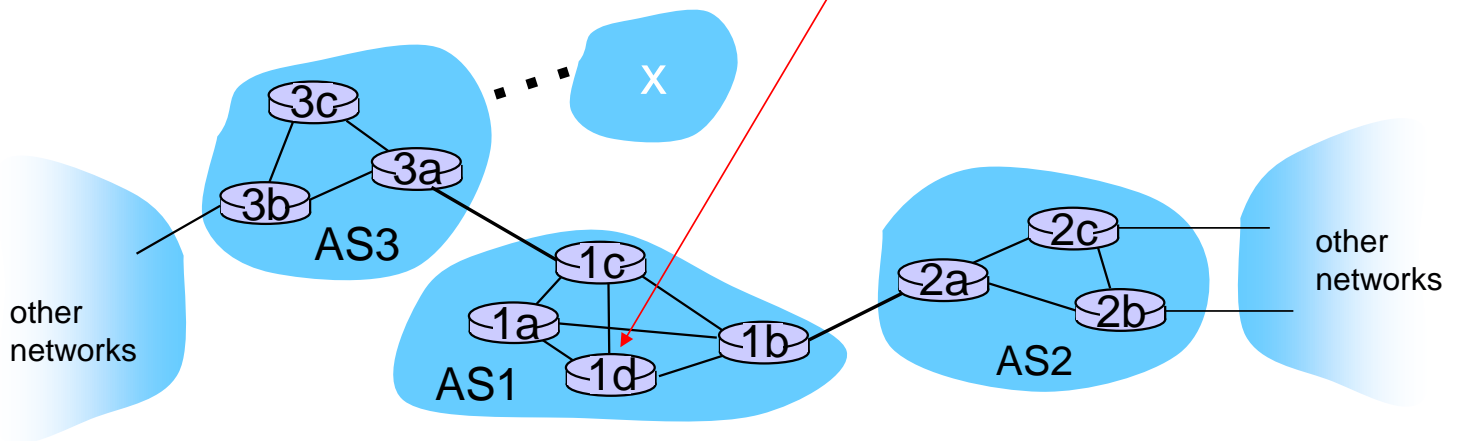
1. learn which destds are reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1

job of inter-AS routing!



Example: setting forwarding table in router 1d

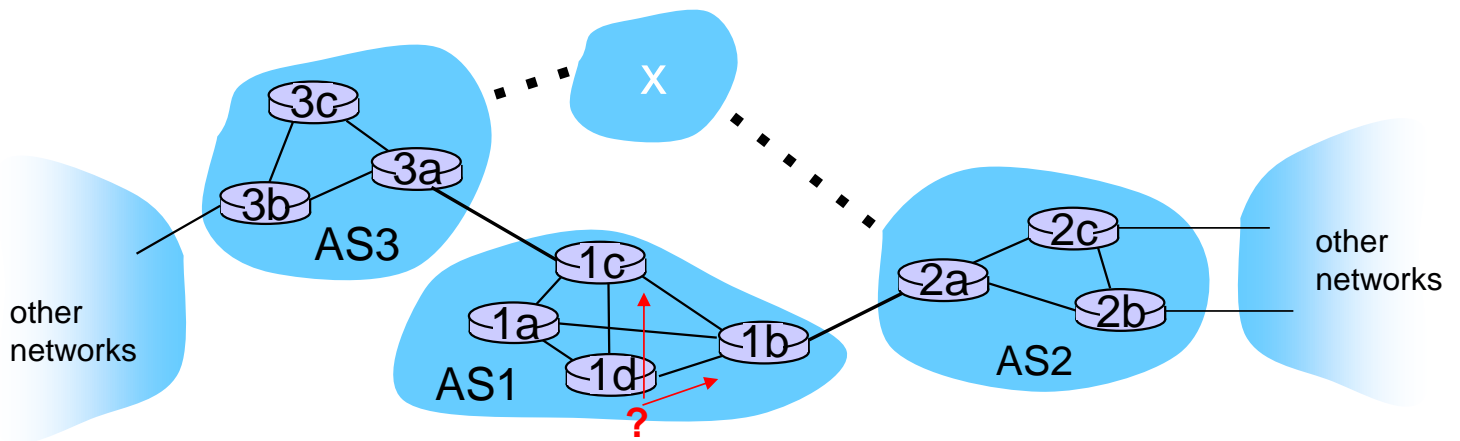
- ❖ suppose AS1 learns (via inter-AS protocol) that subnet **x** reachable via AS3 (gateway 1c), but not via AS2
 - inter-AS protocol propagates reachability info to all internal routers
- ❖ router 1d determines from intra-AS routing info that its interface **1** is on the least cost path to 1c
 - installs forwarding table entry **(x,1)**



Subnet X is reachable by AS3 and not AS2, then the interAS protocol propagates that information to all internal routers. We use intraAS to see that 1B's least cost to 1C is through some interface so it makes an entry for that.

Example: choosing among multiple ASes

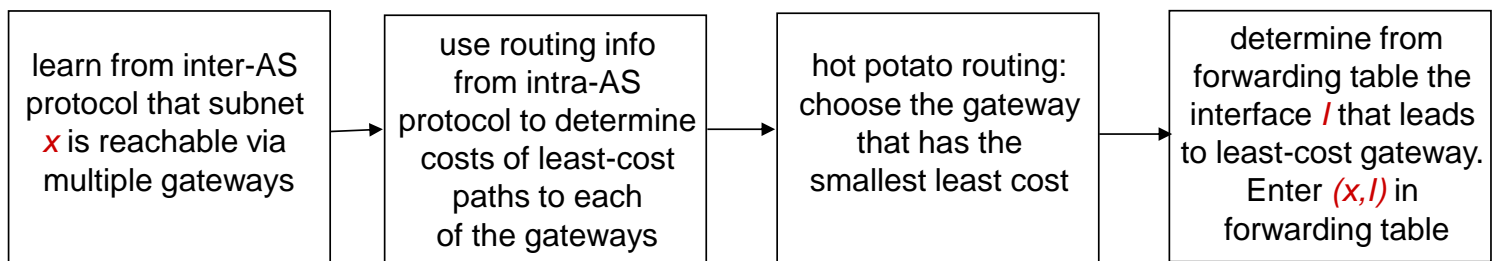
- ❖ now suppose AS1 learns from inter-AS protocol that subnet **x** is reachable from AS3 *and* from AS2.
- ❖ to configure forwarding table, router 1d must determine which gateway it should forward packets towards for dest **x**
 - this is also job of inter-AS routing protocol!



If we now know that X is reachable by AS1, we now have a choice for 1d to figure out the least cost path to get a packet through to X. This is much harder to figure out and done through interAS.

Example: choosing among multiple ASes

- ❖ now suppose AS1 learns from inter-AS protocol that subnet **x** is reachable from AS3 *and* from AS2.
- ❖ to configure forwarding table, router 1d must determine towards which gateway it should forward packets for dest **x**
 - this is also job of inter-AS routing protocol!
- ❖ *hot potato routing: send* packet towards closest of two routers.

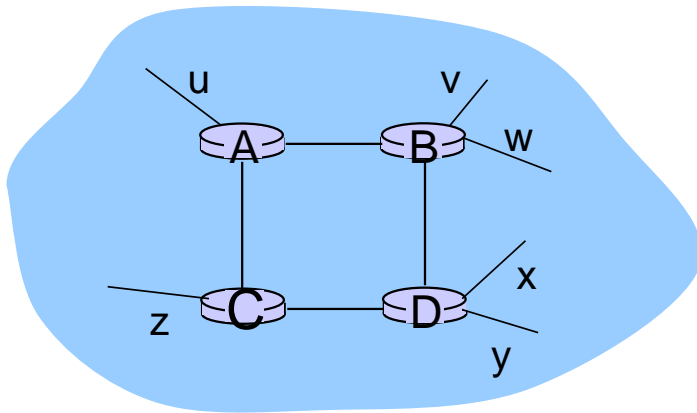


Intra-AS Routing

- ❖ also known as *interior gateway protocols (IGP)*
- ❖ most common intra-AS routing protocols:
 - RIP: Routing Information Protocol
 - OSPF: Open Shortest Path First
 - IGRP: Interior Gateway Routing Protocol (Cisco proprietary)

RIP (Routing Information Protocol)

- ❖ included in BSD-UNIX distribution in 1982
- ❖ distance vector algorithm
 - distance metric: # hops (max = 15 hops), each link has cost 1
 - DVs exchanged with neighbors every 30 sec in response message (aka **advertisement**)
 - each advertisement: list of up to 25 destination **subnets** (in IP addressing sense)

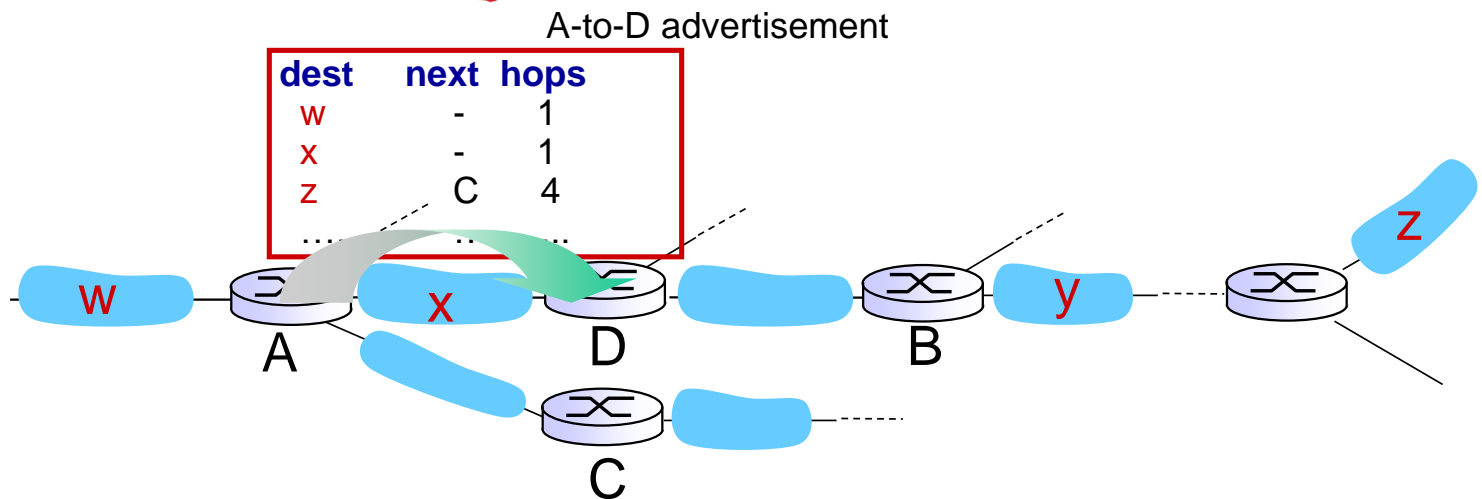


from router A to destination **subnets**:

<u>subnet</u>	<u>hops</u>
u	1
v	2
w	2
x	3
y	3
z	2

Interesting to note that we count a hop from an internal port to external (so the hop to u is one).

RIP: example



routing table in router D

destination subnet	next router	# hops to dest
W	A	2
y	B	2
Z	B A	7 5
X	--	1
....

In this example if we wanted to have the route from internal to external to be 0 we would have the distance from D to W to be equal to 0 which is clearly not true. This is why we make that cost equal to 1.

RIP: link failure, recovery

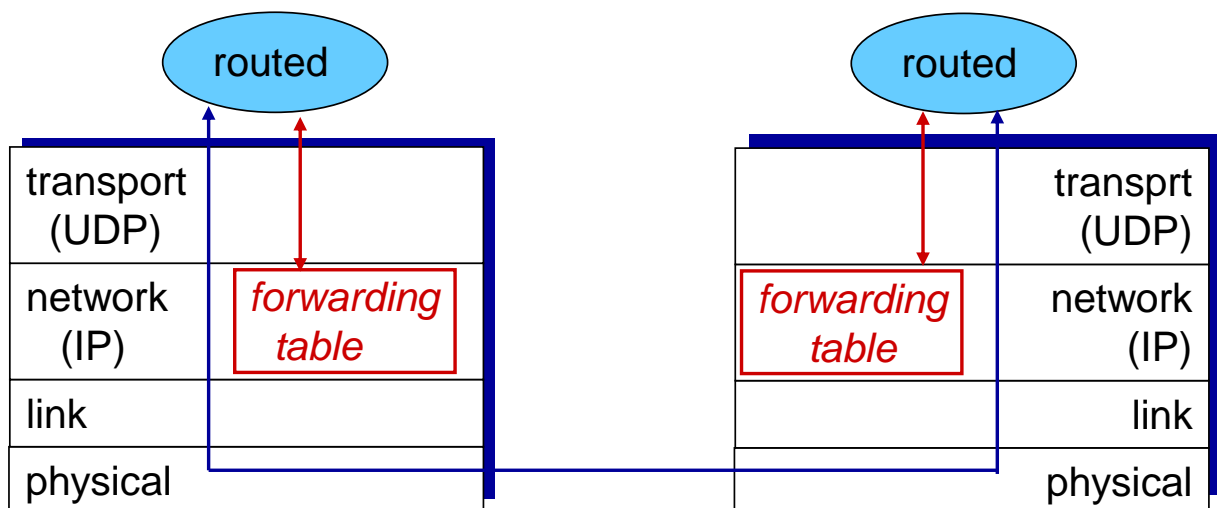
if no advertisement heard after 180 sec -->
neighbor/link declared dead

- routes via neighbor invalidated
- new advertisements sent to neighbors
- neighbors in turn send out new advertisements (if tables changed)
- link failure info quickly (?) propagates to entire net
- *poison reverse* used to prevent ping-pong loops (infinite distance = 16 hops)

If we haven't heard an advertisement in a while we will deem the node dead. Usually the time span is about 3 minutes.

RIP table processing

- ❖ RIP routing tables managed by *application-level* process called route-d (daemon)
- ❖ advertisements sent in UDP packets, periodically repeated



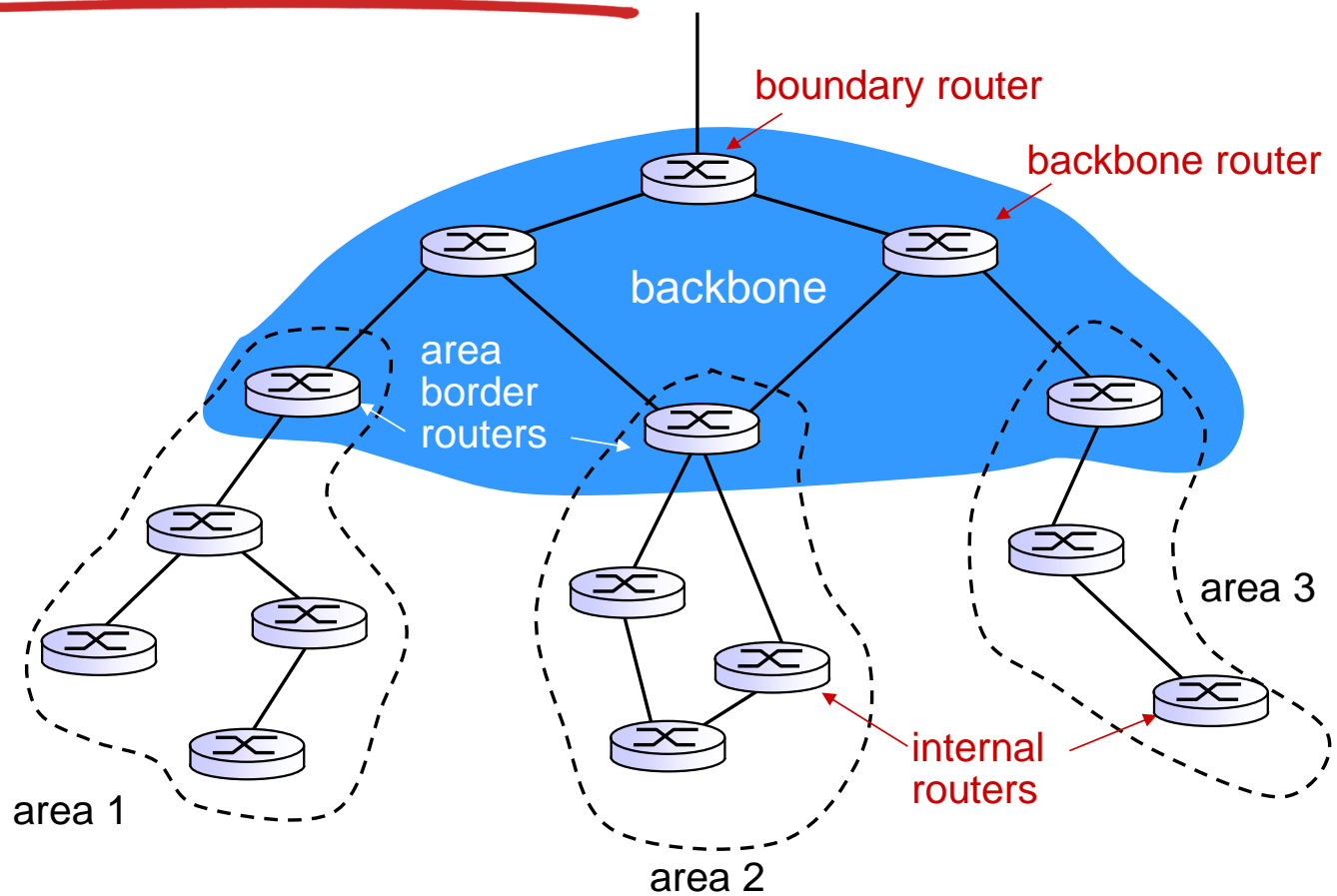
OSPF (Open Shortest Path First)

- ❖ “open”: publicly available
- ❖ uses link state algorithm
 - LS packet dissemination
 - topology map at each node
 - route computation using Dijkstra’s algorithm
- ❖ OSPF advertisement carries one entry per neighbor
- ❖ advertisements flooded to *entire* AS
 - carried in OSPF messages directly over IP (rather than TCP or UDP)
- ❖ *IS-IS routing* protocol: nearly identical to OSPF

OSPF “advanced” features (not in RIP)

- ❖ **security**: all OSPF messages authenticated (to prevent malicious intrusion)
- ❖ **multiple** same-cost **paths** allowed (only one path in RIP)
- ❖ for each link, multiple cost metrics for different **TOS** (e.g., satellite link cost set “low” for best effort ToS; high for real time ToS)
- ❖ integrated uni- and **multicast** support:
 - Multicast OSPF (MOSPF) uses same topology data base as OSPF
- ❖ **hierarchical** OSPF in large domains.

Hierarchical OSPF



Hierarchical OSPF

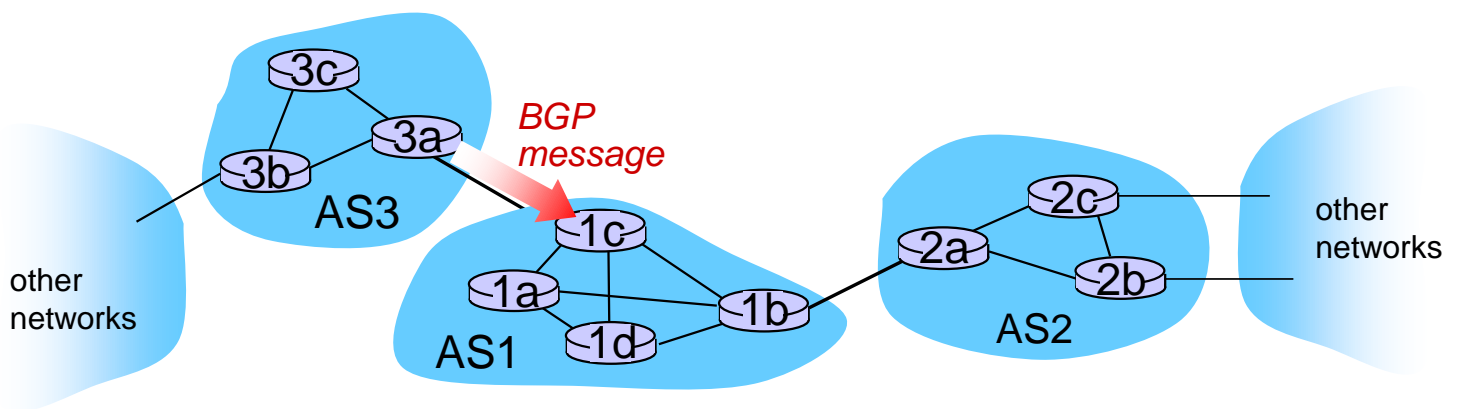
- ❖ *two-level hierarchy*: local area, backbone.
 - link-state advertisements only in area
 - each nodes has detailed area topology; only know direction (shortest path) to nets in other areas.
- ❖ *area border routers*: “summarize” distances to nets in own area, advertise to other Area Border routers.
- ❖ *backbone routers*: run OSPF routing limited to backbone.
- ❖ *boundary routers*: connect to other AS' s.

Internet inter-AS routing: BGP

- ❖ **BGP (Border Gateway Protocol):** *the de facto* inter-domain routing protocol
 - “glue that holds the Internet together”
- ❖ BGP provides each AS a means to:
 - **eBGP:** obtain subnet reachability information from neighboring ASs.
 - **iBGP:** propagate reachability information to all AS-internal routers.
 - determine “good” routes to other networks based on reachability information and policy.
- ❖ allows subnet to advertise its existence to rest of Internet: “*I am here*”

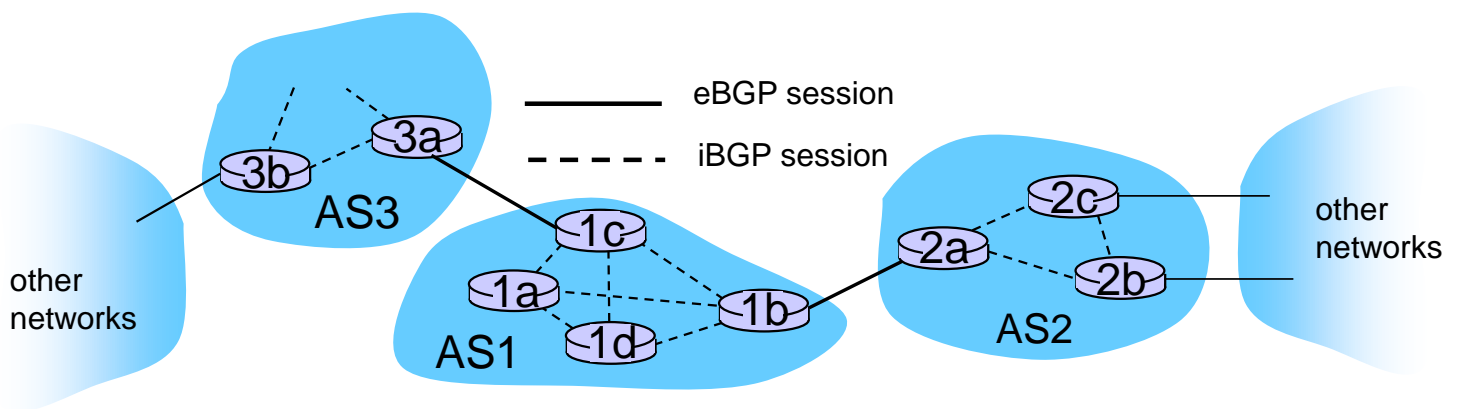
BGP basics

- ❖ **BGP session:** two BGP routers (“peers”) exchange BGP messages:
 - advertising *paths* to different destination network prefixes (“path vector” protocol)
 - exchanged over semi-permanent TCP connections
- ❖ when AS3 advertises a prefix to AS1:
 - AS3 *promises* it will forward datagrams towards that prefix
 - AS3 can aggregate prefixes in its advertisement



BGP basics: distributing path information

- ❖ using eBGP session between 3a and 1c, AS3 sends prefix reachability info to AS1.
 - 1c can then use iBGP to distribute new prefix info to all routers in AS1
 - 1b can then re-advertise new reachability info to AS2 over 1b-to-2a eBGP session
- ❖ when router learns of new prefix, it creates entry for prefix in its forwarding table.



Path attributes and BGP routes

- ❖ advertised prefix includes BGP attributes
 - prefix + attributes = “route”
- ❖ two important attributes:
 - **AS-PATH**: contains ASs through which prefix advertisement has passed: e.g., AS 67, AS 17
 - **NEXT-HOP**: indicates specific internal-AS router to next-hop AS. (may be multiple links from current AS to next-hop-AS)
- ❖ gateway router receiving route advertisement uses **import policy** to accept/decline
 - e.g., never route through AS x
 - *policy-based* routing

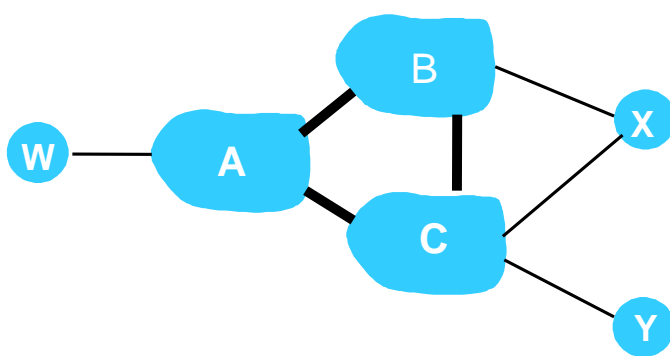
BGP route selection



- ❖ router may learn about more than 1 route to destination AS, selects route based on:
 1. local preference value attribute: policy decision
 2. shortest AS-PATH
 3. closest NEXT-HOP router: hot potato routing
 4. additional criteria

BGP messages

- ❖ BGP messages exchanged between peers over TCP connection
- ❖ BGP messages:
 - **OPEN:** opens TCP connection to peer and authenticates sender
 - **UPDATE:** advertises new path (or withdraws old)
 - **KEEPALIVE:** keeps connection alive in absence of UPDATES; also ACKs OPEN request
 - **NOTIFICATION:** reports errors in previous msg; also used to close connection

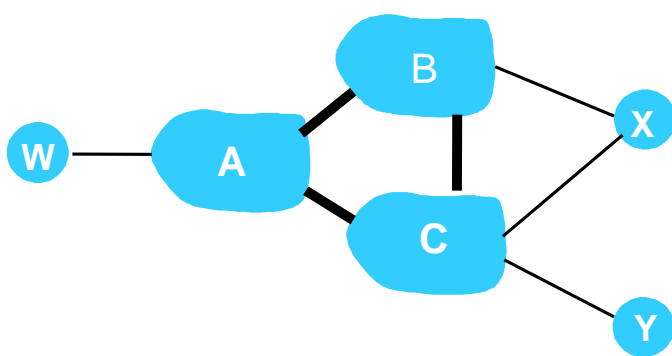
BGP routing policy





legend:  provider network
 customer network:

- ❖ A,B,C are *provider networks*
- ❖ X,W,Y are customer (of provider networks)
- ❖ X is *dual-homed*: attached to two networks
 - X does not want to route from B via X to C
 - .. so X will not advertise to B a route to C

BGP routing policy (2)



legend:  provider network
 customer network:

- ❖ A advertises path AW to B
- ❖ B advertises path BAW to X
- ❖ Should B advertise path BAW to C?
 - No way! B gets no “revenue” for routing CBAW since neither W nor C are B’s customers
 - B wants to force C to route to w via A
 - B wants to route *only* to/from its customers!

Why different Intra-, Inter-AS routing ?

policy:

- ❖ inter-AS: admin wants control over how its traffic routed, who routes through its net.
- ❖ intra-AS: single admin, so no policy decisions needed

scale:

- ❖ hierarchical routing saves table size, reduced update traffic

performance:

- ❖ intra-AS: can focus on performance
- ❖ inter-AS: policy may dominate over performance

Chapter 4: outline

4.1 introduction

4.2 virtual circuit and datagram networks

4.3 what's inside a router

4.4 IP: Internet Protocol

- datagram format
- IPv4 addressing
- ICMP
- IPv6

4.5 routing algorithms

- link state
- distance vector
- hierarchical routing

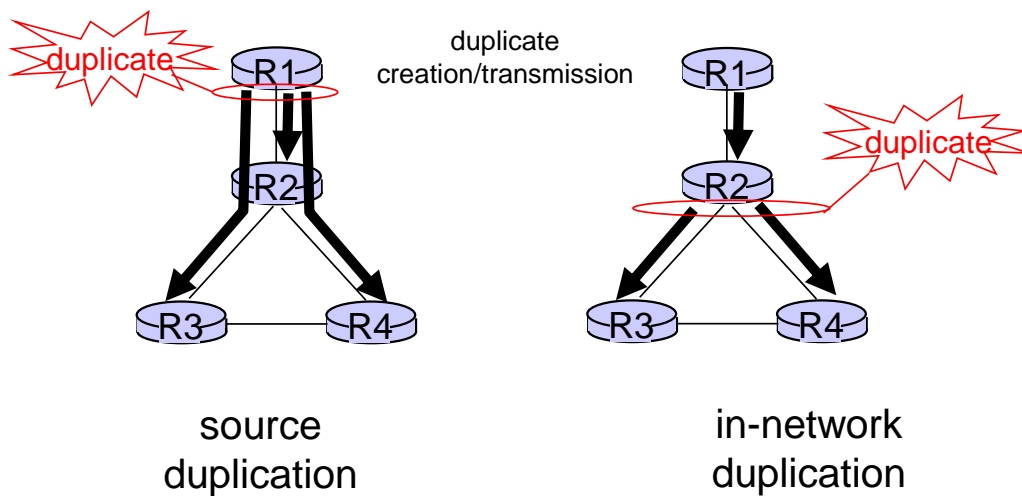
4.6 routing in the Internet

- RIP
- OSPF
- BGP

4.7 broadcast and multicast routing

Broadcast routing

- ❖ deliver packets from source to all other nodes
- ❖ source duplication is inefficient:



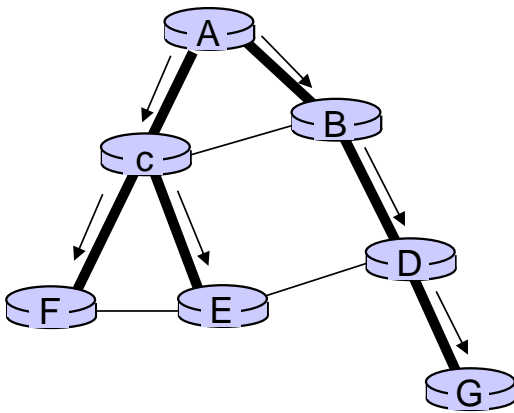
- ❖ source duplication: how does source determine recipient addresses?

In-network duplication

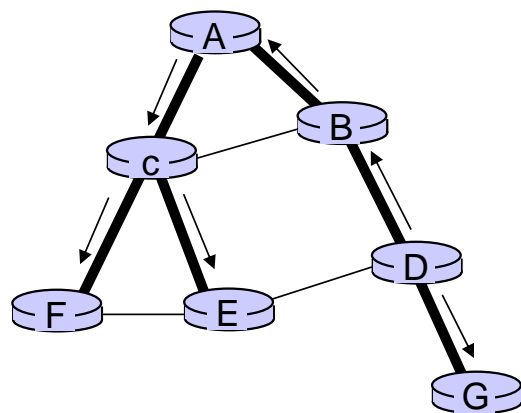
- ❖ *flooding*: when node receives broadcast packet, sends copy to all neighbors
 - problems: cycles & broadcast storm
- ❖ *controlled flooding*: node only broadcasts pkt if it hasn't broadcast same packet before
 - node keeps track of packet ids already broadcasted
 - or reverse path forwarding (RPF): only forward packet if it arrived on shortest path between node and source
- ❖ *spanning tree*:
 - no redundant packets received by any node

Spanning tree

- ❖ first construct a spanning tree
- ❖ nodes then forward/make copies only along spanning tree



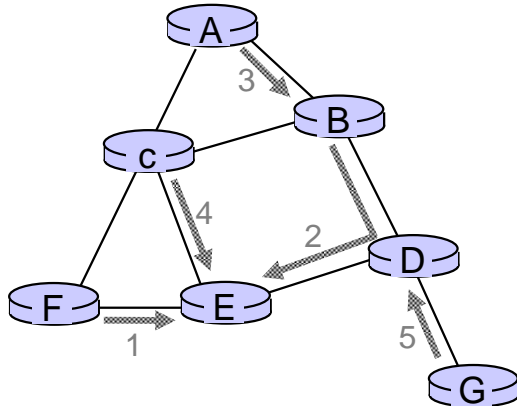
(a) broadcast initiated at A



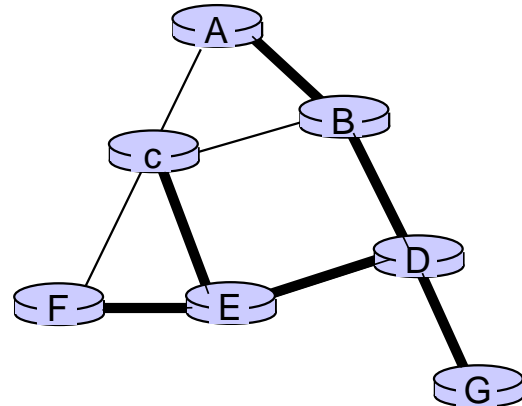
(b) broadcast initiated at D

Spanning tree: creation

- ❖ center node
- ❖ each node sends unicast join message to center node
 - message forwarded until it arrives at a node already belonging to spanning tree



(a) stepwise construction of spanning tree (center: E)



(b) constructed spanning tree

Multicast routing: problem statement

goal: find a tree (or trees) connecting routers having local mcast group members

- ❖ **tree:** not all paths between routers used
- ❖ **shared-tree:** same tree used by all group members
- ❖ **source-based:** different tree from each sender to rcvrs

legend



group member



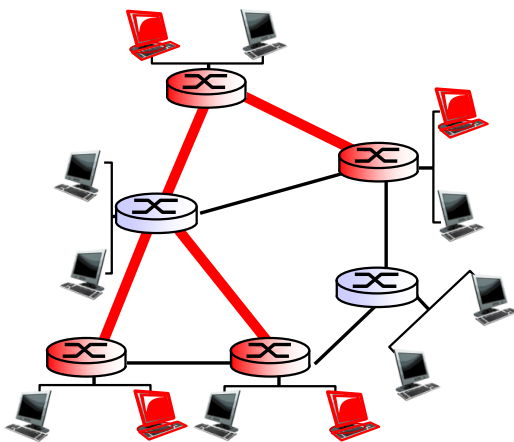
not group member



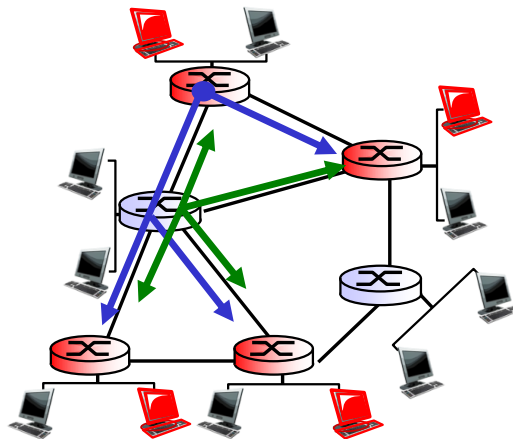
router with a group member



router without group member



shared tree



source-based trees

Approaches for building mcast trees

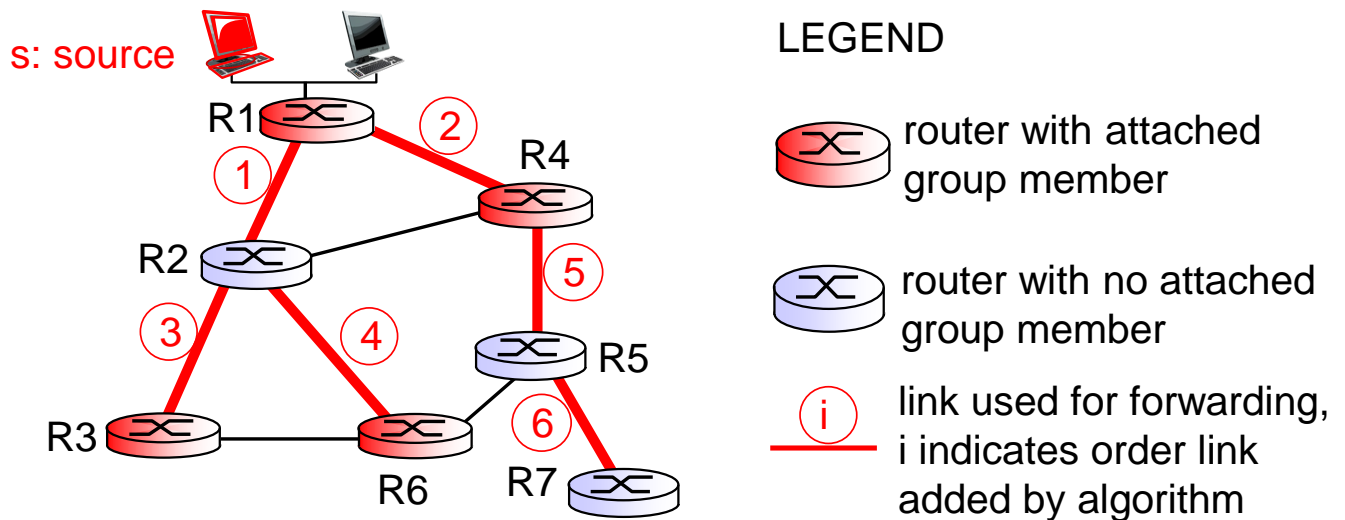
approaches:

- ❖ *source-based tree*: one tree per source
 - shortest path trees
 - reverse path forwarding
- ❖ *group-shared tree*: group uses one tree
 - minimal spanning (Steiner)
 - center-based trees

...we first look at basic approaches, then specific protocols adopting these approaches

Shortest path tree

- ❖ mcast forwarding tree: tree of shortest path routes from source to all receivers
 - Dijkstra's algorithm

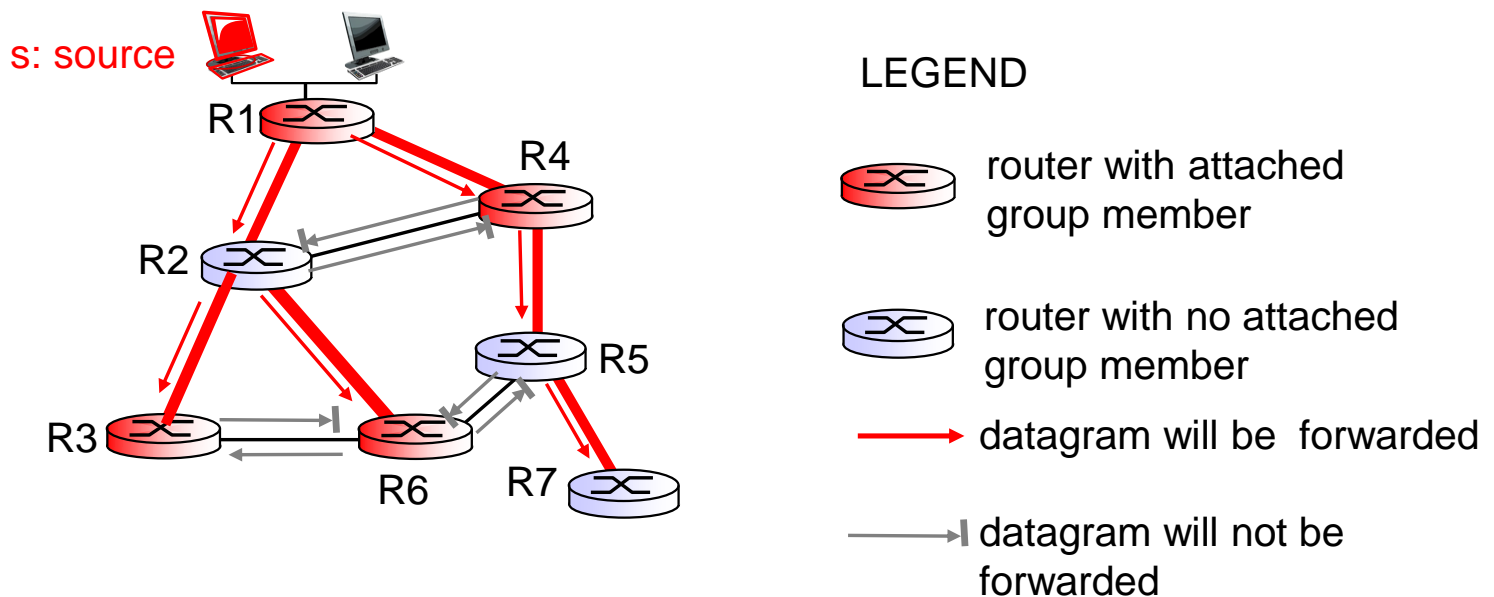


Reverse path forwarding

- ❖ rely on router's knowledge of unicast shortest path from it to sender
- ❖ each router has simple forwarding behavior:

if (mcast datagram received on incoming link on shortest path back to center)
then flood datagram onto all outgoing links
else ignore datagram

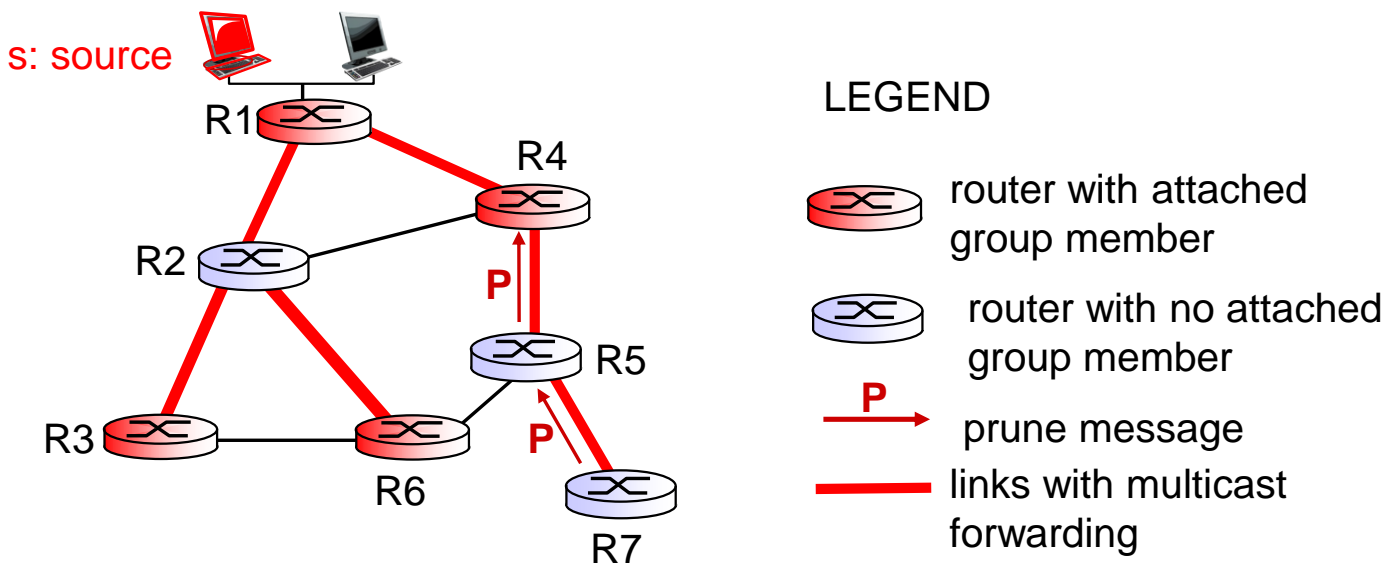
Reverse path forwarding: example



- ❖ result is a source-specific *reverse* SPT
 - may be a bad choice with asymmetric links

Reverse path forwarding: pruning

- ❖ forwarding tree contains subtrees with no mcast group members
 - no need to forward datagrams down subtree
 - “prune” msgs sent upstream by router with no downstream group members



Shared-tree: steiner tree

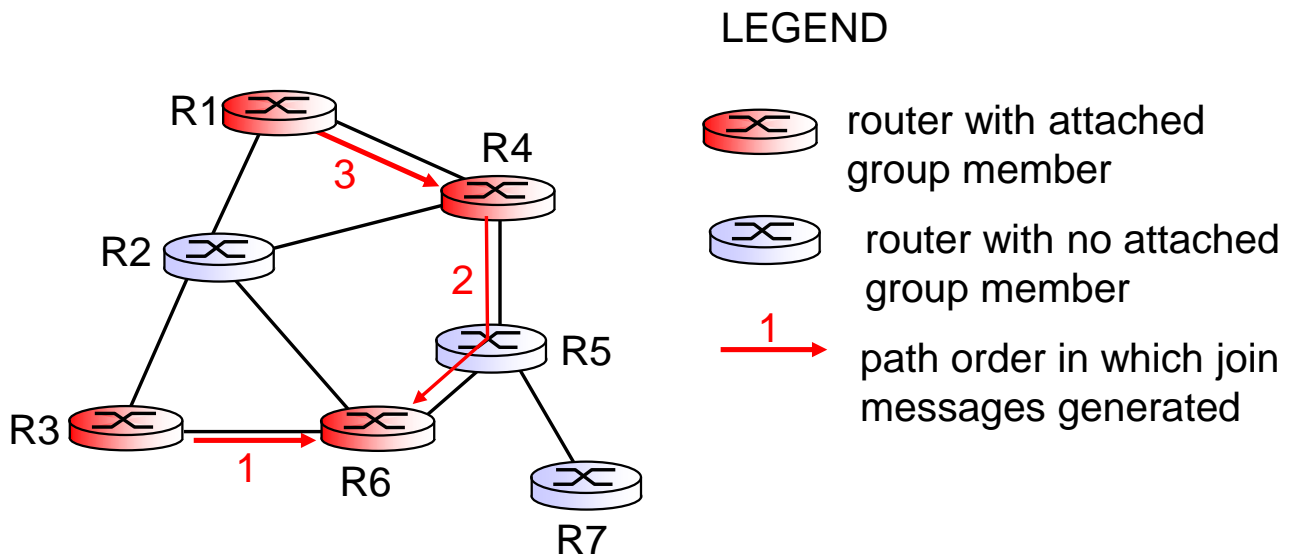
- ❖ *steiner tree*: minimum cost tree connecting all routers with attached group members
- ❖ problem is NP-complete
- ❖ excellent heuristics exists
- ❖ not used in practice:
 - computational complexity
 - information about entire network needed
 - monolithic: rerun whenever a router needs to join/leave

Center-based trees

- ❖ single delivery tree shared by all
- ❖ one router identified as “*center*” of tree
- ❖ to join:
 - edge router sends unicast *join-msg* addressed to center router
 - *join-msg* “processed” by intermediate routers and forwarded towards center
 - *join-msg* either hits existing tree branch for this center, or arrives at center
 - path taken by *join-msg* becomes new branch of tree for this router

Center-based trees: example

suppose R6 chosen as center:



Internet Multicasting Routing: DVMRP

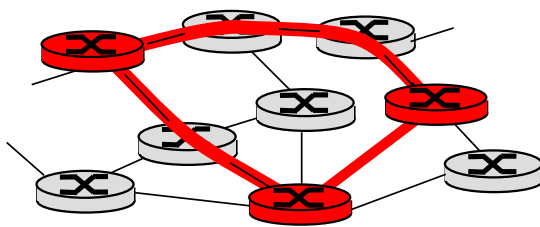
- ❖ **DVMRP**: distance vector multicast routing protocol, RFC1075
- ❖ *flood and prune*: reverse path forwarding, source-based tree
 - RPF tree based on DVMRP's own routing tables constructed by communicating DVMRP routers
 - no assumptions about underlying unicast
 - initial datagram to mcast group flooded everywhere via RPF
 - routers not wanting group: send upstream prune msgs

DVMRP: continued...

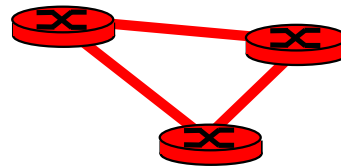
- ❖ *soft state*: DVMRP router periodically (1 min.) “forgets” branches are pruned:
 - mcast data again flows down unpruned branch
 - downstream router: reprune or else continue to receive data
- ❖ routers can quickly regraft to tree
 - following IGMP join at leaf
- ❖ odds and ends
 - commonly implemented in commercial router

Tunneling

Q: how to connect “islands” of multicast routers in a “sea” of unicast routers?



physical topology



logical topology

- ❖ mcast datagram encapsulated inside “normal” (non-multicast-addressed) datagram
- ❖ normal IP datagram sent thru “tunnel” via regular IP unicast to receiving mcast router (recall IPv6 inside IPv4 tunneling)
- ❖ receiving mcast router unencapsulates to get mcast datagram

PIM: Protocol Independent Multicast

- ❖ not dependent on any specific underlying unicast routing algorithm (works with all)
- ❖ two different multicast distribution scenarios :

dense:

- ❖ group members densely packed, in “close” proximity.
- ❖ bandwidth more plentiful

sparse:

- ❖ # networks with group members small wrt # interconnected networks
- ❖ group members “widely dispersed”
- ❖ bandwidth not plentiful

Consequences of sparse-dense dichotomy:

dense

- ❖ group membership by routers *assumed* until routers explicitly prune
- ❖ *data-driven* construction on mcast tree (e.g., RPF)
- ❖ bandwidth and non-group-router processing *profligate*

sparse:

- ❖ no membership until routers explicitly join
- ❖ *receiver-driven* construction of mcast tree (e.g., center-based)
- ❖ bandwidth and non-group-router processing *conservative*

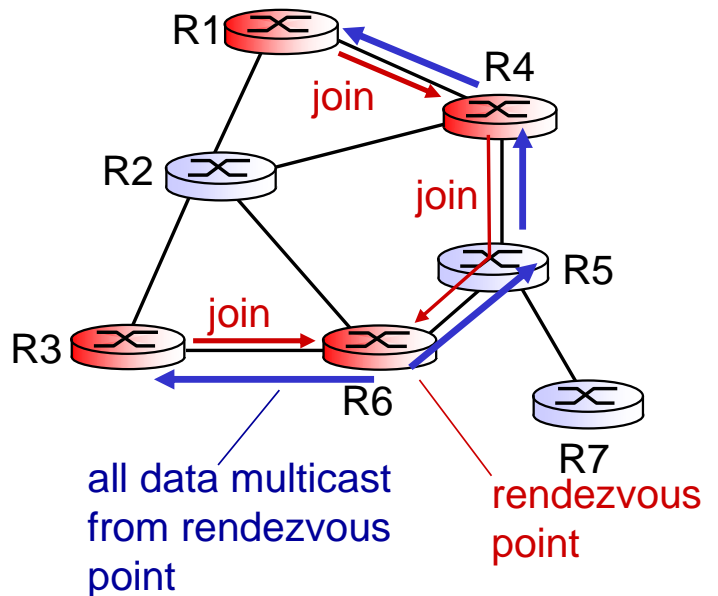
PIM- dense mode

flood-and-prune RPF: similar to DVMRP but...

- ❖ underlying unicast protocol provides RPF info for incoming datagram
- ❖ less complicated (less efficient) downstream flood than DVMRP reduces reliance on underlying routing algorithm
- ❖ has protocol mechanism for router to detect it is a leaf-node router

PIM - sparse mode

- ❖ center-based approach
- ❖ router sends *join* msg to rendezvous point (RP)
 - intermediate routers update state and forward *join*
- ❖ after joining via RP, router can switch to source-specific tree
 - increased performance: less concentration, shorter paths



PIM - sparse mode

sender(s):

- ❖ unicast data to RP, which distributes down RP-rooted tree
- ❖ RP can extend mcast tree upstream to source
- ❖ RP can send *stop* msg if no attached receivers
 - “no one is listening!”

