

Mini-project group 17 (Computer vision/analysis chessboard)

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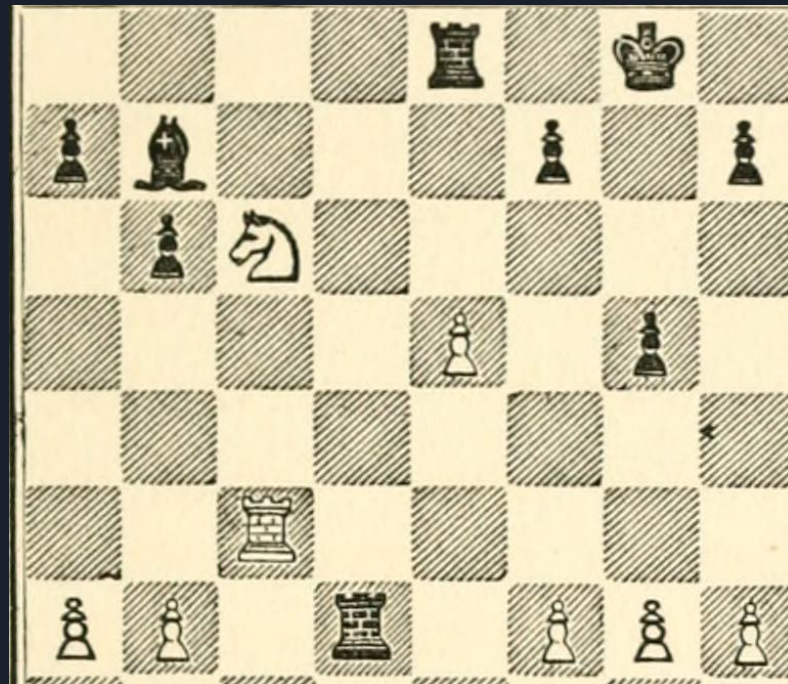
Intro

Computer Vision Chessboard

- Help people recognise stronger positions
- People can upload a picture of the chessboard and the program will suggest the best move

Goals and visions

- Calculate a score for the given board state
- Find the best possible move for the given board state

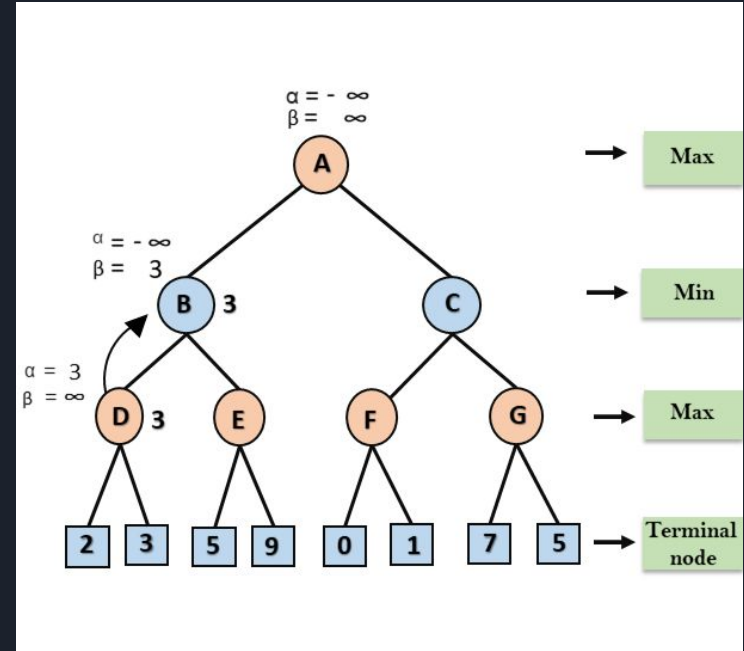




Demo

Board Analysis

- Boardstate analysis based on python chess
- Alpha Beta pruning with reordering based on capturing
- Board evaluation based on quality of pieces on the board



<https://www.javatpoint.com/ai-alpha-beta-pruning>



Computer Vision

1. Chess Pieces Classification
2. Chess Location Detection

Deep learning

Using YOLO(You Only Look Once) v8
to Train the model

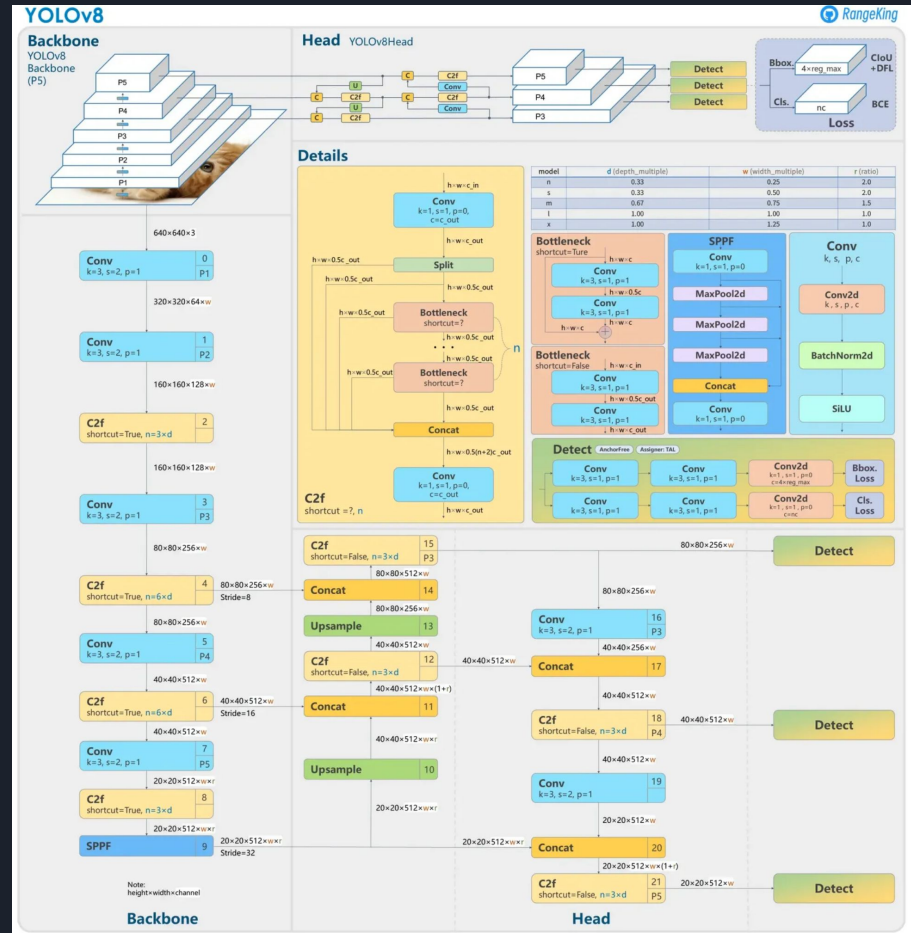
YOLO is based on CNN

Mean layers:

Conv2D layers

Batch Normalization layer

Max Pooling Layers



Data Sets

The Roboflow logo, featuring the word "roboflow" in white lowercase letters on a purple rectangular background.

roboflow

Raw data set only contain 289 pictures

Train
202

Valid
58

Test
29

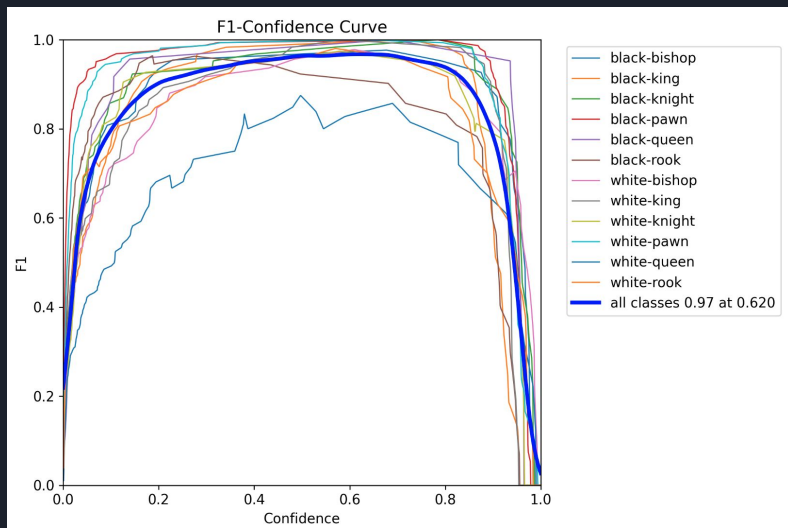




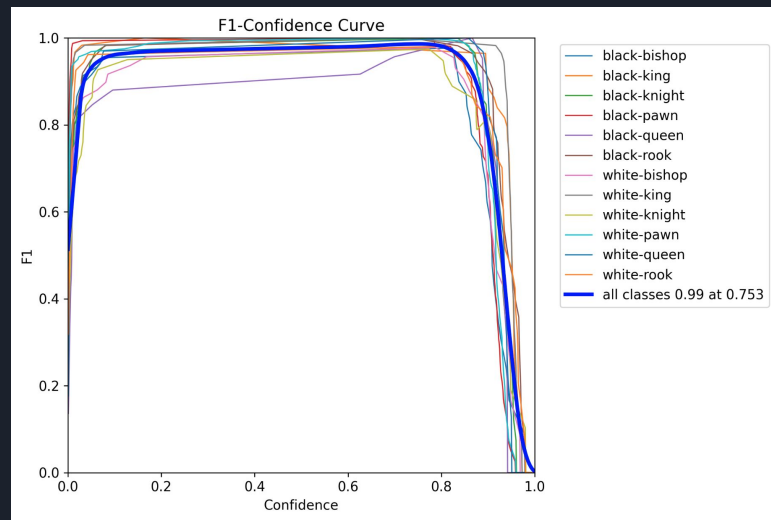
Data Augmenting

```
hsv_h: 0.015
hsv_s: 0.7
hsv_v: 0.4
degrees: 0.4
translate: 0.1
scale: 0.5
shear: 0.0
perspective: 0.0
flipud: 0.0
fliplr: 0.5
bgr: 0.0
mosaic: 1.0
```


Training Result



F1 Score After 10 epoch

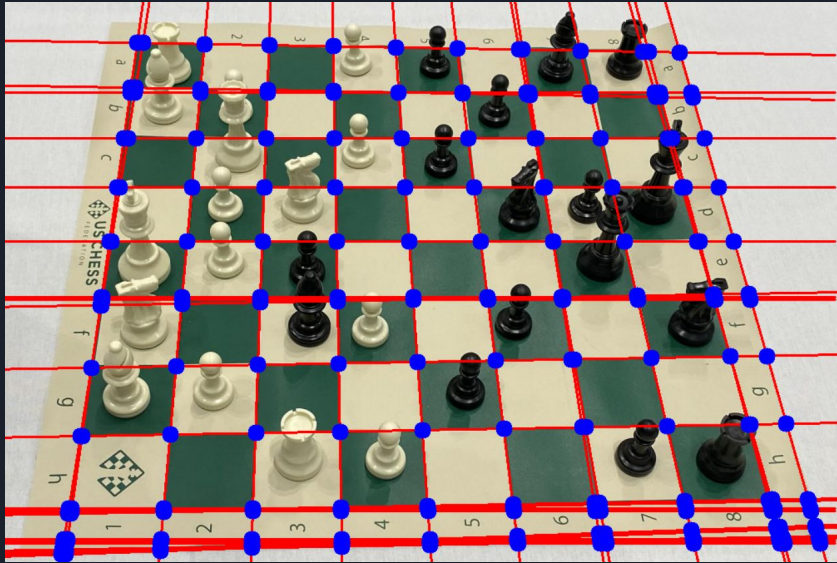


F1 Score After 50 epoch



Chess Pieces Location Detection

Chess Square Detection



1. Use Hough Transform to detect lines
2. Initialize corner list
3. For each pair of detected lines:
 - Calculate and validate intersections as corners
 - Draw corners on image for visualization

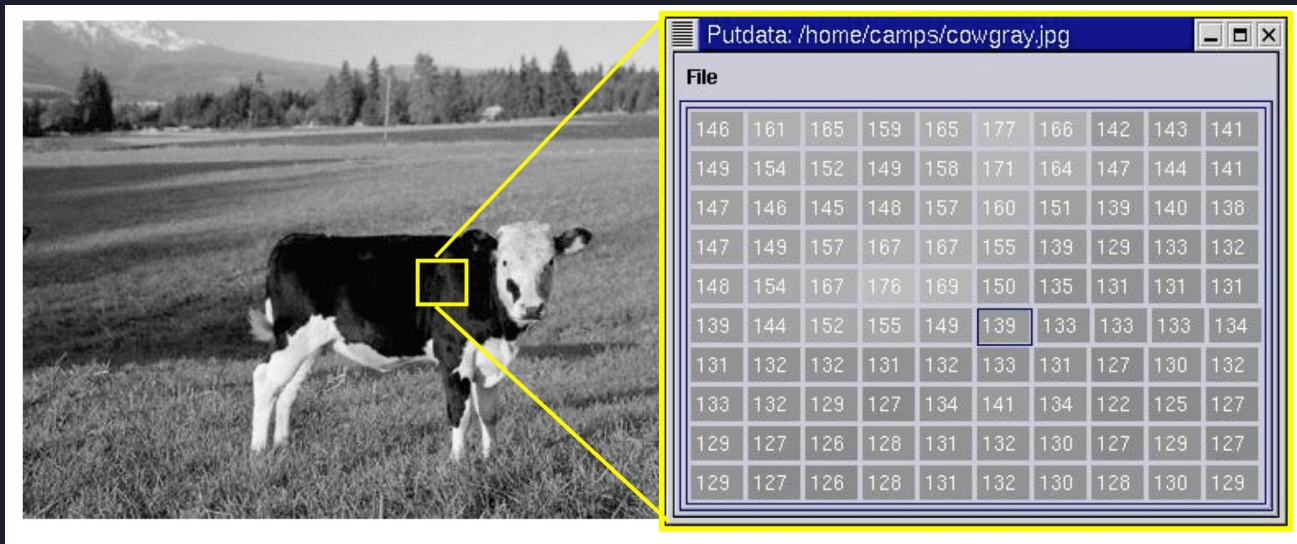


Hough Transform

- Shape Detection Algorithm(Detecting Line)
 - Edge Detection -----> Line Detection
 - Canny Edge Detection

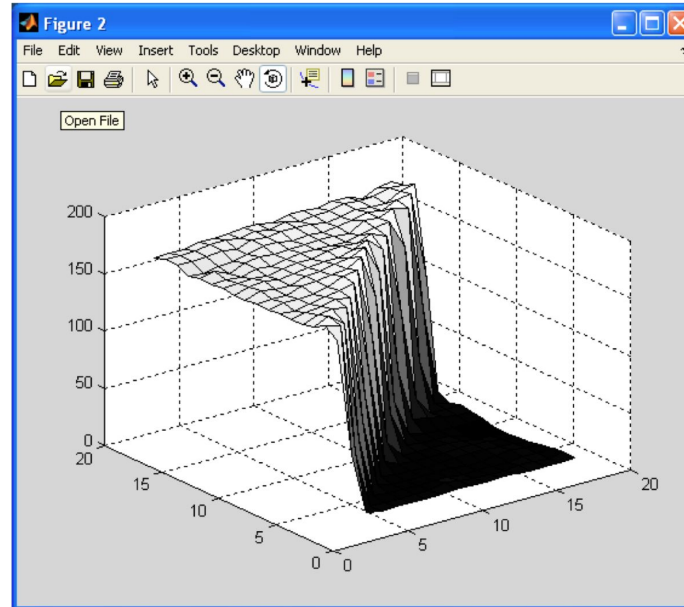
Canny Edge Detection

1. Convert Image to grayscale



Canny Edge Detection

2. Detecting edge based on the gradient intensity





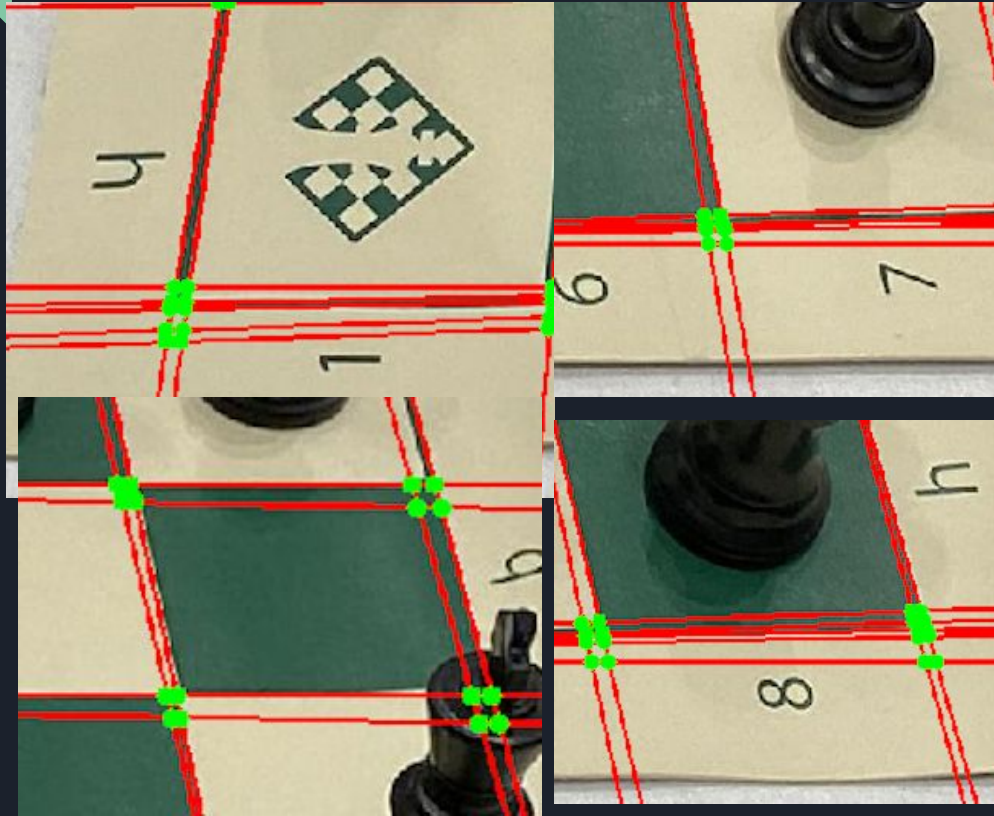
Hough Transform

-Voting Procedure:

Each edge points will vote on the line they belonged

Lines have enough edge points will be consider as a valid line

Noise Points on the Line Detection

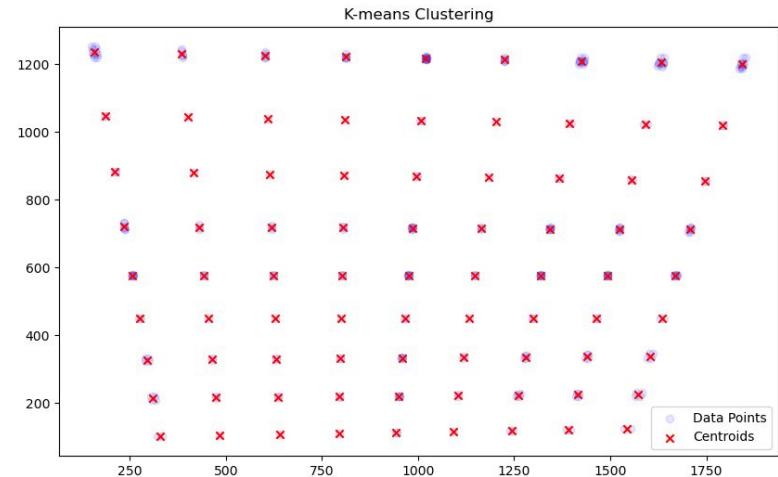


Clustering Algorithm

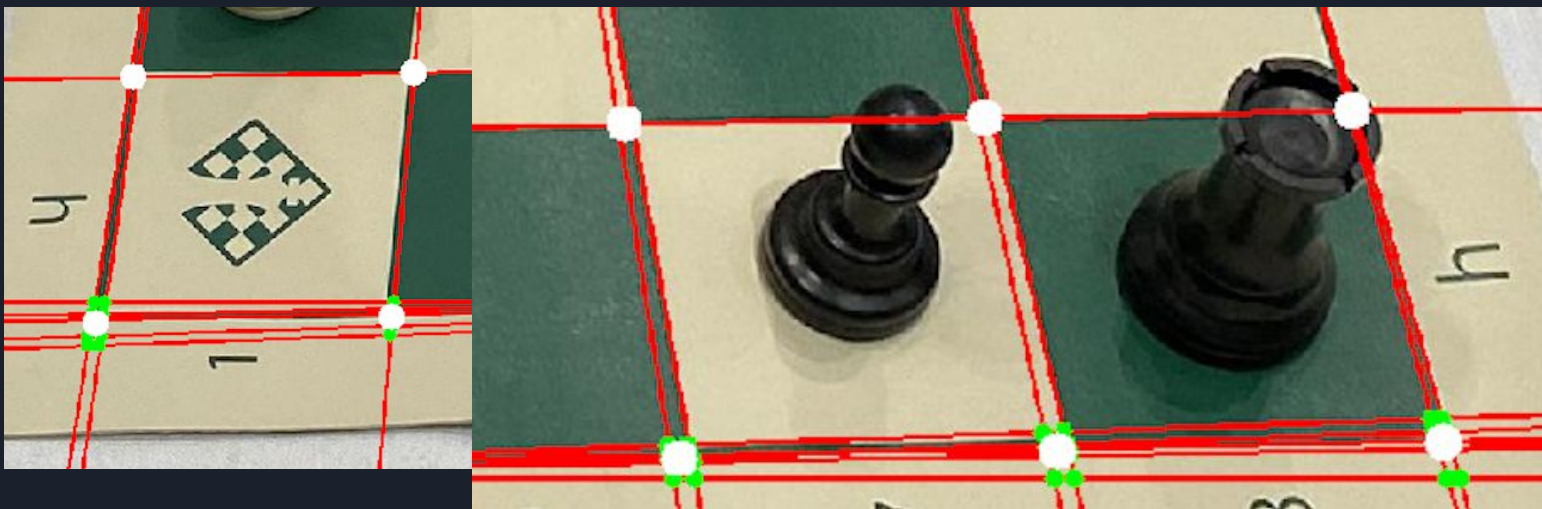
There will only have 81 intersection on the chess board

So I used K-means Clustering

81 Clusters.

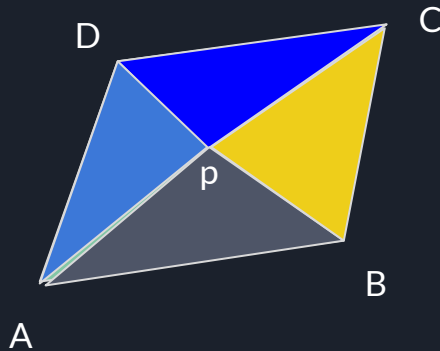


True Corners

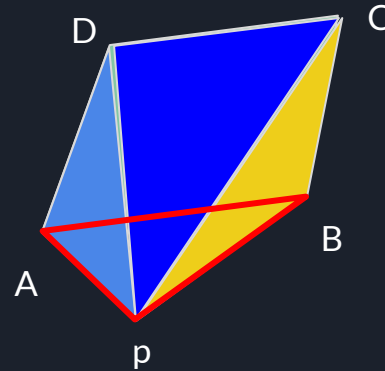


Assign Chess Pieces on Chessboard

1. Sort 81 corners in to a 9×9 array
2. Iterate through all quadrilateral in 9×9 array to assign the coordination of chess pieces on chessboard.

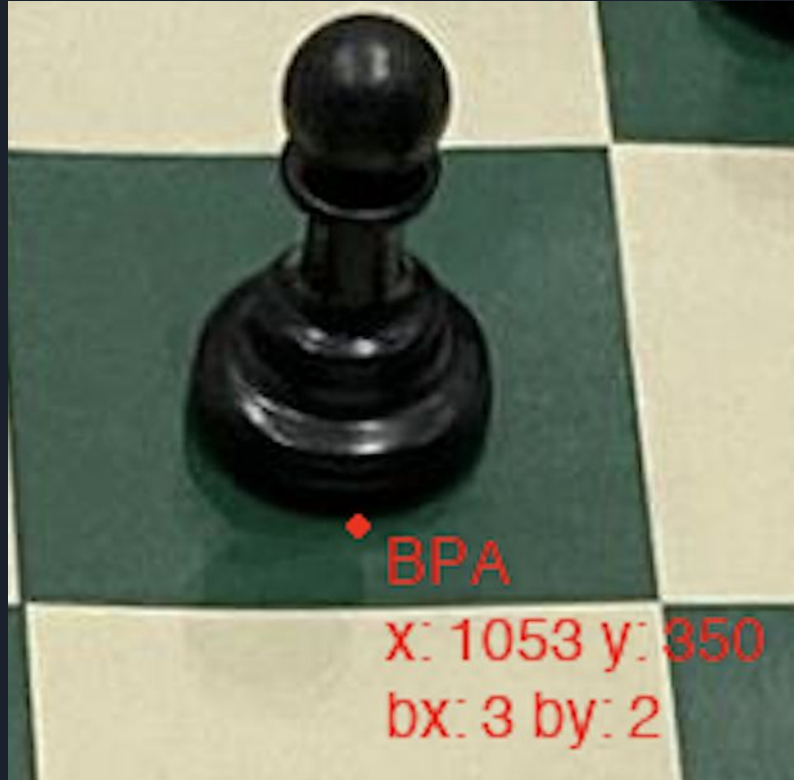


Point p inside the quadrilateral



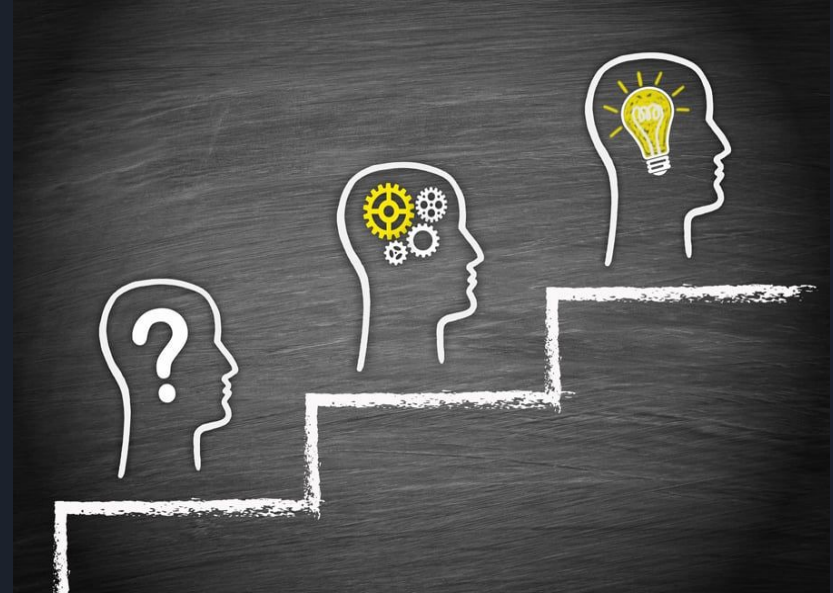
Point p outside the quadrilateral

Assign Chess Pieces on Chessboard



What we learned

- Creating deep network and the troubles that may occur
- Chess board creation from scratch with efficient results is very difficult



<https://www.futurelearn.com/info/courses/train-the-healthcare-trainer/0/steps/97612>



What we learned

Increasing the batch size for training will improve the speed of training, but not always.

Utilization	Dedicated GPU memory	Driver version:	31.0.15.5186
99%	4.0/4.0 GB	Driver date:	3/12/2024
GPU Memory	Shared GPU memory	DirectX version:	12 (FL 11.0)
8.9/19.9 GB	5.0/15.9 GB	Physical location:	PCI bus 1, device 0, function 0
		Hardware reserved memory:	48.8 MB