# 附录

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Table of Contents 附录		
附录 0. 勘误表		
B. Boussinesg 方程的线性化 ••••••	 	
C. 分离变量法		
D. Bessel 方程与 Bessel 函数	 	
E. Theis 模型的不同解法	 	
E3. Laplace 变换法	 	
E4. 总结	 	
F1. Laplace 变换简介	 	
F3. Laplace变换的数值反演	 	

## 0. 勘误表

页	行	列	错误	更正
4	5	1	$ ho_0 e^{-eta(p-p_0)}$	$ ho_0 e^{eta(p-p_0)}$
20	12	20	$ heta_2=90^\circ$	$ heta_1=90^\circ$
27	4	6	单位宽度的流量	总流量
31	9	-6	$\frac{\partial \rho}{\partial t}$	$\frac{\partial p}{\partial t}$
45	-1	-1	$q=K_1rac{H_1-H}{m_1}$	$q=-K_1rac{H_1-H}{m_1}$
63	4	1	2.1.1	2.2.1
101	1	-1	$\int_{0}^{\infty}rac{\partial s}{\partial r}rJ_{0}(eta r)dr$	$\int_0^\infty rac{\partial s}{\partial t} r J_0(eta r) dr$
101	3	1	$\int_{0}^{\infty}rac{\partial s}{\partial r}rJ_{0}(eta r)dr$	$\int_0^\infty rac{\partial s}{\partial t} r J_0(eta r) dr$
107	1	1	$\frac{\partial s}{\partial t}$	$\frac{\partial s}{\partial r}$
107	2	1	$rrac{\partial s}{\partial t}$	$rrac{\partial s}{\partial r}$
111	1	1	图4.6标注数据有误	
112	-10	1	$-rac{2.3Q}{4\pi T}$	$-rac{2.3Q}{2\pi T}$
127	6	1	$T=rac{2.3Q}{2\pi i_p}e^{-rac{r}{B}}$	$T=rac{2.3Q}{4\pi i_p}e^{-rac{r}{B}}$
137	1	1	r/D=0.08	r/D=0.8
137	-14	1	r/D=0.08	r/D=0.8
137	5	-7	0.144	0.114
137	6	-7	0.114	0.144

64 页第 14 行 (2.37) 式更正为下式, 并删除 15~17 行:

$$egin{aligned} u(x,t) = & rac{\Delta\left(h_{0,t}^2
ight)}{2} \left[1 - rac{x}{l} - rac{2}{\pi} \sum_{n=1}^{\infty} rac{1}{n} \sin\left(rac{n\pi x}{l}
ight) e^{-(rac{n\pi}{l})^2 at}
ight] \ & + rac{\Delta\left(h_{l,t}^2
ight)}{2} \left[rac{x}{l} - rac{2}{\pi} \sum_{n=1}^{\infty} rac{(-1)^{n+1}}{n} \sin\left(rac{n\pi x}{l}
ight) e^{-(rac{n\pi}{l})^2 at}
ight] \end{aligned}$$

163 页倒数第5行(5.39)式更正为:

$$s = rac{Q}{4\pi T} \{ \left\{ rac{4\pi}{l} \sqrt{rac{Tt}{S}} f(\lambda) + ln\left(rac{e^{rac{2\pi y}{l}}}{4\left[\coshrac{\pi y}{l} - \cosrac{\pi(x+a)}{l}
ight]\left[\coshrac{\pi y}{l} - \cosrac{\pi(x-a)}{l}
ight]}
ight)
ight\}$$

170 页第 10 行公式更正为:

$$egin{align} D &= rac{m_2}{rac{1}{2a_2}\left(2\lgrac{4m_2}{r_w} - A_2
ight) - \lgrac{4m_2}{R}} \ s(r,t) &= rac{Q}{4\pi T}\left[W(u) + \xi_b\left(u,rac{l}{M},rac{r}{M}
ight)
ight] \end{aligned}$$

## A. 地下水运动方程的柱坐标形式

设h(x,y)的所有二阶偏导数连续,由直角坐标与极坐标的关系:

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \implies \begin{cases} r = \sqrt{x^2 + y^2} \\ \theta = \arctan \frac{y}{x} \end{cases}$$
$$\begin{cases} \frac{\partial r}{\partial x} = \frac{x}{r} = \cos \theta \\ \frac{\partial r}{\partial y} = \frac{y}{r} = \sin \theta \end{cases} \begin{cases} \frac{\partial \theta}{\partial x} = -\frac{\sin \theta}{r} \\ \frac{\partial \theta}{\partial y} = \frac{\cos \theta}{r} \end{cases}$$

根据复合函数的求导法则:

$$\begin{split} \frac{\partial H}{\partial x} &= \frac{\partial H}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial H}{\partial \theta} \frac{\partial \theta}{\partial x} = \cos \theta \frac{\partial H}{\partial r} - \frac{\sin \theta}{r} \frac{\partial H}{\partial \theta} \\ \frac{\partial H}{\partial y} &= \frac{\partial H}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial H}{\partial \theta} \frac{\partial \theta}{\partial y} = \sin \theta \frac{\partial H}{\partial r} + \frac{\cos \theta}{r} \frac{\partial H}{\partial \theta} \\ \frac{\partial H}{\partial y} &= \frac{\partial H}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial H}{\partial \theta} \frac{\partial \theta}{\partial y} = \cos \theta \frac{\partial H}{\partial r} - \frac{\sin \theta}{r} \frac{\partial H}{\partial \theta} \\ \frac{\partial H}{\partial y} &= \frac{\partial H}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial H}{\partial \theta} \frac{\partial \theta}{\partial y} = \sin \theta \frac{\partial H}{\partial r} + \frac{\sin \theta}{r} \frac{\partial H}{\partial \theta} \\ \frac{\partial^2 H}{\partial x^2} &= \frac{\partial}{\partial r} \left( \frac{\partial H}{\partial x} \right) \frac{\partial r}{\partial x} + \frac{\partial}{\partial \theta} \left( \frac{\partial H}{\partial x} \right) \frac{\partial \theta}{\partial x} \\ &= \frac{\partial}{\partial r} \left( \cos \theta \frac{\partial H}{\partial r} - \frac{\sin \theta}{r} \frac{\partial H}{\partial \theta} \right) \cos \theta + \frac{\partial}{\partial \theta} \left( \cos \theta \frac{\partial H}{\partial r} - \frac{\sin \theta}{r} \frac{\partial H}{\partial \theta} \right) \left( -\frac{\sin \theta}{r} \right) \\ &= \cos^2 \theta \frac{\partial^2 H}{\partial r^2} + \frac{2 \sin \theta \cos \theta}{r^2} \frac{\partial H}{\partial \theta} - \frac{2 \sin \theta \cos \theta}{r} \frac{\partial^2 H}{\partial r \partial \theta} + \frac{\sin^2 \theta}{r} \frac{\partial H}{\partial r} + \frac{\sin^2 \theta}{r^2} \frac{\partial^2 H}{\partial \theta^2} \end{split}$$

同理:

$$\frac{\partial^2 H}{\partial y^2} = \sin^2\theta \frac{\partial^2 H}{\partial r^2} - \frac{2\sin\theta\cos\theta}{r^2} \frac{\partial H}{\partial \theta} + \frac{2\sin\theta\cos\theta}{r} \frac{\partial^2 H}{\partial r\partial \theta} + \frac{\cos^2\theta}{r} \frac{\partial H}{\partial r} + \frac{\cos^2\theta}{r^2} \frac{\partial^2 H}{\partial \theta^2}$$

因此

$$\begin{array}{ll} \frac{S}{T}\frac{\partial H}{\partial t} &= \frac{\partial^2 H}{\partial x^2} + \frac{\partial^2 H}{\partial y^2} = \frac{\partial^2 H}{\partial r^2} + \frac{1}{r}\frac{\partial H}{\partial r} + \frac{1}{r^2}\frac{\partial^2 H}{\partial \theta^2} \\ &= \frac{1}{r^2}\left[r\frac{\partial}{\partial r}\left(r\frac{\partial H}{\partial r}\right) + \frac{\partial^2 H}{\partial \theta^2}\right] \end{array}$$

## B. Boussinesg 方程的线性化

Boussinesq 方程:

$$rac{\partial}{\partial x}\left(Khrac{\partial h}{\partial x}
ight)+W=\murac{\partial h}{\partial t}$$

• 第一种线性化方法:

如果 h 变化不大, 用平均值  $\bar{h}$  代替 Kh:

$$K\bar{h}\frac{\partial^2 h}{\partial x^2} + W = \mu \frac{\partial h}{\partial t}$$
 (b-1)

• 第二种线性化方法:

$$\Rightarrow u = \frac{h^2}{2}, \ \frac{\partial h}{\partial t} = \frac{1}{h} \frac{\partial u}{\partial t}, \ 有$$

$$K \frac{\partial^2 u}{\partial x^2} + W = \frac{\mu}{h} \frac{\partial u}{\partial t}$$

h 取平均值  $\bar{h}$ :

$$K\bar{h}\frac{\partial^2 u}{\partial x^2} + W\bar{h} = \mu \frac{\partial u}{\partial t} \tag{b-2}$$

## C. 分离变量法

#### C1.1 维扩散方程的定解问题

$$\begin{cases} \frac{\partial u}{\partial t} = a \frac{\partial^2 u}{\partial x^2} & 0 \le x \le l, \ t > 0 \\ \text{IC} : u(x, 0) = \varphi(x) & 0 \le x \le l \\ \text{BC} : u(0, t) = u(l, t) = 0 & t > 0 \end{cases}$$
(C-I)

设u(x,t) = X(x)T(t),代入方程,有

$$X(x)T'(t) = aX''(x)T(t)$$

因为x与t为两个独立的自由变量,有

$$\frac{X''}{X} = \frac{T'}{aT} = -\lambda^2$$

得到两个常微分方程:

$$T'(t) + \lambda^2 a T(t) = 0 \tag{c-1}$$

$$X''(x) + \lambda^2 X(x) = 0 \tag{c-2}$$

方程 (c-1) 的解:

$$T(t) = C \mathrm{e}^{-\lambda^2 at}$$

方程 (c-2) 与问题 (C-I) 的边界条件构成常微分方程的边值问题:

$$\begin{cases} X''(x) + \lambda^2 X(x) = 0 \\ X(0) = X(l) = 0 \end{cases}$$
 (c-3)

问题(c-3)的通解为

$$X(x) = A\cos(\lambda x) + B\sin(\lambda x)$$

根据边界条件确定常系数:

$$X(0) = 0 \implies A = 0$$
  
 $X(l) = 0 \implies B\sin(\lambda l) = 0$ 

为求非零解,必须  $\sin(\lambda l) = 0$ ,有

$$\lambda_n=rac{n\pi}{l},\ n=1,2,\cdots$$

综上,问题(C-I)的解为:

$$u(x,t) = \sum_{n=1}^{\infty} b_n \sin(\lambda_n x) \mathrm{e}^{-\lambda_n^2 a t}$$
 (c-4)

式中,
$$\lambda_n=rac{n\pi}{l}(n=1,2,\cdots)_\circ$$

• 几个重要积分:

$$\int_{0}^{l} \sin(m\pi x/l) \sin\left(\frac{n\pi x}{l}\right) dx = \begin{cases} 0 & m \neq n \\ \frac{l}{2} & m = n \end{cases}$$
 (c-5)

$$\int_{0}^{l} \cos\left(\frac{m\pi x}{l}\right) \cos\left(\frac{n\pi x}{l}\right) dx = \begin{cases} 0 & m \neq n \\ \frac{l}{2} & m = n \end{cases}$$
 (c-6)

$$\int_0^l \cos\left(\frac{m\pi x}{l}\right) dx = \begin{cases} 0 & m \neq 0\\ l & m = 0 \end{cases}$$
 (c-7)

$$\int_0^l \sin^2\left(\frac{m\pi x}{l}\right) dx = \int_0^l \cos^2\left(\frac{m\pi x}{l}\right) dx = \frac{l}{2}, \quad m \ge 1$$
 (c-8)

• 确定(c-4)的系数  $b_n$ :

由初始条件有

$$u(x,0)=arphi(x)=\sum_{n=1}^{\infty}b_{n}\sin\left(rac{n\pi x}{l}
ight)$$

两边同乘以  $\sin\left(\frac{m\pi x}{l}\right)$ ,并从 0 到 l 积分:

$$\int_0^l \varphi(x) \sin\left(\frac{m\pi x}{l}\right) dx = \sum_{n=1}^\infty \int_0^l b_n \sin\left(\frac{m\pi x}{l}\right) \sin\left(\frac{n\pi x}{l}\right) dx$$

应用公式(c-5),有

$$b_n = \frac{2}{l} \int_0^l \varphi(x) \sin\left(\frac{n\pi x}{l}\right) dx = \frac{2}{l} \int_0^l \varphi(x) \sin(\lambda_n x) dx$$
 (c-9)

式中, $\lambda_n=rac{n\pi}{l},\,n=1,2,\cdots$ 

C2. 其他定解问题

$$\begin{cases} \frac{\partial u}{\partial t} = a \frac{\partial^2 u}{\partial x^2} & 0 \le x \le l, \ t > 0 \\ \text{IC} : u(x, 0) = \varphi_1(x) & 0 \le x \le l \\ \text{BC} : u(0, t) = u_1, \ u(l, t) = u_2, \ t > 0 \end{cases}$$
 (C-II)

设 $v(x,t) = u(x,t) - (1 - \frac{x}{l})u_1 - \frac{x}{l}u_2$ ,则v(x,t)是如下问题的解:

$$\left\{ \begin{array}{ll} \frac{\partial v}{\partial t} = a \frac{\partial^2 v}{\partial x^2} & 0 \leq x \leq l, \ t > 0 \\ \mathrm{IC} : v(x,0) = \varphi(x) & 0 \leq x \leq l \\ \mathrm{BC} : v(0,t) = 0, \ v(l,t) = 0 & t > 0 \end{array} \right.$$

式中, $\varphi(x)=arphi_1(x)-(1-rac{x}{l})u_1-rac{x}{l}u_2$ 。该问题同问题(I)一致,可用分离变量法求解。

•  $\varphi_1(x) = 0$ :

$$\varphi(x) = -(1 - \frac{x}{l})u_1 - \frac{x}{l}u_2$$

此时, 问题 (C-II) 的解为:

$$u(x,t)=(1-rac{x}{l})u_1+rac{x}{l}u_2+\sum_{n=1}^{\infty}b_n\sin(\lambda_nx)\mathrm{e}^{-\lambda_n^2at}$$

式中,

$$b_n=rac{2}{l}\int_0^l arphi(x)\sin(\lambda_n x)\mathrm{d}x, \quad \lambda_n=rac{n\pi}{l}(n=1,2,\cdots)$$

• 计算系数  $b_n$ :

记

$$c_n = -rac{2u_1}{l}\int_0^l \left(1-rac{x}{l}
ight)\sin(\lambda_n x)\mathrm{d}x, \; d_n = -rac{2u_2}{l}\int_0^l rac{x}{l}\sin(\lambda_n x)\mathrm{d}x$$

分两步计算

1. 先计算  $c_n$ ,  $d_n$ 

$$c_n = \frac{2u_1}{l} \frac{1}{\lambda_n} \int_0^l \left(1 - \frac{x}{l}\right) d\cos(\lambda_n x)$$

$$= \frac{2u_1}{n\pi} \left[ \left(1 - \frac{x}{l}\right) \cos(\lambda_n x) \right]_0^l - \frac{2u_1}{n\pi} \int_0^l \cos(\lambda_n x) (-\frac{1}{l}) dx$$

$$= -\frac{2u_1}{n\pi}$$

$$d_n = \frac{2u_2}{l} \frac{1}{\lambda_n} \int_0^l \frac{x}{l} d\cos(\lambda_n x)$$

$$= \frac{2u_2}{n\pi} \left[ \frac{x}{l} \cos(\lambda_n x) \right]_0^l - \frac{2u_2}{n\pi} \int_0^l \cos(\lambda_n x) \frac{1}{l} dx$$

$$= \frac{2u_2}{n\pi} (-1)^n$$

2. 再计算系数  $b_n$ :

$$b_n = c_n + d_n = -\left[rac{2u_1}{n\pi} + rac{2u_2}{n\pi}(-1)^{n+1}
ight]$$

无量纲变换

记
$$ar{x}=rac{x}{l},\;ar{t}=rac{at}{l^2},\;$$
则

$$egin{aligned} u(x,t) &= u_1 \left[ 1 - ar{x} - rac{2}{\pi} \sum_{n=1}^{\infty} rac{1}{n} \sin(n\pi ar{x}) \mathrm{e}^{-(n\pi)^2 ar{t}} 
ight] \ &+ u_2 \left[ ar{x} - rac{2}{\pi} \sum_{n=1}^{\infty} rac{(-1)^{n+1}}{n} \sin(n\pi ar{x}) \mathrm{e}^{-(n\pi)^2 ar{t}} 
ight] \end{aligned}$$

$$F(ar{x},ar{t}) = 1 - ar{x} - rac{2}{\pi} \sum_{n=1}^{\infty} rac{1}{n} \sin(n\pi ar{x}) \mathrm{e}^{-(n\pi)^2 ar{t}} \ F'(ar{x},ar{t}) = ar{x} - rac{2}{\pi} \sum_{n=1}^{\infty} rac{(-1)^{n+1}}{n} \sin(n\pi ar{x}) \mathrm{e}^{-(n\pi)^2 ar{t}}$$

有  $F'(\bar{x},\bar{t}) = F(1-\bar{x},\bar{t})_{\circ}$ 

定解问题(C-II)的解简记为:

$$u(x,t) = u_1 F(\bar{x}, \bar{t}) + u_2 F'(\bar{x}, \bar{t})$$
 (c-10)

• 求  $F(\bar{x},\bar{t})$  的 VBA 程序:

```
Function FF(x,t,nmax)
   If t<=0 Then
        FF=0#
   Else
        Pi=3.141592654
        FF=1-x
        For n=1 To nmax
            alpha=n*Pi
            term=-2*Sin(alpha*x)*Exp(-t*alpha^2)/alpha
            FF=FF+term
        Next n
   End If
End Function</pre>
```

• 问题 ( C-II ) 中  $l \to \infty$ :

$$\begin{cases} \frac{\partial u}{\partial t} = a \frac{\partial^2 u}{\partial x^2} & 0 \le x \le \infty, \ t > 0 \\ \text{IC} : u(x, 0) = 0 & 0 \le x \le \infty \\ \text{BC} : u(0, t) = u_1, \ u(\infty, t) = 0 \ t > 0 \end{cases}$$
(C-III)

若l为有限值,则

$$u(x,t)=u_1\left[1-rac{x}{l}-rac{2}{\pi}\sum_{n=1}^{\infty}rac{1}{n}\sin(rac{n\pi}{l}x)\mathrm{e}^{-(rac{n\pi}{l})^2at}
ight]$$

记 $\xi_n=rac{n\pi}{l},\Delta\xi_n=\xi_{n+1}-\xi_n=rac{\pi}{l}$ ,有

$$rac{u}{u_1}=1-rac{x}{l}-rac{2}{\pi}\sum_{n=1}^{\infty}rac{\sin(\xi_nx)}{\xi_n}\mathrm{e}^{-\xi_n^2at}\Delta\xi_n$$

当  $l \to \infty$  时, $\Delta \xi_n \to 0$ ,上式写成积分形式:

$$\frac{u}{u_1} = 1 - \frac{2}{\pi} \int_0^\infty \frac{\sin(\xi x)}{\xi} e^{-\xi^2 a t} d\xi$$
 (c-11)

• 几个重要积分:

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-u^2} du$$
 (c-12)

$$\operatorname{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_{0}^{\infty} e^{-u^{2}} du = 1 - \operatorname{erf}(x)$$
 (c-13)

$$\int_0^\infty e^{-x^2} dx = \frac{\sqrt{\pi}}{2} \tag{c-14}$$

$$\int_0^\infty e^{-a^2x^2}\cos(bx)\mathrm{d}x = \frac{\sqrt{\pi}}{2a}e^{-\frac{b^2}{4a^2}}, \ \ (a>0)$$
 (c-15)

$$\int_0^\infty \frac{\sin(bx)}{x} e^{-a^2x^2} dx = \frac{\pi}{2} \operatorname{erf}\left(\frac{b}{2a}\right)$$
 (c-16)

· 公式 (c-15) 证明:

记

$$arphi(x) = \int_0^\infty e^{-t^2} \cos(2tx) dt$$
  $\dfrac{\mathrm{d} arphi}{\mathrm{d} x} = -2 \int_0^\infty t e^{-t^2} \sin(2tx) dt$   $= \left[ e^{-t^2} \sin(2tx) \right]_0^\infty - 2x \int_0^\infty e^{-t^2} \cos(2tx) dt$   $= -2x \int_0^\infty e^{-t^2} \cos(2tx) dt$ 

因此,  $\varphi$  满足如下方程:

$$\frac{\mathrm{d}\varphi}{\mathrm{d}x} + 2x\varphi = 0\tag{c-17}$$

方程 (c-17) 通解为

$$arphi(x) = C e^{-x^2}$$

并且满足

$$arphi(0) = \int_0^\infty \mathrm{e}^{-t^2} \, \mathrm{d}t = rac{\sqrt{\pi}}{2}$$

有

$$arphi(x) = \int_0^\infty \mathrm{e}^{-t^2} \cos(2tx) \mathrm{d}t = rac{\sqrt{\pi}}{2} \mathrm{e}^{-x^2}$$

取  $t=au(a>0),\ x=rac{b}{2a}$ ,则有

$$\int_0^\infty \mathrm{e}^{-a^2 u^2} \cos(bu) \mathrm{d} u = rac{\sqrt{\pi}}{2a} \mathrm{e}^{-rac{b^2}{4a^2}}, \ \ (a>0)$$

· 公式 (c-16) 证明:

(c-15) 两边分别对 b 从 0 到  $\beta$  积分:

$$\int_0^\infty \mathrm{e}^{-a^2 x^2} rac{\sin eta x}{x} \mathrm{d}x = rac{\sqrt{\pi}}{2a} \int_0^eta \mathrm{e}^{-rac{h^2}{4a^2}} \, \mathrm{d}b \ = rac{\pi}{2} \mathrm{erf}\left(rac{eta}{2a}
ight)$$

即

$$\int_0^\infty \frac{\sin(bx)}{x} e^{-a^2x^2} dx = \frac{\pi}{2} \operatorname{erf}\left(\frac{b}{2a}\right)$$

• 问题 (C-III)的解:

由公式(c-15),公式(c-11)变为:

$$\begin{aligned} \frac{u}{u_1} &= 1 - \frac{2}{\pi} \int_0^\infty \frac{\sin(\xi x)}{\xi} e^{-\xi^2 a t} d\xi \\ &= 1 - \operatorname{erf}\left(\frac{x}{2\sqrt{at}}\right) = \operatorname{erfc}\left(\frac{x}{2\sqrt{at}}\right) \end{aligned}$$

因此,问题(C-III)的解为

$$u(x,t) = u_1 \operatorname{erfc}\left(\frac{x}{2\sqrt{at}}\right)$$
 (c-18)

## D. Bessel 方程与 Bessel 函数

Bessel 方程:

$$x^{2}\frac{d^{2}y}{dx^{2}} + x\frac{dy}{dx} + (x^{2} - n^{2})y = 0$$
 (d-1)

具有如下形式的解:

$$y(x) = C_1 J_n(x) + C_2 Y_n(x)$$
 (d-2)

式中, $J_n(x)$  为第一类贝塞尔函数, $Y_n(x)$  为第二类贝塞尔函数。

修正贝塞尔方程:

$$x^{2} \frac{d^{2}y}{dx^{2}} + x \frac{dy}{dx} - (x^{2} + n^{2})y = 0$$
 (d-3)

具有如下形式的解:

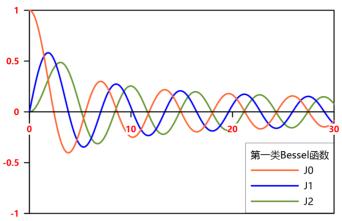
$$y(x) = C_1 I_n(x) + C_2 K_n(x)$$
 (d-4)

式中, $I_n(x)$  为第一类修正贝塞尔函数, $K_n(x)$  为第二类修正贝塞尔函数。

贝塞尔函数(Bessel Functions)是一类特殊函数的总称。

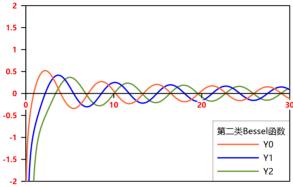
早在 18 世纪中叶,瑞士数学家丹尼尔·伯努利在研究悬链振动时提出了贝塞尔函数的几个正整数阶特例,当时引起了数学界的兴趣。丹尼尔的叔叔雅各布·伯努利,欧拉、拉格朗日等数学大师对贝塞尔函数的研究作出过重要贡献。1817 年,德国数学家贝塞尔在研究开普勒提出的三体引力系统的运动问题时,第一次系统地提出了贝塞尔函数的总体理论框架,后人以他的名字来命名了这种函数。

• 第一类贝塞尔函数  $J_n(x)$  的形状:



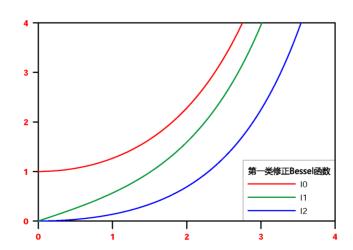
 $J_n(x)$ --的形状大致与按 $\frac{1}{\sqrt{x}}$ 速率衰减的正弦或余弦函数类似,零点不是周期性的,而是随着x的增加零点的间隔会越来越接近周期性。

• 第二类贝塞尔函数  $Y_n(x)$  的形状:



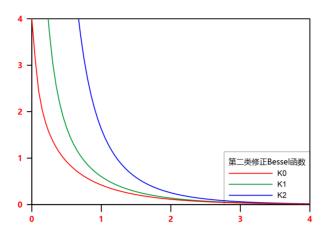
 $Y_n(x)$  又称诺伊曼函数(Neumann function),x=0 点是它的无穷奇点。

• 第一类修正贝塞尔函数  $I_n(x)$  的形状:



 $I_n(x)$  是指数增长的。

• 第二类修正贝塞尔函数  $K_n(x)$  的形状:



## $K_n(x)$ 是指数衰减的。

• 贝塞尔函数的性质:

$J_n(x)$	$Y_n(x)$
$J_{-n}(x) = (-1)^n J_n(x), \ (n$ 为整数)	$Y_{-n}(x) = (-1)^n Y_n(x), \ (n$ 为整数)
$J_{n-1}(x) + J_{n+1}(x) = rac{2n}{x} J_n(x)$	$Y_{n-1}(x)+Y_{n+1}(x)=rac{2n}{x}Y_n(x)$
$J_{n-1}(x) - J_{n+1}(x) = 2J_n^{\prime}(x)$	$Y_{n-1}(x) - Y_{n+1}(x) = 2Y_n'(x)$
$rac{\mathrm{d}}{\mathrm{d}x}[x^{-n}J_n(x)] = -x^{-n}J_{n+1}(x)$	$rac{\mathrm{d}}{\mathrm{d}x}[x^{-n}Y_n(x)] = -x^{-n}Y_{n+1}(x)$
$rac{\mathrm{d}}{\mathrm{d}x}[x^nJ_n(x)]=x^nJ_{n-1}(x)$	$rac{\mathrm{d}}{\mathrm{d}x}[x^nY_n(x)]=x^nY_{n-1}(x)$
$rac{\mathrm{d}}{\mathrm{d}x}[J_0(x)] = -J_1(x)$	$rac{\mathrm{d}}{\mathrm{d}x}[Y_0(x)] = -Y_1(x)$

$I_n(x)$	$K_n(x)$
$I_{-n}(x)=I_n(x),\ (n$ 为整数)	$K_{-n}(x)=K_n(x),\ (n$ 为整数)
$I_{n-1}(x)-I_{n+1}(x)=rac{2n}{x}I_n(x)$	$K_{n-1}(x) - K_{n+1}(x) = -rac{2n}{x}K_n(x)$
$I_{n-1}(x) + I_{n+1}(x) = 2I_n^{\prime}(x)$	$K_{n-1}(x) + K_{n+1}(x) = -2K_n^\prime(x)$
$rac{\mathrm{d}}{\mathrm{d}x}[x^{-n}I_n(x)]=x^{-n}I_{n+1}(x)$	$rac{\mathrm{d}}{\mathrm{d}x}[x^{-n}K_n(x)] = -x^{-n}K_{n+1}(x)$
$rac{\mathrm{d}}{\mathrm{d}x}[x^nI_n(x)]=x^nI_{n-1}(x)$	$rac{\mathrm{d}}{\mathrm{d}x}[x^nK_n(x)] = -x^nK_{n-1}(x)$
$rac{\mathrm{d}}{\mathrm{d}x}[I_0(x)] = I_1(x)$	$rac{\mathrm{d}}{\mathrm{d}x}[K_0(x)] = -K_1(x)$

• 贝塞尔函数的渐进性质:

x o 0	$x o\infty$
$J_n(x)pprox rac{1}{\Gamma(1+n)}\left(rac{x}{2} ight)^n,\ n\geq 0$	$J_n(x)pprox\sqrt{rac{2}{\pi x}}\cos\left(x-rac{n\pi}{2}-rac{\pi}{4} ight)$
$Y_0(x)pprox rac{2}{\pi}\ln(x)$	$Y_n(x)pprox \sqrt{rac{2}{\pi x}}\sinig(x-rac{n\pi}{2}-rac{\pi}{4}ig)$
$Y_n(x)pprox -rac{\Gamma(n)}{\pi}\left(rac{2}{x} ight)^n,\ n>0$	$I_n(x)pprox rac{1}{\sqrt{2\pi x}}e^x$
$I_n(x) pprox rac{1}{\Gamma(1+n)} \left(rac{x}{2} ight)^n$	$K_n(x) pprox \sqrt{rac{\pi}{2x}} e^{-x}$
$K_0(x) pprox - \ln x$	
$K_n(x)pprox rac{\Gamma(n)}{2}\left(rac{2}{x} ight)^n,\ n>0$	

## E. Theis 模型的不同解法

记 $s = H_0 - H$ ,数学模型:

$$\begin{cases} a\left(\frac{\partial^2 s}{\partial r^2} + \frac{1}{r}\frac{\partial s}{\partial r}\right) = \frac{\partial s}{\partial t} & t > 0, \ 0 < r < \infty \\ \text{IC} : s(r,0) = 0 & 0 < r < \infty \\ \text{BC} : \lim_{r \to \infty} s(r,t) = 0 & t > 0 \\ \text{BC} : \lim_{r \to \infty} \frac{\partial s}{\partial r} = 0 & t > 0 \\ \text{BC} : \lim_{r \to \infty} r\frac{\partial s}{\partial r} = -\frac{Q}{2\pi T} & t > 0 \end{cases}$$
(E-I)

式中, $a = \frac{T}{S}$ 。

E1. Bolttzmann 变换法

引入变量  $u=\frac{r^2}{4at}$ ,则有

$$\frac{\partial u}{\partial r} = \frac{r}{2at}, \quad \frac{\partial u}{\partial t} = -\frac{u}{t}$$

依据求导的链式法则,有

$$\frac{\partial s}{\partial r} = \frac{\mathrm{d}s}{\mathrm{d}u} \frac{\partial u}{\partial r} = \frac{\mathrm{d}s}{\mathrm{d}u} \frac{r}{2at}$$

$$\frac{\partial^2 s}{\partial r^2} = \frac{1}{2at} \frac{\mathrm{d}s}{\mathrm{d}u} + \left(\frac{r}{2at}\right)^2 \frac{\mathrm{d}^2 s}{\mathrm{d}u^2}$$

$$\frac{\partial s}{\partial t} = \frac{\mathrm{d}s}{\mathrm{d}u} \frac{\partial u}{\partial t} = -\frac{\mathrm{d}s}{\mathrm{d}u} \frac{u}{t}$$

代入偏微分方程:

$$a\left[\frac{1}{2at}\frac{\mathrm{d}s}{\mathrm{d}u} + \left(\frac{r}{2at}\right)^2\frac{\mathrm{d}^2s}{\mathrm{d}u^2} + \frac{1}{2at}\frac{\mathrm{d}s}{\mathrm{d}u}\right] = -\frac{u}{t}\frac{\mathrm{d}s}{\mathrm{d}u}$$

整理得:

$$u\frac{\mathrm{d}^2 s}{\mathrm{d}u^2} + (1+u)\frac{\mathrm{d}s}{\mathrm{d}u} = 0$$

由初始条件与边界条件:

$$\begin{cases} \lim_{u \to \infty} s = 0 \\ \lim_{u \to 0} \left( 2u \frac{\mathrm{d}s}{\mathrm{d}u} \right) = -\frac{Q}{2\pi T} \end{cases}$$

原定解问题变为:

$$\begin{cases} u \frac{\mathrm{d}^2 s}{\mathrm{d}u^2} + (1+u) \frac{\mathrm{d}s}{\mathrm{d}u} = 0\\ \lim_{u \to \infty} s = 0\\ \lim_{u \to 0} \left( 2u \frac{\mathrm{d}s}{\mathrm{d}u} \right) = -\frac{Q}{2\pi T} \end{cases}$$

记 $s' = \frac{\mathrm{d}s}{\mathrm{d}u}$ ,方程变为:

$$u\frac{\mathrm{d}s'}{\mathrm{d}u} + (1+u)s' = 0$$

分离变量:

$$\frac{1}{s'}\mathrm{d}s' = -\left(1 + \frac{1}{u}\right)\mathrm{d}u$$

等式两边同时积分:

$$\ln s' = -\ln u - u + C$$

即

$$\frac{ds}{du} = s' = e^{-\ln u - u - C} = C_1 \frac{e^{-u}}{u}$$

由边界条件

$$-rac{Q}{2\pi T}=2u\left.rac{\mathrm{d}s}{\mathrm{d}u}
ight|_{u=0}=2C_{1}$$

得

$$C_1 = -rac{Q}{4\pi T}$$

因此

$$\frac{\mathrm{d}s}{\mathrm{d}u} = -\frac{Q}{4\pi T} \frac{e^{-u}}{u}$$

两边同时积分(注意对应的积分限),有

$$\int_{s}^{0} \mathrm{d}s = -\frac{Q}{4\pi T} \int_{u}^{\infty} \frac{e^{-u}}{u} \mathrm{d}u \implies s = \frac{Q}{4\pi T} \int_{u}^{\infty} \frac{e^{-u}}{u} \mathrm{d}u$$

式中, $u=rac{r^2}{4at}$ 。

E2. Hankel 变换法

记

$$ar{s}(eta,t)=\int_0^\infty sr J_0(eta r)\mathrm{d}r$$

为 s(r,t) 的 0 阶 Hankel 变换, $J_0(\beta r)$  为第一类零阶 Bessel 函数。

将方程两端同乘以  $rJ_0(\beta r)$ , 并从 0 到  $\infty$  对 r 积分:

$$a\int_0^\infty rac{1}{r}rac{\partial}{\partial r}\left(rrac{\partial s}{\partial r}
ight)rJ_0(eta r)\mathrm{d}r = \int_0^\infty rac{\partial s}{\partial t}rJ_0(eta r)\mathrm{d}r$$

等式右端:

$$\int_0^\infty \frac{\partial s}{\partial t} r J_0(\beta r) \mathrm{d}r = \frac{\partial}{\partial t} \int_0^\infty s r J_0(\beta r) \mathrm{d}r = \frac{\mathrm{d}\bar{s}}{\mathrm{d}t}$$

等式左端分部积分:

$$a \int_{0}^{\infty} \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial s}{\partial r} \right) r J_{0}(\beta r) dr$$

$$= a \left( r \frac{\partial s}{\partial r} \right) J_{0}(\beta r) \Big|_{0}^{\infty} - a \int_{0}^{\infty} r \frac{\partial s}{\partial r} d[J_{0}(\beta r)]$$

$$= \frac{aQ}{2\pi T} + a \int_{0}^{\infty} r \frac{\partial s}{\partial r} \beta J_{1}(\beta r) dr$$

$$= \frac{aQ}{2\pi T} + a\beta r J_{1}(\beta r) s \Big|_{0}^{\infty} - a \int_{0}^{\infty} s d[\beta r J_{1}(\beta r)]$$

$$= \frac{aQ}{2\pi T} - a \int_{0}^{\infty} s \beta r J_{0}(\beta r) d[\beta r]$$

$$= \frac{aQ}{2\pi T} - a\beta^{2} \bar{s}$$

式中使用了 Bessel 函数的如下性质:

$$J_0(0)=1, \quad J_0'(x)=-J_1(x), \quad rac{\mathrm{d}}{\mathrm{d}x}[x^nJ_n(x)]=x^nJ_{n-1}(x)$$

Hankel 变换将原定解问题化为常微分方程的初值问题:

$$\left\{ egin{aligned} rac{\mathrm{d}ar{s}}{\mathrm{d}t} + aeta^2ar{s} &= rac{aQ}{2\pi T} \ ar{s}\left|_{t=0} &= 0 \end{aligned} 
ight.$$

其解为:

$$ar{s} = rac{aQ}{2\pi T} \int_0^t e^{-aeta^2(t- au)} \mathrm{d} au$$

通过 Hankel 逆变换求 s:

$$egin{aligned} s &= \int_0^\infty ar{s} eta J_0(eta r) \mathrm{d}eta \ &= rac{aQ}{2\pi T} \int_0^t \left[ \int_0^\infty e^{-aeta^2(t- au)} eta J_0(eta r) \mathrm{d}eta 
ight] \mathrm{d} au \end{aligned}$$

记

$$F(r) = \int_0^\infty e^{-aeta^2(t- au)}eta J_0(eta r) \mathrm{d}eta$$

对 F(r) 求导:

$$\begin{split} F'(r) &= \int_0^\infty e^{-a\beta^2(t-\tau)}\beta[-J_1(\beta r)\beta]\mathrm{d}\beta \\ &= \frac{1}{2a(t-\tau)}\int_0^\infty \beta J_1(\beta r)\mathrm{d}e^{-a\beta^2(t-\tau)} \\ &= \frac{\beta J_1(\beta r)}{2a(t-\tau)}e^{-a\beta^2(t-\tau)}\bigg|_0^\infty - \frac{1}{2a(t-\tau)}\int_0^\infty e^{-a\beta^2(t-\tau)}\frac{1}{r}\mathrm{d}[\beta r J_1(\beta r)] \\ &= -\frac{1}{2a(t-\tau)}\int_0^\infty e^{-a\beta^2(t-\tau)}\frac{1}{r}\beta r J_0(\beta r)\mathrm{d}[\beta r] \\ &= -\frac{1}{2a(t-\tau)}\int_0^\infty e^{-a\beta^2(t-\tau)}\beta r J_0(\beta r)\mathrm{d}\beta = -\frac{r}{2a(t-\tau)}F(r) \end{split}$$

式中使用了Bessel函数的如下性质:

$$J_0(0)=1, \quad J_0'(x)=-J_1(x), \quad rac{\mathrm{d}}{\mathrm{d}x}[x^nJ_n(x)]=x^nJ_{n-1}(x)$$

F(r) 满足如下的常微分方程:

$$F'(r) = -rac{r}{2a(t- au)}F(r)$$

分离变量:

$$rac{\mathrm{d}F(r)}{F(r)} = -rac{r}{2a(t- au)}\mathrm{d}r$$

两边积分:

$$\ln F(r) = -rac{r^2}{4a(t- au)} + C \implies F(r) = C_1 e^{-rac{r^2}{4a(t- au)}} 
onumber$$
 $F(0) = \int_0^\infty e^{-aeta^2(t- au)} eta J_0(0) \mathrm{d}eta = rac{1}{2a(t- au)} \implies C_1 = rac{1}{2a(t- au)}$ 

因此

$$F(r)=rac{1}{2a(t- au)}e^{-rac{r^2}{4a(t- au)}}$$

原问题的解

$$s=rac{aQ}{2\pi T}\int_0^trac{1}{2a(t- au)}e^{-rac{ au^2}{4a(t- au)}}\,\mathrm{d} au$$

做变量代换,令

$$y=rac{r^2}{4a(t- au)},\quad \mathrm{d} au=rac{r^2}{4ay^2}\mathrm{d}y$$

当au=0时, $y=rac{r^2}{4at}$ ,当au=t时, $y=\infty$ 。因此

$$s=rac{aQ}{2\pi T}\int_{rac{r^2}{2}}^{\infty}rac{2y}{r^2}e^{-y}rac{r^2}{4ay^2}\mathrm{d}y=rac{Q}{4\pi T}\int_{u}^{\infty}rac{e^{-y}}{y}\mathrm{d}y$$

式中,
$$u = \frac{r^2}{4at}$$
。

E3. Laplace 变换法

偏微分方程:

$$a\left(\frac{\partial^2 s}{\partial r^2} + \frac{1}{r}\frac{\partial s}{\partial r}\right) = \frac{\partial s}{\partial t}$$

记:

$$ar{s}(r,p)=\mathscr{L}\{s\}=\int_0^\infty s(r,t)e^{-pt}\mathrm{d}t$$

对方程两边做 Laplace 变换:

左端 
$$= a \left( rac{\mathrm{d}^2 ar{s}}{\mathrm{d}r^2} + rac{1}{r} rac{\mathrm{d}ar{s}}{\mathrm{d}r} 
ight), \quad 右端 = par{s} - s(r,0)$$

利用初始条件 s(r,0) = 0,有:

$$r^2 rac{\mathrm{d}^2 ar{s}}{\mathrm{d}r^2} + r rac{\mathrm{d}ar{s}}{\mathrm{d}r} - rac{p}{a} r^2 ar{s} = 0$$

此为 0 阶修正 Bessel 方程, 通解为:

$$ar{s} = C_1 I_0 \left( \sqrt{rac{p}{a}} r 
ight) + C_2 K_0 \left( \sqrt{rac{p}{a}} r 
ight)$$

当 $r o\infty$ 时,s o0  $\Longrightarrow$   $ar{s} o0$ 。又 $r o\infty$ 时, $I_0\left(\sqrt{rac{p}{a}}r
ight) o\infty$ ,有 $C_1=0$ 。

因此

$$egin{aligned} ar{s} &= C_2 K_0 \left( \sqrt{rac{p}{a}} r 
ight) \ rac{\mathrm{d} ar{s}}{\mathrm{d} r} &= -C_2 \sqrt{rac{p}{a}} K_1 \left( \sqrt{rac{p}{a}} r 
ight) \end{aligned}$$

由内边界条件(抽水井),有

$$\begin{split} r\left.\frac{\mathrm{d}\bar{s}}{\mathrm{d}r}\right|_{r=r_w} &= -\frac{Q}{2\pi T}\frac{1}{p}\\ \begin{cases} r^2\frac{\mathrm{d}^2\bar{s}}{\mathrm{d}r^2} + r\frac{\mathrm{d}\bar{s}}{\mathrm{d}r} - \frac{p}{a}r^2\bar{s} = 0\\ \lim_{r\to\infty}\bar{s} = 0\\ \lim_{r\to0} r\left(\frac{\mathrm{d}\bar{s}}{\mathrm{d}r}\right) = -\frac{Q}{2\pi T}\frac{1}{p} \end{split}$$

得

$$C_2 = rac{Q}{2\pi T}rac{1}{p}rac{1}{\sqrt{rac{P}{a}}r_w K_1\left(\sqrt{rac{P}{a}}r_w
ight)}$$

取 $r_w o 0$ ,根据 Bessel 函数的性质, $\lim_{x o 0} x K_1(x) = 1$ ,有

$$ar{s} \doteq rac{Q}{4\pi T}rac{2}{p}K_0\left(\sqrt{rac{p}{a}}r
ight) = rac{Q}{4\pi T}rac{r^2}{4a}rac{2}{rac{r^2}{4a}p}K_0\left(2\sqrt{rac{r^2}{4a}p}
ight)$$

由 Laplace 逆变换

$$\mathscr{L}^{-1}\left\{rac{2}{p}K_0(2\sqrt{p})
ight\}=E_1\left(rac{1}{t}
ight)$$

及 Laplace 变换性质

$$\mathscr{L}^{-1}\left\{F(bp)
ight\}=rac{1}{b}f\left(rac{t}{b}
ight)$$

取  $b = \frac{r^2}{4a}$ ,有

$$s=rac{Q}{4\pi T}E_1\left(rac{r^2}{4at}
ight)=rac{Q}{4\pi T}\int_{rac{r^2S}{4T}}^{\infty}rac{e^{-y}}{y}\mathrm{d}y$$

### E4. 总结

Bolttzmann 变换法	Hankel 变换法	Laplace 变换法
$u(r,t)=R(r)T(t)=rac{r^2}{4at}$	$ar{s}(eta,t)=\int_0^\infty sr J_0(eta r) \mathrm{d} r$	$ar{s}(r,p)=\int_0^\infty s(r,t)e^{-pt}\mathrm{d}t$
边值问题	初值问题	边值问题
$egin{cases} urac{\mathrm{d}^2s}{\mathrm{d}u^2}+(1+u)rac{\mathrm{d}s}{\mathrm{d}u}=0\ \lim_{u o\infty}s=0\ \lim_{u o0}\left(2urac{\mathrm{d}s}{\mathrm{d}u} ight)=-rac{Q}{2\pi T} \end{cases}$	$egin{cases} rac{\mathrm{d}ar{s}}{\mathrm{d}t} + aeta^2ar{s} = rac{aQ}{2\pi T} \ \lim_{t o 0}ar{s} = 0 \end{cases}$	$egin{cases} r^2 rac{\mathrm{d}^2 ar{s}}{\mathrm{d}r^2} + r rac{\mathrm{d}ar{s}}{\mathrm{d}r} - rac{p}{a} r^2 ar{s} = 0 \ \lim_{r  o \infty} ar{s} = 0 \ \lim_{r  o 0} r \left( rac{\mathrm{d}ar{s}}{\mathrm{d}r}  ight) = -rac{Q}{2\pi T} rac{1}{p} \end{cases}$
	Hankel 逆变换	Laplace 逆变换
	$s(r,t)=\int_0^\infty ar{s}eta J_0(eta r)\mathrm{d}eta$	$s(r,t)=\mathscr{L}^{-1}\{ar{s}(r,p)\}$

## F. Laplace 变换及应用

## F1. Laplace 变换简介

Laplace 变换定义

设函数 f(t) 是定义在  $(0,\infty)$  上的实值函数,如果对于复参数  $p=\beta+j\omega$ ,积分  $F(p)=\int_0^{+\infty}f(t)e^{-pt}\mathrm{d}t$  在复平面 p 的某一区域内收敛,则称 F(p) 为 f(t) 的 Laplace 变换,记为

$$F(p)=\mathscr{L}\{f(t)\}=\int_0^{+\infty}f(t)e^{-pt}\mathrm{d}t$$

相应地,称 f(t) 为 F(p) 的 Laplace 逆变换,记为

$$f(t) = \mathscr{L}^{-1}\{F(p)\}$$

简单函数的 Laplace 变换

$$(1) \quad \mathcal{L}\{1\} \qquad \qquad = \int_{0}^{+\infty} e^{-pt} dt = -\frac{1}{p} e^{-pt} \Big|_{0}^{+\infty} = \frac{1}{p}$$

$$(2) \quad \mathcal{L}\{e^{at}\} \qquad = \int_{0}^{+\infty} e^{at} e^{-pt} dt = \frac{1}{a-p} e^{(a-p)t} \Big|_{0}^{+\infty} = \frac{1}{p-a}, \quad (p > a)$$

$$(3) \quad \mathcal{L}\{\sin(at)\} \qquad = \int_{0}^{\infty} \sin(at) e^{-pt} dt = -\frac{e^{-pt}}{p^{2}+a^{2}} [p\sin(at) + a\cos(at)]_{0}^{\infty}$$

$$= \frac{a}{p^{2}+a^{2}}, \quad (p > 0)$$

$$(4) \quad \mathcal{L}\{\cos(at)\} \qquad = \int_{0}^{\infty} \cos(at) e^{-pt} dt = \frac{e^{-pt}}{p^{2}+a^{2}} [-p\cos(at) + a\sin(at)]_{0}^{\infty}$$

$$= \frac{p}{p^{2}+a^{2}}, \quad (p > 0)$$

$$(5) \quad \mathcal{L}\{t^{n}\} \qquad = \int_{0}^{\infty} t^{n} e^{-pt} dt = -n! e^{-pt} \sum_{m=0}^{n} \frac{t^{n-m}}{(n-m)!p^{m+1}} \Big|_{0}^{\infty}$$

$$= \frac{n!}{p^{n+1}}, \quad (p > 0)$$

特殊函数的 Laplace 变换

• Heaviside 阶跃函数 (Heaviside step function):

$$H(t) = egin{cases} 0 & for & t < 0 \ 1 & for & t \geq 0 \end{cases}$$

Laplace变换:

$$\mathscr{L}\{H(t-t_0)\}=rac{1}{p}\exp(-pt_0),\quad s>0$$

•  $\delta$  函数 (Dirac Delta function) 或脉冲函数 (Impulse function):

$$\delta(t) = egin{cases} 0 & for & |t| > 0 \ \infty & for & t = 0 \end{cases}, \quad \int_{-arepsilon}^arepsilon \delta(t) \mathrm{d}t = 1$$

也可表示为

$$\delta(t) = egin{cases} 0 & for & |t| > arepsilon \ rac{1}{2arepsilon} & for & |t| \leq arepsilon \end{cases}, \quad arepsilon o 0$$

 $\delta$  函数性质:

$$\int_{-\infty}^{\infty} \delta(t) f(t) \mathrm{d}t = f(0)$$

Laplace 变换:

$$egin{aligned} \mathscr{L}\{\delta(t-t_0)\} &= \int_0^\infty \delta(t-t_0)e^{-pt}\mathrm{d}t = \lim_{arepsilon o 0} \int_{t_0-arepsilon}^{t_0+arepsilon} rac{e^{-pt}}{2arepsilon} \mathrm{d}t \ &= \lim_{arepsilon o 0} rac{e^{-p(t_0-arepsilon)} - e^{-p(t_0+arepsilon)}}{2parepsilon} = e^{-pt_0} \end{aligned}$$

即

$$\mathcal{L}\{\delta(t-t_0)\} = \exp(-pt_0)$$

Laplace 变换存在定理

设函数  $f(t)(t \ge 0)$  满足:

- 1. 在任何有限区间上分段连续;
- 2. 即存在常数 c 及 M>0,使得  $|f(t)| \leq Me^{ct}$ 。

则象函数 F(p) 在半平面 Re p > c 上一定存在且解析。

Laplace 变换性质 设

$$F(p) = \mathcal{L}{f(t)}.$$
  $G(p) = \mathcal{L}{g(t)}$ 

• 线性性质

设a, b为常数,则有

$$\mathcal{L}{af(t) + bg(t)} = aF(p) + bG(p)$$
  
$$\mathcal{L}^{-1}{aF(p) + bG(p)} = af(t) + bg(t)$$

• 相似性质

设a为任一正实数,则

$$\mathscr{L}\{f(at)\} = rac{1}{a}F\left(rac{p}{a}
ight)$$
  $\mathscr{L}^{-1}\{F(ap)\} = rac{1}{a}f\left(rac{t}{a}
ight)$ 

• 延迟性质

设t < 0时, f(t) = 0, 则对任一非负实数 $\tau$ 有

$$\mathscr{L}\{H(t- au)f(t- au)\}=e^{-p au}F(p)$$

• 位移性质

设a为任一复常数,则

$$\mathscr{L}\lbrace e^{at}f(t)\rbrace = F(p-a)$$
  
 $\mathscr{L}\lbrace e^{-at}f(t)\rbrace = F(p+a)$ 

• 微分性质

$$\mathscr{L}\{f'(t)\} = pF(p) - f(0)$$
 $\mathscr{L}\{f^{(n)}(t)\} = p^nF(p) - p^{n-1}f(0) - p^{n-2}f'(0) - \dots - f^{(n-1)}(0)$ 
 $F'(p) = -\mathscr{L}\{tf(t)\}$ 
 $F^{(n)}(p) = (-1)^n\mathscr{L}\{t^nf(t)\}$ 

• 积分性质

$$\mathcal{L}\left\{\int_0^t f(t)dt\right\} = \frac{1}{p}F(p)$$
  $\mathcal{L}\left\{\frac{1}{t}f(t)\right\} = \int_p^\infty F(p)dp$ 

设函数满足: t < 0 时  $f_1(t) = f_2(t) = 0$ , 则定义卷积如下:

$$egin{aligned} f_1(t)*f_2(t) &= \int_0^t f_1( au) f_2(t- au) \mathrm{d} au \ &= \int_0^t f_1(t- au) f_2( au) \mathrm{d} au \end{aligned}$$

由上式给出的卷积满足交换律、结合律及分配律等性质。

### • 卷积定理

$$\mathscr{L}\{f_1(t)*f_2(t)\}=F_1(p)\cdot F_2(p)$$

Laplace 变换与逆变换简表

序号	$f(t)=\mathscr{L}^{-1}\{F(p)\}$	$F(p) = \mathscr{L}\{f(t)\}$
(1)	1	$\frac{1}{p}$
(2)	$H(t-t_0)$	$rac{1}{p}\exp(-pt_0)$
(3)	$\delta(t-t_0)$	$\exp(-pt_0)$
(4)	t	$\frac{1}{p^2}$
(5)	$t^{lpha}$	$rac{\Gamma(lpha+1)}{p^{lpha+1}}$
(6)	$\exp(lpha t)$	$\frac{1}{p-\alpha}$
(7)	$t^n \exp(lpha t)$	$rac{n!}{(p-lpha)^{n+1}}$
(8)	$\frac{1}{\sqrt{\pi t}}$	$\frac{1}{\sqrt{p}}$
(9)	$2\sqrt{rac{t}{\pi}}$	$p^{-3/2}$
(10)	$rac{1}{2\sqrt{\pi t^3}}\exp\left(-rac{1}{4t} ight)$	$\exp(-\sqrt{p})$
(11)	$\operatorname{erfc}\left(rac{1}{2\sqrt{t}} ight)$	$\frac{1}{p}\exp(-\sqrt{p})$
(12)	$\frac{1}{\sqrt{\pi t}}\exp\left(-\frac{1}{4t}\right)$	$rac{1}{\sqrt{p}}\exp(-\sqrt{p})$
(13)	$2\sqrt{rac{t}{\pi}}\exp(-rac{1}{4t})-\operatorname{erfc}(rac{1}{2\sqrt{t}})$	$p^{-rac{3}{2}} \exp(-\sqrt{p})$
(14)	$t\exp(-t)$	$\frac{1}{(p+1)^2}$
(15)	$\frac{1}{t}\exp(-\frac{1}{t})$	$2K_0(2\sqrt{p})$
(16)	$E_1(rac{1}{t})$	$rac{2}{p}K_0(2\sqrt{p})$
(17)	$rac{1}{\sqrt{\pi}}\sin(2\sqrt{t})$	$p^{-rac{3}{2}}\exp(rac{1}{p})$
(18)	$rac{1}{\sqrt{\pi}}\cos(2\sqrt{t})$	$p^{-rac{1}{2}}\exp(rac{1}{p})$
(19)	$-\gamma - \ln t$	$(\ln p)/p$

表中: H(t) 一单位阶跃函数;  $\delta(t)$  一单位阶跃函数;  $\operatorname{erf}(t) = \frac{2}{\sqrt{\pi}} \int_0^t \exp(-y^2) \, \mathrm{d}y$  一误差函数;  $\operatorname{erfc}(t) = 1 - \operatorname{erf}(t) = \frac{2}{\sqrt{\pi}} \int_t^\infty \exp(-y^2) \, \mathrm{d}y$  一余误差函数;  $K_0$  一第二类零阶修正 Bessel 函数;  $E_1(t) = \int_t^\infty \frac{1}{y} \exp(-y) \, \mathrm{d}y$  一指数积分;  $\gamma = 0.577\,215\,6649\cdots$  — 欧拉常数.

#### F2. Laplace变换法求解偏微分方程

利用性质:  $\mathscr{L}{f'(t)} = pF(p) - f(0)$ ,消除变量对t的导数。



1维问题(I-1):

$$\left\{egin{array}{l} arac{\partial^2 s}{\partial x^2} = rac{\partial s}{\partial t} \ \mathrm{IC}: s(x,0) = 0 \ \mathrm{BC}: s(0,t) = H \ \mathrm{BC}: s(\infty,t) = 0 \end{array}
ight.$$

对方程做 Laplace 变换,记:

$$ar{s}(x,p) = \mathscr{L}\{s(x,t)\} = \int_0^\infty s(x,t) \exp(-pt) \mathrm{d}t$$

有

$$arac{\mathrm{d}^2ar{s}(x,p)}{\mathrm{d}x^2}=par{s}(x,p)-s(x,0)=par{s}(x,p)$$

上述方程的通解为

$$ar{s}(x,p) = C_1 \exp\left(\sqrt{rac{p}{a}}x
ight) + C_2 \exp\left(-\sqrt{rac{p}{a}}x
ight)$$

对边界条件做 Laplace 变换:

$$\left\{egin{array}{l} ar{s}(\infty,p)=0 \ ar{s}(0,p)=rac{H}{p} \end{array}
ight.$$

根据边界条件,有  $C_1=0,\ C_2=rac{H}{p}$ , 因此

$$ar{s}(x,p) = Hrac{1}{p}\exp\left(-\sqrt{rac{p}{a}}x
ight)$$

根据 Laplace 变换简表公式(11):

$$L^{-1}\left\{\frac{1}{p}\exp(-\alpha\sqrt{p})\right\}=\operatorname{erfc}\left(\frac{\alpha}{2\sqrt{t}}\right)$$

取 
$$\alpha = \frac{x}{\sqrt{a}}$$
, 得

$$s(x,t) = H \operatorname{erfc}\left(\frac{x}{2\sqrt{at}}\right)$$

1 维问题 (I − 2):

$$\left\{egin{array}{l} arac{\partial^2 s}{\partial x^2} = rac{\partial s}{\partial t} \ \mathrm{IC}: s(x,0) = 0 \ \mathrm{BC}: s(\infty,t) = 0 \ \mathrm{BC}: rac{\partial s}{\partial x}ig|_{x=0} = -rac{q}{T} \end{array}
ight.$$

对方程做 Laplace 变换,记

$$ar{s}(x,p) = \mathscr{L}\{s(x,t)\} = \int_0^\infty s(x,t) \exp(-pt) \mathrm{d}t$$

有

$$arac{\mathrm{d}^2ar{s}(x,p)}{\mathrm{d}x^2}=par{s}(x,p)-s(x,0)=par{s}(x,p)$$

上述方程的通解为

$$ar{s}(x,p) = C_1 \exp\left(\sqrt{rac{p}{a}}x
ight) + C_2 \exp\left(-\sqrt{rac{p}{a}}x
ight)$$

对边界条件做 Laplace 变换:

$$\left\{ \begin{array}{l} \bar{s}(\infty, p) = 0 \\ \left. \frac{\partial \bar{s}}{\partial x} \right|_{x=0} = -\frac{1}{p} \frac{q}{T} \end{array} \right.$$

根据边界条件,有  $C_1=0,~C_2=rac{q}{T}\sqrt{a}p^{-rac{3}{2}}$ ,因此

$$ar{s}(x,p) = rac{q}{T} \sqrt{a} p^{-rac{3}{2}} \exp\left(-\sqrt{rac{p}{a}}x
ight)$$

根据 Laplace 变换简表公式(13)

$$\mathscr{L}^{-1}\left\{p^{-\frac{3}{2}}\exp(-lpha\sqrt{p})
ight\}=2\sqrt{rac{t}{\pi}}\exp\left(-rac{lpha^2}{4t}
ight)-lpha\operatorname{erfc}\left(rac{lpha}{2\sqrt{t}}
ight)$$

取
$$\alpha = \frac{x}{\sqrt{a}}$$
,得

$$\begin{split} s(x,t) &= \frac{q}{T} \sqrt{a} \left[ 2 \sqrt{\frac{t}{\pi}} \exp\left( -\frac{x^2}{4at} \right) - \frac{x}{\sqrt{a}} \operatorname{erfc}\left( \frac{x}{2\sqrt{at}} \right) \right] \\ &= \frac{q}{T} \sqrt{\frac{4at}{\pi}} \exp\left( -\frac{x^2}{4at} \right) - \frac{qx}{T} \operatorname{erfc}\left( \frac{x}{2\sqrt{at}} \right) \\ &= \frac{q}{T} \left[ \frac{1}{\sqrt{\pi}u} \exp(-u^2) - \operatorname{erfc}(u) \right] \end{split}$$

式中, $u^2 = \frac{x^2}{4at}$ .

2维问题(II-1):

记 $s = H_0 - H$ ,数学模型:

$$\left\{ \begin{array}{ll} a\left(\frac{\partial^2 s}{\partial r^2} + \frac{1}{r}\frac{\partial s}{\partial r}\right) = \frac{\partial s}{\partial t} & t>0, \ 0 < r < \infty \\ \mathrm{IC}: s(r,0) = 0 & 0 < r < \infty \\ \mathrm{BC}: s(\infty,t) = 0, \lim_{r \to \infty} \left(\frac{\partial s}{\partial r}\right) = 0 & t>0 \\ \mathrm{BC}: \lim_{r \to 0} \left(r\frac{\partial s}{\partial r}\right) = -\frac{Q}{2\pi T} \end{array} \right.$$

式中,  $a = \frac{T}{S}$ 。

记

$$s(\bar{r},p)=\mathscr{L}\{s\}=\int_0^\infty s(r,t)e^{-pt}\mathrm{d}t$$

对方程两边做 Laplace 变换,并使用初始条件 s(r,0)=0,得:

$$\frac{\mathrm{d}^2 \bar{s}}{\mathrm{d}r^2} + \frac{1}{r} \frac{\mathrm{d}\bar{s}}{\mathrm{d}r} - \frac{p}{a} \bar{s} = 0$$

此为 0 阶修正 Bessel 方程, 通解为:

$$ar{s} = C_1 I_0 \left( \sqrt{rac{p}{a}} r 
ight) + C_2 K_0 \left( \sqrt{rac{p}{a}} r 
ight)$$

对边界条件做 Laplace 变换:

$$\left\{egin{array}{l} ar{s}(\infty,p)=0 \ rrac{\partial ar{s}}{\partial r}ig|_{r=r_w}=-rac{1}{p}rac{Q}{2\pi T} \end{array}
ight.$$

根据边界条件,有  $C_1=0,~C_2=rac{Q}{2\pi T}rac{1}{p}rac{1}{\sqrt{rac{p}{c}}r_wK_1\left(\sqrt{rac{p}{c}}r_w
ight)}$ ,因此

$$ar{s} = rac{Q}{2\pi T}rac{1}{p}rac{K_0\left(\sqrt{rac{p}{a}}r
ight)}{\sqrt{rac{p}{a}}r_wK_1\left(\sqrt{rac{p}{a}}r_w
ight)}$$

设 $r_w 
ightarrow 0$ ,因为 $\displaystyle \lim_{x 
ightarrow 0} x K_1(x) = 1$ ,所以有

$$ar{s} \doteq rac{Q}{4\pi T} rac{2}{p} K_0 \left( \sqrt{rac{p}{a}} r 
ight)$$

根据 Laplace 变换简表公式(16):

$$\mathscr{L}^{-1}\left\{rac{2}{p}K_0(2\sqrt{p})
ight\}=E_1\left(rac{1}{t}
ight)$$

及 Laplace 变换相似性:

$$\mathscr{L}^{-1}\left\{F(bp)
ight\}=rac{1}{b}f\left(rac{t}{b}
ight)$$

有

$$ar{s} \doteq rac{Q}{4\pi T}rac{2}{p}K_0\left(\sqrt{rac{p}{a}}r
ight) = rac{Q}{4\pi T}rac{r^2}{4a}rac{2}{rac{r^2}{4-p}}K_0\left(2\sqrt{rac{r^2}{4a}p}
ight)$$

取 
$$b = \frac{r^2}{4a}$$
:

$$s=rac{Q}{4\pi T}E_1\left(rac{r^2}{4at}
ight)=rac{Q}{4\pi T}\int_{rac{r^2S}{4\pi T}}^{\infty}rac{e^{-y}}{y}\mathrm{d}y$$

• 2 维问题(II-2): Jacob-Lohman 公式

做无量纲变量代换,记 $\bar{r} = \frac{r}{r_n}, \bar{t} = \frac{at}{r^2},$ 定解问题变为

$$\left\{egin{array}{ll} rac{\partial^2 s}{\partial ar{r}^2} + rac{1}{ar{r}}rac{\partial s}{\partial ar{r}} = rac{\partial s}{\partial ar{t}} & ar{t} > 0, \ 1 < ar{r} < \infty \ s(ar{r},0) = 0, & 1 < ar{r} < \infty \ s(\infty,ar{t}) = 0, & ar{t} > 0 \ s(1,ar{t}) = s_w, & ar{t} > 0 \end{array}
ight.$$

对方程两边做 Laplace 变换,并使用初始条件 s(r,0)=0,得

$$rac{\mathrm{d}^2ar{s}}{\mathrm{d}ar{r}^2} + rac{1}{ar{r}}rac{\mathrm{d}ar{s}}{\mathrm{d}ar{r}} - par{s} = 0$$

此为 0 阶修正 Bessel 方程,通解为:

$$ar{s} = C_1 I_0 \left( \sqrt{p} ar{r} \right) + C_2 K_0 \left( \sqrt{p} ar{r} \right)$$

对边界条件做 Laplace 变换:

$$\left\{egin{array}{l} ar{s}(\infty,p)=0 \ ar{s}(1,ar{t})=rac{s_w}{p} \end{array}
ight.$$

根据边界条件,有  $C_1 = 0$ ,  $C_2 = \frac{s_w}{p} \frac{1}{K_0(\sqrt{p})}$ ,因此

$$ar{s} = rac{s_w}{p} rac{K_0(\sqrt{p}ar{r})}{K_0(\sqrt{p})}$$

记

$$egin{align} ar{A}(ar{r},p) &= rac{K_0ig(\sqrt{p}ar{r}ig)}{pK_0ig(\sqrt{p}ig)}, \qquad ar{s} = s_war{A}(ar{r},p) \ & A(ar{r},ar{t}) = \mathscr{L}^{-1}\{ar{A}(ar{r},p)\} \ \end{aligned}$$

则有

$$s=s_w A(ar{r},ar{t})$$

式中,  $A(\bar{r}, \bar{t})$  称为降深函数。

记 $Q_w$  为自流井流量, $\bar{Q}_w$  为 $Q_w$  的 Laplace 变换。有

$$\left.ar{Q}_w = -2\piar{r}T\left.rac{\partialar{s}}{\partialar{r}}
ight|_{ar{x}=1} = 2\pi Trac{s_w}{p}rac{\sqrt{p}K_1(\sqrt{p})}{K_0(\sqrt{p})}$$

记

$$G(ar{t}) = \mathscr{L}^{-1} \left\{ rac{K_1(\sqrt{p})}{\sqrt{p} K_0(\sqrt{p})} 
ight\}$$

有

$$Q_w = 2\pi T s_w G(\bar{t})$$

式中, $G(\bar{t})$ 称为流量函数, $\bar{t} = \frac{at}{r^2}$ 。

• 2 维问题(II-3): Hantush-Jacob 公式

数学模型:

$$\left\{egin{array}{l} rac{\partial^2 s}{\partial r^2} + rac{1}{r}rac{\partial s}{\partial r} - rac{s}{B^2} = rac{1}{a}rac{\partial s}{\partial t} & t>0, \ r_w < r < \infty \ s(r,0) = 0, & r_w < r < \infty \ s(\infty,t) = 0, & t>0 \ \lim\limits_{r o 0} \left(srac{\partial s}{\partial t}
ight) = -rac{Q}{2\pi T}, & t>0 \end{array}
ight.$$

式中,  $a = \frac{T}{S}$ 。

对方程两边做 Laplace 变换, 并使用初始条件 s(r,0) = 0, 得:

$$\frac{\partial^2 \bar{s}}{\partial r^2} + \frac{1}{r} \frac{\partial \bar{s}}{\partial r} - \left(\frac{p}{a} + \frac{1}{B^2}\right) \bar{s} = 0$$

同 Theis 模型,其解为:

$$ar{s}=rac{Q}{4\pi T}rac{2}{p}K_{0}\left(\sqrt{rac{p}{a}+rac{1}{B^{2}}}r
ight)=rac{Q}{4\pi T}rac{2}{p}K_{0}\left(2\sqrt{rac{r^{2}}{4a}\left(p+rac{a}{B^{2}}
ight)}
ight)$$

记  $\alpha = \frac{r^2}{4a}, \; \beta = \frac{a}{B^2}, \;$ 由 Laplace 变换简表公式(15):

$$\mathscr{L}^{-1}\{2K_0(2\sqrt{p})\}=rac{1}{t}\exp\left(-rac{1}{t}
ight)=f(t)$$

及相似性,有

$$\mathscr{L}^{-1}\{2K_0(2\sqrt{lpha p})\}=rac{1}{lpha}f\left(rac{t}{lpha}
ight)=rac{1}{t}\exp\left(-rac{lpha}{t}
ight)$$

根据位移性质,有

$$\mathscr{L}^{-1}\{2K_0(2\sqrt{\alpha(p+eta)})\} = \exp(-eta t) rac{1}{t} \exp\left(-rac{lpha}{t}
ight) = rac{1}{t} \exp\left(-eta t - rac{lpha}{t}
ight)$$

利用卷积计算  $\mathscr{L}^{-1}\{\frac{4\pi T\bar{s}}{Q}\}$ :

$$\frac{4\pi Ts}{Q} = \int_0^t 1 \cdot \frac{1}{\tau} \exp\left(-\beta \tau - \frac{\alpha}{\tau}\right) d\tau$$

做变量代换  $y = \frac{\alpha}{\tau}$ :

$$\begin{split} \frac{4\pi Ts}{Q} &= \int_{-\infty}^{\frac{\alpha}{t}} \frac{y}{\alpha} \exp\left(-\frac{\alpha\beta}{y} - y\right) \left(-\frac{\alpha}{y^2}\right) \mathrm{d}y \\ &= \int_{\frac{r^2}{t+t}}^{\infty} \frac{1}{y} \exp\left(-y - \frac{r^2}{4B^2y}\right) \mathrm{d}y \end{split}$$

F3. Laplace变换的数值反演

Stehfest 算法

设 F(p) 为函数 f(t) 的 Laplace 变换。Stehfest 算法公式如下:

$$f(t) pprox rac{\ln 2}{t} \sum_{i=1}^n c_i F\left(rac{i \ln 2}{t}
ight)$$

式中,  $c_i$  为 Stehfest 系数, 按下式计算:

$$c_i = (-1)^{i+rac{n}{2}} \sum_{k=\left\lceil rac{i+1}{2} 
ight
ceil}^{min(i,rac{n}{2})} rac{k^{rac{n}{2}}(2k)!}{(rac{n}{2}-k)!k!(k-1)!(i-k)!(2k-i)!}$$

```
' n shuld not exceed about 20, and n = 10 is probably sufficient
' for most applications.
' Note that n must be an even integer and that t = time.
Function Lapinv(n,t)
 n=WorksheetFunction.Even(n)
 Lapinv=0#
 For i=1 To n
   Lapinv=Lapinv+Stehcoef(i,n)*Transform(i*Log(2)/t)
 Lapinv=Lapinv*Log(2)/t
End Function
Function Stehcoef(i,n)
 M=WorksheetFunction.Round(n/2,0)
 upperlimit=WorksheetFunction.Min(i,M)
 lowerlimit=WorksheetFunction.RoundDown((i+1)/2,0)
 Stehcoef=0#
 For K=lowerlimit To upperlimit
   num=Fact(2*K)*K^M
   denom=Fact(M-K)*Fact(K)*Fact(K-1)*Fact(i-K)*Fact(2*K-i)
   Stehcoef=Stehcoef+num/denom
 Next K
 Stehcoef=Stehcoef*(-1)^(i+M)
End Function
Function Fact(x)
 Fact=WorksheetFunction.Fact(x)
End Function
Function Transform(p) 'Theis解
 Transform=2*WorksheetFunction.BesselK(2*Sqr(p),0)/p
End Function
```

• Theis 解的反演

$$s = rac{Q}{4\pi T} W(u) = rac{Q}{4\pi T} \mathscr{L}^{-1} \left\{ rac{2}{p} K_0 \left( \sqrt{rac{p}{a}} r 
ight) 
ight\}$$

式中,  $u=\frac{r^2S}{4Tt}$ 。取 $b=\frac{r^2}{4a}$ ,得

$$\frac{1}{b}W\left(\frac{1}{\frac{t}{b}}\right)=\mathscr{L}^{-1}\left\{\frac{2}{bp}K_0(2\sqrt{bp})\right\}$$

由 Laplace 变换性质

$$\mathscr{L}^{-1}\left\{F(bp)
ight\}=rac{1}{b}f\left(rac{t}{b}
ight)$$

$$W\left(rac{1}{t^*}
ight)=\mathscr{L}^{-1}\left\{rac{2}{p^*}K_0(2\sqrt{p^*})
ight\}=W(u)$$

取 u=0.01,即  $t^*=rac{1}{u}=100$ ,可以计算出  $W(0.01)_\circ$ 

```
Function Transform(p)
   Transform=2*WorksheetFunction.BesselK(2*Sqr(p),0)/p
End Function
'
Function Lapinv(n,t)
   n=WorksheetFunction.Even(n)
   Lapinv=0#
   For i=1 To n
        Lapinv=Lapinv+Stehcoef(i,n)*Transform(i*Log(2)/t)
   Next i
   Lapinv=Lapinv*Log(2)/t
End Function
```

• 定降深井模型 (Jacob-Lohman) 反演

记

$$ar{A}(ar{r},p) = rac{K_0(\sqrt{p}ar{r})}{pK_0(\sqrt{p})}$$

有

$$ar{s} = s_w ar{A}(ar{r},p)$$

记 
$$A(\bar{r}, \bar{t}) = \mathcal{L}^{-1}\{\bar{A}(\bar{r}, p)\},$$
 得

$$s = s_w A(\bar{r}, \bar{t})$$

式中,  $A(\bar{r}, \bar{t})$  称为降深函数。

```
Function Transform(p,r)
   Transform=WorksheetFunction.BesselK(r*Sqr(p),0)/WorksheetFunction.BesselK(Sqr(p),0)/p
End Function
'
Function Lapinv(n,t,r)
   n=WorksheetFunction.Even(n)
   Lapinv=0#
   For i=1 To n
        Lapinv=Lapinv+Stehcoef(i,n)*Transform(i*Log(2)/t,r)
   Next i
   Lapinv=Lapinv*Log(2)/t
End Function
```

记 $Q_w$ 为自流井流量,有

$$egin{aligned} Q_w &= 2\pi T s_w G(ar{t}) \ &= 2\pi T s_w \mathscr{L}^{-1} \left\{ rac{K_1(\sqrt{p})}{\sqrt{p} K_0(\sqrt{p})} 
ight\} \end{aligned}$$

式中, $G(\bar{t})$ 称为流量函数, $\bar{t} = \frac{at}{r_{cc}^2}$ 。

```
Function Transform(p)
    s=Sqr(p)
    Transform=WorksheetFunction.BesselK(s,1)/WorksheetFunction.BesselK(s,0)/s
End Function
.

Function Lapinv(n,t)
    n=WorksheetFunction.Even(n)
    Lapinv=0#
    For i=1 To n
        Lapinv=Lapinv+Stehcoef(i,n)*Transform(i*Log(2)/t)
    Next i
    Lapinv=Lapinv*Log(2)/t
End Function
```

• 越流含水层完整井模型 (Hantush-Jacob) 反演

$$s = rac{Q}{4\pi T} W(u,eta) = rac{Q}{4\pi T} \mathscr{L}^{-1} \left\{ rac{2}{p} K_0 \left( \sqrt{rac{p}{a} + rac{1}{B^2}} r 
ight) 
ight\}$$

式中, $u=\frac{r^2S}{4Tt}$ , $\beta=\frac{r}{B}$ 。取 $b=\frac{r^2}{4a}$ ,有:

$$W\left(rac{b}{t},eta
ight)=\mathscr{L}^{-1}\left\{rac{2}{p}K_0\left(\sqrt{4bp+eta^2}
ight)
ight\}$$

由 Laplace 变换的相似性:

$$\mathscr{L}^{-1}\left\{F(bp)
ight\}=rac{1}{b}f\left(rac{t}{b}
ight)$$

得

$$W\left(rac{1}{t^*},eta
ight)=\mathscr{L}^{-1}\left\{rac{2}{p^*}K_0\left(\sqrt{4p^*+eta^2}
ight)
ight\}$$

```
Function Transform(p,beta)
   Transform=2*WorksheetFunction.BesselK(Sqr(4*p+beta^2),0)/p
End Function
'
Function Lapinv(n,t,beta)
   n=WorksheetFunction.Even(n)
   Lapinv=0#
   For i=1 To n
        Lapinv=Lapinv+Stehcoef(i,n)*Transform(i*Log(2)/t,beta)
   Next i
   Lapinv=Lapinv*Log(2)/t
End Function
```