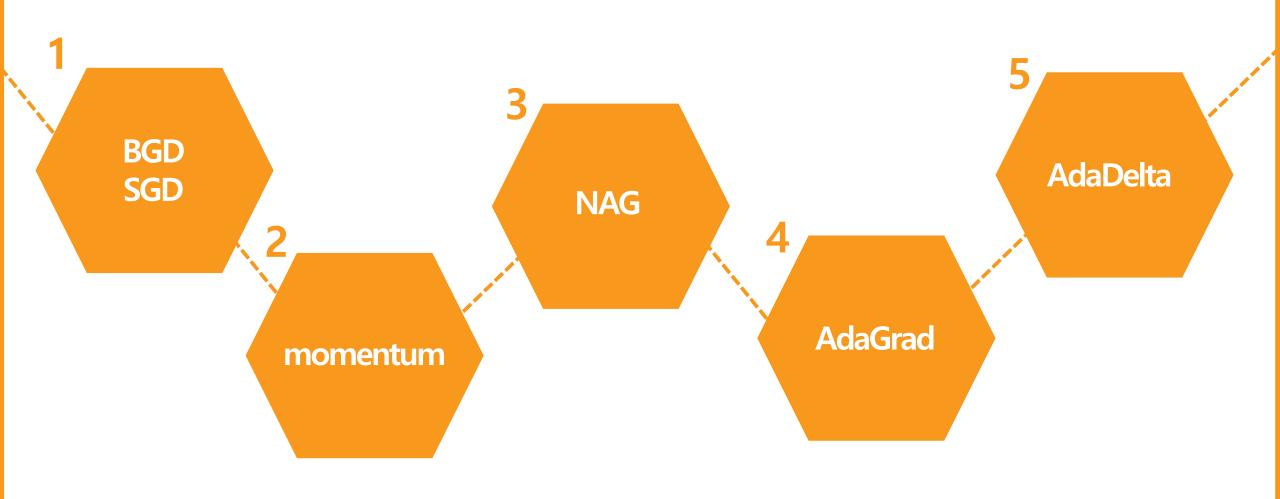
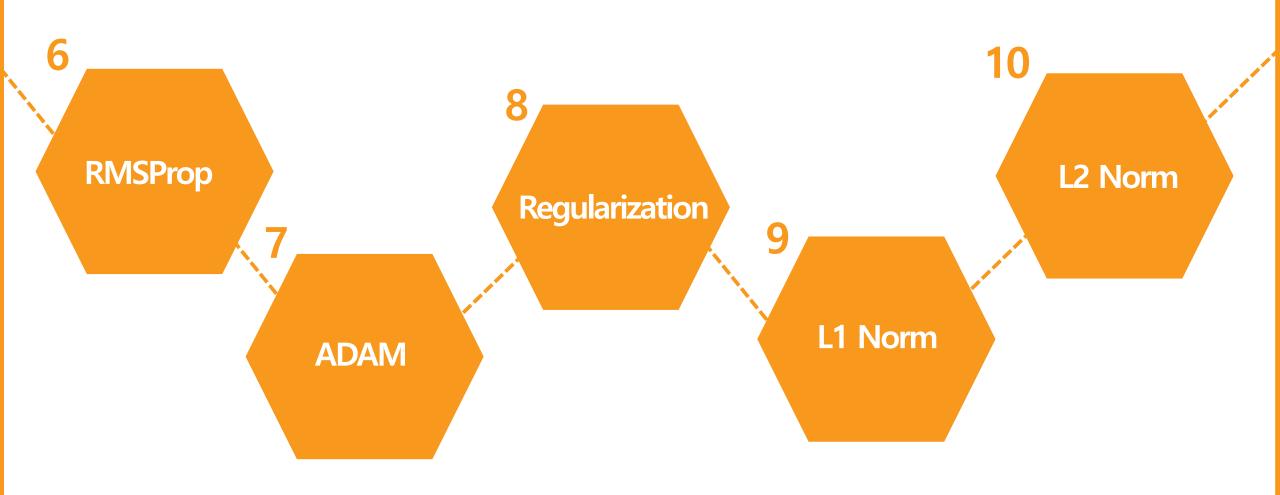
Advanced Gradient Descent Methods Regularization

CONTENTS



CONTENTS



Batch Gradient Descent

BGD

BGD

Based on Batch(total Data)

$$W \coloneqq W - \alpha \frac{1}{m} \sum_{i=1}^{m} (Wx^i - y^i) x^i$$

Stochastic Gradient Descent

SGD

SGD

Based on (One Data)

$$W := W - \alpha \frac{1}{m} (Wx^i - y^i) x^i$$

Mini-Batch Gradient Descent

MSGD

MSGD

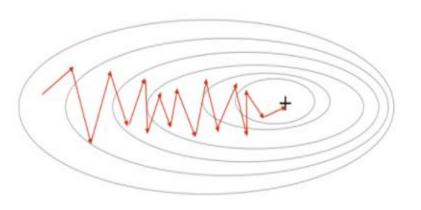
Based on Mini Batch (One Data)

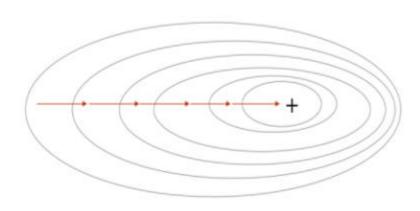
$$W \coloneqq W - \alpha \frac{1}{m} \sum_{i=1}^{m} (Wx^i - y^i) x^i$$

Visualize

Stochastic Gradient Descent

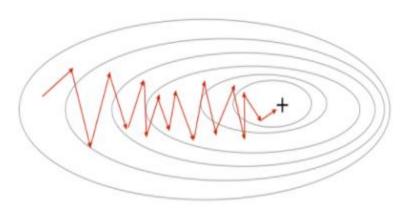
Gradient Descent

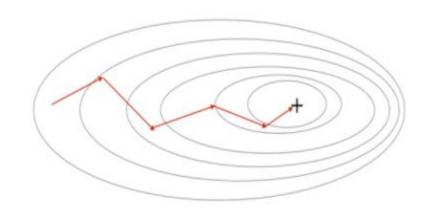




Stochastic Gradient Descent

Mini-Batch Gradient Descent





출처: https://light-tree.tistory.com/133

Momentum

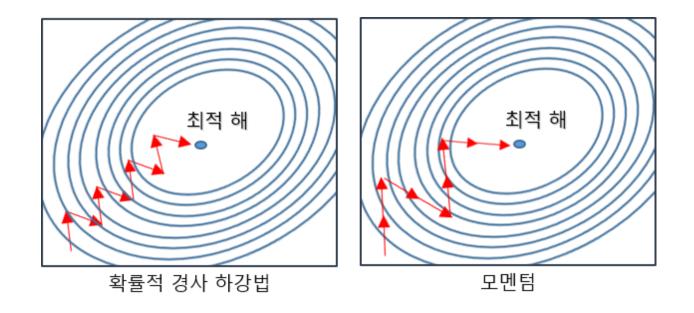
Momentum

Momentum

Like Acceleration => Rolling a ball

$$V(t) = m * V(t - 1) - \alpha \frac{\partial}{\partial w} Cost(w) - V(0) = 0$$

Momentum

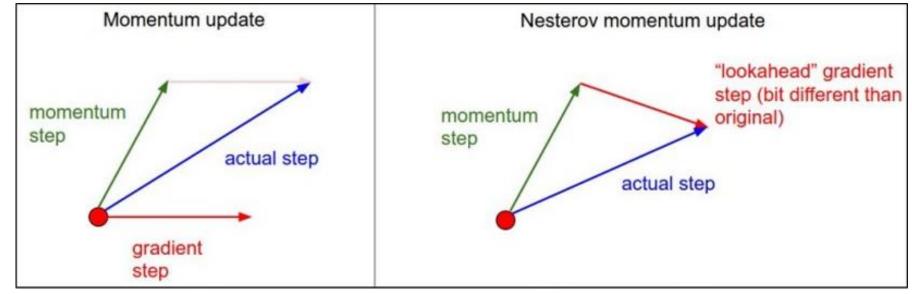


Nesterov Accelrated Gradient

NAG

NAG

In Momentum Step, gradient



Difference between Momentum and NAG. Picture from CS231.

NAG

$$V(t)=m*V(t-1)-\alpha \frac{\partial}{\partial (w+m*V(t-1))}Cost(w)$$

$$W(t+1)=W(t)+V(t)$$

NAG

Adaptive Gradient

Adagrad

Adagrad

$$G(t)=G(t-1)+\left(\frac{\partial}{\partial w(t)}Cost(w(t))\right)^2$$
 $G(t)=Vector W[i] element$

$$W(t+1)=W(t)-\alpha\frac{1}{\sqrt{G(t)+\epsilon}}\frac{\partial}{\partial w(i)}Cost(w(i)) \ W(t)=Vector\ W[i]\ element$$

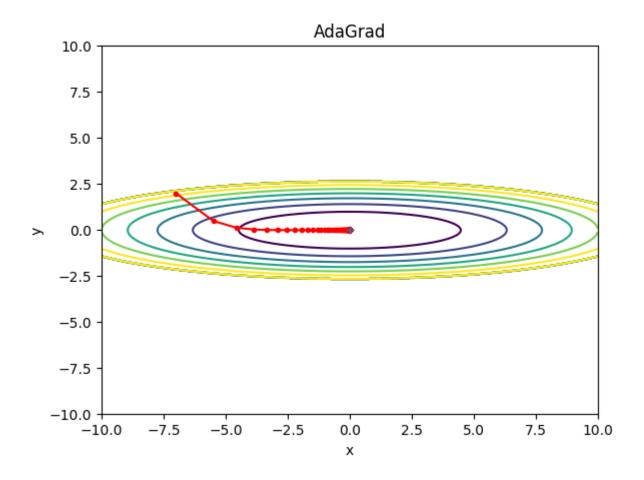
Adagrad

Problem

1. G(0)=0 and G(t)=0, insert \in

2. Infinite Training G(t) is infinite

Adagrad



Adaptive Gradient

RMSProp

RMSProp

It Complements the adagrad

G(t)=
$$\gamma$$
 G(t-1)+(1- γ) $\left(\frac{\partial}{\partial w(t)}$ Cost(w(t)) $\right)^2$ G(t) = Vector W[i] element

$$W(t+1)=W(t)-\alpha\frac{1}{\sqrt{G(t)+\epsilon}}\frac{\partial}{\partial w(i)}Cost(w(i)) \qquad W(t)=Vector\ W[i]\ element$$

$$\gamma$$
 's Value => 0.9~0.999

Adaptive Gradient

AdaDelta

Adadelta

Update Parameter W, W's unit? Remove Learning Rate

$$G(t) = \gamma G(t-1) + (1-\gamma) \left(\frac{\partial}{\partial w(t)} Cost(w(t))\right)^{2} \quad G(t) = Vector W[i] element$$

$$S(t) = \gamma S(t-1) + (1-\gamma)\Delta\theta^{2}$$
 Hesian Matrix
$$W(t+1) = W(t) \frac{\sqrt{S(t) + \epsilon}}{\sqrt{G(t) + \epsilon}} \frac{\partial}{\partial w(i)} Cost(w(i))$$
 W(t) = Vector W[i] element

 γ 's Value => 0.9~0.999

Hesian Matrix: https://bskyvision.com/661

Animation

애니메이션 http://shuuki4.github.io/deep%20learning/2016/05/20/Gradient-Descent-Algorithm-Overview.html

Adaptive Moment Estimation

Adam

Adam

Moment + Adaptive

Moment is not Momentum Probability Moment

What is Moment? => Kocw 김충락 교수님(수리통계학)

1-Moment = > E[X]

Not Known Moment => Estimation

 $2-Moment = > E[X^2]$

Adam

$$m_t = \beta_1 m_{t-1} + (1 + \beta_1) g_t$$

$$v_t = \beta_2 v_{t-1} + (1 + \beta_2) g_t^2$$

If Initial m, v is 0, weight=>Zero biased

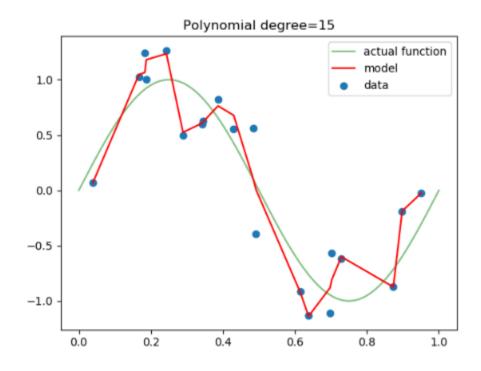
If decay rate is small, $(\beta_1, \beta_2 \ close \ one)$ weight=>biased

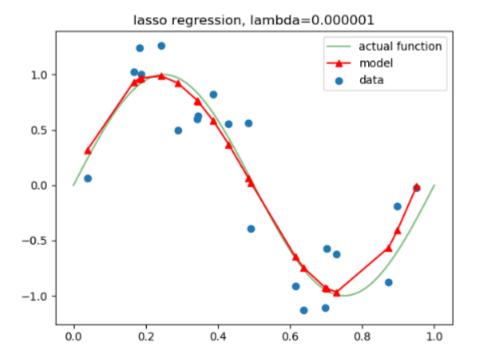
$$m_t = \beta_1 m_{t-1} + (1 + \beta_1) g_t$$

Regularization

Regularization

Regularization





Lasso

L1-Norm

L1-Norm

Lasso

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} \left(h(x^i) - y^i \right)^2$$

$$J(\theta) = \frac{1}{2m} \sum_{i} \left(h(x^i) - y^i \right)^2 + \frac{\tau}{2} \sum_{i} |\theta_j|$$

Ridge

L2-Norm

L2-Norm

Ridge

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} \left(h(x^i) - y^i \right)^2$$

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{\infty} \left(h(x^i) - y^i \right)^2 + \frac{\tau}{2} \sum_{i=1}^{\infty} \theta_j^2$$

L2-Norm

Ridge

$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^i) - y^i) x_j^i$$

$$\theta_j \coloneqq \theta_j (1 - \alpha \frac{\tau}{m}) - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^i) - y^i) x_j^i$$

감사합니다 THANK YOU