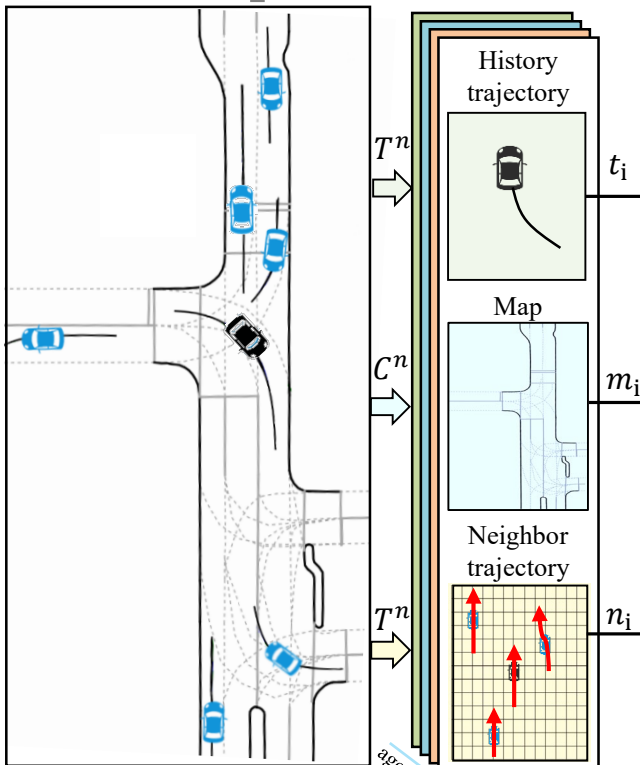
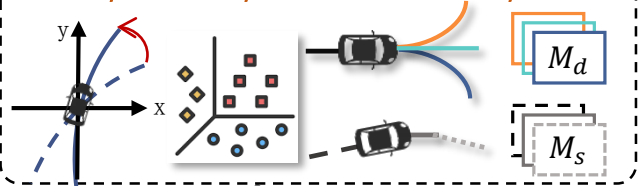
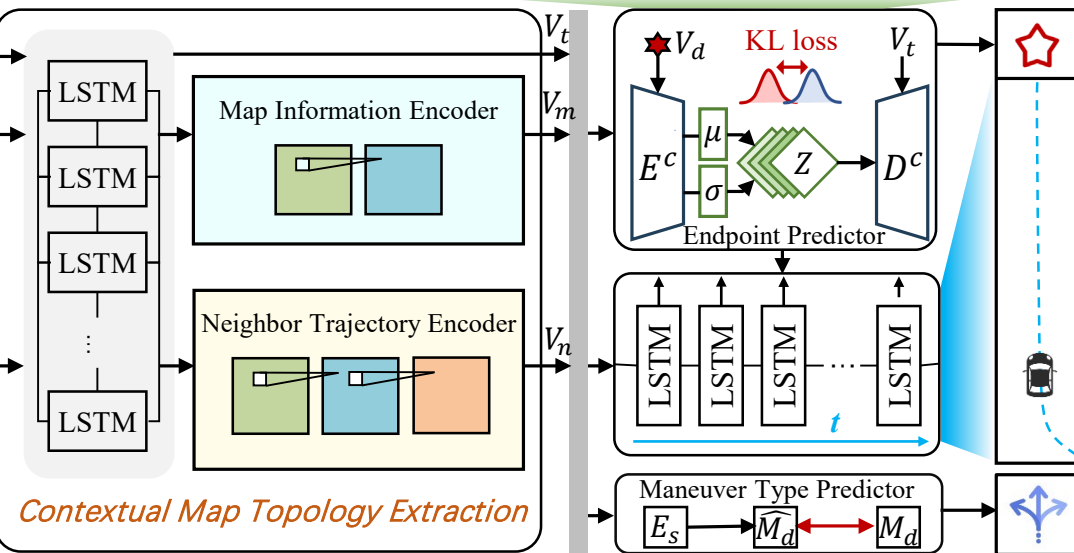
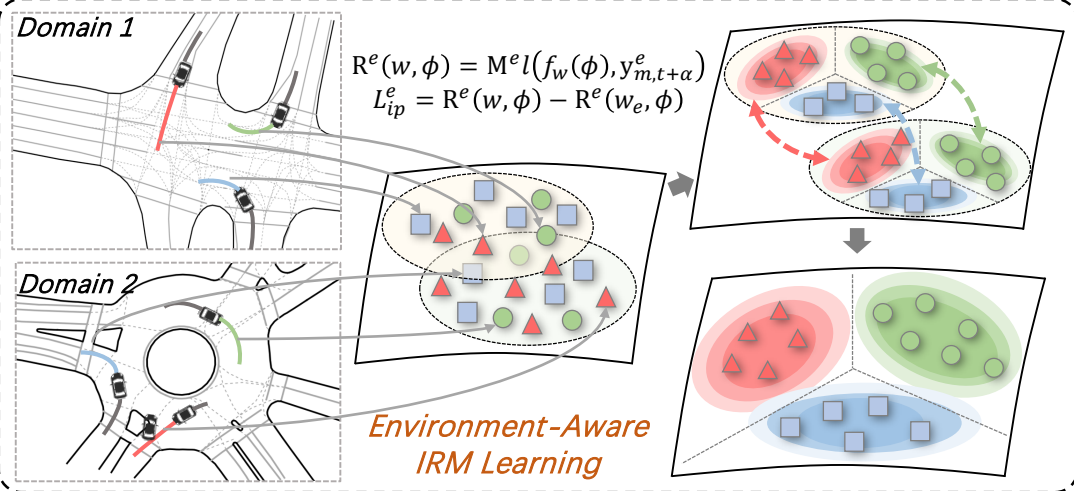


Self-supervised prior maneuver acquisition



Interaction scenario n

Trajectory related



Contextual Map Topology Extraction