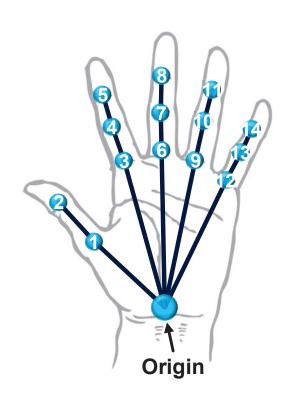


WR-Hand:

Wearable Armband Can Track User's Hand

Yang Liu, Chengdong Lin, Zhenjiang Li City University of Hong Kong

Human Hand Tracking











SL Translation

HCI

Gaming







Smart Car

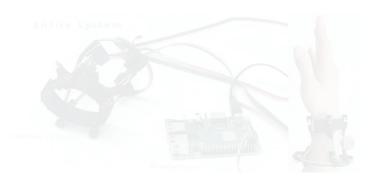


AR/VR

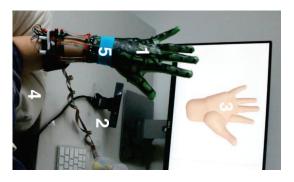
Existing Works



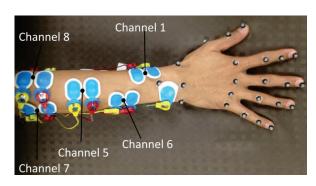
Leap Motion



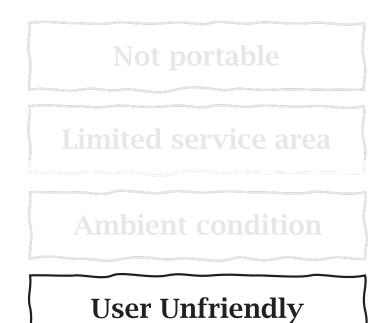
Wearable thermal cameras



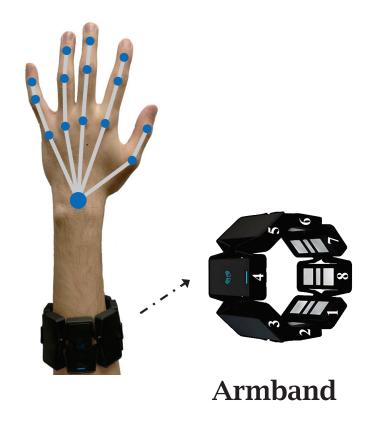
Soft glove

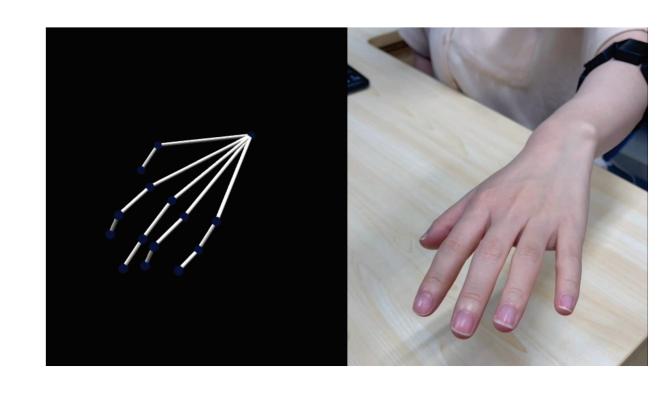


Isolated EMG sensors



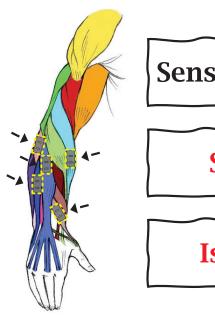
Our System: WR-Hand





EMG Sensors

Existing bio-medical models:

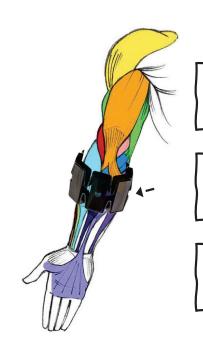


Sensing specific spots

Strong signals

Isolated signals

Using armband:



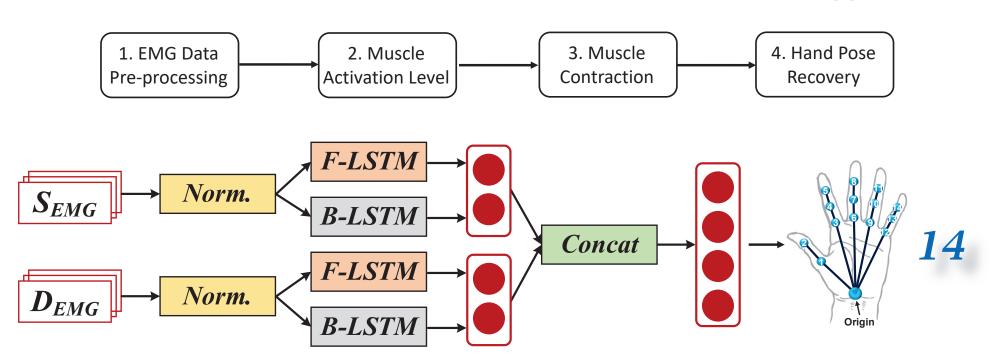
Sensing cross-section

Weak signals

Mixed signals

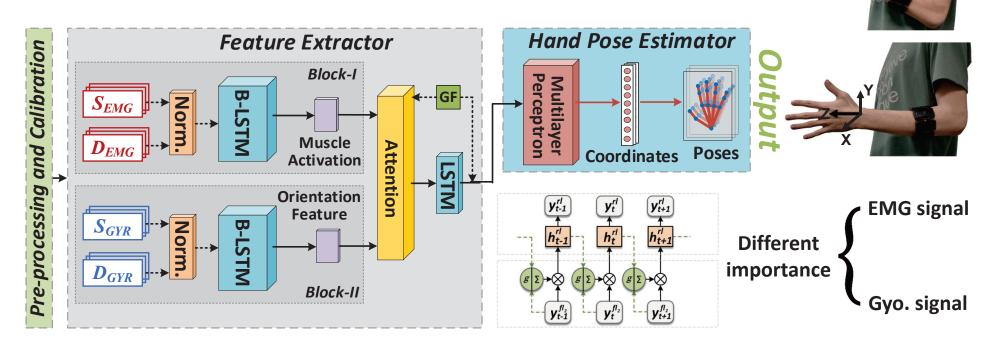
Primary Hand Pose Recovery

- Bio-models meet armband data? RNN-enhanced model
 - Recursive functions → Ineffective
- - Following bio-model suggested steps



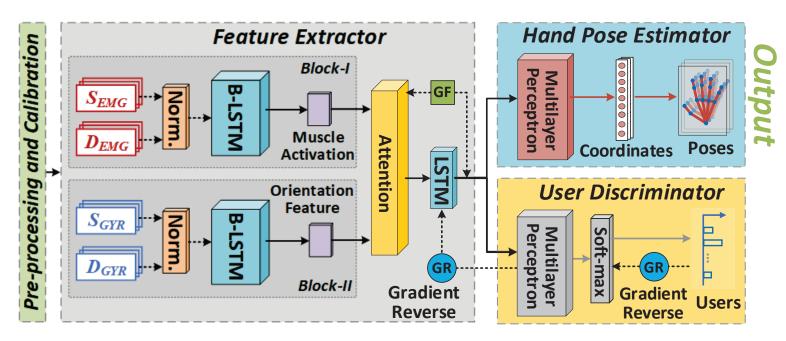
Upgraded Hand Poses

- Place poses in a global coordinate system
 - Forearm orientation



Practical Issue #1: New Users

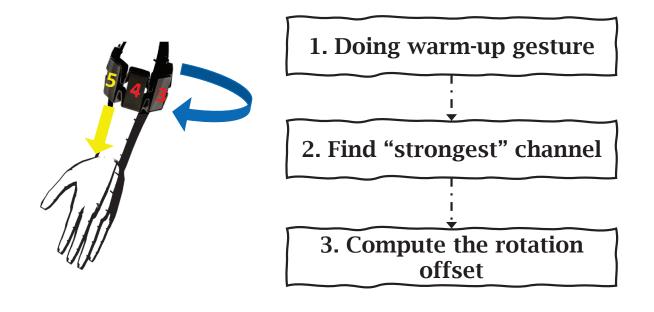
- Remove the user-dependent features
 - Skip training for new users (plug-and-play)

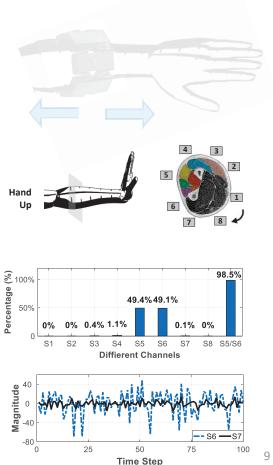


$$L_{loss}(\theta_f, \theta_e, \theta_d) = L_{tra}(\theta_f, \theta_e) - \lambda \times L_{dis}(\theta_f, \theta_d)$$

Practical Issue #2: Armband Position

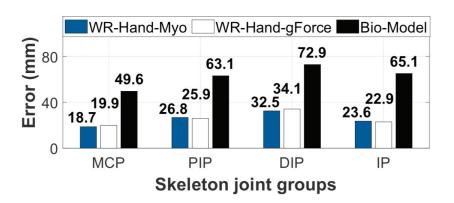
- **Armband wearing-position differences**
 - Distance difference → Normalization
 - **Rotation difference** → **Virtual re-ordering**





Evaluation

- Two armbands
 - Myo data for training and testing
 - gForce data for testing only
- 18 subjects
 - Data from 10 subjects for training and testing
 - Data from other 8 subjects for testing only







Testing Training

Our performance

- 2.57cm error using Myo
- 2.61cm error using gForce
- >58% error reduction

Conclusion

- Topic:
 - Human hand tracking using a Commercial armband
- Design considerations:
 - Hand tracking of 14 skeleton points with arm orientation
 - Plug-and-play version for new users
 - Compensation for armband wearing position

Thank you Q&A

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