

Busan Software Meister High School

# ***MICROPROCESSOR***

2309 양유빈

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# 가변저항값에 따라 LED밝기 변경

Change LED brightness according to variable resistance value

LED(PC6)의 밝기가 가변저항(ADC1\_IN10, PC0)에 따라 변화하도록 프로그래밍

- TIM3 설정 : Clock = 72MHz, PSC = 71(72-1), Counter = 999(1000-1)
- ADC1 설정 : Clock = 12MHz, Continuous Conversion Mode = Enable, Sampling Time = 13.5
- 참고) -  $CCR1 = (adc\_value * 1000) / 4095$

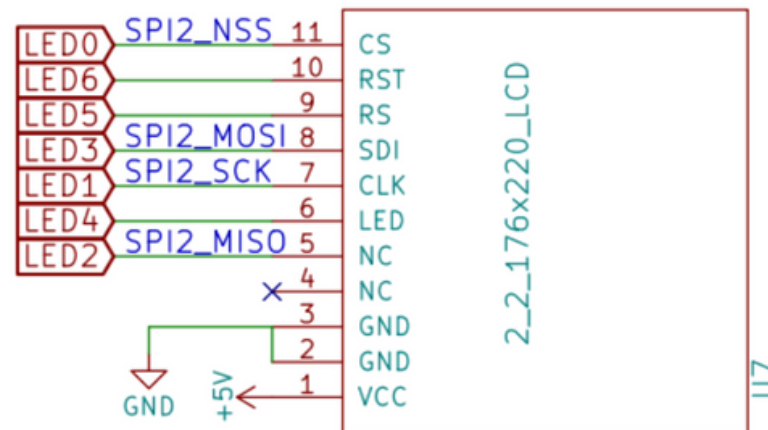
```
10
47 /* USER CODE BEGIN PV */
48 uint16_t adc_value;
49 uint16_t led_ccr1;
50 /* USER CODE END PV */
```

```
95 MX_TIM3_Init();
96 /* USER CODE BEGIN 2 */
97 HAL_ADCEx_Calibration_Start(&hadcl);
98 HAL_ADC_Start(&hadcl);
99 HAL_TIM_PWM_Start(&htim3, TIM_CHANNEL_1);
100 /* USER CODE END 2 */
101
102 /* Infinite loop */
103 /* USER CODE BEGIN WHILE */
104 while (1)
105 {
106     if(HAL_ADC_PollForConversion(&hadcl, 10) == HAL_OK) {
107         adc_value = HAL_ADC_GetValue(&hadcl);
108         led_ccr1 = (adc_value*1000)/4095;
109         __HAL_TIM_SET_COMPARE(&htim3, TIM_CHANNEL_1, led_ccr1);
110     }
111 }
112 /* USER CODE END WHILE */
113
114 /* USER CODE BEGIN 3 */
115 }
116 /* USER CODE END 3 */
117 }
```

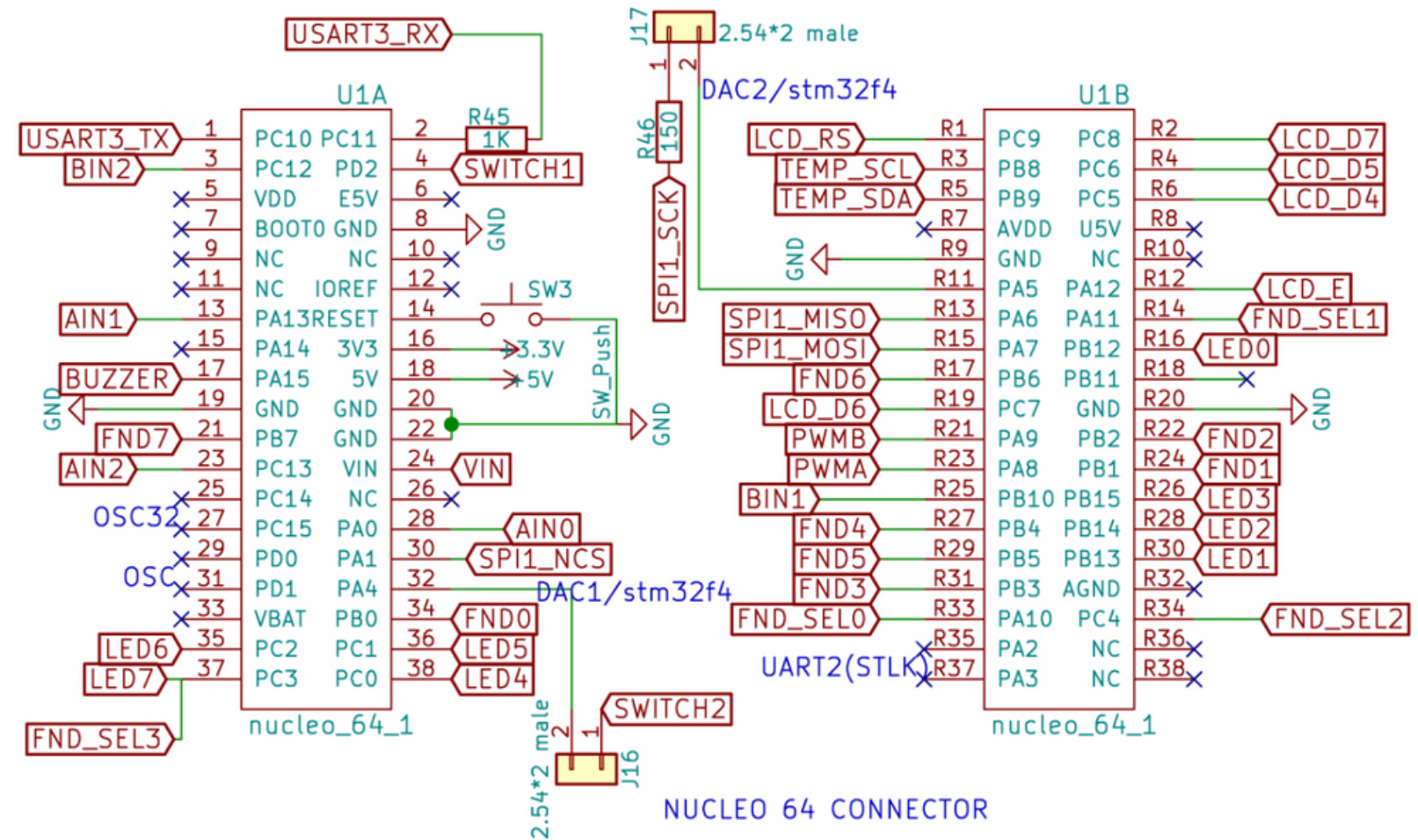
# ADC1 IN10~IN13

ADC1 IN10~IN13

- PC0 : ADC1\_IN10
- PC1 : ADC1\_IN11
- PC2 : ADC1\_IN12
- PC3 : ADC1\_IN13



PB12  
PC2  
PC1  
PB15  
PB13  
PC0  
PB14  
  
GND  
GND  
5V

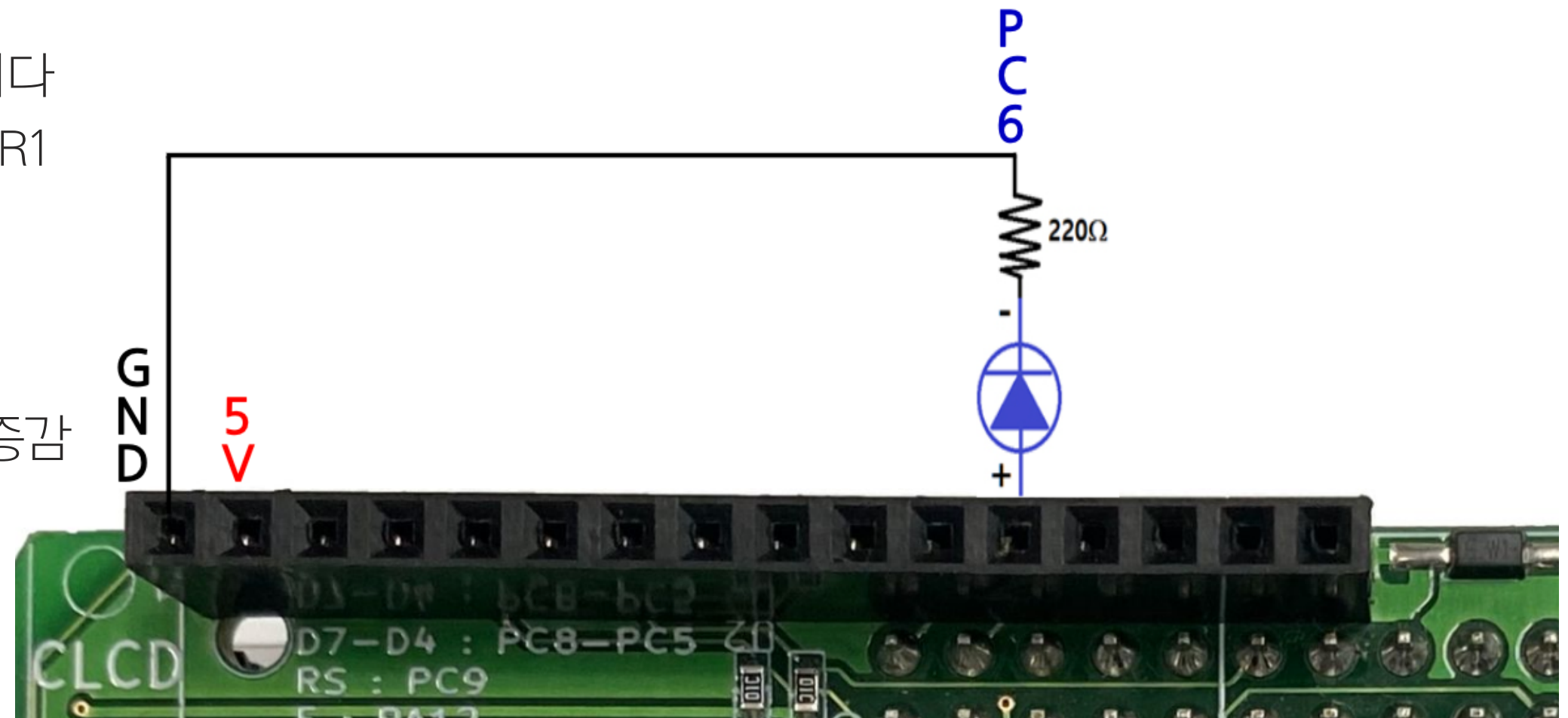


# 변화하는 LED 밝기값 출력

Output of changing LED brightness value

LED(PC6)의 밝기가 반복적으로 변화(점점 밝아지다가 점점 어두워짐)하도록 하고, 그 때의 ARR값, CCR1의 값을 화면에(Tera Term) 출력

- TIM3 설정 : Clock = 72MHz, PSC = 71(72-1), Counter = 999(1000-1)
- PWM Pulse(Duty Cycle)값 0.5초마다 100씩 증감
- 참고)
  - Counter Period : ARR 값 설정
  - Pulse(Duty Cycle) : CCR1 값 설정





# 변화하는 LED 밝기값 출력

Output of changing LED brightness value

```
60 /* Private user code -----
61  /* USER CODE BEGIN 0 */
62 int __io_putchar(int ch) {
63     HAL_UART_Transmit(&huart2, (uint8_t *)&ch, 1, 0xFFFF); // 0xFFFF
64     if (ch == '\n') {
65         HAL_UART_Transmit(&huart2, (uint8_t *)"\r", 1, 0xFFFF);
66     }
67     return ch;
68 }
69
70 void print_pwm() {
71     led_ccr1 = __HAL_TIM_GET_COMPARE(&htim3, TIM_CHANNEL_1);
72     led_arr = __HAL_TIM_GET_AUTORELOAD(&htim3);
73     printf("LED_ARR : %d, LED_CRR1 : %d\n\n", led_arr, led_ccr1);
74 }
75 /* USER CODE END 0 */
76
24 #include<stdio.h>
25 /* USER CODE END Includes */
--
112 /* USER CODE BEGIN WHILE */
113 while (1)
114 {
115     #if 0
116     // led 밝기 연속 변화
117     for (int i = 0; i < 1000; i += 10) {
118         __HAL_TIM_SET_COMPARE(&htim3, TIM_CHANNEL_1, i); // TIM3 -> CCR1 = i;
119         HAL_Delay(100);
120     }
121     for (int j = 999; j >= 0; j -= 10) {
122         __HAL_TIM_SET_COMPARE(&htim3, TIM_CHANNEL_1, j); // TIM3 -> CCR1 = j;
123         HAL_Delay(100);
124     }
125     #endif
126     for (int i = 0; i < 1000; i += 100) {
127         __HAL_TIM_SET_COMPARE(&htim3, TIM_CHANNEL_1, i);
128         print_pwm();
129         HAL_Delay(500);
130     }
131     for (int i = 1000; i > 0; i -= 100) {
132         __HAL_TIM_SET_COMPARE(&htim3, TIM_CHANNEL_1, i); // TIM3 -> CCR1 = j;
133         print_pwm();
134         HAL_Delay(100);
135     }
136 }
137 /* USER CODE END WHILE */
138
139 /* USER CODE BEGIN 3 */
```