

pcl::IterativeClosestPoint< PointT, PointT >

ModifiedICP\_G

ModifiedICP\_T< pcl::IterativeClosestPoint< PointT, PointT >, PointT >

ModifiedICP< PointT >

```
classDiagram
    class A["pcl::IterativeClosestPoint< PointT, PointT >"]
    class B["ModifiedICP_G"]
    class C["ModifiedICP_T< pcl::IterativeClosestPoint< PointT, PointT >, PointT >"]
    class D["ModifiedICP< PointT >"]
    C --> A
    C --> B
    D --> C
```