First-Order Low/Highpass Filter Design

Yangang Cao

February 13, 2019

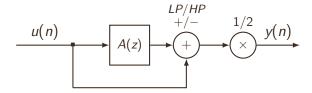
Definition of low/highpass filter:

- Lowpass (LP) filters select low frenquencies up to the cut-off frenquency f_c and attenuate frenquencies higher than f_c .
- **Highpass (HP)** filters select high frenquencies higher than f_c and attenuate frenquencies below f_c .

A first-order lowpass/highpass filter can be achieved by adding or subtracting (+/-) the output signal from the input signal of a first-order allpass filter

$$H(z) = rac{1}{2}(1 \pm A(z)) \quad (LP/HP + /-)$$
 $A(z) = rac{z^{-1} + c}{1 + cz^{-1}}$
 $c = rac{ an(\pi f_c/f_S) - 1}{ an(\pi f_c/f_S) + 1}.$

Block diagram of first-order low/highpass filter:



The difference equations of first-order lowpass filter are

$$x(n) = u(n) - cx(n-1)$$

$$y(n) = \frac{1+c}{2}x(n) + \frac{1+c}{2}x(n-1),$$

and corresponding state and output equations are

$$x(n) = -cx(n-1) + u(n)$$

$$y(n) = \frac{1-c^2}{2}x(n-1) + \frac{1+c}{2}u(n).$$

Matlab code:

The difference equations of first-order highpass filter are

$$x(n) = u(n) - cx(n-1)$$

$$y(n) = \frac{1-c}{2}x(n) + \frac{c-1}{2}x(n-1)$$

and corresponding state and output equations are

$$x(n) = -cx(n-1) + u(n)$$

$$y(n) = \frac{c^2 - 1}{2}x(n - 1) + \frac{1 - c}{2}u(n)$$

Matlab code: