Second-Order Bandpass/Bandreject Filter Design

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February 15, 2019

Definition of Bandpass/Bandreject filter:

- **Bandpass (BP)** filters select frenquencies between a lower cut-off frenquency f_{cl} and a higher cut-off frenquency f_{ch}. Frenquencies below f_{cl} and frenquencies higher than f_{ch} are attenuated.
- **Bandreject (BR)** filters attenuate frenquencies between a lower cut-off frenquency f_{cl} and a higher cut-off frenquency f_{ch}. Frenquencies below f_{cl} and frenquencies higher than f_{ch} are passed.

Second-order bandpass and bandreject filters can be described by the following transfer function

$$H(z) = \frac{1}{2}[1 \mp A(z)] \quad (BP/BR - /+)$$

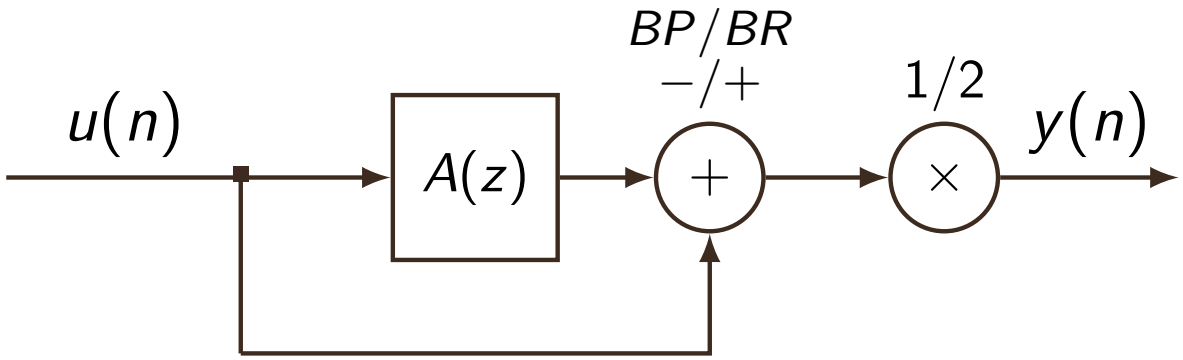
$$A(z) = \frac{-c + d(1-c)z^{-1} + z^{-2}}{1 + d(1-c)z^{-1} - cz^{-2}}$$

$$c = \frac{\tan(\pi f_b/f_S) - 1}{\tan(\pi f_b/f_S) + 1}$$

$$d = -\cos(2\pi f_c/f_S),$$

where a tunable second-order allpass $A(z)$ with tuning parameters c and d is used. The minus sign (-) denotes the bandpass operation and the plus sign $(+)$ the bandreject operation.

Block diagram of second-order bandpass/bandreject filter:



The difference equations of second-order bandpass filter are

$$x(n) = u(n) - d(1-c)x(n-1) + cx(n-2)$$

$$y(n) = \frac{1+c}{2}x(n) - \frac{1+c}{2}x(n-2),$$

and corresponding state and output equations are

$$\begin{bmatrix} x(n) \\ x(n-1) \end{bmatrix} = \begin{bmatrix} -d(1-c) & c \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x(n-1) \\ x(n-2) \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u(n)$$

$$y(n) = \begin{bmatrix} \frac{d(c^2-1)}{2} & \frac{c^2-1}{2} \end{bmatrix} \begin{bmatrix} x(n-1) \\ x(n-2) \end{bmatrix} + \frac{1+c}{2}u(n).$$

Matlab code:

```
function y = apbandpassunit(audio, para)
% Applies a bandpass filter to the input signal.
% para(1) is the normalized center frequency ...
    in (0,1), i.e. 2*fc/fs.
% para(2) is the normalized bandwidth in (0,1) ...
    i.e. 2*fb/fs.
c = (tan(pi*para(2)/2)-1) / ...
    (tan(pi*para(2)/2)+1);
d = -cos(pi*para(1));
x = [0; 0];
x_1 = 0;
A = [-d*(1-c), c; 1, 0];
B = [1; 0];
C = [d*(c^2-1)/2, (c^2-1)/2];
D = (1+c)/2;
for n=1:length(audio)
    x_1 = A * x + B * audio(n);
    y(n) = C * x + D * audio(n);
    x = x_1;
end
```

The difference equations of second-order bandreject filter are

$$x(n) = u(n) - d(1-c)x(n-1) + cx(n-2)$$

$$y(n) = \frac{1-c}{2}x(n) + d(1-c)x(n-1) + \frac{1-c}{2}x(n-2),$$

and corresponding state and output equations are

$$\begin{bmatrix} x(n) \\ x(n-1) \end{bmatrix} = \begin{bmatrix} -d(1-c) & c \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x(n-1) \\ x(n-2) \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u(n)$$

$$y(n) = \begin{bmatrix} \frac{d(1-c^2)}{2} & \frac{1-c^2}{2} \end{bmatrix} \begin{bmatrix} x(n-1) \\ x(n-2) \end{bmatrix} + \frac{1-c}{2}u(n).$$

Matlab code:

```
function y = apbandrejectunit(audio, para)
% Applies a bandreject filter to the input ...
    signal.
% para(1) is the normalized center frequency ...
    in (0,1), i.e. 2*fc/fs.
% para(2) is the normalized bandwidth in (0,1) ...
    i.e. 2*fb/fs.
c = (tan(pi*para(2)/2)-1) / ...
    (tan(pi*para(2)/2)+1);
d = -cos(pi*para(1));
x = [0; 0];
x_1 = 0;
A = [-d*(1-c), c; 1, 0];
B = [1; 0];
C = [d*(1-c^2)/2, (1-c^2)/2];
D = (1-c)/2;
for n=1:length(audio)
    x_1 = A * x + B * audio(n);
    y(n) = C * x + D * audio(n);
    x = x_1;
end
```