

QUESTION 2 - The Cμ rule

a. we define the following MDP for the server problem:

State space: state S_t will hold all jobs which are still unfinished in the system.

The state space is actually $S = \mathcal{P}(\{1, \dots, n\})$ - the power set of $\{1, \dots, n\}$. Thus $|S| = 2^n$

Action space: action a_t will mark the job chosen by the server. The action space is $A = \{1, \dots, n\}$
Thus $|A| = n$

Transition probabilities: when choosing an action $a_t = i$

there are two options - the job is completed and it is taken out of the system or the job is uncompleted and is putted back in the system. Thus

$$P(S | S_t = B, a_t = i) = \begin{cases} \mu_i & S = B \setminus \{i\} \\ 1 - \mu_i & S = B \\ 0 & \text{else} \end{cases}$$

cost: cost $c_t(S_t, a_t)$ will be the total cost of all jobs which are still in the system. we notice that the cost doesn't depend on the action or the time.

we have

$$c_t(S_t, a_t) = c_t(S_t) = \sum_{i=1}^n \mathbb{I}(i \in S_t) \cdot C_i$$

The total cost we wish to minimize is

$$J^T(S = \{1, \dots, n\}) = E^{T, S} \left(\sum_{t=0}^{\infty} c(S_t) \right)$$

we also notice that once we reached ~~at~~ the state $S_t = \{\}$

the process ends and the cost for all $t \geq T$ is $c_t(S_t) = 0$

Bellman equation:

$$V(S) = \min_{\alpha \in A} \left\{ c(S) + \sum_{S'} P(S' | S, \alpha) V(S') \right\} = c(S) + \min_{\alpha \in A} \left\{ \mu_i V(S \setminus \{i\}) + (1 - \mu_i) V(S) \right\}$$

b. we wish to prove that the stationary policy $j^* = \arg \max_{j \in \{1, \dots, K\}}$ is an optimal policy. we know that a policy is optimal if its Value Function satisfies the Bellman equation. we will compute the value function for the above policy and show that it does.

for convenience we mark $S = \{i_1, \dots, i_K\}$ s.t. the jobs i_1, \dots, i_K are in an ordered way s.t. $M_{i_1} C_{i_1} \geq \dots \geq M_{i_K} C_{i_K}$

In the suggested policy and using the above marking we take job i_1 .

$$V(S) = V(\{i_1, \dots, i_K\}) = (C_{i_1}) + M_{i_1} V(S/\{i_1\}) + (1 - M_{i_1}) V(S)$$

$$\Rightarrow V(S) = \frac{C_{i_1}}{M_{i_1}} + V(S/\{i_1\}) = \frac{1}{M_{i_1}} \sum_{j=1}^K C_{i_j} + V(S/\{i_1\})$$

Applying the recursion to $V(S_K)$ we get

$$V(S) = \frac{1}{M_{i_1}} \sum_{j=1}^K C_{i_j} + V(S/\{i_1\}) = \frac{1}{M_{i_1}} \sum_{j=1}^K C_{i_j} + \dots + \frac{1}{M_{i_K}} \sum_{j=K}^K C_{i_j}$$

Similarly for $V(S/\{i_a\})$ we take C_{i_a} out from each summand and cancel the $\frac{1}{M_{i_a}}$ term

$$V(S/\{i_a\}) = V(S) - \left(C_{i_a} \sum_{j=1}^{a-1} \frac{1}{M_{i_j}} + \frac{1}{M_{i_a}} \sum_{j=a}^K C_{i_j} \right)$$

now we show that for each state S in the Bellman equation holds:

$$V(S) = (C_S) + \min_{i_a \in A} \{ M_{i_a} V(S/\{i_a\}) + (1 - M_{i_a}) V(S) \}$$

$$= (C_S) + V(S) + \min_{i_a \in A} \{ M_{i_a} V(S/\{i_a\}) - M_{i_a} V(S) \}$$

$$(C_S) = - \min_{i_a \in A} \{ M_{i_a} (V(S/\{i_a\}) - V(S)) \} = \max_{i_a \in A} \{ M_{i_a} (V(S) - V(S/\{i_a\})) \}$$

$$= \max_{i_a \in A} \left\{ M_{i_a} C_{i_a} \sum_{j=1}^{a-1} \frac{1}{M_j} + \sum_{j=a}^K C_{i_j} \right\}$$

The maximum above is achieved for $i_a = 1$,
and thus we get:

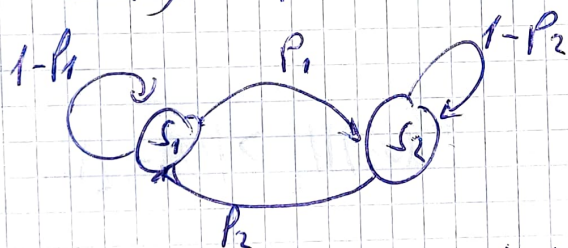
$$= M_1 C_{i_1} \sum_{j=1}^{1-1} \frac{1}{M_j} + \sum_{j=1}^K C_{i_j} = \sum_{j=1}^K C_{i_j} = C(s)$$

Question 3 - Df operator not contracting in Euclidean norm

The fixed operator T^π :

$$(T^\pi(J))(s) = r(s, \pi(s)) + \gamma \sum_{s'} P(s'|s, \pi(s)) J(s')$$

We wish to prove that T^π is not necessarily a contraction in the Euclidean norm. As hinted, we will use the following MDP:



We also define the rewards as $r(s_1) = r_1$, $r(s_2) = r_2$
we will show that for all p_1, p_2, γ , there exist J_1, J_2
such that:

$$\|T^\pi(J_1) - T^\pi(J_2)\|_2 \geq \|J_1 - J_2\|_2$$

First for the above MDP we have:

$$(T^\pi(J))(s_1) = r_1 + \gamma((1-p_1)J(s_1) + p_1 J(s_2))$$

$$\Rightarrow (T^\pi(J_1) - T^\pi(J_2))(s_1) = \gamma((1-p_1)(J_1(s_1) - J_2(s_1)) + p_1(J_1(s_2) - J_2(s_2)))$$

$$T^{\pi}(J_1) - T^{\pi}(J_2) = \begin{pmatrix} \delta(1-p_1)(J_1(s_1) - J_2(s_1)) + p_1(J_1(s_2) - J_2(s_2)) \\ \delta(1-p_2)(J_1(s_2) - J_2(s_2)) + p_2(J_1(s_1) - J_2(s_1)) \end{pmatrix}$$

$$\begin{aligned} \|T^{\pi}(J_1) - T^{\pi}(J_2)\|_2^2 &= \delta^2((1-p_1)^2 + p_1^2)(J_1(s_1) - J_2(s_1))^2 \\ &+ 2(p_1(1-p_1) + p_2(1-p_2))(J_1(s_1) - J_2(s_1))(J_1(s_2) - J_2(s_2)) \\ &+ ((1-p_2)^2 + p_2^2)(J_1(s_2) - J_2(s_2))^2 \end{aligned}$$

We take the following $J_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $J_2 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

for these we have:

$$\|J_1 - J_2\|_2^2 = 1$$

$$\|T^{\pi}(J_1) - T^{\pi}(J_2)\|_2^2 = \delta^2((1-p_2)^2 + p_1^2) = \textcircled{*}$$

Let take $p_1 = 1, p_2 = 0, \delta = 0.8$.

$$\textcircled{*} = 1.28 > 1 = \|J_1 - J_2\|_2^2$$

We have found that for a given J_1, J_2 we

get

$$\|T^{\pi}(J_1) - T^{\pi}(J_2)\|_2 > \|J_1 - J_2\|_2$$

Thus T^{π} is not a contraction under the Euclidean norm.