

## A Appendix

### A.1 Proofs

**Lemma 1.** *If  $\text{mbody}(\mathbf{m}, I_d, I_s) = (J, \overline{I_x} \ \overline{x}, I_e \ e_0)$ , then  $\overline{x} : \overline{I_x}, \text{this} : J \vdash e_0 : I_0$  for some  $I_0 <: I_e$ .*

*Proof.* By the definition of  $\text{mbody}$ , the target method  $\mathbf{m}$  is found in  $J$ . By the method typing rule (T-METHOD), there exists some  $I_0 <: I_e$  such that  $\overline{x} : \overline{I_x}, \text{this} : J \vdash e_0 : I_0$ .  $\square$

**Lemma 2 (Weakening).** *If  $\Gamma \vdash e : I$ , then  $\Gamma, x : J \vdash e : I$ .*

*Proof.* Straightforward induction.  $\square$

**Lemma 3 (Method Type Preservation).** *If  $\text{mbody}(\mathbf{m}, J, J) = (K, \overline{I_x} \_, I_e \_)$ , then for any  $I <: J$ ,  $\text{mbody}(\mathbf{m}, I, J) = (K', \overline{I_x} \_, I_e \_)$ .*

*Proof.* Since  $\text{mbody}(\mathbf{m}, J, J)$  is defined, by (T-INTF) we derive that  $\text{mbody}(\mathbf{m}, I, J)$  is also defined. Suppose that

$$\begin{aligned} \text{findOrigin}(\mathbf{m}, J, J) &= \{I_0\} \\ \text{findOverride}(\mathbf{m}, J, I_0) &= \{K\} \\ \text{findOrigin}(\mathbf{m}, I, J) &= \{I'_0\} \\ \text{findOverride}(\mathbf{m}, I, I'_0) &= \{K'\} \end{aligned}$$

Below we use  $I[\mathbf{m} \uparrow J]$  to denote the type of method  $\mathbf{m}$  defined in  $I$  that overrides  $J$ . We have to prove that  $K'[\mathbf{m} \uparrow I'_0] = K[\mathbf{m} \uparrow I_0]$ . Two facts:

- A. By (T-INTF),  $\text{canOverride}$  ensures that an override between any two original methods preserves the method type. Formally,

$$I_1 <: I_2 \Rightarrow I_1[\mathbf{m} \uparrow I_1] = I_2[\mathbf{m} \uparrow I_2]$$

- B. By (T-METHOD) and (T-ABSMETHOD), any partial override also preserves method type. Formally,

$$I_1 <: I_2 \Rightarrow I_1[\mathbf{m} \uparrow I_2] = I_2[\mathbf{m} \uparrow I_2]$$

By definition of  $\text{findOverride}$ ,  $K <: I_0, K' <: I'_0$ . By Fact B,

$$K[\mathbf{m} \uparrow I_0] = I_0[\mathbf{m} \uparrow I_0] \quad K'[\mathbf{m} \uparrow I'_0] = I'_0[\mathbf{m} \uparrow I'_0]$$

Hence it suffices to prove that  $I'_0[\mathbf{m} \uparrow I'_0] = I_0[\mathbf{m} \uparrow I_0]$ . Actually when calculating  $\text{findOrigin}(\mathbf{m}, J, J)$ , by the definition of  $\text{findOrigin}$  we know that  $I_0 <: J$  and  $I_0[\mathbf{m} \text{ override } I_0]$  is defined. So when calculating  $\text{findOrigin}(\mathbf{m}, I, J)$  with  $I <: J$ ,  $I_0$  should also appear in the set before pruning, since the conditions are again satisfied. But after pruning, only  $I'_0$  is obtained, by definition of  $\text{prune}$  it implies  $I'_0 <: I_0$ . By Fact A, the proof is done.  $\square$

**Lemma 4 (Term Substitution Preserves Typing).** *If  $\Gamma, \bar{x} : \bar{I}_x \vdash e : I$ , and  $\Gamma \vdash \bar{y} : \bar{I}_x$ , then  $\Gamma \vdash [\bar{y}/\bar{x}]e : I$ .*

*Proof.* We prove by induction. The expression  $e$  has the following cases:

**Case Var.** Let  $e = x$ . If  $x \notin \bar{x}$ , then the substitution does not change anything. Otherwise, since  $\bar{y}$  have the same types as  $\bar{x}$ , it immediately finishes the case.

**Case Invk.** Let  $e = e_0.m(\bar{e})$ . By (T-INVK) we can suppose that

$$\Gamma, \bar{x} : \bar{I}_x \vdash e_0 : I_0 \quad \text{mbody}(m, I_0, I_0) = (\_, \bar{J} \_, I \_)$$

$$\Gamma, \bar{x} : \bar{I}_x \vdash \bar{e} : \bar{I}_e \quad \bar{I}_e <: \bar{J} \quad \Gamma, \bar{x} : \bar{I}_x \vdash e : I$$

By induction hypothesis,

$$\Gamma \vdash [\bar{y}/\bar{x}]e_0 : I_0 \quad \Gamma \vdash [\bar{y}/\bar{x}]\bar{e} : \bar{I}_e$$

Again by (T-INVK),  $\Gamma \vdash [\bar{y}/\bar{x}]e : I$ .

**Case New.** Straightforward.

**Case Anno.** Straightforward by induction hypothesis and (T-ANNO).  $\square$

## Proof for Theorem 1

*Proof.*

**Case S-Invk.** Let

$$e = ((J)\text{new } I()).m(\bar{v}) \quad \Gamma \vdash e : I_e$$

$$e' = (I_{e_0})[(\bar{I}_x)\bar{v}/\bar{x}, (I_0)\text{new } I()/\text{this}]e_0$$

$$\text{mbody}(m, I, J) = (I_0, \bar{I}_x \bar{x}, I_{e_0} e_0)$$

Since  $\text{mbody}(m, I, J)$  is defined, the definition of  $\text{mbody}$  ensures that  $I <: J$ . And since  $e$  is well-typed, by (T-INVK),

$$\Gamma \vdash \bar{v} : \bar{I}_v \quad \bar{I}_v <: \bar{I}_x$$

By the rules (T-ANNO) and (T-NEW),

$$\Gamma \vdash \overline{(\bar{I}_x)\bar{v}} : \bar{I}_x \quad \Gamma \vdash (I_0)\text{new } I() : I_0$$

On the other hand, by Lemma ??,

$$\bar{x} : \bar{I}_x, \text{this} : I_0 \vdash e_0 : I'_{e_0} \quad I'_{e_0} <: I_{e_0}$$

By Lemma ??,

$$\Gamma, \bar{x} : \bar{I}_x, \text{this} : I_0 \vdash e_0 : I'_{e_0}$$

Hence by Lemma ??, the substitution preserves typing, thus

$$\Gamma \vdash [(\bar{I}_x)\bar{v}/\bar{x}, (I_0)\text{new } I()/\text{this}]e_0 : I'_{e_0}$$

Since  $I'_{e_0} <: I_{e_0}$ , the conditions of (T-ANNO) are satisfied, hence  $\Gamma \vdash e' : I_{e_0}$ . Now we only need to prove that  $I_{e_0} = I_e$ . Since  $I_{e_0}$  is from  $\text{mbody}(\mathbf{m}, I, J)$ , whereas  $I_e$  is from  $\text{mbody}(\mathbf{m}, J, J)$ , by the rule (T-INVK) on  $e$ . Since  $I <: J$ , by Lemma ??,  $I_{e_0} = I_e$ .

**Case C-Receiver.** Straightforward induction.

**Case C-Args.** Straightforward induction.

**Case C-StaticType.** Immediate by (T-ANNO).

**Case C-FReduce.** Immediate by (T-ANNO) and induction.

**Case C-AnnoReduce.** Immediate by (T-ANNO) and transitivity of  $<:$ .  $\square$

## Proof for Theorem 2

*Proof.* Since  $e$  is well-typed, by (T-INVK) and (T-ANNO) we know that

$$I <: J, \text{ and } \text{mbody}(\mathbf{m}, J, J) \text{ is defined}$$

By (T-INTF),  $\text{mbody}(\mathbf{m}, I, J)$  is also defined, and the type checker ensures the expected number of arguments.

On the other hand, since  $I <: J$ , by the definition of `findOrigin`,

$$\text{findOrigin}(\mathbf{m}, I, J) \subseteq \text{findOrigin}(\mathbf{m}, I, I)$$

By (T-NEW), `canOverride(I) = True`. By the definition of `canOverride`, any  $J_0 \in \text{findOrigin}(\mathbf{m}, I, I)$  satisfies that `findOverride(m, I, J0)` contains only one interface, in which the  $\mathbf{m}$  that overrides  $J_0$  is a concrete method. Therefore  $\text{mbody}(\mathbf{m}, I, J)$  also provides a concrete method, which finishes the proof.  $\square$