

Grassmann Valued Gaussian Processes (GrassGP) for Probabilistic Active Subspaces *

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1 Introduction

Dimension reduction is a task of vital importance in the modern day fields of data analysis and scientific computing. Simulations and mathematical models are increasingly important tools in the study of complex physical processes in many scientific and engineering disciplines. Unfortunately, complex mathematical models often involve a large number of parameters, leading to increased computational intensity as well as to

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a degradation in model performance, a phenomenon infamously referred to as *the curse of dimensionality*.

Many statistical/machine learning tasks boil down to approximating some unknown function $f : \mathbb{R}^d \rightarrow \mathbb{R}$. In many real world applications the dimension d of the domain is very large and many popular approaches for estimating f , such as Gaussian process (GP) regression, suffer from the aforementioned *curse of dimensionality*. However, suppose that our function f is such that not all of the d input variables are significant, and only a subset M of \mathbb{R}^d matters. Learning such a subspace M allows us to perform *model order reduction* which can enable us to emulate the true function f more efficiently. This idea originates in the study of *Active subspaces (AS)* [2], where the active subspace can be thought of as the collection of directions along which f is most sensitive to perturbations (on average). This concept will be expanded on in more detail in Section 1.4.

In the original formulation of active subspaces one makes the assumption that there exists a **single global** dimension reducing subspace and any emulators based on AS approximations are constructed within this single subspace. In practice such an assumption does not always hold, especially when dealing with highly complex models which can exhibit diverse behaviour across different parameter regimes. This observation naturally motivates one to instead consider finding **different** low dimensional subspaces which are only valid locally in some subregion of the original input space. This task leads one to consider the formal problem of learning a subspace-valued mapping $P : \mathbb{R}^d \rightarrow G(d, n)$, where $G(d, n)$ is the Grassmann manifold of all n -dimensional (linear) subspaces of \mathbb{R}^d . This problem is a member of the more general field of research which deals with the statistical analysis of data lying in a Riemannian manifold. In particular, in this paper we will develop and investigate a probabilistic model based on GPs which can be used to interpolate a field of Grassmann-valued response variables. I.e. given a set of N spatially indexed points in $G(d, n)$, $\{(\mathbf{x}_i, P(\mathbf{x}_i))\}_{i=1}^N$, we will develop a probabilistic model capable of making predictions for $P(\tilde{\mathbf{x}})$ at unobserved test points $\tilde{\mathbf{x}} \in \mathbb{R}^d$.

add references to development of active subspaces in related work section, see Pranay's paper.

1.1 Related Work

Read these references more closely and expand on them as well as contrasting them with our method.

The main motivation of this paper stems from the literature surrounding active subspaces. The early development of active subspaces can be attributed to the work of Samarov [5], while more recent developments are due to the works of Constantine et al. [2, 1, 3].

There has been extensive research into the problem of learning a subspace-valued mapping. These works include non-parametric methods [12, see also references therein] as well as semi-parametric methods [8]. The approach we investigate in this paper is motivated by that taken in [4] where we utilise a GP instead of a simple linear regression to allow us to more flexibly discover the spatial dependence of our manifold valued field. The linear model approach taken in [4] builds on the work of [9]. In [13] another GP based probabilistic model is considered for this problem.

Read this and make sure this is an accurate statement.

There are also several works which lie at the intersection of the study of ridge functions and active subspaces. Such works include [7, 10, 6].

The idea of considering several different low dimensional subspaces instead of one global active subspace is not new and has been investigated in [11].

1.2 Contributions

1.3 Structure of the Paper

1.4 Background

2 Grassmann Valued Gaussian Processes

3 Experiments

4 Conclusion

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Supplementary Material

For: Grassmann Valued Gaussian Processes (GrassGP) for Probabilistic
Active Subspaces^{*}

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S1 Implementation Details for Experiments

In this section we present remarks which give further details on the implementation of the experiments in Section 3.

S2 Proofs

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