

An overview of data calibration algorithms of NeuLAND in the R³B setup

Yanzhao Wang¹, Paula Ulrich¹, Igor Gasparic², Andreas Zilges¹

¹ University of Cologne, Institute for Nuclear Physics, Germany

² GSI Helmholtzzentrum für Schwerionenforschung, Germany

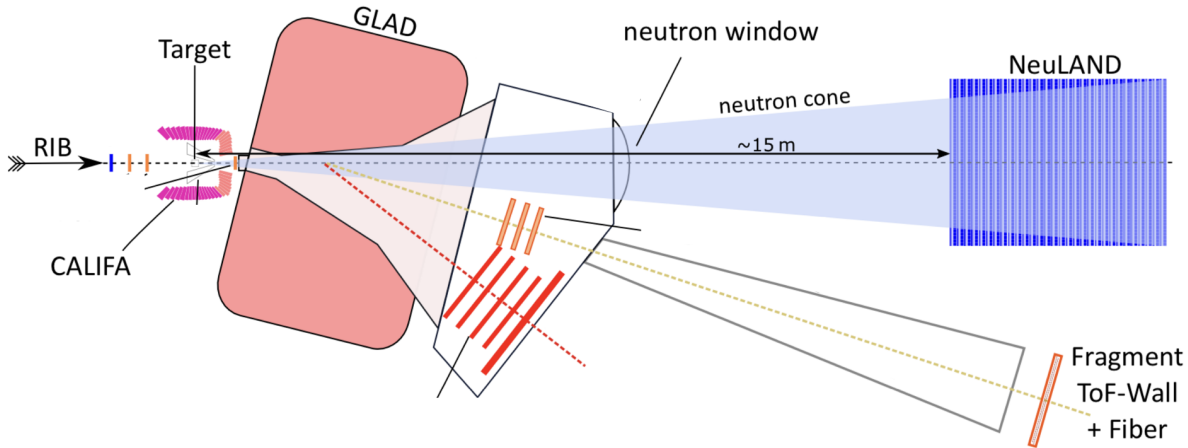
HK 44.4
DPG-Frühjahrstagung
Cologne 2025

Supported by BMBF (05P21PKFN1)



Email: ywang@ikp.uni-koeln.de

NeuLAND setup in R³B^[1]



^[1] K. Boretzky *et al.*, Nucl. Instrum. Methods Phys. Res., Sect. A **1014**, 165701 (2021).

NeuLAND setup in R³B^[1]

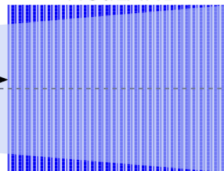


neutron window

Geometry:

- 26 planes
- $250 \times 250 \text{ cm}^2$
- 50 scintillators each plane
- 2600 PMTs in total

NeuLAND



Fragment
ToF-Wall
+ Fiber

^[1] K. Boretzky *et al.*, Nucl. Instrum. Methods Phys. Res., Sect. A **1014**, 165701 (2021).

NeuLAND setup in R³B^[1]



neutron window

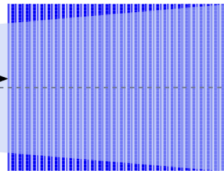
Geometry:

- 26 planes
- $250 \times 250 \text{ cm}^2$
- 50 scintillators each plane
- 2600 PMTs in total

Measurements:

- interaction position
- interaction time
- energy deposition

NeuLAND

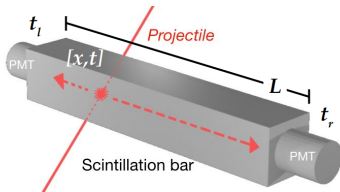


Fragment
ToF-Wall
+ Fiber

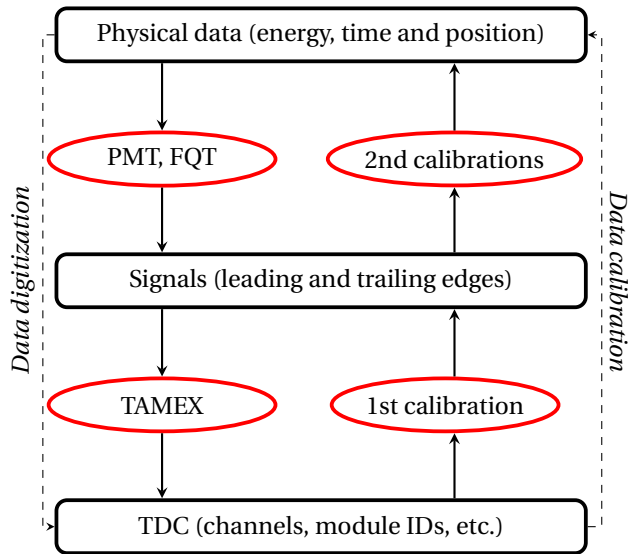
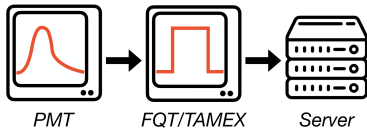
^[1] K. Boretzky *et al.*, Nucl. Instrum. Methods Phys. Res., Sect. A **1014**, 165701 (2021).

Processes of digitization

Physical interactions:

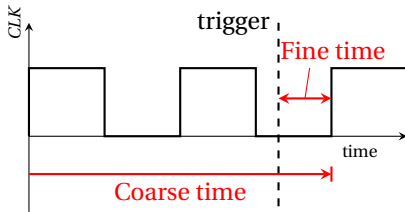


Digitization of PMT signals:



Time measurement and TDC calibration

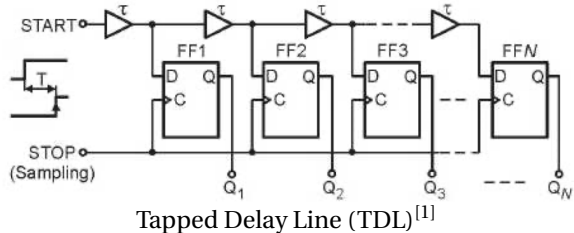
Time measurement with clocks:



Real time calculation:

$$T_{\text{real}} = T_{\text{coarse}} - T_{\text{fine}}$$

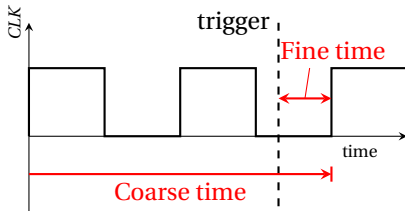
- T_{real} : Time value relative to START detector
- T_{coarse} : Clock cycles with a frequency of 200 MHz
- T_{fine} : Fine channel numbers (TDL)



^[1]J. Kalisz, *Metrologia* **41**, 17 (2003).

Time measurement and TDC calibration

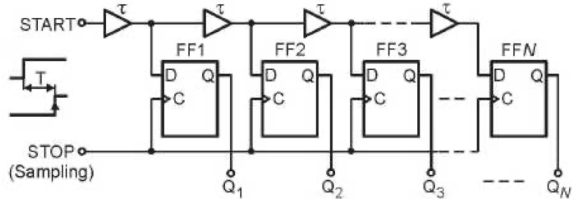
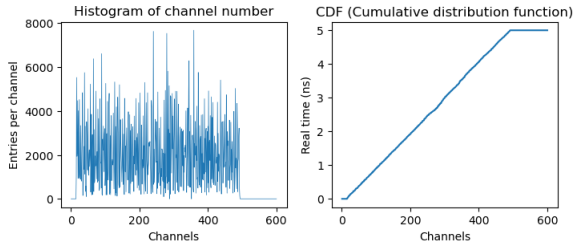
Time measurement with clocks:



Real time calculation:

$$T_{\text{real}} = T_{\text{coarse}} - T_{\text{fine}}$$

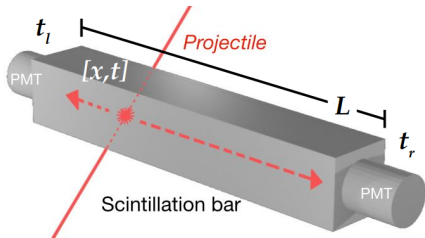
- T_{real} : Time value relative to START detector
- T_{coarse} : Clock cycles with a frequency of 200 MHz
- T_{fine} : Fine channel numbers (TDL)

Tapped Delay Line (TDL)^[1]

TDC Calibration (Time resolution ~ 10 ps)

[1] J. Kalisz, Metrologia 41, 17 (2003).

Position, time and energy calibration parameters



Position-Time calibration:

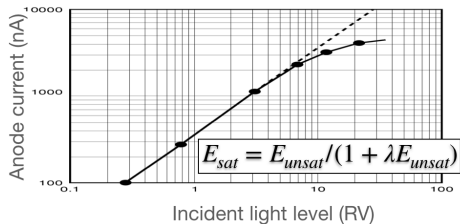
Interaction time:

$$t = \frac{t_r + t_l}{2} - \frac{L}{2 \cdot C_e} + t_{\text{sync}}$$

Interaction position:

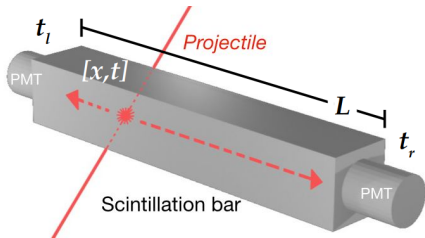
$$x = \frac{C_e}{2} (t_r - t_l + t_{\text{offset}})$$

PMT saturation effect^[1]:



^[1] *Photomultiplier tubes: basics and applications*, 3a, Hamamatsu (Nov. 2007), p. 197.

Position, time and energy calibration parameters



Position-Time calibration:

Interaction time:

$$t = \frac{t_r + t_l}{2} - \frac{L}{2 \cdot C_e} + t_{\text{sync}}$$

Interaction position:

$$x = \frac{C_e}{2} (t_r - t_l + t_{\text{offset}})$$

Energy calibration relations:

Light attenuation effect:

$$I_{\text{PMT}} = E_{\text{dep}} \cdot \exp(-\alpha \cdot l)$$

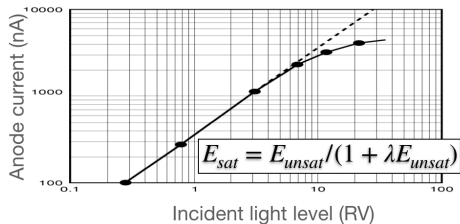
PMT saturation:

$$I_{\text{sat}} = I_{\text{PMT}} \cdot (1 + \lambda \cdot I_{\text{PMT}})$$

PMT gain:

$$W = \mathcal{G} \cdot I_{\text{sat}} + W_0$$

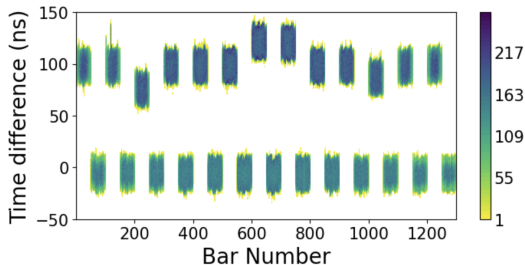
PMT saturation effect^[1]:



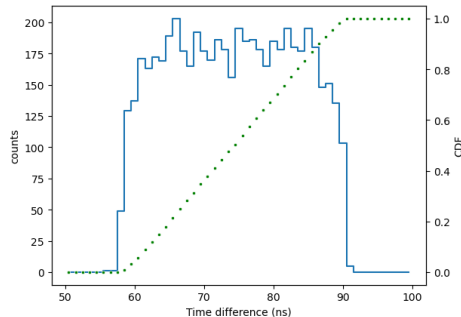
^[1] *Photomultiplier tubes: basics and applications*, 3a, Hamamatsu (Nov. 2007), p. 197.

New position calibration

Time differences of adjacent PMTs:



Parameter fitting:

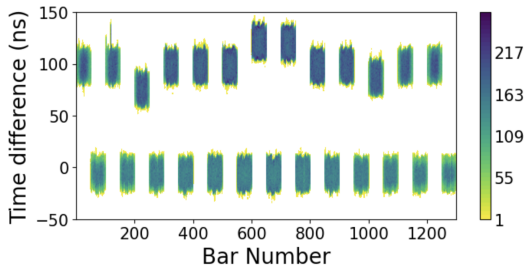


Calibration steps:

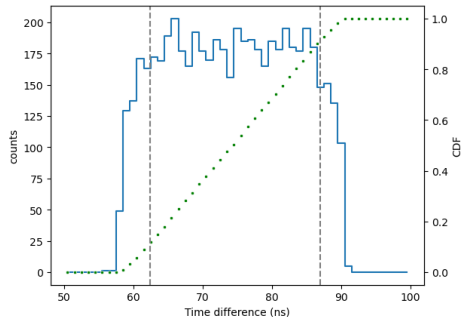
1. Collect time differences of adjacent PMT signals
2. Normalize the distribution and convert to the CDF for each bar
3. Linear fitting of the CDF within its quantiles of 0.05 to 0.95

New position calibration

Time differences of adjacent PMTs:



Parameter fitting:

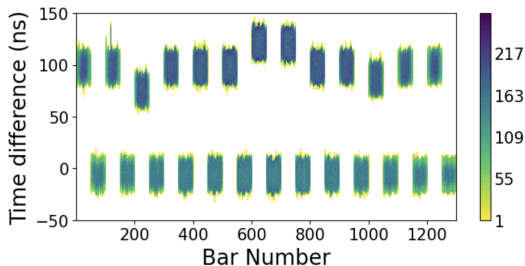


Calibration steps:

1. Collect time differences of adjacent PMT signals
2. Normalize the distribution and convert to the CDF for each bar
3. Linear fitting of the CDF within its quantiles of 0.05 to 0.95

New position calibration

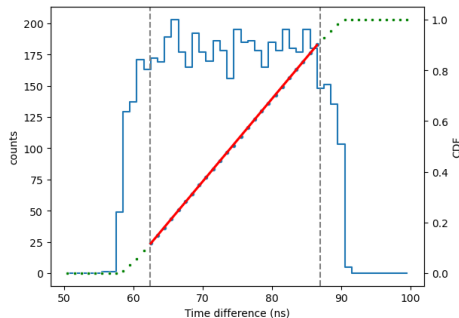
Time differences of adjacent PMTs:



Calibration steps:

1. Collect time differences of adjacent PMT signals
2. Normalize the distribution and convert to the CDF for each bar
3. Linear fitting of the CDF within its quantiles of 0.05 to 0.95

Parameter fitting:



Fitting function:

$$y = a \cdot x + 0.5 - a \cdot b$$

Calculation of parameters:

$$C_e = 2 \cdot a \cdot \text{bar length}$$

$$t_{\text{offset}} = b$$

Energy calibration relations

Light attenuation effect for both PMTs:

$$I_{\text{PMT}} = E_{\text{dep}} \cdot \exp(-\alpha \cdot l) \quad (1)$$

PMT saturation:

$$I_{\text{sat}} = I_{\text{PMT}} / (1 + \lambda \cdot I_{\text{PMT}}) \quad (2)$$

PMT gain:

$$W = \mathcal{G} \cdot I_{\text{sat}} + W_0 \quad (3)$$

Assumptions

- PMT saturation factor differs from gain factor by a constant value:
$$\lambda = 0.00175 \times \mathcal{G}$$
- Cosmic muon's stopping power is 1.73 MeV cm^{-1}
- Adjacent PMTs have the same gain factor

Calculation of parameters:

- PMT baseline W_0 is determined by the minimum cut on signal widths (i.e. trailing time – leading time).

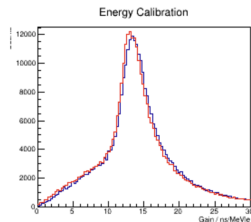
- Calculation of attenuation factor:

$$\alpha = \ln((W_r - W_0) / (W_l - W_0)) / (2 \cdot x)$$

- Calculation of gain factor:

$$\mathcal{G} = \frac{W - W_0}{I_{\text{PMT}} (1 - 0.00175(W - W_0))}$$

PMT gains from each event:



Residual minimization

$$\partial \sum_{j=0}^n \sum_i \frac{(\mathcal{Z}_i^j(g_1, \dots, g_m, p_1^j, \dots, p_l^j))^2}{2(\sigma_i^j)^2} = 0$$

$g_{1\dots m}$: m global parameters

$p_{1\dots l}^j$: l local parameters for the j th μ track

n : the total number of μ tracks

Residual minimization

$$\partial \sum_{j=0}^n \sum_i \frac{(\mathcal{Z}_i^j(g_1, \dots, g_m, p_1^j, \dots, p_l^j))^2}{2(\sigma_i^j)^2} = 0$$

$g_{1\dots m}$: m global parameters

$p_{1\dots l}^j$: l local parameters for the j th μ track

n : the total number of μ tracks

Features

- Simultaneous fitting of all parameters
- Separation to global and local parameters
- Computation complexity independent of local parameter size
- No muon track reconstruction
- Calibration relation **must be linear**

Residual minimization

$$\partial \sum_{j=0}^n \sum_i \frac{(\mathcal{Z}_i^j(g_1, \dots, g_m, p_1^j, \dots, p_l^j))^2}{2(\sigma_i^j)^2} = 0$$

$g_{1\dots m}$: m global parameters

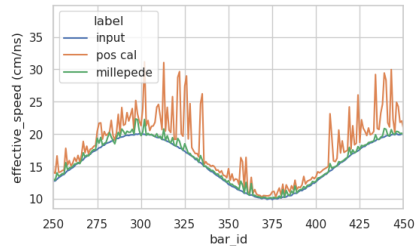
$p_{1\dots l}^j$: l local parameters for the j th μ track

n : the total number of μ tracks

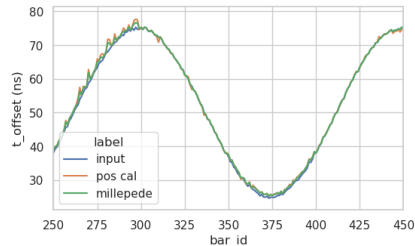
Features

- Simultaneous fitting of all parameters
- Separation to global and local parameters
- Computation complexity independent of local parameter size
- No muon track reconstruction
- Calibration relation **must be linear**

Fine tuning on C_e :



Fine tuning on t_{offset} :

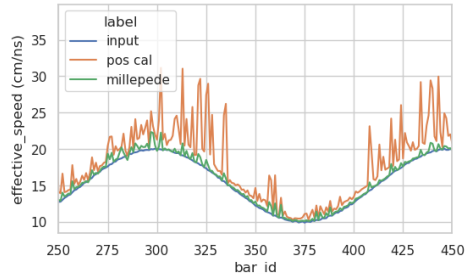
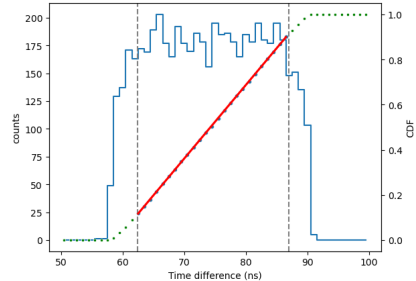


Summary

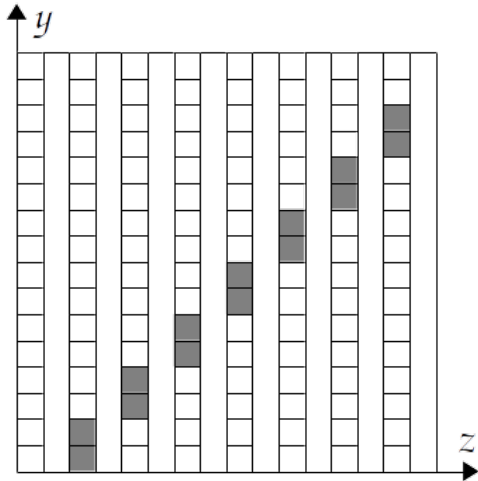
- Principle of digitization processes
- Calibration with TDC for time values
- Calibration with time values for physical values
- Fine tuning with the Millepede-II algorithm

Outlook

- Improve energy calibration
- Apply Millepede-II algorithm on energy-related parameters
- Verify energy parameters via simulation



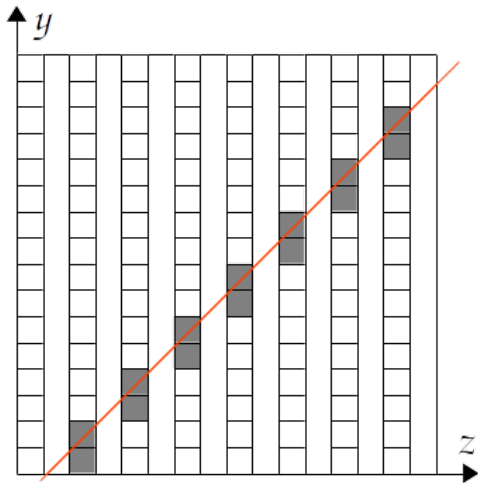
Side view of NeuLAND



Procedures

1. Obtain the positions of bars with signals
2. Reconstruct the muon track from the bar positions
3. Calculate the positions of the interaction points of the muon
4. Calculate the calibration parameters via data fitting

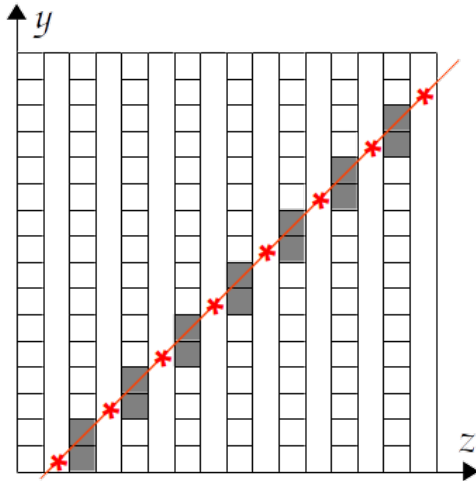
Side view of NeuLAND



Procedures

1. Obtain the positions of bars with signals
2. Reconstruct the muon track from the bar positions
3. Calculate the positions of the interaction points of the muon
4. Calculate the calibration parameters via data fitting

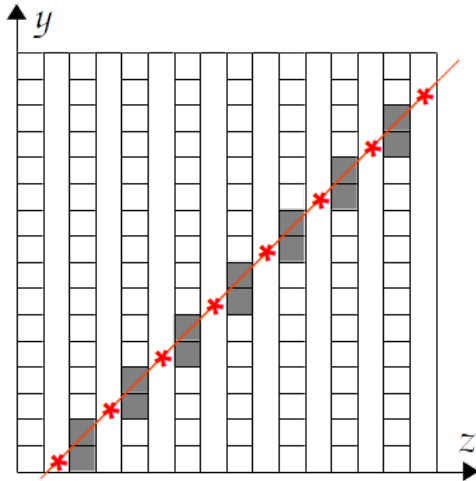
Side view of NeuLAND



Procedures

1. Obtain the positions of bars with signals
2. Reconstruct the muon track from the bar positions
3. Calculate the positions of the interaction points of the muon
4. Calculate the calibration parameters via data fitting

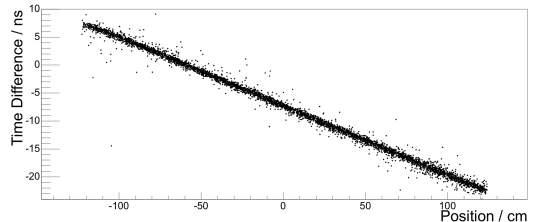
Side view of NeuLAND



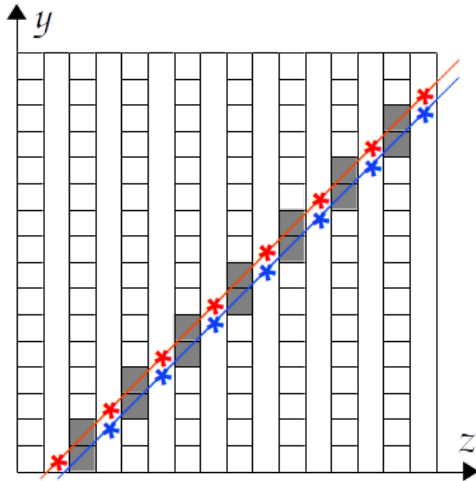
Procedures

1. Obtain the positions of bars with signals
2. Reconstruct the muon track from the bar positions
3. Calculate the positions of the interaction points of the muon
4. Calculate the calibration parameters via data fitting

Data fitting in the position calibration:



Side view of NeuLAND



Procedures

1. Obtain the positions of bars with signals
2. Reconstruct the muon track from the bar positions
3. Calculate the positions of the interaction points of the muon
4. Calculate the calibration parameters via data fitting

Data fitting in the position calibration:

