

and the contact lines' x values $x_l(t)$, $x_r(t)$ such that

$$\begin{aligned} & - (p, \nabla \cdot \boldsymbol{\omega})_{\Omega_1} + (\eta_1(\nabla \mathbf{u} + (\nabla \mathbf{u})^T), \nabla \boldsymbol{\omega})_{\Omega_1} \\ & + \frac{1}{Ca} (\partial_s \boldsymbol{\ell}, \partial_s \boldsymbol{\omega})_{\Sigma_{3,l}} + \frac{1}{Ca} (\partial_s \mathbf{r}, \partial_s \boldsymbol{\omega})_{\Sigma_{3,r}} - \frac{1}{Ca} (\nu, \nabla_s \cdot \boldsymbol{\omega})_{\Sigma_1} \\ & - \frac{\nu_l}{Ca} (\boldsymbol{\omega} \cdot \boldsymbol{\tau}) \Big|_{\Lambda_l} + \frac{\gamma_1 - \gamma_2}{Ca} \left((\boldsymbol{\omega} \cdot \boldsymbol{\tau}) \Big|_{\Lambda_r} - (\boldsymbol{\omega} \cdot \boldsymbol{\tau}) \Big|_{\Lambda_l} \right) = 0, \quad \forall \boldsymbol{\omega} \in \mathbb{U}_2, \end{aligned} \quad (3.86a)$$

$$(\nabla \cdot \mathbf{u}, \varphi)_{\Omega_1} = 0, \quad \forall \varphi \in L^2(\Omega), \quad (3.86b)$$

$$\begin{aligned} & \frac{l_s}{\mu_1} (\nabla_s \nu, \nabla_s g)_{\Sigma_1} + Ca (\nabla_s \cdot \mathbf{u}, g)_{\Sigma_1} + \frac{1}{\mu_\Lambda} ((\nu - \nu_l)g) \Big|_{\Lambda_l} + \frac{1}{\mu_\Lambda} (\nu, g) \Big|_{\Lambda_r} = 0, \\ & \forall g \in H^1([x_l, x_r]), \end{aligned} \quad (3.86c)$$

$$- \int_{\Sigma_{2,l}} \frac{\kappa}{|\partial_x \mathbf{q}|} \frac{\partial y}{\partial t} dl + (\mathbf{u} \cdot \boldsymbol{\tau}) \Big|_{\Lambda_l} - \frac{1}{\mu_\Lambda Ca} (\nu - \nu_l) \Big|_{\Lambda_l} = 0, \quad (3.86d)$$

$$(\dot{\boldsymbol{\ell}}, \boldsymbol{\psi}_1)_{\Sigma_{3,l}} - (\mathbf{u}, \boldsymbol{\psi}_1)_{\Sigma_{3,l}} = 0, \quad \forall \boldsymbol{\psi}_1 \in H^1(D) \times H_0^1(D), \quad (3.86e)$$

$$(\dot{\mathbf{r}}, \boldsymbol{\psi}_2)_{\Sigma_{3,r}} - (\mathbf{u}, \boldsymbol{\psi}_2)_{\Sigma_{3,r}} = 0, \quad \forall \boldsymbol{\psi}_2 \in H^1(D) \times H_0^1(D), \quad (3.86f)$$

$$\boldsymbol{\ell}(0, t) = (x_l(t), y(x_l(t), t)), \quad \mathbf{r}(0, t) = (x_r(t), y(x_r(t), t)). \quad (3.86g)$$

3.4.2 Numerical method

Similarly, we could propose a procedure to simulate the dynamics of the system, including two FEM schemes for the corresponding weak formulations (3.85a)-(3.85h) and (3.86a)-(3.86g).

The temporal discretization and the spatial discretization for the membrane in Sec. 3.3.2 are still available here by modifying $D_{\mathbf{q}}$ from $[-1, 1]$ to $[0, B_x]$. We have two separated fluid-vacuum interfaces $\Sigma_{3,l}$ and $\Sigma_{3,r}$, but they share the same reference domain $D = [0, 1]$. For simplicity, we set the same spatial discretization for these two fluid-vacuum interfaces as what we have done for the fluid-fluid interface Σ_3 in Sec. 3.3.2. We use the following finite-dimensional spaces to approximate V_y , $H_{0,r}^1(D_{\mathbf{q}}^m)$, $H_0^1([0, x_l^m])$, $H^1([x_l^m, x_r^m])$, $H_{0,l}^1([x_r^m, B_x])$, respectively,

$$V_y^m := \{f \in V^m : f(0) = -B_y\}, \quad (3.87a)$$

$$V_\kappa^m := \{f \in V^m : f(B_x) = 0\}, \quad (3.87b)$$

$$V_1^m := \left\{g \in C([0, x_l^m]) : g|_{D_{\mathbf{q},j}^m} \in \mathcal{P}_2(D_{\mathbf{q},j}^m), \forall j = 1, 2, \dots, j_l, g(0) = g(x_l^m) = 0\right\}, \quad (3.87c)$$

$$V_2^m := \left\{g \in C([x_l^m, x_r^m]) : g|_{D_{\mathbf{q},j}^m} \in \mathcal{P}_2(D_{\mathbf{q},j}^m), \forall j = j_l + 1, \dots, j_r\right\}, \quad (3.87d)$$

$$V_3^m := \left\{g \in C([x_r^m, B_x]) : g|_{D_{\mathbf{q},j}^m} \in \mathcal{P}_2(D_{\mathbf{q},j}^m), \forall j = j_r + 1, \dots, \mathcal{Q}, g(x_r^m) = 0\right\}, \quad (3.87e)$$

where V^m is defined in (3.58a). Besides, $H^1(D)$ can be approximated by W^h defined in (3.58e). $H_0^1(D)$ can be approximated by W_0^h defined in (3.58f). $H_{0,r}^1(D)$ can be approximated by

$$W_1^h := \{u \in W^h : u(1) = 0\}. \quad (3.88)$$

Using similar definitions in Sec. 3.3.2, the whole membrane Ξ at $t = t_m$ is approximated by Ξ^m . x_l^m and x_r^m separate Ξ^m into parts Σ_1^m , $\Sigma_{2,l}^m$, $\Sigma_{2,r}^m$, which numerically approximate Σ_1 , $\Sigma_{2,l}$ and $\Sigma_{2,r}$, respectively, at $t = t_m$. For piecewise continuous functions u and v defined on the $D_{\mathbf{q}}^m$, the inner products on $\Sigma_{2,l}^m$ and $\Sigma_{2,r}^m$ can be approximated as

$$(u, v)_{\Sigma_{2,l}^m} := \sum_{j=1}^{j_l} |\partial_x \mathbf{q}^m|_j \int_{x_{j-1}^m}^{x_j^m} u(x)v(x)dx, \quad (3.89a)$$

$$(u, v)_{\Sigma_{2,r}^m} := \sum_{j=j_r+1}^{\mathcal{Q}} |\partial_x \mathbf{q}^m|_j \int_{x_{j-1}^m}^{x_j^m} u(x)v(x)dx. \quad (3.89b)$$

Let ν^m , ν_l^m be the numerical approximations to the membrane inner tension for Σ_1^m and $\Sigma_{2,l}^m$, respectively, at $t = t_m$.

Let $\Sigma_{3,l}^m := \boldsymbol{\ell}^m = (x_{\boldsymbol{\ell}}^m(\zeta), y_{\boldsymbol{\ell}}^m(\zeta)) \in W^h \times W_1^h$ and $\Sigma_{3,r}^m := \mathbf{r}^m = (x_{\mathbf{r}}^m(\zeta), y_{\mathbf{r}}^m(\zeta)) \in W^h \times W_1^h$ be the numerical approximations to the fluid-vacuum interfaces at $t = t_m$. For piecewise continuous functions u and v defined on D , the inner products on $\Sigma_{3,l}^m$

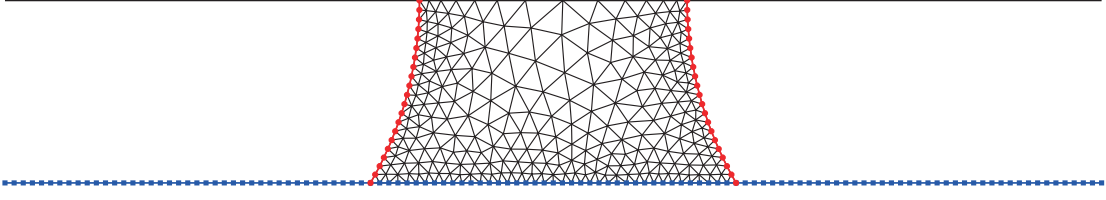


Figure 3.13: The initial fitted mesh used for the convergence test of the numerical method for bendotaxis. The red line with circle markers represents the fluid-vacuum interfaces. The blue line with square markers represents the lower membrane. The upper black line is the center line.

and $\Sigma_{3,r}^m$ can be approximated as

$$(u, v)_{\Sigma_{3,l}^m} := \sum_{j=1}^{\mathcal{R}} |\ell^m(\zeta_j) - \ell^m(\zeta_{j-1})| \int_{\zeta_{j-1}}^{\zeta_j} u(\zeta)v(\zeta)d\zeta, \quad (3.90a)$$

$$(u, v)_{\Sigma_{3,r}^m} := \sum_{j=1}^{\mathcal{R}} |\mathbf{r}^m(\zeta_j) - \mathbf{r}^m(\zeta_{j-1})| \int_{\zeta_{j-1}}^{\zeta_j} u(\zeta)v(\zeta)d\zeta, \quad (3.90b)$$

where $|\ell^m(\zeta_j) - \ell^m(\zeta_{j-1})|$ and $|\mathbf{r}^m(\zeta_j) - \mathbf{r}^m(\zeta_{j-1})|$ are the lengths of the line segments $[\ell^m(\zeta_{j-1}), \ell^m(\zeta_j)]$ and $[\mathbf{r}^m(\zeta_{j-1}), \mathbf{r}^m(\zeta_j)]$, respectively, for $j = 1, 2, \dots, \mathcal{R}$.

We still denote $\mathbf{q}_j^m = (x_j^m, y^m(x_j^m))$, $j = 0, 1, \dots, \mathcal{Q}$ as markers to represent the membrane Ξ^m . For fluid-vacuum interfaces $\Sigma_{3,l}^m$ and $\Sigma_{3,r}^m$, let $\ell_j^m = \ell^m(\zeta_j)$, $j = 0, 1, \dots, \mathcal{R}$ and $\mathbf{r}_j^m = \mathbf{r}^m(\zeta_j)$, $j = 0, 1, \dots, \mathcal{R}$ denote markers. Then, we have $\ell_0^m = \mathbf{q}_{l_l}^m = (x_{l_l}^m, y^m(x_{l_l}^m))$ marking the left contact line $\Lambda_{l_l}^m$ and $\mathbf{r}_0^m = \mathbf{q}_{r_r}^m = (x_{r_r}^m, y^m(x_{r_r}^m))$ marking the right contact line $\Lambda_{r_r}^m$.

Since Ω_2^m is a vacuum, a triangulation is only required for Ω_1^m . Let $\mathcal{T}^m := \bigcup_{j=1}^N \bar{o}_j^m$ be a triangulation of Ω_1^m at the time step $t = t_m$. The mesh contains J vertices denoted by $\{\mathbf{p}_k^m\}_{k=1}^J$. We use a fitted mesh (see Fig. 3.13) such that line segments of Σ_1^m , $\Sigma_{3,l}^m$ and $\Sigma_{3,r}^m$ are edges from \mathcal{T}^m , i.e., $\Sigma_1^m \cup \Sigma_{3,l}^m \cup \Sigma_{3,r}^m \subset \bigcup_{j=1}^N \partial o_j^m$. Compared to the triangulation for the first application, the number of triangles N and the number of vertices J are both independent of time here. It is because that no triangulation is reproduced in the numerical procedure introduced later.

We denote the corresponding finite element spaces for \mathbb{U}_i ($i = 1, 2, 3$) and \mathbb{P} as

\mathbb{U}_i^m ($i = 1, 2, 3$) and \mathbb{P}^m , respectively. These finite element spaces are chosen to use the standard P2-(P1+P0) elements as

$$\mathbb{U}_1^m = [S_2^m]^2 \cap \mathbb{U}_1, \quad \mathbb{U}_2^m = [S_2^m]^2 \cap \mathbb{U}_2, \quad \mathbb{P}^m = (S_1^m + S_0^m) \cap \mathbb{P}, \quad (3.91a)$$

$$\mathbb{U}_3^m = \left\{ \boldsymbol{\omega} \in \mathbb{U}_1^m : \boldsymbol{\omega} \cdot \mathbf{n}^m = -\frac{1}{|\partial_x \mathbf{q}^m|} \frac{y^m - y^{m-1}}{\tau} \text{ on } \Sigma_1^m \right\}, \quad (3.91b)$$

where $|\partial_x \mathbf{q}^m| = \sqrt{1 + (\frac{\partial y^m}{\partial x})^2}$. These choices satisfy the inf-sup stability condition,

$$\inf_{\varphi \in \mathbb{P}^m} \sup_{0 \neq \boldsymbol{\omega} \in \mathbb{U}_i^m} \frac{(\varphi, \nabla \cdot \boldsymbol{\omega})_{\Omega_1^m}}{\|\varphi\|_0 \|\boldsymbol{\omega}\|_1} \geq C_0 > 0, \quad i = 1, 2, \quad (3.92)$$

where C_0 is a constant, and $\|\cdot\|_0$ and $\|\cdot\|_1$ denote the L^2 and H^1 -norm on Ω_1^m , respectively.

The overall procedure of the numerical method is summarized as follows. Given the initial configuration of the system including $D_{\mathbf{q}}^0$, y^0 and κ^0 for the membrane Ξ^0 , ℓ^0 and \mathbf{r}^0 for the fluid-vacuum interfaces $\Sigma_{3,l}^0$ and $\Sigma_{3,r}^0$, and \mathcal{T}^0 for the triangulation of Ω_1^0 . Set $m = 0$ and then go through the following steps.

- (1) Fix the current configuration of fluid-vacuum interfaces ℓ^m and \mathbf{r}^m , and the positions of the contact lines x_l^m and x_r^m , based on the mesh \mathcal{T}^m , find the fluid velocity $\mathbf{u}^{m+\frac{1}{2}} \in \mathbb{U}_1^m$, the fluid pressure $p^{m+\frac{1}{2}} \in \mathbb{P}^m$, the membrane configuration $y^{m+\frac{1}{2}} \in V_y^m$, the curvature of the membrane $\kappa^{m+\frac{1}{2}} \in V_\kappa^m$, the inner tension of the membrane $\nu^{m+\frac{1}{2}} \in V_2^m$, and the constant inner tension $\nu_l^{m+\frac{1}{2}}$ for the membrane $\Sigma_{2,l}^{m+\frac{1}{2}}$ such that

$$\begin{aligned} & - \left(p^{m+\frac{1}{2}}, \nabla \cdot \boldsymbol{\omega}^h \right)_{\Omega_1^m} + \left(\eta_1 (\nabla \mathbf{u}^{m+\frac{1}{2}} + (\nabla \mathbf{u}^{m+\frac{1}{2}})^T), \nabla \boldsymbol{\omega}^h \right)_{\Omega_1^m} \\ & + \frac{1}{Ca} (\partial_s \ell^m, \partial_s \boldsymbol{\omega}^h)_{\Sigma_{3,l}^m} + \frac{1}{Ca} (\partial_s \mathbf{r}^m, \partial_s \boldsymbol{\omega}^h)_{\Sigma_{3,r}^m} \\ & + \frac{1}{Ca} \left(c_b \partial_s^m \left(\frac{\kappa^{m+\frac{1}{2}}}{|\partial_x \mathbf{q}^m|} \right) - \gamma^m \partial_s^m y^{m+\frac{1}{2}}, \partial_s^m (|\partial_x \mathbf{q}^m| \boldsymbol{\omega}^h \cdot \mathbf{n}^m) \right)_{\Xi^m} \\ & + \frac{3c_b}{2Ca} ((\kappa^m)^2 \partial_s^m y^m, \partial_s^m (|\partial_x \mathbf{q}^m| \boldsymbol{\omega}^h \cdot \mathbf{n}^m))_{\Xi^m} - \frac{1}{Ca} \left(\nu^{m+\frac{1}{2}}, \nabla_s^m \cdot \boldsymbol{\omega}^h \right)_{\Sigma_1^m} \end{aligned} \quad (3.93a)$$

$$\begin{aligned}
& -\frac{1}{Ca} \left(\kappa^m \nu_l^{m+\frac{1}{2}}, \omega^h \cdot \mathbf{n}^m \right)_{\Sigma_{2,l}^m} - \frac{\nu_l^{m+\frac{1}{2}}}{Ca} (\omega^h \cdot \boldsymbol{\tau}^m) \Big|_{\Lambda_l^m} \\
& + \frac{\gamma_1 - \gamma_2}{Ca} \left(\left(|\partial_x \mathbf{q}^m| \omega_1^h \right) \Big|_{\Lambda_r^m} - \left(|\partial_x \mathbf{q}^m| \omega_1^h \right) \Big|_{\Lambda_l^m} \right) = 0, \quad \forall \omega^h = (\omega_1^h, \omega_2^h) \in \mathbb{U}_1^m, \\
& \left(\nabla \cdot \mathbf{u}^{m+\frac{1}{2}}, \varphi^h \right)_{\Omega_1^m} = 0, \quad \forall \varphi^h \in \mathbb{P}^m,
\end{aligned} \tag{3.93b}$$

$$\begin{aligned}
& \left(c_b \partial_s^m \left(\frac{\kappa^{m+\frac{1}{2}}}{|\partial_x \mathbf{q}^m|} \right) - \gamma_2 \partial_s^m y^{m+\frac{1}{2}}, \partial_s^m (|\partial_x \mathbf{q}^m| f_1^h) \right)_{\Sigma_{2,l}^m} - \left(\kappa^m \nu_l^{m+\frac{1}{2}}, f_1^h \right)_{\Sigma_{2,l}^m} \\
& + \frac{3c_b}{2} \left((\kappa^m)^2 \partial_s^m y^m, \partial_s^m (|\partial_x \mathbf{q}^m| f_1^h) \right)_{\Sigma_{2,l}^m} = 0, \quad \forall f_1^h \in V_1^m,
\end{aligned} \tag{3.93c}$$

$$\left(\frac{y^{m+\frac{1}{2}} - y^m}{\tau}, f_2^h \right)_{\Sigma_1^m} + \left(|\partial_x \mathbf{q}^m| \mathbf{u}^{m+\frac{1}{2}} \cdot \mathbf{n}^m, f_2^h \right)_{\Sigma_1^m} = 0, \quad \forall f_2^h \in V_2^m, \tag{3.93d}$$

$$\left(c_b \partial_s^m \left(\frac{\kappa^{m+\frac{1}{2}}}{|\partial_x \mathbf{q}^m|} \right) - \gamma_2 \partial_s^m y^{m+\frac{1}{2}}, \partial_s^m (|\partial_x \mathbf{q}^m| f_3^h) \right)_{\Sigma_{2,r}^m} \tag{3.93e}$$

$$+ \frac{3c_b}{2} \left((\kappa^m)^2 \partial_s^m y^m, \partial_s^m (|\partial_x \mathbf{q}^m| f_3^h) \right)_{\Sigma_{2,r}^m} = 0, \quad \forall f_3^h \in V_3^m,$$

$$\left(\frac{\kappa^{m+\frac{1}{2}}}{|\partial_x \mathbf{q}^m|}, \beta^h \right)_{\Xi^m} + \left(\partial_s^m y^{m+\frac{1}{2}}, \partial_s^m \beta^h \right)_{\Xi^m} = 0, \quad \forall \beta^h \in V_\kappa^m, \tag{3.93f}$$

$$\frac{l_s}{\mu_1} \left(\partial_s^m \nu^{m+\frac{1}{2}}, \partial_s^m g^h \right)_{\Sigma_1^m} + Ca \left(\nabla_s^m \cdot \mathbf{u}^{m+\frac{1}{2}}, g^h \right)_{\Sigma_1^m} \tag{3.93g}$$

$$\begin{aligned}
& + \frac{1}{\mu_\Lambda} \left((\nu^{m+\frac{1}{2}} - \nu_l^{m+\frac{1}{2}}) g^h \right) \Big|_{\Lambda_l^m} + \frac{1}{\mu_\Lambda} \left(\nu^{m+\frac{1}{2}} g^h \right) \Big|_{\Lambda_r^m} = 0, \quad \forall g^h \in V_2^m, \\
& - \int_{\Sigma_{2,l}^m} \frac{\kappa^m}{|\partial_x \mathbf{q}^m|} \frac{y^{m+\frac{1}{2}} - y^m}{\tau} dl + (\mathbf{u}^{m+\frac{1}{2}} \cdot \boldsymbol{\tau}^m) \Big|_{\Lambda_l^m} - \frac{1}{\mu_\Lambda Ca} (\nu^{m+\frac{1}{2}} - \nu_l^{m+\frac{1}{2}}) \Big|_{\Lambda_l^m} = 0,
\end{aligned} \tag{3.93h}$$

where $\gamma^m = \gamma_1 \chi_{\Sigma_1^m} + \gamma_2 \chi_{\Sigma_{2,l}^m} + \gamma_2 \chi_{\Sigma_{2,r}^m}$.

- (2) Due to the condition that the fluid-vacuum interfaces always stay on the membrane, update the y value of $\ell^m(0)$ and $\mathbf{r}^m(0)$ as

$$\ell^{m+\frac{1}{2}}(\zeta) = \begin{cases} (x_l^m, y^{m+\frac{1}{2}}(x_l^m)), & \zeta = 0, \\ \ell^m(\zeta), & 0 < \zeta \leq 1, \end{cases} \tag{3.94a}$$

$$\mathbf{r}^{m+\frac{1}{2}}(\zeta) = \begin{cases} (x_r^m, y^{m+\frac{1}{2}}(x_r^m)), & \zeta = 0, \\ \mathbf{r}^m(\zeta), & 0 < \zeta \leq 1. \end{cases} \quad (3.94b)$$

Use the computed membrane configuration $y^{m+\frac{1}{2}}$ to update mesh from \mathcal{T}^m to $\mathcal{T}^{m+\frac{1}{2}}$. Furthermore, we set $D_{\mathbf{q}}^{m+\frac{1}{2}}$ as $D_{\mathbf{q},j}^{m+\frac{1}{2}} = D_{\mathbf{q},j}^m$ for $j = 1, 2, \dots, \mathcal{Q}$.

- (3) Using the computed $y^{m+\frac{1}{2}}$ and $\kappa^{m+\frac{1}{2}}$, based on the mesh $\mathcal{T}^{m+\frac{1}{2}}$, find the fluid velocity $\mathbf{u}^{m+1} \in \mathbb{U}_3^{m+\frac{1}{2}}$, the fluid pressure $p^{m+1} \in \mathbb{P}^{m+\frac{1}{2}}$, the inner tension of the membrane $\nu^{m+1} \in V_2^{m+\frac{1}{2}}$, the constant inner tension ν_l^{m+1} for the membrane $\Sigma_{2,l}^{m+1}$, and the fluid-vacuum interfaces ℓ^{m+1} , $\mathbf{r}^{m+1} \in W^h \times W_1^h$ such that

$$- (p^{m+1}, \nabla \cdot \omega^h)_{\Omega_1^{m+\frac{1}{2}}} + (\eta_1 (\nabla \mathbf{u}^{m+1} + (\nabla \mathbf{u}^{m+1})^T), \nabla \omega^h)_{\Omega_1^{m+\frac{1}{2}}} \quad (3.95a)$$

$$+ \frac{1}{Ca} (\partial_s \ell^{m+1}, \partial_s \omega^h)_{\Sigma_{3,l}^{m+\frac{1}{2}}} + \frac{1}{Ca} (\partial_s \mathbf{r}^{m+1}, \partial_s \omega^h)_{\Sigma_{3,r}^{m+\frac{1}{2}}} - \frac{1}{Ca} (\nu^{m+1}, \nabla_s^{m+\frac{1}{2}} \cdot \omega^h)_{\Sigma_1^{m+\frac{1}{2}}} - \frac{\nu_l^{m+1}}{Ca} (\omega^h \cdot \tau^{m+\frac{1}{2}}) \Big|_{\Lambda_l^{m+\frac{1}{2}}} + \frac{\gamma_1 - \gamma_2}{Ca} \left((\omega^h \cdot \tau^{m+\frac{1}{2}}) \Big|_{\Lambda_r^{m+\frac{1}{2}}} - (\omega^h \cdot \tau^{m+\frac{1}{2}}) \Big|_{\Lambda_l^{m+\frac{1}{2}}} \right) = 0, \quad \forall \omega^h \in \mathbb{U}_2^{m+\frac{1}{2}},$$

$$(\nabla \cdot \mathbf{u}^{m+1}, \varphi^h)_{\Omega_1^{m+\frac{1}{2}}} = 0, \quad \forall \varphi^h \in \mathbb{P}^{m+\frac{1}{2}}, \quad (3.95b)$$

$$\frac{l_s}{\mu_1} (\partial_s^{m+\frac{1}{2}} \nu^{m+1}, \partial_s^{m+\frac{1}{2}} g^h)_{\Sigma_1^{m+\frac{1}{2}}} + Ca (\nabla_s^{m+\frac{1}{2}} \cdot \mathbf{u}^{m+1}, g^h)_{\Sigma_1^{m+\frac{1}{2}}} \quad (3.95c)$$

$$+ \frac{1}{\mu_\Lambda} ((\nu^{m+1} - \nu_l^{m+1}) g^h) \Big|_{\Lambda_l^{m+\frac{1}{2}}} + \frac{1}{\mu_\Lambda} (\nu^{m+1} g^h) \Big|_{\Lambda_r^{m+\frac{1}{2}}} = 0, \quad \forall g^h \in V_2^{m+\frac{1}{2}},$$

$$- \int_{\Sigma_{2,l}^{m+\frac{1}{2}}} \frac{\kappa^{m+\frac{1}{2}}}{|\partial_x \mathbf{q}^{m+\frac{1}{2}}|} \frac{y^{m+\frac{1}{2}} - y^m}{\tau} dl + (\mathbf{u}^{m+1} \cdot \tau^{m+\frac{1}{2}}) \Big|_{\Lambda_l^{m+\frac{1}{2}}} \quad (3.95d)$$

$$- \frac{1}{\mu_\Lambda Ca} (\nu^{m+1} - \nu_l^{m+1}) \Big|_{\Lambda_l^{m+\frac{1}{2}}} = 0,$$

$$\left(\frac{\ell^{m+1} - \ell^{m+\frac{1}{2}}}{\tau}, \psi_1^h \right)_{\Sigma_{3,l}^{m+\frac{1}{2}}} - (\mathbf{u}^{m+1}, \psi_1^h)_{\Sigma_{3,l}^{m+\frac{1}{2}}} = 0, \quad \forall \psi_1^h \in W^h \times W_0^h, \quad (3.95e)$$

$$\left(\frac{\mathbf{r}^{m+1} - \mathbf{r}^{m+\frac{1}{2}}}{\tau}, \psi_2^h \right)_{\Sigma_{3,r}^{m+\frac{1}{2}}} - (\mathbf{u}^{m+1}, \psi_2^h)_{\Sigma_{3,r}^{m+\frac{1}{2}}} = 0, \quad \forall \psi_2^h \in W^h \times W_0^h, \quad (3.95f)$$

$$\frac{y_{\ell}^{m+1}(0) - y_{\ell}^{m+\frac{1}{2}}(0)}{\tau} = \frac{\partial y^{m+\frac{1}{2}}}{\partial x} \Big|_{x=x_l^m} \frac{x_{\ell}^{m+1}(0) - x_{\ell}^{m+\frac{1}{2}}(0)}{\tau}, \quad (3.95g)$$

$$\frac{y_{\mathbf{r}}^{m+1}(0) - y_{\mathbf{r}}^{m+\frac{1}{2}}(0)}{\tau} = \frac{\partial y^{m+\frac{1}{2}}}{\partial x} \Big|_{x=x_r^m} \frac{x_{\mathbf{r}}^{m+1}(0) - x_{\mathbf{r}}^{m+\frac{1}{2}}(0)}{\tau}. \quad (3.95h)$$

(4) Update x_l^{m+1} , x_r^{m+1} with

$$x_l^{m+1} = x_{\ell}^{m+1}(0), \quad x_r^{m+1} = x_{\mathbf{r}}^{m+1}(0). \quad (3.96)$$

Then we could update markers for the membrane \mathbf{q}_j^{m+1} , $j = 0, 1, \dots, \mathcal{Q}$ as

$$\mathbf{q}_j^{m+1} = \begin{cases} (x_l^{m+1}, y_{\ell}^{m+1}(0)), & j = j_l, \\ (x_r^{m+1}, y_{\mathbf{r}}^{m+1}(0)), & j = j_r, \\ (x_j^m, y^{m+\frac{1}{2}}(x_j^m)), & j = 0, 1, \dots, \mathcal{Q} \text{ but } j \neq j_l, j_r. \end{cases} \quad (3.97)$$

(5) Fix the markers $\ell_0^{m+1} = \mathbf{q}_{j_l}^{m+1}$, $\mathbf{r}_0^{m+1} = \mathbf{q}_{j_r}^{m+1}$ for the contact lines, according to the equal arclength, redistribute markers ℓ_j^{m+1} , $j = 1, 2, \dots, \mathcal{R} - 1$ for the fluid-vacuum interface $\Sigma_{3,l}^{m+1}$, markers \mathbf{r}_j^{m+1} , $j = 1, 2, \dots, \mathcal{R} - 1$ for the fluid-vacuum interface $\Sigma_{3,r}^{m+1}$, and markers \mathbf{q}_j^{m+1} , $j = j_l + 1, \dots, j_r - 1$ for the membrane segment Σ_1^{m+1} . We compute the average arclength of Σ_1^{m+1} , and redistribute markers for $\Sigma_{2,l}^{m+1}$ and $\Sigma_{2,r}^{m+1}$ according to this average arclength. Due to the motion of the droplet towards the right end, We may add markers on $\Sigma_{2,l}^{m+1}$ or discard markers on $\Sigma_{2,r}^{m+1}$ to keep a good approximation. Once there is any addition or discard, we should update the values of j_l , j_r and \mathcal{Q} , but keep the values of $j_r - j_l$ and \mathcal{R} . After these redistribution, we obtain $D_{\mathbf{q}}^{m+1}$ and $y^{m+1} \in V_y^{m+1}$, and then compute the membrane curvature $\kappa^{m+1} \in V_{\kappa}^{m+1}$.

(6) Use the moving mesh method to generate the new fitted mesh \mathcal{T}^{m+1} from \mathcal{T}^m .

Then, go to step (1) with $m = m + 1$.