Yaolin Ge

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Summary

- Ph.D. candidate in the statistics group at Dept. of mathematical sciences at NTNU.
- Experience with data-driven machine learning software system development.
- Experience in Linux administration and SQL databases.
- Practice data analytics and agile development in a daily routine.

Experience

Norwegian University of Science and Technology

Trondheim, Norway

Ph.D. candidate, Dept. Mathematical Sciences

Aug. 2020 – present

- Design and implement multi-scale data-driven machine learning software systems.
- Deploy and integrate the systems onboard an unmanned robot for several successful field experiments.
- Collaborate and communicate closely with multiple customers including SINTEF Ocean, AURLab NTNU, LSTS, MARETEC for knowledge dissemination to foster novel ideas.
- Document and publish the results to relevant stakeholders and clients and share knowledge with the public. Three papers accomplished.

Peking University

Beijing, China

Summer research student at AI+Art Lab, PKU

Jul. 2019 – Aug. 2019

- Studied machine learning and deep learning principles, particularly computer vision techniques.
- Applied and integrated motion-capturing algorithms *OpenPose* onboard a humanoid robot. [video]
- Demonstrated the performance of the algorithms with a robot dance show. [video]

Education

Norwegian University of Science and Technology

Trondheim, Norway

*Ph.D. candidate in the statistics group, Dept. Mathematical Sciences*Aug. 2020 – present (expected Aug. 2023)
Thesis project: Developing multi-scale machine learning software systems for data analytics purposes to boost the autonomy of robotic oceanographic sampling.

KTH Royal Institute of Technology

Stockholm, Sweden

MSc, Maritime Engineering, G.P.A. 4.625/5.00

Aug. 2019 – Jul. 2020

Thesis project: Developed an embedded software system to estimate and predict the location of robots.

Norwegian University of Science and Technology

Trondheim, Norway

MSc, Marine Technology, G.P.A. 3.93/4.00

Aug. 2018 – Jun. 2019

Relevant project: Developed numerical prediction system for the lifting forces of a propeller.

University of Strathclyde

Glasgow, United Kingdom

International Student Exchange Program, G.P.A. 3.85/4.00

Sept. 2017 – Jan. 2018

Relevant project: Analyzed structural static and dynamic behavior using the finite element method.

Skills & Interests

Programming: Python, Git, C/C++, Bash scripting, Matlab, SQL, R, Julia

Frameworks: Numpy, Pandas, Scipy, Matplotlib, Plotly, CUDA

Software: PyCharm, QGIS, Microsoft Office365, Anaconda, VS Code, Adobe Photoshop/Illustrator

Language: English (full professional), Norwegian (conversational), Mandarin (native) **Interests:** Outdoor life (camping, sailing, skiing ...), Taekwondo, Dance, Music, Travelling

Awards & Competitions

2023	NTNUI Yngling Sailing Cup, 2 nd out of 12, Norway
2021	Taekwondo WT – NM 2021, 3 rd in KAMP, 4 th in Poomsae, Norway
2019	Best Popular Prize, AI + Art in Robot Dancing Competition, PKU, China
2016	National Scholarship, MOE, China

Extra-curricular

Taekwondo instructor Trondheim, Norway

NTNUI Taekwondo Jan. 2020 – present

- I am a Taekwondo instructor who plans and adapts training for all members.
- Competed in the Norwegian Championships in 2021, won 1 bronze medal in combat senior M 74+.

Salsa line instructor Trondheim, Norway

NTNUI Dans Sept. 2021 – present

• I am involved in the organization of the weekly dance classes.

Certificates

Deep Learning Specialization

acquired: 15th April 2020, Coursera This is offered by deeplearning.ai, covers basic and advanced topics in deep learning with practical programming tasks, which enable me to build deep learning models and solve real-world problems.

acquired: 20th-April-2022, NVIDIA **Fundamentals of Accelerated Computing with CUDA Python** I have learned about how to speed up the calculation using GPU programs using CUDA.

CS50 acquired: 26th-March-2023, Harvard University CS50 is an introductory computer science course taught at Harvard University that covers fundamental concepts in programming, algorithms, data structures, and web development.

Reference

Jo Eidsvik Professor	Dept. of Mathematical Sciences, NTNU jo.eidsvik@ntnu.no	+47 7359 0153
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Tore Mo-Bjørkelund Head of Operations	Skarv Technologies AS tore.mo-bjorkelund@ntnu.no	+47 9028 8012

Publication

- [1] Yaolin Ge, André Julius Hovd Olaisen, Jo Eidsvik, R. Praveen Jain, and Tor Arne Johansen. Long-horizon informative path planning with obstacles and time constraints. IFAC-PapersOnLine, 55(31):124–129, 2022. 14th IFAC Conference on Control Applications in Marine Systems, Robotics, and Vehicles CAMS 2022.
- [2] Yaolin Ge, Jo Eidsvik, Tore Mo-Bjørkelund. 3D Adaptive AUV Sampling for Classification of Water Masses. IEEE Journal of Oceanic Engineering, 2023.
- [3] Yaolin Ge, Jo Eidsvik, André Julius Hovd Olaisen. Robotic exploration of a river plume system using a flexible cost valley concept. Field Robotics, 2023 [sendt inn]