

Yaolin Ge

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PERSONAL INFORMATION

Date of Birth: October 20, 1996

Place of Birth: Shaanxi, China

Citizenship: Chinese

Gender: Male

EDUCATION

Aug. 2019 – Present	KTH Royal Institute of Technology, Stockholm, Sweden M.S. Maritime Engineering
Aug. 2018 – Jun. 2019	Norwegian University of Science and Technology, Trondheim, Norway G.P.A. 3.93/4.00 M.S. Marine Technology
Sept. 2017 – Jan. 2018	University of Strathclyde, Glasgow, United Kingdom G.P.A. 3.85/4.00 B.S. Naval Architecture & Ocean and Marine Engineering
Sept. 2014 – Jun. 2018	Jiangsu University of Science and Technology, Zhenjiang, China G.P.A. 3.89/4.00 B.S. Naval Architecture & Ocean Engineering

PROJECT EXPERIENCE

Aug. 2019 – Present	Maribot Vane 2.0 Design Project KTH & SMaRC (Swedish Maritime and Robotic Center), Stockholm, Sweden <ul style="list-style-type: none">Designed and built the Maribot Vane 2.0, an autonomous sailing vesselEngineered and manufactured the glass fibre-made rudderEvaluated the mechanical behaviour under certain load conditions for most of 3D printed parts as well as parts made from composite materialsStudied and assessed the performance of the components made from composite materials in terms of weight and strength
Jan. 2019 – Jun. 2019	Project on numerical analysis of a Wageningen B-screw series propeller TMR4220 Naval Hydrodynamics, NTNU, Trondheim <ul style="list-style-type: none">Analysed the propeller with induction-factor-enhanced lifting line methodInvestigated rake, skew and hub effects on the propeller bladeConducted an experimental testing in the towing tank at MARINTEK Supervisors: Kourosh Koushan, Professor
Sept. 2018 – Dec. 2018	Project on simulation-based design of the cruise ship balcony TMR4320 Simulation-Based Design, NTNU, Trondheim <ul style="list-style-type: none">Developed an initial design concept and assessed the principle dimensions, stress distribution & deflectionConducted the FEA analysis under multiple loading conditions and simulated theEstablished a parametric model and optimised the model using PSO codes out of minimum weight Supervisor: Ekaterina Kim, Associate Professor

Aug. 2018 – Dec. 2018

Project on dynamic & static analysis of marine structures

TMR4305 Advanced Analysis of Marine Structures, NTNU, Trondheim

- Developed the dynamic response model for a marine riser subjected to waves by use of mode superposition method and analysed the drag forces in both time and frequency domain
- Applied static condensation (concentrated mass) & master-slave (consistent mass) for reduction of number of degrees of freedoms and evaluated the riser performance using frequency response method
- Conducted ABAQUS analysis for an elastic-plastic jacket structure and a stiffened plate and studied the linear buckling analysis and nonlinear ultimate strength analysis

Supervisor: Svein Sævik, Professor; Erin Bachynski, Associate Professor

Jan. 2018 – Jun. 2018

Research on the added mass effect of VIV for flexible risers

Bachelor's thesis, Jiangsu University of Science and Technology, Zhenjiang

- Studied the VIV phenomenon and physics behind VIV and summarised the current research model and developed the time-domain VIV model for low mass ratio system considering added mass effect
- Conducted the sensitivity analysis for different top tension force, current velocity as well as mass ratio working conditions

Supervisor: ZHOU Hong, Professor; WANG Kunpeng, Associate Professor

Aug. 2017 – Jan. 2018

Project on the investigation of flow pattern on a circular cylinder

NM402 Theory and Practice of Marine CFD, Univ. of Strathclyde, Glasgow

- Studied the vortex shedding phenomenon and physics behind VIV and applied the time-domain VIV model for low mass ratio system
- Reviewed analysis methods such as finite volume method and finite difference method for necessary analysis of computational fluid dynamics
- Simulated the behaviour of the flow pattern for a rigid body circular cylinder under steady flow condition using Star-CCM+

Supervisor: Qing Xiao, Reader; Wendi Liu, Research Associate

PROFESSIONAL QUALIFICATIONS

Personal Skills:

Programming language with C/C++, Python & MATLAB; FEA analysis using Abaqus & ANSYS APDL; Foil analysis using Xfoil; CFD analysis using Star-CCM+; CAD modelling with Solidworks/AutoCAD; Simulation with Simlink (Simevents); 3D FDM printing; Microsoft Office; Latex

Languages:

English (fluent)

Chinese (native)

Swedish (conversational)

AWARDS

2019

Intel® Edge AI Scholarship, Intel

2019

Best Popular Prize, AI + Art in Robot Dancing Competition, PKU

2017

Merit Student, MOE

2017

First Prize, Academic Competition in Mechanics Knowledge, JUST

2016 – 2017

National Scholarship, MOE

2016

Second Prize Scholarship, CSSC Huangpu Wenchong

2015

National Encouragement Scholarship, MOE

2015

Honourable Mention, Xuediao Structural Innovative Design Contest, JUST

2014

Honourable Mention, CMIH Simulation Model Design Contest, JUST

2014

First Prize, Diesel Engine Assembly & Disassembly Contest, SIYANG

PROFESSIONAL MEMBERSHIPS

The Royal Institute of Naval Architects (RINA)
Kongl. Skeppssällskapet

EXTRA-CURRICULAR

Jul. 2019 – Aug. 2019

Project on computer vision for robotic perception

Peking University, Beijing, China

- Applied OpenPose algorithm to achieve the motion capture activities
- Employed the motion mapping tool to convert 2D motions to 3D skeleton ones
- Programmed Yanshee Robot to dance following human motions

Oct. 2014 – Jun. 2018

Team Leader

Student Volunteer Association, Zhenjiang, China

- Organised local and on-campus volunteering activities regularly

Mar. 2017 – Apr. 2017

Interpreter Intern

IDP Education Ltd., Nanjing, China

- Organised the introduction events for university's admission committee and expected applicants
- Interpreted and assisted applicants with communications with admission committees' representatives

REFEREES:

Ivan Stenius
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Tahsin Tezdogan (Ph.D.)
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ZHOU Hong
Professor

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INTERESTS

Sailing, running, bicycling, swimming, Taekwondo, cross-country skiing