

Yaolin Ge

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Summary

- Ph.D. candidate in the statistics group at Dept. of mathematical sciences at NTNU.
- Experience with data-driven machine learning software system development.
- Experience with software architecture design, data analytics, and statistics.
- Practice agile methodologies and test-driven development in a daily routine.

Experience

Norwegian University of Science and Technology

Trondheim, Norway

Ph.D. candidate, Dept. Mathematical Sciences

Aug. 2020 – present

- Design and implement multi-scale data-driven machine learning software systems for remote sensing.
- Develop data-driven models and software to incorporate various in-situ data collected in the ocean to better understand the phenomenon of water mass mixing.
- Deploy and integrate the systems onboard an unmanned robot for several successful field experiments.
- Collaborate and communicate closely with multiple customers including SINTEF Ocean, AURLab NTNU, LSTS, and MARETEC for knowledge dissemination to foster novel ideas.
- Document and publish the results to relevant stakeholders and clients and share knowledge with the public. Three papers were accomplished.

Education

Norwegian University of Science and Technology

Trondheim, Norway

Ph.D. candidate, Dept. Mathematical Sciences

Aug. 2020 – present (expected Aug. 2023)

Thesis project: Developing multi-scale machine learning software systems for data analytics purposes to boost the autonomy of robotic oceanographic sampling.

KTH Royal Institute of Technology

Stockholm, Sweden

MSc, Maritime Engineering, G.P.A. 4.625/5.00

Aug. 2019 – Jul. 2020

Thesis project: Developed an embedded software system to estimate and predict the location of robots.

Norwegian University of Science and Technology

Trondheim, Norway

MSc, Marine Technology, G.P.A. 3.93/4.00

Aug. 2018 – Jun. 2019

Relevant project: Developed numerical prediction system for the lifting forces of a propeller.

University of Strathclyde

Glasgow, United Kingdom

International Student Exchange Program, G.P.A. 3.85/4.00

Sept. 2017 – Jan. 2018

Relevant project: Analyzed structural static and dynamic behavior using the finite element method.

Skills & Interests

Programming: Python, Git, C/C++, Bash scripting, Matlab, SQL, R, Julia

Frameworks: TensorFlow, CUDA, OpenCL, Numpy, Pandas, Scipy, Matplotlib, Plotly

Software: PyCharm, QGIS, Microsoft Office365, Anaconda, VS Code, Adobe Photoshop/Illustrator

Language: English (full professional), Norwegian (conversational), Mandarin (native)

Interests: Outdoor life (camping, sailing, skiing hiking ...), Taekwondo, Dance, Music, Travelling

Awards & Competitions

2023

NTNUI Yngling Sailing Cup, 2nd out of 12, Norway

2021

Taekwondo WT – NM 2021, 3rd in KAMP, 4th in Poomsae, Norway

Extra-curricular

Taekwondo instructor

NTNUI Taekwondo

Trondheim, Norway

Jan. 2020 – present

- I am a Taekwondo instructor who plans and adapts training for all members.
- Competed in the Norwegian Championships in 2021, won 1 bronze medal in combat senior M 74+.

Salsa line instructor

NTNUI Dans

Trondheim, Norway

Sept. 2021 – present

- I am involved in the organization of the weekly dance classes.

Courses & Certificates

Deep Learning Specialization

acquired: 15th-April-2020, Coursera

This is offered by deeplearning.ai, which covers basic and advanced topics in deep learning with practical programming tasks, which enable me to build deep learning models and solve real-world problems.

Software Design Methods and Tools

acquired: 15th-April-2020, University of Colorado

I have learned various methods and tools to create and analyze software designs.

Fundamentals of Accelerated Computing with CUDA Python

acquired: 20th-April-2022, NVIDIA

I have learned how to speed up the calculation using CUDA GPU programs.

CS50

acquired: 26th-March-2023, Harvard University

CS50 is an introductory computer science course taught at Harvard University that covers fundamental concepts in programming, algorithms, data structures, and web development.

References

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Publication

[1] **Yaolin Ge**, André Julius Hovd Olaisen, Jo Eidsvik, R. Praveen Jain, and Tor Arne Johansen. Long-horizon informative path planning with obstacles and time constraints. IFAC-PapersOnLine, 55(31):124–129, 2022. 14th IFAC Conference on Control Applications in Marine Systems, Robotics, and Vehicles CAMS 2022.

[2] **Yaolin Ge**, Jo Eidsvik, Tore Mo-Bjørkelund. 3D Adaptive AUV Sampling for Classification of Water Masses. IEEE Journal of Oceanic Engineering, 2023.

[3] **Yaolin Ge**, Jo Eidsvik, André Julius Hovd Olaisen. Robotic exploration of a river plume system using a flexible cost valley concept. Field Robotics, 2023 [submitted]