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so so a college or and and and an experience monder and a superconnect true and or

$$T_{\lambda}(\omega) = \frac{1}{2} \|y\|^2 + \frac{\Omega}{2} \|\omega\|_2^2 + \lambda \|\omega\|_1 - y^T X \omega$$

Since the together
$$\frac{\partial}{\partial w} \left( \mathcal{T} \left\{ w \right\} \right) = n w + \frac{\partial}{\partial w} \|w\|_{1} - \left( X^{T} Y \right) = 0$$

$$= n w + sigh(w) - x^{T} Y = 0$$

$$w = \frac{1}{n} \left[ X^{T} Y - sign(w)(\lambda) \right]$$

Solve for w. Seprener

$$\frac{2}{2\omega_{r}} \int_{0}^{\infty} \int_{0}^{\infty} \left[ \frac{1}{2} w^{2} - (y^{T} X_{i})w_{i} + \lambda |w_{i}| \right]$$

$$= n w_{i} - y^{T} X_{i} + \lambda |sq_{i}| w_{i} = 0$$

$$w_{i} = \frac{1}{n} \left[ \frac{1}{n} y^{T} X_{i} - \lambda |sq_{i}| w_{i} \right]$$

60 - Jun

b) 
$$\hat{x}_i = \frac{1}{n} \left[ \frac{1}{n} \left[ \frac{1}{n} \frac{1}{n} \frac{1}{n} + \frac{1}{n} \frac{1}{n} \right] = \frac{1}{n} \frac{1$$

e) 
$$\hat{G} = (XTX + \lambda I)^{-1} X^{T}y$$
  
 $\hat{G} = (XTX + \lambda I)^{-1} X^{T}y$   
 $\hat$ 

```
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      Pr(17:17, 26 Nogd) (e = (26 Nogd) 2/262 - 4 12 log d
   J* (Pr (12i) 7/2 (logd)) ((J2)·d' = 1/32
cut of non <2 (logd)) ((J2)·d' = 1/32 P(MX|2i) >26 √logd)
e) w = (X^T X) X^T (y) = (X^T X) X^T (y^* + z) = w^* + (X^T X)' X z
                                  because (XX) X X (XXX) [
       wings = T(w) = Ts(w*+21) =
                                                             cdumns
     e = was (s) - w+ (assuming w+ is s-space)
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     Wax circ occurs when wippls) spredicts s-originally o entries in
    wo to have some value.
     max (whop(s) - W) → + will give 8-wongly prodicted non-zero
                              2- negative S entrict of original
                                 weights
  hax(Sprsny(e))= 2s
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G. Given that from (d) => Prinot E) < 1/2 1> Pr(8) 5,1-1/2

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(12) The variance would only be 62 because that's the variance of the noise ture is a factor of 325 log of that we pay for not knowing which features to use.

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1) When x has very little counts of anyming meaning We don't have much informer on about X when W > 1e-15

When would is not spen it is easy to classify become they mostly only have characters and no keywords of the over above.

W (1e-35

# **Bias and Variance of Sparse Linear Regression**

In this notebook, you will explore numerically how sparse vectors change the rate at which we can estimate the underlying model. This corresponds to parts (a), (b), (c) of Homework 12.

First, some setup. We will only be using basic libraries.

```
In [5]: import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

The following functions produce the ground truth matrix  $A \in \mathbb{R}^{n \times d}$  (denoted by U since it is unitary), as well as the vector  $w^* \in \mathbb{R}^d$  and observations  $y \in \mathbb{R}^n$ . They have been implemented for you, but it is worth going through the code to observe its limitations.

```
In [6]:
        def ground truth(n, d, s):
             Input: Two positive integers n, d. Requires n \ge d \ge s. If d < s, w
        e let s = d
             Output: A tuple containing i) random matrix of dimension n X d wi
        th orthonormal columns. and
                      ii) a d-dimensional, s-sparse wstar with (large) Gaussia
        n entries
             11 11 11
             if d > n:
                 print ("Too many dimensions")
                 return None
             if d < s:
                 s = d
             A = np.random.randn(n, d) #random Gaussian matrix
             U, S, V = np.linalg.svd(A, full matrices=False) #reduced SVD of G
        aussian matrix
             wstar = np.zeros(d)
             wstar[:s] = 10 * np.random.randn(s)
             np.random.shuffle(wstar)
             return U, wstar
        def get_obs(U, wstar):
             Input: U is an n X d matrix and wstar is a d X 1 vector.
             Output: Returns the n-dimensional noisy observation y = U * wstar
         + Z.
             n, d = np.shape(U)
             z = np.random.randn(n) #i.i.d. noise of variance 1
             y = np.dot(U, wstar) + z
             return y
```

We now implement the estimators that we will simulate. The least squares estimator has already been implemented for you. You will be implementing the top k and threshold estimators in part (b), but it is fine to skip this for now and compile.

```
elif param == 's':
        arg range = np.arange(5, 55, 5)
        lmbda = 2 * np.sqrt(np.log(d))
        for s in arg_range:
            U, wstar = ground truth(n, d, s) if s model else ground t
ruth(n, d, true s)
            error wls = 0
            error wtopk = 0
            error wthresh = 0
            for count in range(num iters):
                y = get obs(U, wstar)
                wls = LS(U, y)
                wtopk = topk(U, y, s)
                wthresh = thresh(U, y, lmbda)
                error wls += np.linalg.norm(wstar - wls)**2
                error wtopk += np.linalg.norm(wstar - wtopk)**2
                error wthresh += np.linalg.norm(wstar - wthresh)**2
            wls error.append(float(error wls)/ n / num iters)
            wtopk error.append(float(error wtopk)/ n / num iters)
            wthresh error.append(float(error wthresh)/ n / num iters)
    return arg range, wls error, wtopk error, wthresh error
```

We are now ready to perform the parts of the question.

## Part (a)

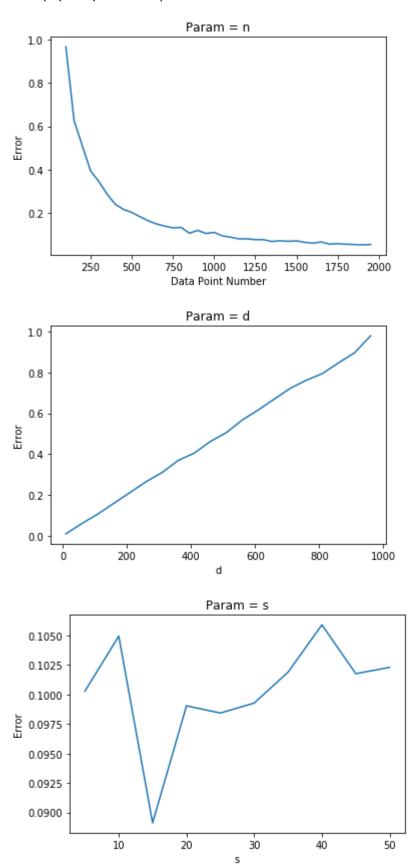
As an example, in the following cell, we run the helper function above to return error values of the OLS estimate for various values of n. You are required to:

- 1) Plot the error as a function of n. You may find a log-log plot useful to see the expected bahavior.
- 2) Run the helper function to return the error as a function of d and s, and plot your results.

You need to have 3 plots in your answer. Make sure to label axes properly, and to make the plotting visible in general. Feel free to play with the parameters, but ensure that your answer describes your parameter choices. At this point, s model is True, since we are only interested in the variance of the model.

#nrange contains the range of n used, ls\_error the corresponding erro In [14]: rs for the OLS estimate nrange, ls\_error, \_, \_ = error\_calc(num\_iters=10, param='n', n=1000, d=100, s=5, s model=True, true s=5) plt.figure() plt.plot(nrange, ls\_error) plt.xlabel('Data Point Number') plt.title('Param = n') plt.ylabel('Error') nrange, ls\_error, \_, \_ = error\_calc(num\_iters=10, param='d', n=1000, d=100, s=5, s model=**True**, true s=5) plt.figure() plt.plot(nrange, ls error) plt.xlabel('d') plt.title('Param = d') plt.ylabel('Error') nrange, ls\_error, \_, \_ = error\_calc(num\_iters=10, param='s', n=1000, d=100, s=5, s\_model=**True**, true\_s=5) plt.figure() plt.plot(nrange, ls error) plt.xlabel('s') plt.title('Param = s') plt.ylabel('Error')

Out[14]: Text(0,0.5,'Error')



Are these plots as expected? Discuss. Also put down your parameter choices (either here or in plot captions.) It's fine to use the default values, but put them down nonetheless.

They are as expected. For LS, the higher the dimensions, the more the bias error. Moreover, the higher the complexity of our Model. S, the sparsity is unrelated to our OLS solver, so as expected, the error is uncorrelated to the sparsity s. Also, as n increases, as expected, the error decreases, as the effect of noise has less effect on our most likely weights. Online 1: d = 1. n = infinity s = anything

# Part (b)

Now fill out the functions implementing the sparsity-seeking estimators: thresh, and topk in the above cells. You should be able to test these functions using some straightforward examples.

We will now simulate the error of all the estimators, as a function of n, d, and s. An example of this for n is given below. You must:

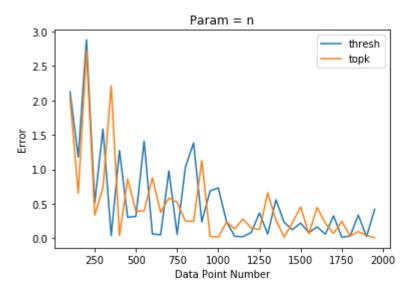
- 1) Plot the error of all estimators as a function of n.
- 2) Run the helper function to sweep over d and s, and plot the behavior of all three estimators.

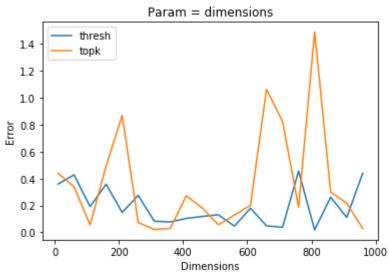
You should report 3 plots here once again. Make sure to make them fully readable.

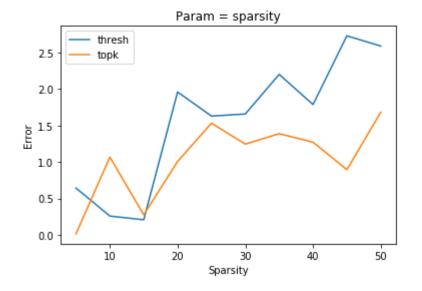
In [34]: nrange, ,wtopk error, wthresh error= error calc(num iters=10, param= 'n', n=1000, d=100, s=5, s model=**True**, true s=5) plt.figure() plt.plot(nrange, wtopk\_error, nrange, wthresh\_error) plt.xlabel('Data Point Number') plt.title('Param = n') plt.vlabel('Error') plt.legend({'topk', 'thresh'}) nrange, ,wtopk error, wthresh error= error calc(num iters=10, param= 'd', n=1000, d=100, s=5, s\_model=**True**, true\_s=5) plt.figure() plt.plot(nrange, wtopk error, nrange, wthresh error) plt.xlabel('Dimensions') plt.title('Param = dimensions') plt.ylabel('Error') plt.legend() plt.legend({'topk', 'thresh'}) nrange, \_,wtopk\_error, wthresh\_error= error\_calc(num\_iters=10, param= 's', n=1000, d=100, s=5, s\_model=**True**, true s=5) plt.figure() plt.plot(nrange, wtopk error, nrange, wthresh error) plt.xlabel('Sparsity') plt.title('Param = sparsity') plt.ylabel('Error') plt.legend() plt.legend({'topk', 'thresh'})

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Out[34]: <matplotlib.legend.Legend at 0x7f9d9652d748>







# Part (c)

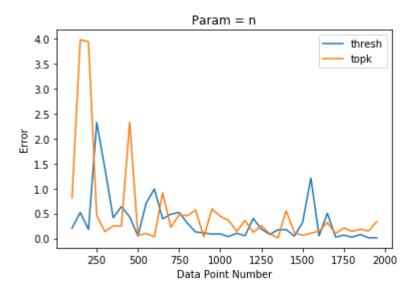
Now, call the helper function with the true sparsity being greater than the sparsity assumed by the top-k estimator. Remember to set s\_model to False! Plot the behavior of all three estimators once again, as a function of n, d, s, where s is the assumed sparsity of the top-k model.

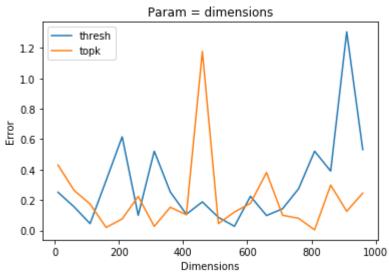
You should return 3 plots, and explain what you see in terms of the bias variance tradeoff.

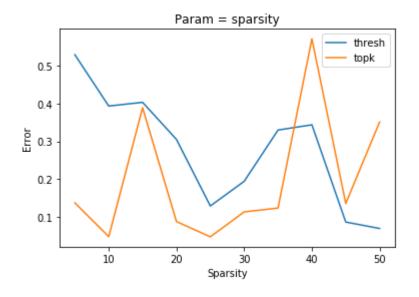
In [38]: nrange, ,wtopk error, wthresh error= error calc(num iters=10, param= 'n', n=1000, d=100, s=5, s model=**False**, true s=5) plt.figure() plt.plot(nrange, wtopk\_error, nrange, wthresh\_error) plt.xlabel('Data Point Number') plt.title('Param = n') plt.vlabel('Error') plt.legend({'topk', 'thresh'}) nrange, ,wtopk error, wthresh error= error calc(num iters=10, param= 'd', n=1000, d=100, s=5, s\_model=**False**, true\_s=5) plt.figure() plt.plot(nrange, wtopk error, nrange, wthresh error) plt.xlabel('Dimensions') plt.title('Param = dimensions') plt.ylabel('Error') plt.legend() plt.legend({'topk', 'thresh'}) nrange, \_,wtopk\_error, wthresh\_error= error\_calc(num\_iters=10, param= 's', n=1000, d=100, s=5, s\_model=**False**, true s=5) plt.figure() plt.plot(nrange, wtopk error, nrange, wthresh error) plt.xlabel('Sparsity') plt.title('Param = sparsity') plt.ylabel('Error') plt.legend() plt.legend({'topk', 'thresh'})

No handles with labels found to put in legend. No handles with labels found to put in legend.

Out[38]: <matplotlib.legend.Legend at 0x7f9d97c40b70>







In the Model we see that with higher dimensional data we don't get more error, that is because we are setting our complexity within our sparsity to be set. Therefore, our variance is set, and our bias is already high. However when looking at the assumed sparsity of our model (which should be 100, since we don't have any sparsity), we see that the error stays the same. The randomness comes from our noise, however there seems to be no visible trend. We expect that as we increase sparsity, the more our error will decrease because we are approaching optimal variance and bias tradeoff as we approach the true model.

```
In [1]: import matplotlib.pyplot as plt
import matplotlib.image as mpimg
%matplotlib notebook
```

#### PART A

```
In [2]:
         #
               @staticmethod
               def information_gain(X, y, thresh):
         #
         #
                   X0, y0, X1, y1 = split(X, y, thresh)
         #
                   def g(y):
         #
                       pyk_2 = 0
                        for i in range(2):
         #
         #
                            try:
                                pyeqk = len(y[y == i])/float(len(y))
         #
         #
                                pyk_2 = pyeqk**2
                            except ZeroDivisionError:
         #
         #
                                pyeqk = 0
                        return 1 - pyk 2
                   return\ len(X0)*g(y0)/float(len(X)) + len(X1)*g(y1)/float(len(X))
         n(X)
         #
               @staticmethod
         #
               def gini_impurity(X, y, thresh):
         #
                   X0, y0, X1, y1 = split(X, y, thresh)
                   def h(y):
         #
                       hy = 0
         #
                        for i in range(2):
         #
                            try:
         #
                                pyeqk = len(y[y == i])/float(len(y))
         #
                                hy = hy - pyeqk*np.log(pyeqk)
         #
                            except ZeroDivisionError :
         #
                                pyeqk = 0
                        return hy
                   return len(X0)*h(y0)/float(len(X)) + len(X1)*h(y1)/float(len(X))
         n(X)
```

#### **PART C**



### PART D (Bagged Trees)

```
In [ ]: # class BaggedTrees(BaseEstimator, ClassifierMixin):
               def __init__(self, params=None, n=200):
                   if params is None:
                       params = \{\}
        #
                   self.params = params
                   self.n = n
        #
                   self.decision trees = [
                       sklearn.tree.DecisionTreeClassifier(random_state=i, **s
        elf.params)
                       for i in range(self.n)
                   1
        #
              def fit(self, X, y):
        #
                 self.mask = []
        #
                 for tree in self.decision_trees:
        #
                         mask = np.random.randint(0, high = len(X), size= len
         (X)
                         Xsampling = X[mask,:]
        #
        #
                         ysampling = y[mask]
        #
                         tree.fit(Xsampling,ysampling)
        #
                         self.mask.append(mask)
              def predict(self, X):
        #
                 preds = []
        #
                 for tree in self.decision_trees:
        #
                         preds.append(tree.predict(X))
        #
                 return stats.mode(np.array(preds), axis = 0 )[0].reshape(len
         (X)
```

## PART F (Random Forest)

```
In [ ]: | # class RandomForest(BaggedTrees):
              def __init__(self, params=None, n=200, m=2):
                 super().__init__(params = params , n = n )
        #
                 self.m = m
               def fit(self, X,y):
        #
                 self.mask = []
                 self.features = []
        #
        #
                 for tree in self.decision trees:
        #
                         mask = np.random.randint(0, high = len(X), size= len
         (X)
                         features = np.random.choice( X.shape[1], size = self.
        #
        m)
        #
                         Xsampling = X[mask,:]
                         Xsampling = Xsampling[:,features]
        #
        #
                         ysampling = y[mask]
        #
                         tree.fit(Xsampling,ysampling)
        #
                         self.mask.append(mask)
        #
                         self.features.append(features)
               def predict(self,X):
        #
        #
                 preds = []
        #
                 k = 0
                 for tree in self.decision trees:
                         preds.append(tree.predict(X[:,self.features[k]]))
        #
                 return stats.mode(np.array(preds), axis = 0 )[0].reshape(len
        #
         (X)
```

## PART H (AdaBoost)

```
# class BoostedRandomForest(RandomForest):
In [ ]:
               def fit(self, X, y ):
        #
                   self.w = np.ones(X.shape[0]) / X.shape[0] # Weights on dat
        а
        #
                   self.a = np.zeros(self.n) # Weights on decision trees
        #
                   k = 0
                   self.features = []
        #
        #
                   for tree in self.decision trees:
        #
                         mask = np.random.randint(0, high = len(X), size= len
         (X)
        #
                         features = np.random.choice(X.shape[1], size = self.m
                         Xsampling = X[mask,:]
        #
        #
                         Xsampling = Xsampling[:,features]
        #
                         ysampling = y[mask]
        #
                         tree.fit(Xsampling,ysampling)
                         self.features.append(features)
         #
        #
                         ei = 0
        #
                         for j in range(len(Xsampling)):
        #
                                 ej = checkXY(Xsampling[j,:], ysampling[j], tr
        ee )*self.w[j] + ej
        #
                         ej = ej/float(sum(self.w))
        #
                         self.a[k] = 0.5*np.log((1-ej)/float(ej))
         #
                         for i in range(len(Xsampling)):
        #
                                 if checkXY(Xsampling[i,:],ysampling[i], tree)
         > 0.5 :
        #
                                          self.w[i] = self.w[i]*np.exp(self.a
         [k]
                                 else :
        #
                                          self.w[i] = self.w[i]*np.exp(-self.a
         [k]
                         k = k + 1
        #
        #
               def predict(self, X):
        #
                   classes = list(set(y))
        #
                   preds_tot = []
        #
                   for i in range(len(X)):
        #
                         preds = []
        #
                         for c in classes :
        #
                                 zj = 0
         #
                                  k = 0
        #
                                  for tree in self.decision trees:
                                          Xcheck = X[:,self.features[k]]
        #
        #
                                          Xcheck = Xcheck[i,:]
         #
                                          zj = zj + self.a[k]*checkXY(Xcheck,
          c, tree)
                                          k = k + 1
         #
        #
                                 preds.append(zj)
        #
                                 preds_tot.append(classes[np.argmax(preds)])
         #
                         return preds tot
```

## Part J (Results)

```
In [ ]: #TITANIC :
        # accuracy = [kfold1, kfold2, kfold3, avg training]
        # DecisionTree
        # [0.5993975903614458, 0.63855421686746983, 0.60240963855421692, 0.61
        3693153423288341
        # BaggedTrees
        # accuracy = [kfold1, kfold2, kfold3, avg training]
        # [0.79518072289156627, 0.76204819277108438, 0.77710843373493976, 0.9
        78010994502748531
        # RandomForest
        # accuracy = [kfold1, kfold2, kfold3, avg training]
        # [0.5993975903614458, 0.4006024096385542, 0.60240963855421692, 0.580
        209895052473781
        # Adaboost
        # [0.21686746987951808, 0.63855421686746983, 0.21385542168674698, 0.2
        48375812093953011
        # SPAM
        # DecisionTree
        # accuracy = [kfold1, kfold2, kfold3, avg training]
        # [0.5993975903614458, 0.63855421686746983, 0.60240963855421692, 0.61
        3693153423288341
        # BaggedTrees
        # accuracy = [kfold1, kfold2, kfold3, avg training]
        # [0.78915662650602414, 0.76204819277108438, 0.77409638554216864, 0.9
        78010994502748531
        # RandomForest
        # accuracy = [kfold1, kfold2, kfold3, avg training]
        # [0.5993975903614458, 0.6506024096385542, 0.61144578313253017, 0.628
        685657171414221
        # Adaboost
        # accuracy = [kfold1, kfold2, kfold3, avg training]
        # [0.5993975903614458, 0.22289156626506024, 0.21987951807228914, 0.24
        8875562218890591
```

