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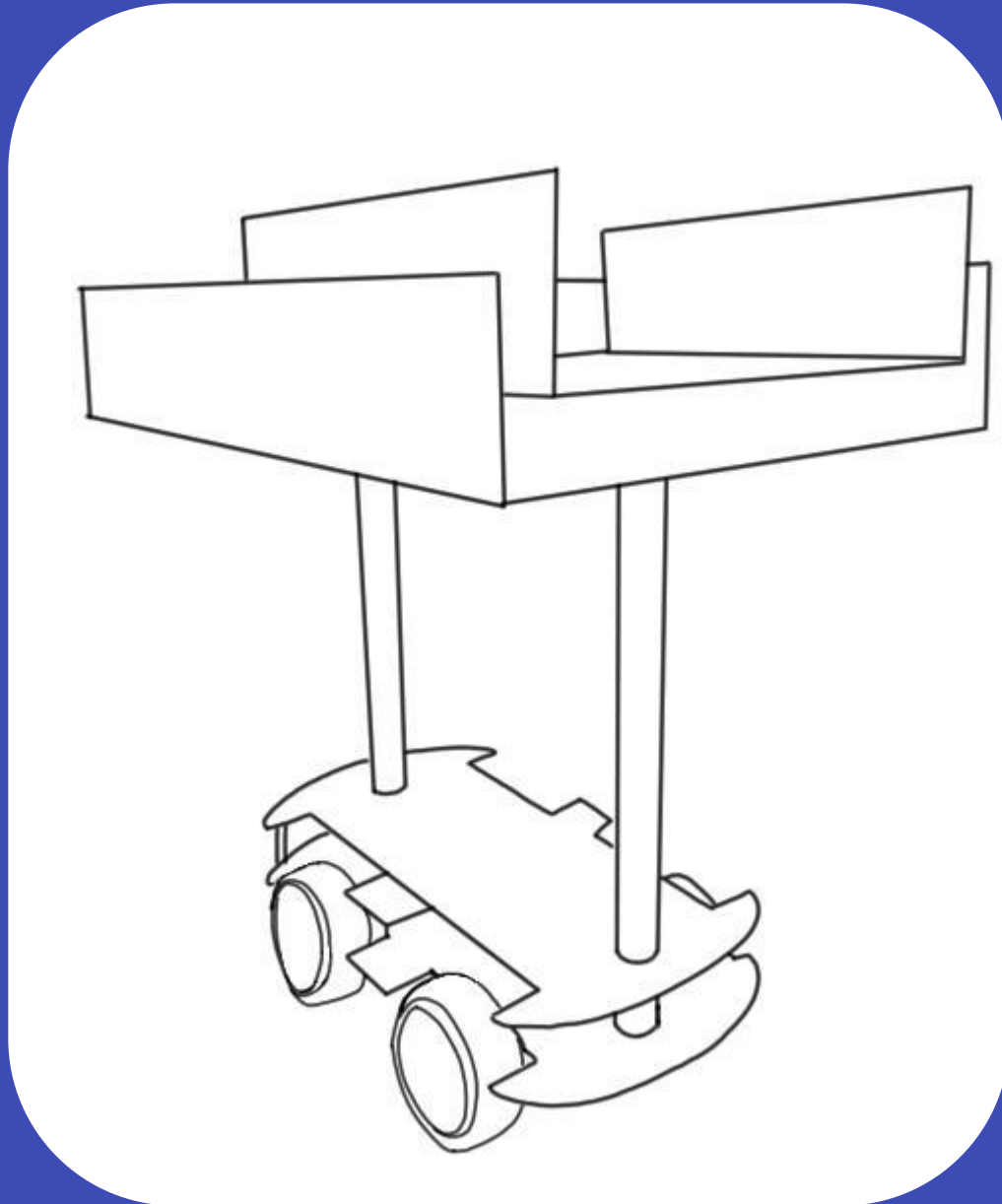


Coventry University



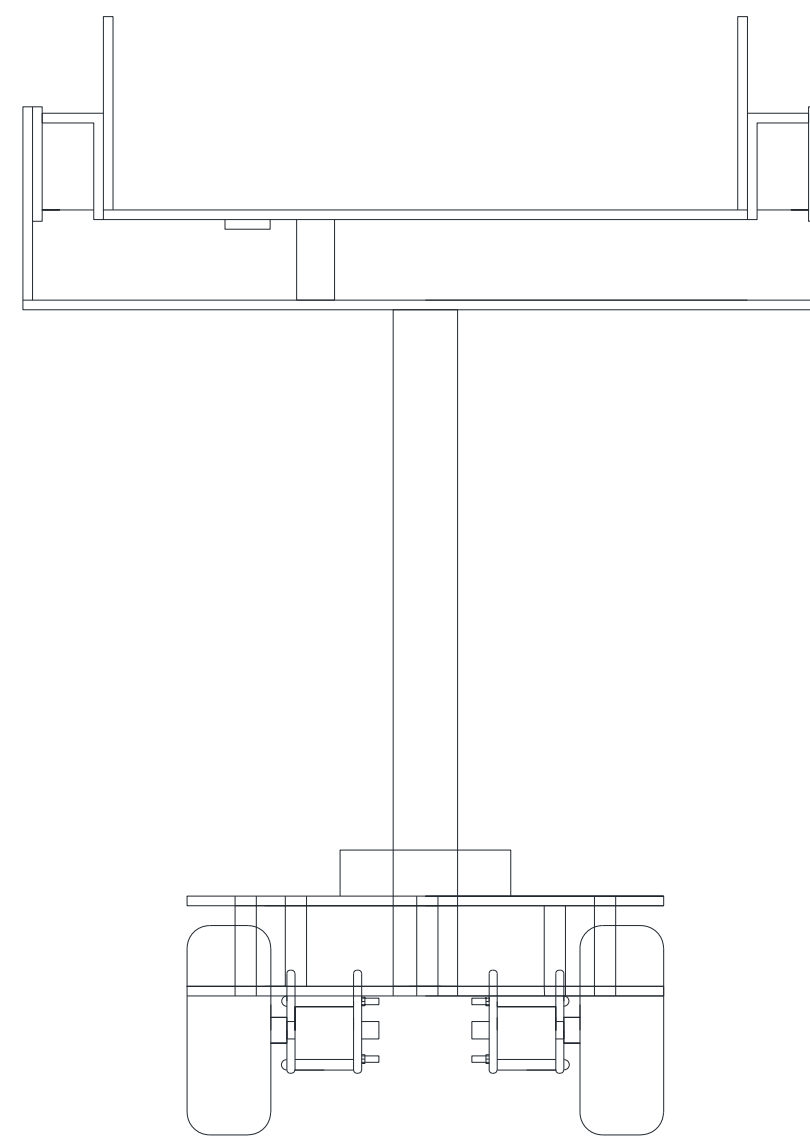
The Knowledge Hub Universities

Free hand sketch of the system

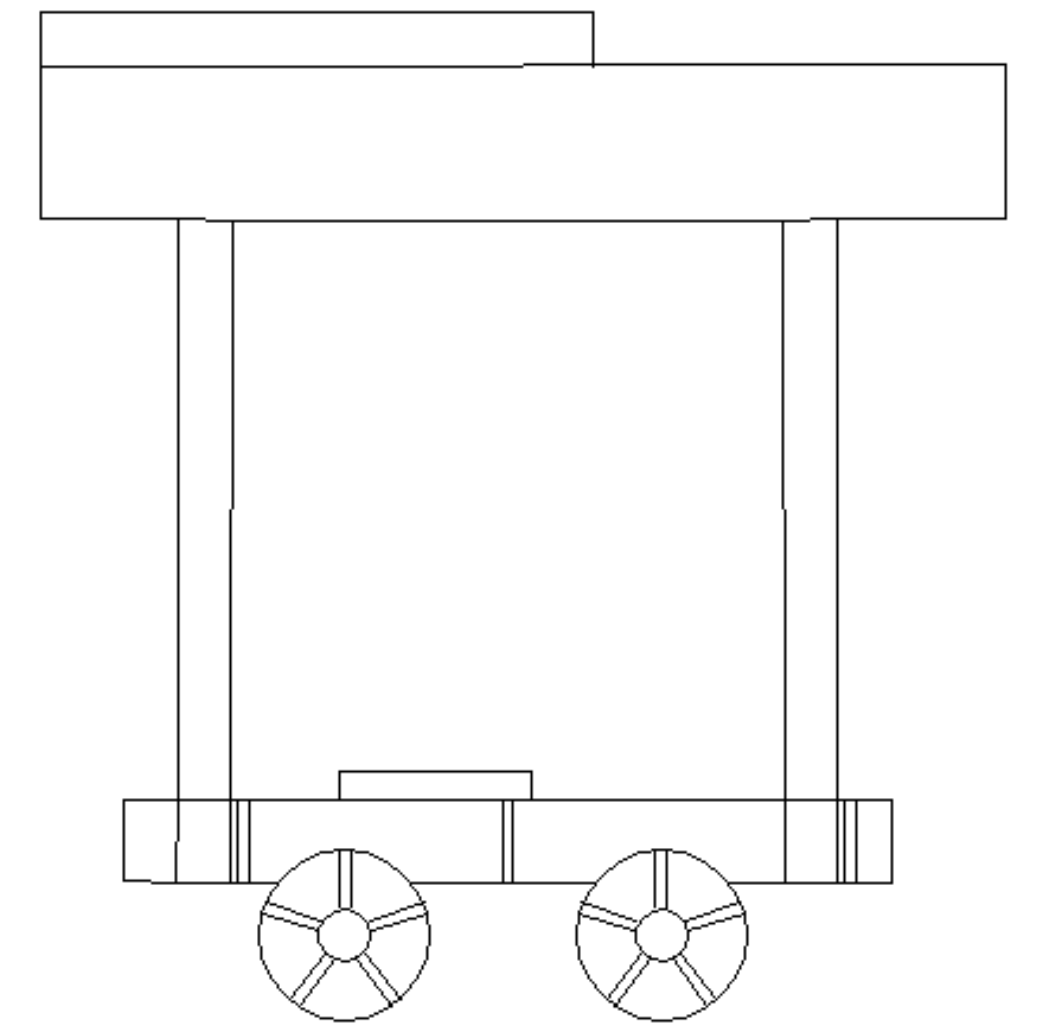


AutoCAD drawings of the system

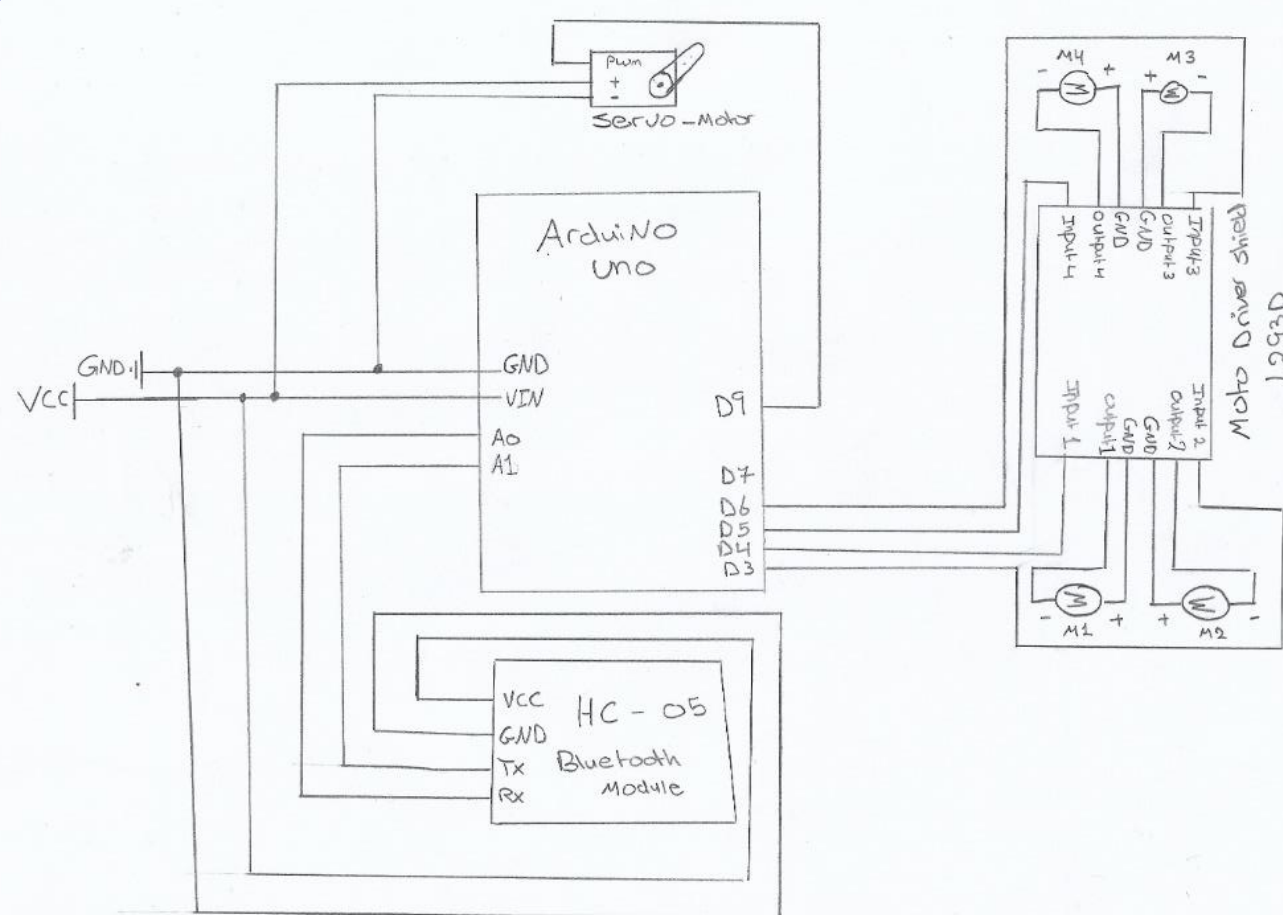
Front view



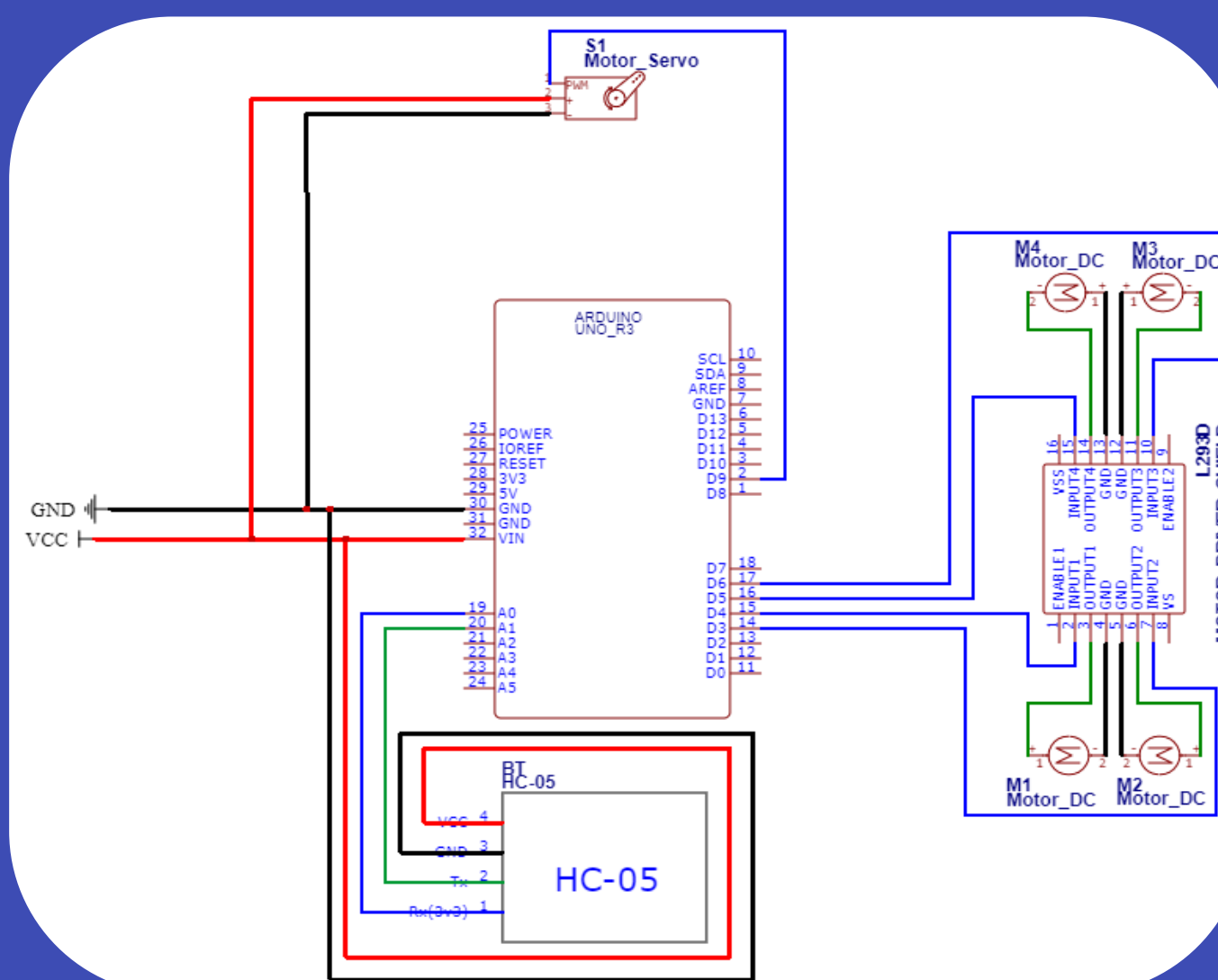
Side view



Free hand sketch of the electric schematic



AutoCAD drawing of the electric schematic



Prototype



Calculations

Total load

Live Load+ Dead Load = 22.05 N

Load per wheel

$$\frac{\text{Total Load}}{\text{Number of Wheels}} = \frac{22.050}{4} = 5.513 \text{ N}$$

Friction

per wheel = $0.4 \times 5.513 = 2.210 \text{ N}$
 Total friction = $4 \times 2.205 \text{ N} = 8.820 \text{ N}$

Torque per wheel

$$\tau \geq F \times r \geq 5.513 \times 0.033 \text{ m} \geq 0.179 \text{ Nm}$$

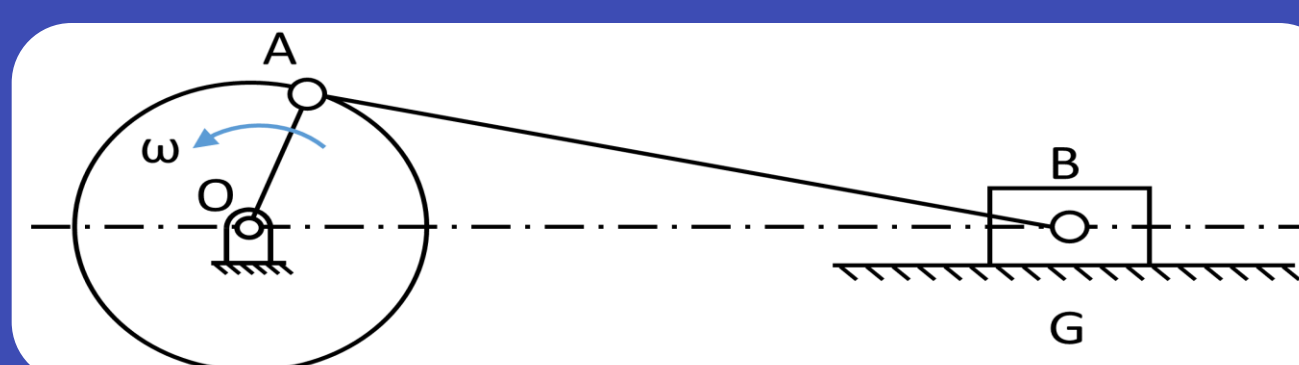
Power Consumption with 20% margin

$$P_{\text{total}} = 9.652 + 9.652 \times 20\% = 11.582 \text{ watt}$$

Battery Capacity

$$\geq \frac{\text{Energy}}{\text{Voltage}} \geq \frac{11.582}{12} \geq 0.9652 \text{ A}$$

In-line crank mechanism



Inline crank mechanism is a 4-bar mechanism that converts the servo's rotary motion to the tray's linear motion.

Also, the prototype was built using affordable sustainable materials.

Android application

