view_frames Result Recorded at time: 1649764260.977 world Broadcaster: /virtual_joint_broadcaster_1 Average rate: 10000.000 Hz Most recent transform: 0.000 (1649764260.977 sec old) Buffer length: 0.000 sec panda_link0 Broadcaster: /robot_state_publisher Average rate: 30.203 Hz Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 4.900 sec panda_link1 Broadcaster: /robot_state_publisher Average rate: 30.203 Hz Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 4.900 sec panda_link2 Broadcaster: /robot_state_publisher Average rate: 30.203 Hz Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 4.900 sec panda_link3 Broadcaster: /robot_state_publisher Average rate: 30.203 Hz Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 4.900 sec panda_link4 Broadcaster: /robot_state_publisher Average rate: 30.203 Hz Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 4.900 sec panda_link5 Broadcaster: /robot_state_publisher Average rate: 30.203 Hz Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 4.900 sec panda_link6 Broadcaster: /robot_state_publisher Average rate: 30.203 Hz Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 4.900 sec panda_link7 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1649764260.977 sec old) Buffer length: 0.000 sec panda_link8 Broadcaster: /robot_state_publisher Broadcaster: /franka_control Average rate: 29.580 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1649764260.977 sec old) Most recent transform: 1649764260.957 (0.020 sec old) Buffer length: 0.000 sec Buffer length: 4.902 sec panda_hand panda_EE Broadcaster: /hand_to_cameraTemp Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /franka_control Average rate: 10000.000 Hz Average rate: 30.203 Hz Average rate: 30.203 Hz Average rate: 29.580 Hz Most recent transform: 1649764260.957 (0.020 sec old) Most recent transform: 0.000 (1649764260.977 sec old) Most recent transform: 1649764260.940 (0.037 sec old) Most recent transform: 1649764260.940 (0.037 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.902 sec panda_leftfinger panda_K panda_rightfinger camera_link_temp Broadcaster: /cameraTemp_to_camera Average rate: 10000.000 Hz Most recent transform: 0.000 (1649764260.977 sec old) Buffer length: 0.000 sec camera_link Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1649764260.977 sec old) Most recent transform: 0.000 (1649764260.977 sec old) Most recent transform: 0.000 (1649764260.977 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera_color_frame camera_aligned_depth_to_color_frame camera_depth_frame Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz

Most recent transform: 0.000 (1649764260.977 sec old) Average rate: 10000.000 Hz

Most recent transform: 0.000 (1649764260.977 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_color_optical_frame camera_depth_optical_frame Broadcaster: /ar_track_alvar Average rate: 8.184 Hz Most recent transform: 1649764260.837 (0.140 sec old) Buffer length: 4.888 sec ar_marker_0