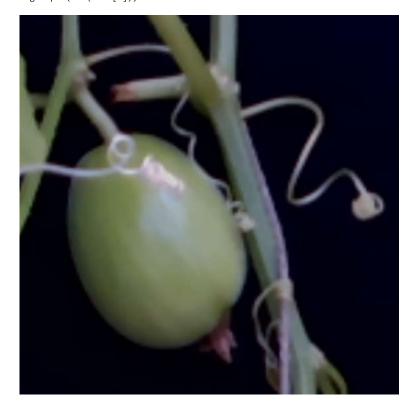
Mounting drive

```
from google.colab import drive
drive.mount('/content/drive')
     Mounted at /content/drive
{\tt import\ matplotlib.pyplot\ as\ plt}
import numpy as np
import os
import PIL
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
from tensorflow.keras.models import Sequential
import pathlib
dataset_url = '/content/drive/MyDrive/Colab Notebooks/dataset/'
data_dir = pathlib.Path(dataset_url)
image_count = len(list(data_dir.glob('**/*.jpg')))
print(image_count)
     101
```

buah = list(data_dir.glob('**/buah/*'))
PIL.Image.open(str(buah[0]))



PIL.Image.open(str(buah[1]))



daun = list(data_dir.glob('**/daun/*'))
PIL.Image.open(str(daun[0]))



PIL.Image.open(str(daun[1]))



```
batch_size = 32
img_height = 180
img_width = 180
train_ds = tf.keras.utils.image_dataset_from_directory(
 data_dir,
  validation_split=0.2,
  subset="training",
  seed=123,
  image_size=(img_height, img_width),
  batch_size=batch_size)
     Found 101 files belonging to 3 classes.
     Using 81 files for training.
val_ds = tf.keras.utils.image_dataset_from_directory(
  data_dir,
  validation_split=0.2,
  subset="validation",
  seed=123,
  image_size=(img_height, img_width),
  batch_size=batch_size)
     Found 101 files belonging to 3 classes.
     Using 20 files for validation.
class_names = train_ds.class_names
print(class_names)
     ['buah', 'daun', 'testing']
import matplotlib.pyplot as plt
plt.figure(figsize=(10, 10))
for images, labels in train_ds.take(1):
  for i in range(9):
    ax = plt.subplot(3, 3, i + 1)
    plt.imshow(images[i].numpy().astype("uint8"))
    plt.title(class_names[labels[i]])
    plt.axis("off")
```

```
buah
                                           daun
                                                                       buah
for image_batch, labels_batch in train_ds:
  print(image_batch.shape)
  print(labels_batch.shape)
 break
     (32, 180, 180, 3)
     (32,)
     100
AUTOTUNE = tf.data.AUTOTUNE
train_ds = train_ds.cache().shuffle(1000).prefetch(buffer_size=AUTOTUNE)
val_ds = val_ds.cache().prefetch(buffer_size=AUTOTUNE)
normalization_layer = layers.Rescaling(1./255)
normalized_ds = train_ds.map(lambda x, y: (normalization_layer(x), y))
image_batch, labels_batch = next(iter(normalized_ds))
first_image = image_batch[0]
# Notice the pixel values are now in `[0,1]`.
print(np.min(first_image), np.max(first_image))
    0.0 0.8547599
     num_classes = len(class_names)
model = Sequential([
  layers.Rescaling(1./255, input_shape=(img_height, img_width, 3)),
 layers.Conv2D(16, 3, padding='same', activation='relu'),
 layers.MaxPooling2D(),
  layers.Conv2D(32, 3, padding='same', activation='relu'),
 layers.MaxPooling2D(),
  layers.Conv2D(64, 3, padding='same', activation='relu'),
 layers.MaxPooling2D(),
 layers.Flatten(),
 layers.Dense(128, activation='relu'),
 layers.Dense(num_classes)
model.compile(optimizer='adam',
loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=True),
metrics=['accuracy'])
model.summary()
```

Model: "sequential"

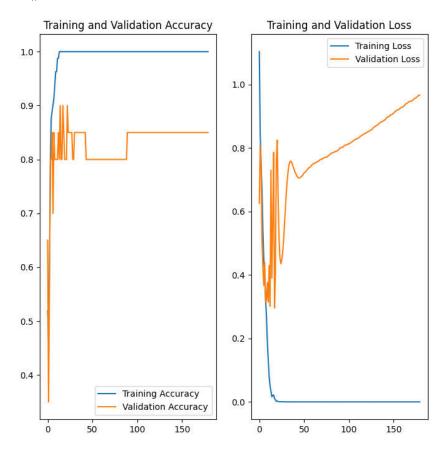
Layer (type)	Output Shape	Param #
rescaling_1 (Rescaling)	(None, 180, 180, 3)	0
conv2d (Conv2D)	(None, 180, 180, 16)	448
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 90, 90, 16)	0
conv2d_1 (Conv2D)	(None, 90, 90, 32)	4640
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 45, 45, 32)	0
conv2d_2 (Conv2D)	(None, 45, 45, 64)	18496
<pre>max_pooling2d_2 (MaxPooling 2D)</pre>	(None, 22, 22, 64)	0
flatten (Flatten)	(None, 30976)	0
dense (Dense)	(None, 128)	3965056
dense_1 (Dense)	(None, 3)	387
Total params: 3,989,027		

Total params: 3,989,027 Trainable params: 3,989,027 Non-trainable params: 0

```
epochs=180
history = model.fit(
train ds,
validation_data=val_ds,
epochs=epochs
    Epoch 1/180
    3/3 [================================] - 10s 3s/step - loss: 1.1035 - accuracy: 0.5185 - val_loss: 0.6255 - val_accuracy: 0.6500
    Epoch 2/180
    3/3 [============] - 3s 1s/step - loss: 0.8423 - accuracy: 0.4691 - val loss: 0.8067 - val accuracy: 0.3500
    Epoch 3/180
    3/3 [=====
                      ==========] - 5s 2s/step - loss: 0.7487 - accuracy: 0.5926 - val loss: 0.7424 - val accuracy: 0.5500
    Epoch 4/180
    3/3 [=============] - 3s 935ms/step - loss: 0.6632 - accuracy: 0.7778 - val_loss: 0.5086 - val_accuracy: 0.8000
    Epoch 5/180
    3/3 [=====
                     =========] - 3s 961ms/step - loss: 0.5411 - accuracy: 0.8765 - val_loss: 0.4208 - val_accuracy: 0.8000
    Epoch 6/180
    3/3 [=====
                          =======] - 5s 2s/step - loss: 0.4495 - accuracy: 0.8889 - val_loss: 0.3666 - val_accuracy: 0.8500
    Epoch 7/180
    3/3 [======
                    :=========] - 4s 1s/step - loss: 0.3994 - accuracy: 0.9012 - val_loss: 0.4395 - val_accuracy: 0.7000
    Epoch 8/180
                     ==========] - 3s 1s/step - loss: 0.3240 - accuracy: 0.9136 - val_loss: 0.3150 - val_accuracy: 0.8500
    3/3 [======
    Epoch 9/180
    Epoch 10/180
    3/3 [======
                        ========] - 6s 2s/step - loss: 0.1860 - accuracy: 0.9630 - val_loss: 0.3764 - val_accuracy: 0.8000
    Epoch 11/180
    3/3 [===========================] - 3s 957ms/step - loss: 0.1336 - accuracy: 0.9630 - val_loss: 0.3143 - val_accuracy: 0.8000
    Epoch 12/180
    3/3 [======
                     ========] - 5s 2s/step - loss: 0.0789 - accuracy: 0.9877 - val_loss: 0.4299 - val_accuracy: 0.8000
    Epoch 13/180
    3/3 [=============] - 3s 955ms/step - loss: 0.0504 - accuracy: 0.9877 - val loss: 0.3013 - val accuracy: 0.8500
    Epoch 14/180
                     =========] - 3s 1s/step - loss: 0.0328 - accuracy: 1.0000 - val_loss: 0.7301 - val_accuracy: 0.8000
    3/3 [=======
    Epoch 15/180
    3/3 [======
                    ==========] - 5s 2s/step - loss: 0.0160 - accuracy: 1.0000 - val_loss: 0.3902 - val_accuracy: 0.9000
    Epoch 16/180
    3/3 [======
                       ========] - 3s 998ms/step - loss: 0.0205 - accuracy: 1.0000 - val_loss: 0.5683 - val_accuracy: 0.8000
    Epoch 17/180
    3/3 [=======
                  Epoch 18/180
    3/3 [======
                       =========] - 4s 1s/step - loss: 0.0106 - accuracy: 1.0000 - val loss: 0.2962 - val accuracy: 0.9000
    Epoch 19/180
    3/3 [==============] - 3s 975ms/step - loss: 0.0069 - accuracy: 1.0000 - val loss: 0.4110 - val accuracy: 0.8500
    Epoch 20/180
    3/3 [=======
                   ==========] - 3s 1s/step - loss: 0.0013 - accuracy: 1.0000 - val_loss: 0.7574 - val_accuracy: 0.8000
    Epoch 21/180
    3/3 [============] - 3s 1s/step - loss: 0.0029 - accuracy: 1.0000 - val_loss: 0.8247 - val_accuracy: 0.8000
    Epoch 22/180
    3/3 [======
                         ========] - 3s 989ms/step - loss: 0.0014 - accuracy: 1.0000 - val_loss: 0.6453 - val_accuracy: 0.8000
    Epoch 23/180
    3/3 [===========] - 3s 949ms/step - loss: 6.3638e-04 - accuracy: 1.0000 - val_loss: 0.5155 - val_accuracy: 0.9
    Epoch 24/180
    3/3 [=======
                    Epoch 25/180
    3/3 [============] - 3s 1s/step - loss: 5.3514e-04 - accuracy: 1.0000 - val_loss: 0.4352 - val_accuracy: 0.8500
    Epoch 26/180
    3/3 [======
                    Epoch 27/180
    3/3 [=======
                    ==========] - 3s 1s/step - loss: 4.1922e-04 - accuracy: 1.0000 - val_loss: 0.4690 - val_accuracy: 0.8500
    Epoch 28/180
    3/3 [======
                   ===========] - 4s 2s/step - loss: 3.1578e-04 - accuracy: 1.0000 - val_loss: 0.5054 - val_accuracy: 0.8500
    Epoch 29/180
acc = history.history['accuracy']
val_acc = history.history['val_accuracy']
loss = history.history['loss']
val_loss = history.history['val_loss']
epochs_range = range(epochs)
plt.figure(figsize=(8, 8))
plt.subplot(1, 2, 1)
plt.plot(epochs_range, acc, label='Training Accuracy')
plt.plot(epochs_range, val_acc, label='Validation Accuracy')
plt.legend(loc='lower right')
plt.title('Training and Validation Accuracy')
plt.subplot(1, 2, 2)
plt.plot(epochs_range, loss, label='Training Loss')
plt.plot(epochs_range, val_loss, label='Validation Loss')
```

plt.legend(loc='upper right')

plt.title('Training and Validation Loss')
plt.show()



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