

CS 230 : Discrete Computational Structures

**Spring Semester, 2021**

HOMEWORK ASSIGNMENT #8

**Due Date:** Wednesday, Apr 7

**Suggested Reading:** Rosen Sections 5.3; Lehman et al. Chapters 5, 6.1 - 6.2, 7

For the problems below, explain your answers and show your reasoning.

1. [8 Pts] Prove that  $f_0 - f_1 + f_2 - \cdots - f_{2n-1} + f_{2n} = f_{2n-1} - 1$  where  $f_i$  are the Fibonacci numbers.

(a) Base case:  $k = 1$ ,  $f_0 - f_1 + f_2 = f_1 - 1$  aka  $0 - 1 + 1 = 1 - 1 = 0$

(b) Induction Hypothesis:  $f_0 - f_1 + f_2 - \cdots - f_{2k-1} + f_{2k} = f_{2k-1} - 1$

(c) Prove:  $f_0 - f_1 + f_2 - \cdots - f_{2k-1} + f_{2k} - f_{2(k+1)-1} + f_{2(k+1)} = f_{2(k+1)-1} - 1$

(d)  $(f_{2k-1} - 1) - f_{2(k+1)-1} + f_{2(k+1)} = f_{2(k+1)-1} - 1$  IH

(e)  $f_{2k-1} - f_{2k+1} + f_{2k+2} = f_{2k+1}$

(f)  $f_{2k-1} - f_{2k+1} + (f_{2k+1} + f_{2k}) = f_{2k+1}$   $f_{2k+2} = f_{2k+1} + f_{2k}$

(g)  $(f_{2k-1} + f_{2k}) = f_{2k+1}$

(h)  $f_{2k+1} = f_{2k+1}$  QED

2. [12 Pts] Let  $S$  defined recursively by (1)  $4 \in S$  and (2) if  $s \in S$  and  $t \in S$ , then  $st \in S$ . Let  $A = \{4^i \mid i \in \mathbb{Z}^+\}$ . Prove that

- (a) [6 Pts]  $A \subseteq S$  by mathematical induction.

i. Base case:  $k = 1$ ,  $4^1 = 4 \in S$

ii. Induction Hypothesis:  $s, t \in S$ ,  $4^k = st \in S$

iii. Prove:  $x, y \in S$ ,  $4^{k+1} = xy \in S$

iv.  $4 * 4^k = xy$

v.  $4 * st = xy$

vi.  $4 \in S$  and  $st \in S$ , so  $xy, 4^{k+1} \in S$

IH

QED

- (b) [6 Pts]  $S \subseteq A$  by structural induction.

i. Base case:  $4 = 4^1$ , so  $4 \in S$  and  $4 \in A$

ii. Induction Hypothesis:  $x, y \in S$ , assume  $x, y \in A$ . By (2),  $xy \in S$

iii. Prove:  $xy \in A$

iv.  $x, y \in A$ , so  $x = 4^a$ ,  $a \in \mathbb{Z}^+$  and  $y = 4^b$ ,  $b \in \mathbb{Z}^+$

IH

v.  $xy = 4^{a+b}$ ,  $a + b \in \mathbb{Z}^+$ . Therefore,  $xy \in A$

Def. of A; QED

3. [5 Pts] Define the set  $S = \{2^k 3^m 5^p \mid k, m, p \in \mathbb{Z}\}$  inductively. You do not need to prove that your construction is correct.

Basis:  $k, m, p = 0$ ,  $1 \in S$

Inductive Step: if  $a \in S$  and  $b \in \{2, 3, 5\}$ , then  $ab \in S$

4. [10 Pts] Consider the following state machine with five states, labeled 0, 1, 2, 3 and 4. The start state is 0. The transitions are  $0 \rightarrow 1$ ,  $1 \rightarrow 2$ ,  $2 \rightarrow 3$ ,  $3 \rightarrow 4$ , and  $4 \rightarrow 0$ .

Prove that if we take  $n$  steps in the state machine we will end up in state 0 if and only if  $n$  is divisible by 5. Argue that to prove the statement above by induction, we first have to *strengthen the induction hypothesis*. State the strengthened hypothesis and prove it.

- (a) Predicate:  $P(n)$ : After  $n$  steps, the state machine is in state 0 iff  $n$  is divisible by 5.
- (b) Basis:  $5 \mid 0$ , so  $P(0)$  is true
- (c) Inductive Step: Assume  $P(k)$
- (d) Prove:  $P(k + 1)$
- (e) Suppose  $5 \mid k$ . By IH, statemachine is in 0 after  $k$  steps. However,  $5 \nmid k + 1$  because the state machine is in state 1 after  $k + 1$  steps. State machine is in state 0 after  $k + 1$  steps iff  $5 \mid k + 1$ . Both are false, therefore  $P(k + 1)$
- (f) Should  $5 \nmid k$ , By IH, state machine is in state 1, 2, 3, or 4. We cannot know if going 1 step after  $k$  steps will result in state 0. We need a stronger hypothesis to account for the other states.
- (g) Stronger Induction Hypothesis:  $P(n)$ : After  $n$  steps, the state machine is in state  $p$ , where  $p = n \% 5$ .
- (h) Prove  $\forall n, P(n)$ 
  - i. Basis:  $n = 0$ , state machine is in state 0 and  $0 = 0 \% 5$
  - ii. Induction Steps:
    - A. Case 1:  $k \% 5 = 0$ , By IH, in state 0 after  $k$  steps.
    - B. Case 2:  $k \% 5 = 1$ , By IH, in state 1 after  $k$  steps.
    - C. Case 3:  $k \% 5 = 2$ , By IH, in state 2 after  $k$  steps.
    - D. Case 4:  $k \% 5 = 3$ , By IH, in state 3 after  $k$  steps.
    - E. Case 5:  $k \% 5 = 4$ , By IH, in state 4 after  $k$  steps.
  - iii. Proof by Case:
    - A. Case 1:  $k + 1 \% 5 = 1$ , By IH, in state 1 after  $k + 1$  steps.
    - B. Case 2:  $k + 1 \% 5 = 2$ , By IH, in state 2 after  $k + 1$  steps.
    - C. Case 3:  $k + 1 \% 5 = 3$ , By IH, in state 3 after  $k + 1$  steps.
    - D. Case 4:  $k + 1 \% 5 = 4$ , By IH, in state 4 after  $k + 1$  steps.
    - E. Case 5:  $k + 1 \% 5 = 0$ , By IH, in state 5 after  $k + 1$  steps.

5. [10 Pts] A robot wanders around a 2-dimensional grid. He starts out at (0,0) and can take the following steps: (-1,+3), (+2,-2) and (+4,0). Define a state machine for this problem. Then, define a Preserved Invariant and prove that the robot will never get to (2,0).

States:  $\{(a, b) \mid a, b \in \mathbb{Z}\}$ , Transitions:  
 $\{(a, b) \rightarrow (a - 1, b + 3), (a, b) \rightarrow (a + 2, b - 2), (a, b) \rightarrow (a + 4, b)\}$

- (a) Preserved Invariant Theorem: For every reachable state  $s = (a, b)$ ,  $(a - b) \% 4 = 0$   
 (b) Basis: (0,0) is reachable in 0 steps.  
 (c) Induction Hypothesis: Assume  $(r_1 - r_2) \% 4 = 0$  for any state  $r = (r_1, r_2)$  that is reachable in  $k$  steps.  
 (d) Prove:  $(s_1 - s_2) \% 4 = 0$  for any state  $s = (s_1, s_2)$  that is reachable in  $k + 1$  steps.  
 (e)  $r_1 - r_2 = 4n$ ,  $n \in \mathbb{Z}$  Definition of  $\% 4 = 0$   
 (f) 3 CASES:

- i. CASE 1: reach  $s$  in  $k + 1$  steps  
 ii.  $(s_1, s_2) = (r_1 - 1, r_2 + 3)$   
 iii.  $r_1 - 1 - (r_2 + 3) = 4n - 4$  by IH  
 iv.  $4(n - 1)$ , so  $(s_1 - s_2) \% 4 = 0$   
 i. CASE 2: reach  $s$  in  $k + 1$  steps  
 ii.  $(s_1, s_2) = (r_1 + 2, r_2 - 2)$   
 iii.  $r_1 + 2 - (r_2 - 2) = 4n + 4$  by IH  
 iv.  $4(n + 1)$ , so  $(s_1 - s_2) \% 4 = 0$   
 i. CASE 3: reach  $s$  in  $k + 1$  steps  
 ii.  $(s_1, s_2) = (r_1 + 4, r_2)$   
 iii.  $r_1 + 4 - r_2 = 4n + 4$  by IH  
 iv.  $4(n + 1)$ , so  $(s_1 - s_2) \% 4 = 0$

QED

- (g) Therefore, (2, 0) is not reachable because  $2 - 0 \% 4 = 2$ , not 0.

6. [15 Pts] Let  $L = \{(a, b) \mid a, b \in \mathbb{Z}, (a - b) \bmod 4 = 0\}$ . We want to program a robot that can get to each point  $(x, y) \in L$  starting at (0,0).

- (a) [5 Pts] Give an inductive definition of  $L$ . This will describe the steps you want the robot to take to get to points in  $L$  starting at (0,0). Let  $L'$  be the set obtained by your inductive definition.

$L'$  is the set of all points, starting at (0, 0), that is reachable taking the following steps: (-1,+3), (+2,-2), and (+4,0)

- (b) **Extra Credit** [5 Pts] Prove inductively that  $L' \subseteq L$ , i.e., every point that the robot can get to is in  $L$ .

- i. Base case: (0, 0) is a reachable in 0 steps defined by  $L'$  and in  $L$  because  $(0 - 0) \% 4 = 0$   
 ii. Inductive Hypothesis: Suppose  $(x, y) \in L'$ , therefore reachable by the defined steps.

- iii. Prove:  $(x, y) \in L$ .
- iv. By the Preserved Invariant Theorem proved in question 5, if  $(x, y) \in L'$ ,  $(x-y) \% 4 = 0$
- v. By definition of  $L$ ,  $(x, y) \in L$  QED
- (c) **Extra Credit [5 Pts]** Prove that  $L \subseteq L'$ , i.e., the robot can get to every point in  $L$ . To prove this, you need to give the path the robot would take to get to every point in  $L$  from  $(0, 0)$ , following the steps defined by your inductive rules.  
See Image:

Suppose  $\begin{bmatrix} a \\ b \end{bmatrix} \in L$ . So,  $a - b \% 4 = 0$

By the proven Preserved Invariant Theorem of  $L'$ ,  $\begin{bmatrix} a \\ b \end{bmatrix}$  is reachable by the defined steps.

That is,  $\begin{bmatrix} a \\ b \end{bmatrix}$  is a linear combination of  $\begin{bmatrix} -1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \end{bmatrix}$

$$\underset{A}{\begin{bmatrix} -1 & 2 & 4 \\ 3 & 2 & 0 \end{bmatrix}} \underset{X}{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}} = \begin{bmatrix} a \\ b \end{bmatrix}, \quad X \in \mathbb{N} \times \mathbb{N} \times \mathbb{N}$$

Since  $A$  contains 2 rows, at least 2 unique vectors, and more columns than rows,  $A$  is linearly dependent. This means we simply have one free variable. Therefore we can construct any positive integer solution coefficients for all  $v \in L$ . So,  $v \in L'$

$L \subseteq L'$

QED

For more practice, work on the problems from Rosen Sections 5.3; Lehman et al. Chapters 5, 6.1 - 6.2, 7