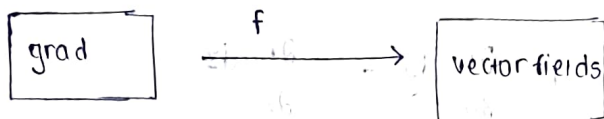


## Module - 2

→ Gradient : For a scalar (function)



Notation : grad on  $\vec{\nabla}$  (nabla).

$$\therefore \text{grad } \{f(x, y, z) \text{ (or)} \vec{\nabla} f(x, y, z)$$

$$\Rightarrow \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$$

Example : Let  $f(x, y, z) = x + y + z$  then

$$\text{grad } f_1(x, y, z) = \frac{\partial}{\partial x}(x+y+z) \hat{i} + \frac{\partial}{\partial y}(x+y+z) \hat{j} + \frac{\partial}{\partial z}(x+y+z) \hat{k}$$

$$\text{grad } (f_1) = \frac{\partial(f_1)}{\partial x} \hat{i} + \frac{\partial(f_1)}{\partial y} \hat{j} + \frac{\partial(f_1)}{\partial z} \hat{k}$$

$$\text{grad } f_1 = 1 \hat{i} + 1 \hat{j} + 1 \hat{k}$$

This is a constant vector.

$$* f_2(x, y, z) = x^2 y z$$

$$\text{grad } (f_2) = 2xyz \hat{i} + x^2 z \hat{j} + x^2 y \hat{k} \quad (\text{imp})$$

→ this is a ~~constant~~ vector.

→ one in many

grad  $(f_2)$  at particular point → then it is the vector

→ only one

$$\nabla T = \frac{\partial T}{\partial x} \hat{i} + \frac{\partial T}{\partial y} \hat{j} + \frac{\partial T}{\partial z} \hat{k}$$

(x, y, z)

det  $T$  is a scalar for  $T(x, y, z)$

$$dT = \frac{\partial T}{\partial x} dx + \frac{\partial T}{\partial y} dy + \frac{\partial T}{\partial z} dz$$

$$dT = \vec{\nabla} T \cdot d\vec{l}$$

where  $\vec{l} = x\hat{i} + y\hat{j} + z\hat{k}$  is the position vector

$$d\vec{l} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

$$dT = \vec{\nabla} T \cdot d\vec{l} = |\vec{\nabla} T| |d\vec{l}| \cos \theta \quad [\text{dot product}]$$

\* if we fix the magnitude  $|d\vec{l}|$  and search around various directions (i.e. we vary  $\theta$ ), the max<sup>m</sup> change the func<sup>n</sup> (i.e.  $T$ ) evidently occurs when  $\theta$  is zero ( $\cos \theta = 1$ )

\* which more precisely to say, for a fixed distance ( $|d\vec{l}| = \text{const}$ ),  $dT$  (change of the scalar) is max<sup>m</sup> where you move in the same dir<sup>n</sup> of  $\text{grad}(T)$

$$dT = \vec{\nabla} T \cdot d\vec{l} = |\vec{\nabla} T| |d\vec{l}| \cos \theta$$

\* The gradient ( $\vec{\nabla} T$ ) points in the max<sup>m</sup> increment of the func<sup>n</sup>.

\* The magnitude (i.e.  $|\vec{\nabla} T|$ ) gives the slope (rate of increment) along this maximal dir<sup>n</sup>.

⇒ The height of a certain hill.

$$H(x, y) = 10(2xy - 3x^2 - 4y^2 - 18x + 28y + 12)$$

where  $y$  is the dist<sup>n</sup> in north (some unit length)

$x$  is the dist<sup>n</sup> in east (some unit length)

i) Where is the top of the hill located?

ii) How high is the hill?

Sol<sup>n</sup> Using gradient

$$i) \frac{\partial H}{\partial x} = 10[2y - 6x - 18] = 0$$

$$\Rightarrow y = 3x + 9 \rightarrow (1)$$

$$\frac{\partial H}{\partial y} = 10[2x - 8y + 28] = 0$$

$$\Rightarrow x = 4y - 14 \rightarrow (2)$$

$$\therefore y = 3(4y - 14) + 9 \Rightarrow y = 12y - 42 + 9$$

$$\Rightarrow 11y = -33$$

$$\Rightarrow y = -3$$

$$\& x = -2$$

∴ Top of hill is located at 2 miles west

& 3 miles north.

$$ii) \text{ Height} = \sqrt{(-2-0)^2 + (3-0)^2} = \sqrt{4+9} = \underline{\underline{\sqrt{13}}}$$

~~Prob~~

⇒ Complete the following gradient

$\vec{\nabla} \eta$  where  $\vec{r}$  is the position vector

Soln: ATQ:  $\vec{r} = (x, y, z)$

$$|\vec{r}| = \sqrt{x^2 + y^2 + z^2}$$

grad is taken for magnitudes or scalar

$$\vec{\nabla} \eta = \frac{\partial \eta}{\partial x} \hat{i} + \frac{\partial \eta}{\partial y} \hat{j} + \frac{\partial \eta}{\partial z} \hat{k}$$

$$= \frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial x} \hat{i} + \frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial y} \hat{j} + \frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial z} \hat{k}$$

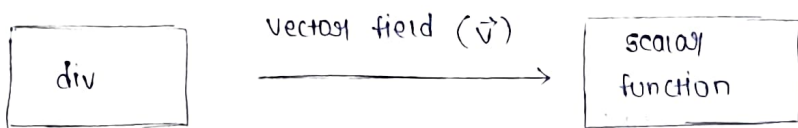
$$= \frac{x\hat{i} + y\hat{j} + z\hat{k}}{\sqrt{x^2 + y^2 + z^2}} = \frac{\vec{r}}{|\vec{r}|} = \hat{r} \text{ (unit vector)}$$

$$\therefore \vec{\nabla} \eta = \hat{r}$$

$$\boxed{\frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial x} = \frac{1}{2} \cdot (2x) = x}$$

# DIVERGENCE

\* Notation  $\longrightarrow \operatorname{div}(\vec{v})$  or  $\vec{\nabla} \cdot \vec{v}$



$$\vec{\nabla} \cdot \vec{v} = \left( \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z} \right) \quad \text{where } \vec{v} = (v_1, v_2, v_3)$$

$$v_1 = v_1(x, y, z)$$

$$v_2 = v_2(x, y, z) \Rightarrow v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}$$

$$v_3 = v_3(x, y, z)$$

$$\Rightarrow \vec{v}_1 = x \hat{i} + y \hat{j}$$

$$\text{Soln} \quad \operatorname{div}(\vec{v}_1) = 1 + 1 = 2 \quad (\text{const})$$

$$\Rightarrow \vec{v}_2 = x^2 \hat{i} + y^2 \hat{j} \Rightarrow \operatorname{div}(\vec{v}_2) = 2(x+y) \quad (\text{not const})$$

But if we choose a point, then it is const.

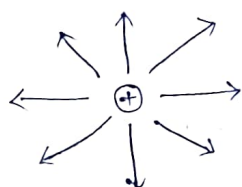
$$\therefore \operatorname{div}(\vec{v}_2)|_P = 2(a_1 + a_2) = \text{const}$$

$$\therefore \operatorname{div}(\vec{v})|_P > 0 \longrightarrow \text{Fountain}$$

$$\operatorname{div}(\vec{v})|_P < 0 \longrightarrow \text{Sink}$$

$$\operatorname{div}(\vec{v})|_P = 0 \longrightarrow \text{Streamline}$$

\*



electric field  
 $\vec{E} = (x, y)$

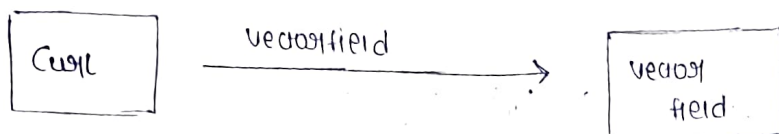
$$\operatorname{div}(\vec{E})|_P > 0 \quad (\text{Fountain})$$

\*  $\vec{\nabla} \cdot \vec{A}$ , looks like dot product, but it is not

Because  $\vec{\nabla} \cdot \vec{A} \neq \vec{A} \cdot \vec{\nabla}$

## CURL

\* Notation:  $\text{curl}(\vec{A})$  or  $\vec{\nabla} \times \vec{A}$



$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix}$$

where

$$\vec{A} = (A_1, A_2, A_3)$$

$$A_n = A_n(x, y, z)$$

$$n = 1, 2, 3$$



$$\hat{i} \left( \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \hat{j} \left( \frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \hat{k} \left( \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right)$$

$$\Rightarrow \vec{v}_1 = (-y, x) \quad \text{curl}(\vec{v}_1)$$

So only  $\text{curl}(\vec{v}_1) = \vec{v}_1 = (-y, x, 0)$  using this

$$\text{curl}(\vec{v}_1) = \hat{k}$$

$$\Rightarrow \vec{v}_2 = (0, x, 0) \Rightarrow \text{curl}(\vec{v}_2) = \hat{k}$$

So only

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & x & 0 \end{vmatrix} \Rightarrow \hat{i} \left( 0 - \frac{\partial x}{\partial z} \right) - \hat{j} (0 - 0) + \hat{k} \left( \frac{\partial x}{\partial x} - 0 \right)$$

$$\Rightarrow \underline{\underline{\hat{k}}} \text{ (Ans)}$$

30-Aug-2023

# VOLUME / SURFACE INTEGRAL :

\* line Integral :  $\int \vec{A} \cdot d\vec{l} \Rightarrow \int f(x) dx$

\* Surface Integral :  $\iint f(x,y) dx dy$

(or)

$\iint \vec{A} \cdot d\vec{s}$  or  $\iint_{\text{surf}} \vec{A} \cdot d\vec{s}$

\* Volume Integral :  $\iiint f(x,y,z) dx dy dz$

$\Rightarrow \int_{\text{vol}} T(x,y,z) dz$

## # THREE THEOREMS :

\*  $\int_{\vec{a}}^{\vec{b}} (\text{grad } T) \cdot d\vec{l} = T(\vec{b}) - T(\vec{a})$

\*  $\int_{\text{vol}} (\text{div } \vec{v}) dz = \int_{\text{surf}} \vec{v} \cdot d\vec{s}$  (divergence theorem).

\*  $\int_{\text{surf}} (\text{curl } \vec{v}) \cdot d\vec{s} = \int_{\text{line}} \vec{v} \cdot d\vec{l}$  (Stokes theorem).

## # Maxwell's Eq<sup>n</sup> IN DIFFERENTIAL FORMAT :

\* Gauss law of electrostatics :  $\vec{\nabla} \cdot \vec{E} = \frac{\rho_{\text{gen}}}{\epsilon_0}$

$\iint \vec{E} \cdot d\vec{s} = \frac{\rho_{\text{gen}}}{\epsilon_0} \Rightarrow \int (\vec{\nabla} \cdot \vec{E}) dz = \frac{\iiint \rho dz}{\epsilon_0}$

using divergence theorem.

$(\vec{A} \cdot \vec{v}) \text{ corp} = (\vec{A}_{\text{new}})_{\text{new}}$



\* Gauss law of magnetostatics :  $\vec{\nabla} \cdot \vec{B} = 0$  (no magnetic monopoles)

\* Faraday's law :  $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\phi_0}{dt}$$

$$\Rightarrow \iint_{\text{surf}} (\vec{\nabla} \times \vec{E}) \cdot d\vec{s} = -\frac{d}{dt} \iint_{\text{surf}} \vec{B} \cdot d\vec{s} \quad \phi = \int \vec{B} \cdot d\vec{s}$$

\* Ampere's law :  $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$ , where  
(modified)

$\vec{J}$  is current density.

|| Maxwell's Eq<sup>N</sup> IN FREE SPACE : ( $\rho=0, \vec{J}=0$ ).

$$* \vec{\nabla} \cdot \vec{E} = 0$$

$$* \vec{\nabla} \cdot \vec{B} = 0$$

$$* \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$* \vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

|| Maxwell's WAVE Eq<sup>N</sup> IN FREE SPACE : (Derivation).

\* We need to use a vector identity.

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A}$$

(091)

$$\text{curl (curl } \vec{A}) = \text{grad (div } \vec{A}) - \text{Lap} (\vec{A})$$



→ Case - 1 : For electric field ( $\vec{E}$ )

$$\text{LHS : } \vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \vec{\nabla} \times \left( -\frac{\partial \vec{B}}{\partial t} \right)$$

$$= -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B})$$

$$= -\frac{\partial}{\partial t} (\mu_0 \epsilon_0 \frac{d\vec{E}}{dt}) = -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\text{RHS : } \vec{\nabla} \cdot (\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\nabla^2 \vec{E} \quad \leftarrow \text{Wolt}$$

$$\therefore -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = -\nabla^2 \vec{E}$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} = \nabla^2 \vec{E}$$

$$\Rightarrow \left( \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \vec{E} = 0$$

$$\square \vec{E} = 0$$

→ Case - 2 : For magnetic field : ( $\vec{B}$ )

$$\square \vec{B} = 0$$

$$\square \left\{ \begin{matrix} \vec{E} \\ \vec{B} \end{matrix} \right\} = 0, \text{ in free space}$$

\* Important :

$$\text{i) curl (grad } f) = \nabla \times \nabla f = 0$$

$$\text{ii) div (grad } f) = \nabla \cdot \nabla f = \nabla^2 f$$

$$\text{iii) div (curl } f) = \nabla \cdot (\nabla \times f) = 0$$

imp. (proof after 2 pgs)

$$\text{Trick: } \text{CG}_1, \text{DC} = 0$$

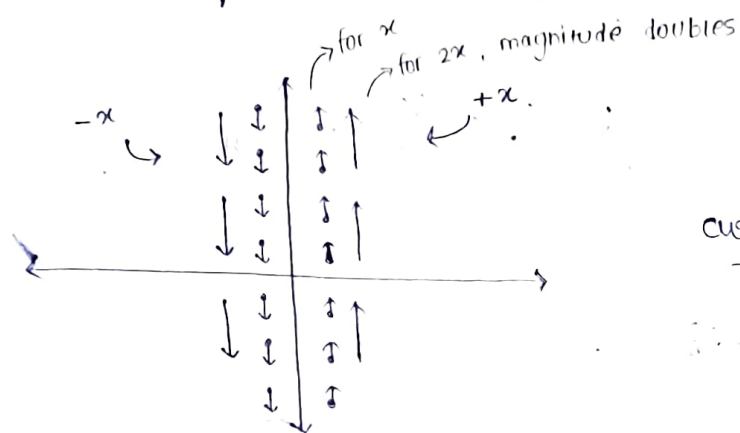
$$\text{DG}_1 = \nabla^2 \downarrow$$

$$\text{(03) } \text{DCCG}_1 = 0$$

# # PROBLEMS ON MODULE - 2 :

•  $\Rightarrow \vec{V}_1 = x \hat{j}$  , Plot this vector field in the (x,y) plane.

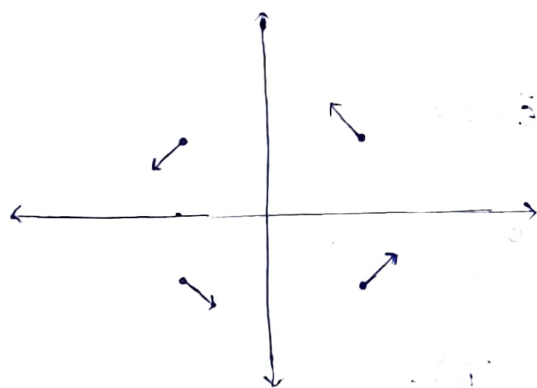
Soln)



$$\text{curl } \vec{V}_1 = \hat{k}$$

$\Rightarrow \vec{V}_2 (x, y) = (-y, x) = -y \hat{i} + x \hat{j}$

Soln)



$$V_2 (1, 1) = -\hat{i} + \hat{j}$$

$$V_2 (-1, 1) = -\hat{i} - \hat{j}$$

$$V_2 (-1, -1) = +\hat{i} - \hat{j}$$

$$V_2 (1, -1) = +\hat{i} + \hat{j}$$

$$\therefore \text{curl}(\vec{V}_2) = 2\hat{k}$$

$\Rightarrow$  Compute  $\text{grad}(\eta^n)$ .

Soln)  $\vec{\eta} = x \hat{i} + y \hat{j} + z \hat{k}$

$$\eta = \sqrt{x^2 + y^2 + z^2}$$

$$\eta^n = (x^2 + y^2 + z^2)^{n/2}$$

$$\Rightarrow \frac{\partial}{\partial x} [(x^2 + y^2 + z^2)^{n/2}] = \frac{n-2}{2} [2x + 2y + 2z]$$

$$\Rightarrow \underline{\underline{\frac{n}{2} \eta^{n-2} \vec{\eta}}}$$

$$\vec{\nabla} \eta^n = n \eta^{n-2} \vec{\eta}$$

$$\vec{\nabla} \eta = \frac{\vec{\eta}}{\eta} = \hat{\eta} \rightarrow \text{from pre que.}$$

partial diff.

⇒ Compute  $\nabla^2 \left( \frac{1}{r} \right)$ .

Soln/  $\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$

$$\therefore \frac{\partial}{\partial x} \left( \frac{\partial}{\partial x} (x^2 + y^2 + z^2)^{-1/2} \right) \Rightarrow \frac{\partial}{\partial x} \left( -\frac{1}{2} (x^2 + y^2 + z^2)^{-3/2} (2x) \right)$$

$$\Rightarrow \frac{\partial}{\partial x} \left( -x (x^2 + y^2 + z^2)^{-3/2} \right)$$

$$\Rightarrow \frac{\partial}{\partial x} \left( \frac{-x}{(x^2 + y^2 + z^2)^{3/2}} \right)$$

$$\Rightarrow \frac{(x^2 + y^2 + z^2)^{3/2} (-1) - (-x) \left( \frac{3}{2} (x^2 + y^2 + z^2)^{1/2} (2x) \right)}{(x^2 + y^2 + z^2)^3}$$

$$\Rightarrow \frac{-(x^2 + y^2 + z^2)^{3/2} + 3x^2 (x^2 + y^2 + z^2)^{1/2}}{(x^2 + y^2 + z^2)^3}$$

$$\Rightarrow \frac{3x^2 (x^2 + y^2 + z^2)^{1/2} - (x^2 + y^2 + z^2)^{3/2}}{(x^2 + y^2 + z^2)^3}$$

$$\Rightarrow \frac{(x^2 + y^2 + z^2)^{1/2} [3x^2 - (x^2 + y^2 + z^2)]}{(-)^3}$$

$$\Rightarrow \frac{\partial x^2 - y^2 - z^2}{(-)^{5/2}}$$

∴ similarly : for y :

$$\frac{\partial y^2 - x^2 - z^2}{(-)^{5/2}}$$

$$\left( \frac{\partial}{\partial x} \right) \left( \frac{\partial}{\partial x} \right) \left( \frac{1}{r} \right) = \frac{\partial x^2 - y^2 - z^2}{(-)^{5/2}}$$

∴ Add we get zero

Hence :  $\nabla^2 \left( \frac{1}{r} \right) = 0$

$$\Rightarrow \text{curl} (\text{grad } f) = ? \quad , \quad f = f(x, y, z)$$

$$\Rightarrow \text{div} (\text{curl } \vec{A}) = ? \quad , \quad \vec{A} = (f_1(x, y, z), f_2(x, y, z), f_3(x, y, z))$$

Sol<sup>n</sup> 1)

$$\text{curl} (\text{grad } f)$$

$$\text{grad } f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$$

$$\text{curl} (\text{grad } f) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix}$$

$$\Rightarrow \hat{i} \left( \frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right) - \hat{j} \left( \frac{\partial^2 f}{\partial x \partial z} - \frac{\partial^2 f}{\partial z \partial x} \right) + \hat{k} \left( \frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right)$$

$$= 0\hat{i} + 0\hat{j} + 0\hat{k}$$

Sol<sup>n</sup> 2)

$$\text{div} (\text{curl } \vec{A})$$

$$\text{curl } \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_1 & f_2 & f_3 \end{vmatrix}$$

$$\Rightarrow \hat{i} \left( \frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \right) - \hat{j} \left( \frac{\partial f_3}{\partial x} - \frac{\partial f_1}{\partial z} \right) + \hat{k} \left( \frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right)$$

$$\text{div} (\text{curl } \vec{A}) = \frac{\partial}{\partial x} \left( \frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \right) - \frac{\partial}{\partial y} \left( \frac{\partial f_3}{\partial x} - \frac{\partial f_1}{\partial z} \right) + \frac{\partial}{\partial z} \left( \frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right)$$

$$= \frac{\partial^2 f_3}{\partial x \partial y} - \frac{\partial^2 f_2}{\partial x \partial z} - \frac{\partial^2 f_3}{\partial y \partial x} + \frac{\partial^2 f_1}{\partial y \partial z} + \frac{\partial^2 f_2}{\partial z \partial x} - \frac{\partial^2 f_1}{\partial z \partial y}$$

$$= \underline{\underline{0}} \quad (\text{Ans})$$

(Qualitatively and Quantitatively)

→ Maxwell's eq<sup>n</sup> before modification.

$$* \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$* \vec{\nabla} \cdot \vec{B} = 0$$

$$* \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Apply the th<sup>m</sup> in eq<sup>n</sup> (3).

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E}) = \vec{\nabla} \cdot \left( -\frac{\partial \vec{B}}{\partial t} \right)$$

$$\parallel \quad \parallel$$

$$0 \quad -\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{B}) = 0$$

$$* \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Apply the th<sup>m</sup> in eq<sup>n</sup> (4).

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J})$$

$$\parallel \quad \parallel$$

$$0 \quad 0$$

$$* \text{Theorem : } \text{div} (\text{curl } \vec{A}) = 0$$

$$* \vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} \rightarrow \text{continuity eq<sup>n</sup> in electrodynamics.}$$

$$\therefore \vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}) + \vec{\nabla} \cdot \left( \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}) + \mu_0 \left( \epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) \right)$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}) + \mu_0 \epsilon_0 \frac{\partial \rho}{\partial t}$$

Hence, Maxwell's eq<sup>n</sup> after modification :

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \vec{J}_d$$

→ displ<sup>n</sup> current

$$\therefore \underline{\underline{\vec{J}_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t}}}$$

$$\vec{\nabla} \cdot \vec{J} + \vec{\nabla} \cdot (\#)$$

to get zero  
we have to  
add some value

$$\therefore \vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$\therefore (\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}) \rightarrow -\frac{\partial}{\partial t} (\epsilon_0 \vec{\nabla} \cdot \vec{E})$$

$$= -\epsilon_0 \left( \vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t} \right)$$

$$\therefore \vec{\nabla} \cdot \left[ \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right]$$

⇒ let  $\vec{v}$  be a vector value func<sup>n</sup> :

$$\vec{v} = (-4x - 3y + 4z, -3x + 3y + 5z, 4x + 5y + 3z)$$

Find a scalar func<sup>n</sup>  $f(x, y, z)$  such that  $\vec{v} = \text{grad}(f)$

Sol<sup>n</sup> 
$$\vec{v} = \frac{\partial(f)}{\partial x} \hat{i} + \frac{\partial(f)}{\partial y} \hat{j} + \frac{\partial(f)}{\partial z} \hat{k}$$

$\therefore \frac{\partial(f)}{\partial x} = -4$

But to get  $f$ , we need to do partial integration.

$\therefore \vec{f} = (-2x^2 - 3xy + 4xz), (-\frac{3}{2}x^2 + 3xy + 5xz)$

$$f = (-2x^2 - 3xy + 4xz), (-3xy + \frac{3}{2}y^2 + 5zy), (4xz + 5yz + \frac{3}{2}z^2)$$

$$\therefore f(x, y, z) = -2x^2 + \frac{3}{2}y^2 + \frac{3}{2}z^2 - 3xy + 4xz + 5zy$$

only repeat once

∵ when diff w.r.t  $x, y, z$ , same

value gives two values.

## # DEFINITIONS : (IMP)

→ GRADIENT :

- \* It is a vector quantity but it is applied on scalar quantity.
- \* It explains the variations of function in  $x, y, z = \text{dir}^n$ .
- \* ex : if we apply gradient to function of temp, then from gradient we can understand rate of change of temp in  $x, y$  &  $z = \text{dir}^n$ .



→ DIVERGENCE :

- \* It is scalar quantity but applied on vector quantity.
- \* ~~it explains overall variation of function in x, y & z dir<sup>n</sup>.~~
- \* it explains how fast the area of span is changing.
- \* ex: If 4 friends float down the river, each making corner square. If square is getting bigger, then river has +ve div, if it shrinks then -ve div.

→ CURL :

- \* It is a vector quantity & applied on vector quantity.
- \* It describes the circulation of vector field in 3-D space.
- \* ex: At surface of river turbine rotate fast but ~~at~~ inside the river it rotates slowly.

→ Explanation of 4 Maxwells eq<sup>n</sup>:

- i) Electric field diverges from electric charge.
- ii) There are no isolated magnetic poles
- iii) ~~The~~ Electric field are produced by changing magnetic fields
- iv) circulating magnetic field are produced by changing electric fields.

→ Displacement Current :

The change in electric field gives rise to a current.  
As a result, magnetic field is induced.



→ Assumption of string vibration :

\* Strings are assumed to be inextensible

\* The vibratory displ<sup>n</sup> are small

\* The  $\theta$  is very small.