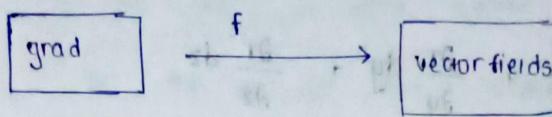


MODULE - 2

→ Gradient : For a scalar (function)



Notation : grad or $\vec{\nabla}$
(nabia).

$$\therefore \text{grad } f(x,y,z) \text{ (or) } \vec{\nabla} f(x,y,z)$$

$$\Downarrow \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$$

* $f_1(x,y,z) = (x+y+z)$ (e.g. x, y, z) smooth

$$\text{grad } (f_1) = \frac{\partial (f_1)}{\partial x} \hat{i} + \frac{\partial (f_1)}{\partial y} \hat{j} + \frac{\partial (f_1)}{\partial z} \hat{k}$$

$$\text{Ansatz basis} = 1\hat{i} + 1\hat{j} + 1\hat{k}$$

From this (is 'a' constant vector) it has infinite points.

* $f_2(x,y,z) = x^2yz$ so, we call it as vector fields.

$$\text{grad } (f_2) = 2xyz \hat{i} + x^2z \hat{j} + x^2y \hat{k}$$

↳ this is 'a' constant vector.

so, we can say \vec{f} is one in many.

grad (f_2) at particular point → then it is the vector

(constant vector) equal to $(1,1,1)$ by one.

Take random the prob

$$\nabla \vec{\Delta T} = \frac{\partial T}{\partial x} \hat{i} + \frac{\partial T}{\partial y} \hat{j} + \frac{\partial T}{\partial z} \hat{k}$$

$\det T$ is a scalar for $T(x, y, z)$

$$dT = \frac{\partial T}{\partial x} dx + \frac{\partial T}{\partial y} dy + \frac{\partial T}{\partial z} dz$$

$$dT = \vec{\nabla T} \cdot d\vec{r}$$

where $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ is the position vector

$$d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

$$dT = \vec{\nabla T} \cdot d\vec{r} = |\vec{\nabla T}| |\vec{dr}| \cos \theta \quad [\text{dot product}]$$

* if we fix the magnitude $|d\vec{r}|$ and search around various directions (i.e., we vary θ), the max^m change the funcⁿ (*i.e.* T) evidently occurs when θ is zero ($\cos \theta = 1$)

* which more precisely to say, for a fixed distant ($|d\vec{r}| = \text{const}$), dT (change of the scalar) is max^m where you move in the same dirⁿ of grad(T)

$$dT = \vec{\nabla T} \cdot d\vec{r} = |\vec{\nabla T}| |\vec{dr}| \cos \theta$$

* The gradient ($\vec{\nabla T}$) points in the max^m increment of the funcⁿ.

* The magnitude (*i.e.*, $|\vec{\nabla T}|$) gives the slope (rate of increment) along this maximal dirⁿ.

\Rightarrow The height of a certain hill.

$$H(x,y) = 50(2xy - 3x^2 - 4y^2 - 18x + 88y + 12)$$

where y is the distn in north (some unit length).

x is the distn in east (some unit length).

i) Where is the top of the hill located?

ii) How high is the hill?

Sol) Using gradient

$$\text{if } \frac{\partial H}{\partial x} = \frac{\partial H}{\partial x} = 50[2y - 6x - 18] = 0$$

$$\Rightarrow y = 3x + 9 \rightarrow ①$$

$$\frac{\partial H}{\partial y} = 50[2x - 8y + 28] = 0$$

$$\Rightarrow x = 4y - 14 \rightarrow ②$$

$$\therefore y = 3(4y - 14) + 9 \Rightarrow y = 12y - 42 + 9.$$

$$\Rightarrow 11y = 33$$

$$\Rightarrow y = 3$$

$$\& x = -2$$

\therefore Top of hill is located at 2 miles west

& 3 miles north.

$$\text{ii) Height} = \sqrt{(-2-0)^2 + (3-0)^2} = \sqrt{4+9} = \underline{\underline{\sqrt{13}}}$$

~~Prob~~

⇒ Complete the following gradient?

$\vec{\nabla} \vec{r}$ where \vec{r} is the position vector

Ans) ATQ : $\vec{r} = (x, y, z)$

$$|\vec{r}| = \sqrt{x^2 + y^2 + z^2}$$

$$\vec{\nabla} \vec{r} = \frac{\partial \vec{r}}{\partial x} \hat{i} + \frac{\partial \vec{r}}{\partial y} \hat{j} + \frac{\partial \vec{r}}{\partial z} \hat{k}$$

grad is taken for magnitudes or scalar

$$= \frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial x} \hat{i} + \frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial y} \hat{j} + \frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial z} \hat{k}$$

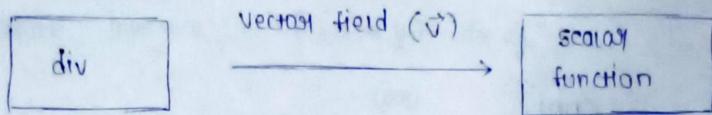
$$= \frac{x\hat{i} + y\hat{j} + z\hat{k}}{\sqrt{x^2 + y^2 + z^2}} = \frac{\vec{r}}{|\vec{r}|} = \hat{r}$$
 (unit vector)

$$\text{∴ } \vec{\nabla} \vec{r} = \hat{r}$$

$$\boxed{\frac{\partial \sqrt{x^2 + y^2 + z^2}}{\partial x} = \frac{1}{2}(2x) = x}$$

DIVERGENCE

* Notation $\rightarrow \operatorname{div}(\vec{v})$ or $\vec{\nabla} \cdot \vec{v}$



$$\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z} \right) \quad \text{where } \vec{v} = (v_1, v_2, v_3)$$

$$v_1 = v_1(x, y, z)$$

$$v_2 = v_2(x, y, z) \Rightarrow v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}$$

$$v_3 = v_3(x, y, z)$$

$$\Rightarrow \vec{v}_1 = x \hat{i} + y \hat{j}$$

$$\text{So? } \operatorname{div}(\vec{v}_1) = 1 \hat{i} + 1 \hat{j} = 2 \text{ (const)}$$

$$\Rightarrow \vec{v}_2 = x^2 \hat{i} + y^2 \hat{j} \Rightarrow \operatorname{div}(\vec{v}_2) = 2(x+y) \text{ (not const)}$$

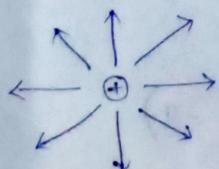
But if we choose a point, then it is const.

$$\therefore \operatorname{div}(\vec{v}_2)|_P = 2(a_1+a_2) = \text{const}$$

$$\therefore \operatorname{div}(\vec{v})|_P > 0 \rightarrow \text{Fountain}$$

$$\operatorname{div}(\vec{v})|_P < 0 \rightarrow \text{Sink}$$

$$\operatorname{div}(\vec{v})|_P = 0 \rightarrow \text{Streamline}$$



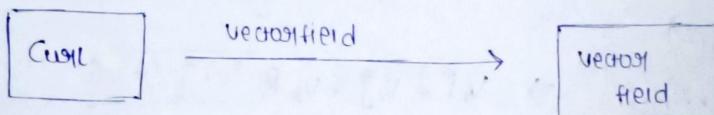
electric field
 $\vec{E} = (x, y)$

$$\operatorname{div}(\vec{E})|_P > 0 \text{ (Fountain)}$$

* $\vec{\nabla} \cdot \vec{A}$, looks like dot product, but it is not
Because $\vec{\nabla} \cdot \vec{A} \neq \vec{A} \cdot \vec{\nabla}$

CURL

* Notation : $\text{curl}(\vec{A})$ or $\vec{\nabla} \times \vec{A}$



$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} \quad \text{where } \vec{A} = (A_1, A_2, A_3) \Rightarrow A_n \Rightarrow A_n(x, y, z), \quad n = 1, 2, 3.$$

$$\hat{i} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \hat{j} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \hat{k} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right)$$

$$\Rightarrow \vec{v}_1 = (-y, x), \quad \text{curl}(\vec{v}_1)$$

$$\text{so } \text{curl}(\vec{v}_1) \Rightarrow \vec{v}_1 = (-y, x, 0) \quad \text{using this}$$

$$\text{curl}(\vec{v}_1) = \vec{\nabla} \cdot \vec{A}$$

$$\Rightarrow \vec{v}_2 = (0, x, 0) \Rightarrow \text{curl}(\vec{v}_2) = \hat{k}$$

$$\text{so } \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & x & 0 \end{vmatrix} \Rightarrow \hat{i}(0 - \frac{\partial x}{\partial z}) - \hat{j}(0 - 0) + \hat{k}(\frac{\partial x}{\partial x} - 0) \Rightarrow \hat{k} (\text{Ans})$$

30-Aug-2023

VOLUME / SURFACE INTEGRAL

* Line Integral : $\int \vec{A} \cdot d\vec{l} \Rightarrow \int f(x) dx$

* Surface Integral : $\iint f(x,y) dx dy$
(or)

$$\iint \vec{A} \cdot d\vec{s} \text{ or } \iint \vec{A} \cdot d\vec{s}$$

surf

* Volume Integral : $\iiint f(x,y,z) dx dy dz$

$$\Rightarrow \int T(x,y,z) dz$$

vol

(inuition)

THREE THEOREMS OF \vec{F}

* $\int_{\vec{a}}^{\vec{b}} (\nabla \cdot \vec{F}) \cdot d\vec{l} = T(\vec{b}) - T(\vec{a})$

* $\int_{\text{VOL}} (\text{div } \vec{v}) dz = \iint_{\text{surf.}} \vec{v} \cdot d\vec{s}$ (divergence theorem).

* $\iint_{\text{surf}} (\text{curl } \vec{v}) \cdot d\vec{s} = \int_{\text{line}} \vec{v} \cdot d\vec{l}$ (stokes theorem).

MAXWELL'S Eqs IN DIFFERENTIAL FORMAT :

* Gauss law of electrostatics : $\vec{\nabla} \cdot \vec{E} = \frac{P_{\text{gen}}}{\epsilon_0}$

$$\iint \vec{E} \cdot d\vec{s} = \frac{P_{\text{gen}}}{\epsilon_0} \Rightarrow \iint (\vec{\nabla} \cdot \vec{E}) dz = \frac{\iint P dz}{\epsilon_0}$$

using divergence theorem.

(3) $E_x = (A_{x0})_{\text{out}} - (A_{x0})_{\text{in}}$

* Gauss law of magnetostatics : $\nabla \cdot \vec{B} = 0$ (no magnetic monopoles)

* Faraday's law : $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\phi_B}{dt}$$

$$\Rightarrow \iint_{\text{surf}} (\nabla \times \vec{E}) \cdot d\vec{s} = -\frac{d}{dt} \iint_{\text{surf}} \vec{B} \cdot d\vec{s} \quad \rightarrow \phi = \int \vec{B} \cdot d\vec{s}$$

* Ampere's law : $\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$, where
(modified)

\vec{J} is current density.

MAXWELL'S Eqs IN FREE SPACE : ($\rho=0$, $\vec{J}=0$).

* $\nabla \cdot \vec{E} = 0$

* $\nabla \cdot \vec{B} = 0$

* $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

* $\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

MAXWELL'S WAVE Eqs IN FREE SPACE : (Derivation).

* We need to use a vector identity.

$$\nabla \times (\nabla \times \vec{A}) = \nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A}$$

(eq)

$$\text{curl}(\text{curl } \vec{A}) = \text{grad}(\text{div } \vec{A}) - \text{Lap}(\vec{A})$$

→ Case - 1 : For electric field (\vec{E})

$$\text{LHS} : \vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \vec{\nabla} \times \left(-\frac{\partial \vec{B}}{\partial t} \right)$$

$$= -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B})$$

$$= -\frac{\partial}{\partial t} \left(\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) = -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

RHS : ~~$\vec{\nabla} \cdot (\vec{\nabla} \cdot \vec{E})$~~ - $\nabla^2 \vec{E}$ ← 1066 L

$$\rightarrow -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = -\nabla^2 \vec{E}$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} = \nabla^2 \vec{E}$$

$$\Rightarrow \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \vec{E} = 0.$$

$$\square \vec{E} = 0.$$

→ Case - 2 : For magnetic field : (\vec{B}) .

$$\square \vec{B} = 0.$$

$$\square \left\{ \begin{array}{l} \vec{E} \\ \vec{B} \end{array} \right\} = 0, \text{ in free space.}$$

* Important :

i) curl (grad f) = $\nabla \times \nabla f = 0$.

ii) div (grad f) = $\nabla \cdot \nabla f = \nabla^2 f$

iii) div (curl f) = $\nabla \cdot (\nabla \times f) = 0$.

} imp. (proof after 2 pgs.)

Trick: CG, DC = 0

$$DG = \nabla^2 J$$

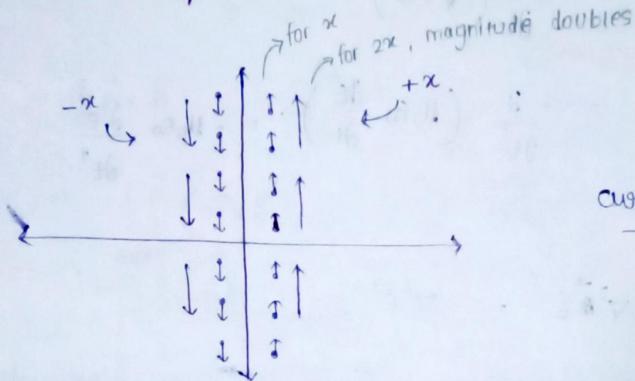
$$DCG = 0$$

31-08-23

PROBLEMS ON MODULE - 2 :

$\Rightarrow \vec{v}_1 = x\hat{i}$, Plot this vector field in the (x,y) plane.

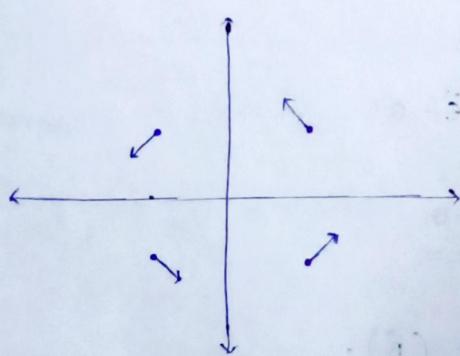
soln)



$$\text{curl } \vec{v}_1 = \hat{k}$$

$$\Rightarrow \vec{v}_1(x,y) = (-y, x) = -y\hat{i} + x\hat{j}$$

soln)



$$v_2(1,1) = -\hat{i} + \hat{j}$$

$$v_2(-1,1) = -\hat{i} + \hat{j}$$

$$v_2(-1,-1) = \hat{i} - \hat{j}$$

$$v_1(1,-1) = \hat{i} + \hat{j}$$

$$\therefore \text{curl } (\vec{v}_2) = 2\hat{k}$$

\Rightarrow Compute grad (η^n)

$$\eta^n = (x^2 + y^2 + z^2)^{\frac{n}{2}}$$

$$\text{soln) } \vec{\eta} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\eta = \sqrt{x^2 + y^2 + z^2}$$

$$\vec{\eta} = n\eta^{n-2} \vec{\eta}$$

$$\vec{\nabla} \eta = \frac{\vec{\eta}}{\eta^2} = \frac{\vec{\eta}}{\eta} \rightarrow \text{from pre que.}$$

partial diff.

$$\Rightarrow \frac{\eta}{\eta^2} [x^2 + y^2 + z^2]^{\frac{n-2}{2}} [2x + 2y + 2z]$$

$$\Rightarrow n\eta^{n-2} \vec{\eta}$$

$$\vec{\nabla} \eta = \frac{\vec{\eta}}{\eta^2} = \frac{\vec{\eta}}{\eta} \rightarrow \text{from pre que.}$$

$$\vec{\nabla} \eta = \frac{\vec{\eta}}{\eta^2} = \frac{\vec{\eta}}{\eta} \rightarrow \text{from pre que.}$$

$$\vec{\nabla} \eta = \frac{\vec{\eta}}{\eta^2} = \frac{\vec{\eta}}{\eta} \rightarrow \text{from pre que.}$$

\Rightarrow Compute $\nabla^2 \left(\frac{1}{r} \right)$.

Sol' / $\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$

$$\begin{aligned}\therefore \frac{\partial}{\partial x} \left(\frac{\partial}{\partial x} (x^2 + y^2 + z^2)^{-\frac{1}{2}} \right) &\Rightarrow \frac{\partial}{\partial x} \left(-\frac{1}{2} (x^2 + y^2 + z^2)^{-\frac{3}{2}} (2x) \right) \\ &\Rightarrow \frac{\partial}{\partial x} \left(-x (x^2 + y^2 + z^2)^{-\frac{3}{2}} \right) \\ &\Rightarrow \frac{\partial}{\partial x} \left(\frac{-x}{(x^2 + y^2 + z^2)^{\frac{3}{2}}} \right) \\ &\Rightarrow \frac{(x^2 + y^2 + z^2)^{\frac{3}{2}} (-1) - (-x) \left(\frac{3}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} (2x) \right)}{(x^2 + y^2 + z^2)^3} \\ &\Rightarrow \frac{- (x^2 + y^2 + z^2)^{\frac{3}{2}} + 3x^2 (x^2 + y^2 + z^2)^{\frac{1}{2}}}{(x^2 + y^2 + z^2)^3} \\ &\Rightarrow \frac{3x^2 (x^2 + y^2 + z^2)^{\frac{1}{2}} + - (x^2 + y^2 + z^2)^{\frac{1}{2}} (x^2 + y^2 + z^2)}{(x^2 + y^2 + z^2)^3} \\ &\Rightarrow \frac{(x^2 + y^2 + z^2)^{\frac{1}{2}} [3x^2 - (x^2 + y^2 + z^2)]}{(-)^3} \\ &\Rightarrow \frac{\partial x^2 - y^2 - z^2}{(-)^{\frac{5}{2}}} \rightarrow\end{aligned}$$

similarly : for y :

$$\frac{\partial y^2 - x^2 - z^2}{(-)^{\frac{5}{2}}}$$

\therefore Add we get zero

Hence : $\nabla^2 \left(\frac{1}{r} \right) = 0$

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = 0$$

$$\Rightarrow \text{curl}(\text{grad } f) = ? , \quad f = f(x, y, z)$$

$$\Rightarrow \text{div}(\text{curl } \vec{A}) = ? , \quad \vec{A} = (f_1(x, y, z), f_2(x, y, z), f_3(x, y, z))$$

$$\text{Soln: } \text{curl}(\text{grad } f) = ?$$

$$\text{grad } f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$$

$$\text{curl}(\text{grad } f) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix}$$

$$\Rightarrow \hat{i} \left(\frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right) - \hat{j} \left(\frac{\partial^2 f}{\partial x \partial z} - \frac{\partial^2 f}{\partial z \partial x} \right) + \hat{k} \left(\frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right)$$

$$= 0\hat{i} + 0\hat{j} + 0\hat{k}$$

$$\text{Soln: } \text{div}(\text{curl } \vec{A}) = ?$$

$$\text{curl } \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_1 & f_2 & f_3 \end{vmatrix}$$

$$\Rightarrow \hat{i} \left(\frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \right) - \hat{j} \left(\frac{\partial f_3}{\partial x} - \frac{\partial f_1}{\partial z} \right) + \hat{k} \left(\frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right)$$

$$\text{div}(\text{curl } \vec{A}) = \frac{\partial}{\partial x} \left(\frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \right) - \frac{\partial}{\partial y} \left(\frac{\partial f_3}{\partial x} - \frac{\partial f_1}{\partial z} \right) + \frac{\partial}{\partial z} \left(\frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right).$$

$$= \frac{\partial^2 f_3}{\partial x \partial y} - \frac{\partial^2 f_2}{\partial x \partial z} - \frac{\partial^2 f_3}{\partial y \partial x} + \frac{\partial^2 f_1}{\partial y \partial z} + \frac{\partial^2 f_2}{\partial z \partial x} - \frac{\partial^2 f_1}{\partial z \partial y}$$

$$= \underline{\underline{0}} \quad (\text{Ans})$$

04-09-2023

DISPLACEMENTCURRENT

(Qualitatively and Quantitatively)

→ Maxwell's eqⁿ before modification.

Apply the thm in eqⁿ (3).

$$* \vec{\nabla} \cdot \vec{E} = \frac{P}{\epsilon_0}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot \left(-\frac{\partial \vec{B}}{\partial t} \right)$$

$$* \vec{\nabla} \cdot \vec{B} = 0$$

$$\text{|| } 0$$

$$* \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$-\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{B}) = 0$$

$$* \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Apply the thm in eqⁿ (4).

$$* \text{Theorem: } \operatorname{div} (\operatorname{curl} \vec{A}) = 0$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J})$$

$$* \vec{\nabla}_0 \vec{J} = -\frac{\partial \vec{P}}{\partial t} \rightarrow \text{continuity eqⁿ in electrodynamics.}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}) + \vec{\nabla} \cdot \left(\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) \xrightarrow{\text{SMOTHTH}} \text{THM}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}) + \mu_0 \left(\epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) \right)$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}) + \mu_0 \epsilon_0 \frac{\partial \vec{P}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{J} + \vec{\nabla} \cdot (\#)$$

↑
to get zero
we have to
add some value

$$\therefore \vec{\nabla}_0 \vec{J} = -\frac{\partial \vec{P}}{\partial t}$$

$$\because (\vec{\nabla} \cdot \vec{E} = \frac{P}{\epsilon_0}) \Rightarrow -\frac{\partial}{\partial t} (\epsilon_0 \vec{\nabla} \cdot \vec{E})$$

$$= -\epsilon_0 \left(\vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t} \right)$$

$$\therefore \vec{\nabla} \cdot \left[\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right]$$

Hence, Maxwell's eqⁿ after modification:

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \vec{J}_d$$

↳ dispⁿ current

$$\therefore \vec{J}_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

\Rightarrow let \vec{v} be a vector value funcⁿ:

$$\vec{v} = (-4x - 3y + 4z; -3x + 3y + 5z, 4x + 5y + 3z)$$

Find a scalar funcⁿ $f(x, y, z)$ such that $\vec{v} = \text{grad}(f)$

So?

$$\vec{v} = \frac{\partial(f)}{\partial x} \hat{i} + \frac{\partial(f)}{\partial y} \hat{j} + \frac{\partial(f)}{\partial z} \hat{k}$$

$$\therefore \frac{\partial^2(f)}{\partial x^2} = -4$$

But to get f , we need to do partial integration.

$$\therefore f = (-\cancel{8x^2} - 3xy + 4xz), (\cancel{-\frac{3}{2}x^2} + 3xy + 5xz)$$

$$f = (-\partial x^2 - 3xy + 4xz), (-3xy + \frac{3}{2}y^2 + 5zy), (4xz + 5yz + \frac{3}{2}z^2)$$

$$\therefore f(x, y, z) = -\partial x^2 + \frac{3}{2}y^2 + \frac{3}{2}z^2 - 3xy + 4xz + 5zy$$

only repeat once

\because when diff wrt x, y, z , same

value gives two values.

DEFINITIONS : (IMP)

→ GRADIENT :

- * It is a vector quantity but it is applied on scalar quantity
- * It explains the variations of function in x, y, z dir.
- * ex: if we apply gradient to function of temp., then from gradient we can understand rate of change of temp in x, y & z dir.

→ DIVERGENCE :

- * It is scalar quantity but applied on vector quantity;
- * it explains overall variation of function in x,y & z dirⁿ;
- * it explains how fast the area of span is changing.
- * ex: If 4 fins float down the river, each making corner square. If square is getting bigger, then gives +ve div, if it shrinks then -ve div.

→ CURL:

- * It is a vector quantity & applied on vector quantity.
- * It describes the circulation of vector field in 3-D space.
- * ex: At surface of river turbine rotates fast but ~~at~~ inside the river it rotates slowly.

→ Explanation of 4 Maxwell's eqn:

- i) Electric field diverges from electric charge.
- ii) There are no isolated magnetic poles.
- iii) Electric field are produced by changing magnetic fields.
- iv) Circulating magnetic field are produced by changing electric fields.

→ Displacement Current:

The change in electric field gives rise to a current.
As a result, magnetic field is induced.

→ Assumption of string vibration :

- * Strings are assumed to be inextensible
- * The vibratory displacement is small
- * The θ is very small