linear control systems HW3 solutions

1. id)
$$|\omega_{n}|^{2} = 16 \text{ f/s}$$
, $27_{1} \omega_{n} = 3 = 7 \frac{7}{1} = 0.375$

$$|\omega_{n}| = 4$$

$$|\nabla_{s}| = \frac{4}{3} \omega_{n} = 2.667$$

$$|\nabla_{s}| = \frac{7}{3} \frac{7}{1-5^{2}} = e^{-3.75} \frac{7}{1-5^{2}} = e^{-3.75} \frac{7}{1-5^{2}} = e^{-3.867}$$

$$(2) W_{n}^{2} = 0.04, 25W_{n} = 0.02 = 75 = 0.05$$

$$[W_{n} = 0.2]$$

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$$[S = 4005]$$

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$$\frac{7}{2} |\omega_{n}|^{2} = 1.05 \times 10^{7}, 25 \omega_{n} = 1.6 \times 10^{3} = 7 = 0.247$$

$$\frac{1}{2} = 0.247$$

$$\frac{1}{2} = 0.005$$

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2.
$$\frac{V_{c(s)}}{V_{i(s)}} = \frac{\frac{1}{cs}}{\frac{1}{cs}} = \frac{0.703}{s+0.703}, V_{i(s)} = \frac{5}{s}$$

$$V_{e}(s) = \frac{5}{s} \left(\frac{0.703}{s + 0.703} \right) = \frac{5}{s} - \frac{5}{s + 0.703} = V_{e}(t) = 5 - 5e^{-0.703}$$

$$T = \frac{1}{0.703} = 1.422 / Tr = \frac{2.2}{0.703} = 3.129 / Ts = \frac{4}{0.703} = 5.69$$

3.
$$Q = \frac{-\ln(12\cdot3/100)}{\sqrt{\pi^2 + \ln^2(12\cdot3/100)}} = 0.5549$$
 $T_5 = \frac{4}{5W_0} = \gamma W_0 = 7.21$
 $G(s) = \frac{w_0^2}{s^2 + 25W_0 + W_0^2} = \frac{51.96}{s^2 + 85 + 51.96}$

4. $T(s) = \frac{K}{s^3 + 18s^2 + 77s + K}$
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$$\frac{5}{5s^{3}+16s^{2}+(12+5k)s+20k}$$

Routh Table:

$$T(s) = \frac{5000}{s^2 + 75s + 5000}$$

d)
$$k_V = \frac{5000}{75} = 66.67$$
, $e_{SS} = \frac{5}{k_V} = 0.075$