

# APMA 2822B Homework 3 Report

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## Math Setup

Assume that  $\Delta x = \Delta y = h$ .

Using the second derivative approximations we were given, we have

$$f(x, y) = \frac{u[i-1, j] + u[i+1, j] + u[i, j-1] + u[i, j+1] - 4u[i, j]}{h^2}$$

Substituting in the given  $f(x, y)$ , we get

$$\begin{aligned} -8\pi^2 \sin(2\pi x) \cos(2\pi y) &= \frac{u[i-1, j] + u[i+1, j] + u[i, j-1] + u[i, j+1] - 4u[i, j]}{h^2} \\ -8\pi^2 h^2 \sin(2\pi x) \cos(2\pi y) &= u[i-1, j] + u[i+1, j] + u[i, j-1] + u[i, j+1] - 4u[i, j] \end{aligned}$$

Solving for  $u[i, j]$ , we have

$$\begin{aligned} 4u[i, j] &= u[i-1, j] + u[i+1, j] + u[i, j-1] + u[i, j+1] + 8\pi^2 h^2 \sin(2\pi x) \cos(2\pi y) \\ u[i, j] &= \frac{1}{4} (u[i-1, j] + u[i+1, j] + u[i, j-1] + u[i, j+1] + 8\pi^2 h^2 \sin(2\pi x) \cos(2\pi y)) \end{aligned}$$

We can use this equation to iteratively solve for  $u$  with the given  $f(x, y)$  using the Jacobi method.

We will consider our solution to have converged when the maximum residual in  $u$  across all grid points is less than a specified tolerance  $\epsilon$ . I chose  $\epsilon = 0.001$  for this assignment.

## Results

I implemented three versions of the Jacobi iterative solver. One runs sequentially, one uses OpenMP to parallelize using shared memory, and one uses OpenMPI to parallelize using distributed memory. The OpenMP implementation uses 8 threads, and the OpenMPI implementation uses 8 processes.

I also precompute the values of  $f(x, y)$  and store them in an array to avoid recomputing them at every iteration. All my calculations will account for this precomputation in terms of the memory accesses and FLOPs.

All versions produce correct and also exactly identical results at every iteration. They converge when the max residual is less than 0.001. The performance results are summarized below, where  $N$  is the size of the array used.

Version	N	Time (s)	GB/s	Iterations
Sequential	256	14.764	9.751	54,917
Sequential	512	238.846	9.682	220,536
Sequential	1024	-	-	-
OpenMP	256	1.973	72.657	54,917
OpenMP	512	24.469	95.506	220,536
OpenMP	1024	375.660	98.686	883,877
OpenMPI	256	2.340	61.519	54,917
OpenMPI	512	37.489	61.685	220,536
OpenMPI	1024	578.134	64.124	883,877

We can clearly observe that both of parallelism provided massive performance boosts. The OpenMP version performed better than the OpenMPI version by a significant margin.

## Roofline Model

### FLOPs

To generate a roofline model, we first need to calculate the number of floating point operations (FLOPs) for our separate operations.

The FLOPs calculation depends on precomputing the values of  $f(x, y)$  and storing them in an array.

For the loop in which we update our solution, we have the following operations for each grid point:

- Scaling  $f(x, y)$  by some constant: 1 FLOP
- Summing the four neighboring  $u$  values: 3 FLOPs
- Adding the scaled  $f(x, y)$  value to the sum of neighbors: 1 FLOP
- Dividing the total by 4: 1 FLOP

This gives a total of 6 FLOPs per grid point for updating our solution. Thus, the total number of FLOPs for updating our solution is  $6N^2$ .

For the loop in which we calculate our max residual or convergence error, we have the following operations for each grid point:

- Scale the current  $u$  value by -4: 1 FLOP
- Sum the four neighboring  $u$  values: 3 FLOPs
- Scale the resulting sum by  $1/h^2$ : 1 FLOP
- Subtract the result from the precomputed  $f(x, y)$  value: 1 FLOP

While there are other operations, they are not floating point operations, so we do not count them here. This gives a total of 6 FLOPs per grid point for calculating the residual. Thus, the total number of FLOPs for calculating the residual is also  $6N^2$ .

## Memory Accesses

We also need to calculate the memory usage for our separate operations.

We use double precision floating point numbers for all calculations, which are each 8 bytes. Let the size of the matrix be  $N \times N$ .

For the loop in which we update our solution, we must read the u matrix, write the new u matrix, and read the f values matrix. This means the number of bytes we access for updating our matrix is

$$2 * 8 * N^2 + 8 * N^2 = 24N^2$$

For the loop in which we calculate our max residual or convergence error, we must read the u matrix and the f values matrix. This gives the number of bytes accessed as

$$8 * N^2 + 8 * N^2 = 16N^2$$