IC260- Signals and Systems Tutorial-2

Date : 06/04/2012

Time : 10.00 am to 11.30 am

Max. marks : 20

Good Luck!!

Q.1 The zero-state response of an LTIC system to an input $x(t) = 2e^{-2t}u(t)$ is $y(t) = [7e^{-2t} - 6e^{-3t}]u(t)$. Find the impulse response of the system.

Marks: 4

Q.2 For a given LTI continuous-time system, if unit step response (let say s(t)) is given instead of unit impulse response then suggest solution to compute the response of system for any arbitrary input x(t) in terms of s(t).

Marks: 3

Q.3 Compute the response of a LTI-CT system defined as $(D^2 + 5D + 6)y(t) = (D+1)x(t)$ for input $x(t) = e^{-2t}u(t-3)$. Initial conditions are $\frac{\partial y(0^-)}{\partial t} = -1$ and $y(0^-) = 2$.

Marks: 6

Q.4 Determine and sketch the convolution of two sequences

$$x[n] = \begin{cases} -1 &: 0 \le n \le 4 \\ 0 &: \text{elsewhere} \end{cases}$$

and

$$h[n] = \begin{cases} \alpha^n : 0 \le n \le 6 \\ 0 : \text{elsewhere} \end{cases}$$

Assume α is greater then 1.

Marks: 7