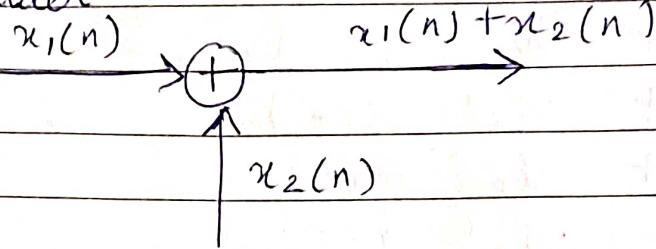
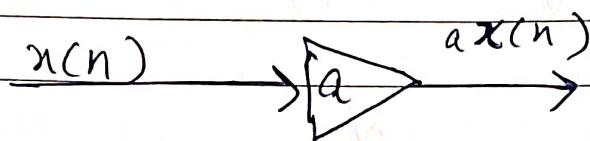


Block Diagram Representation

1) Adder



2) Constant Multiplier



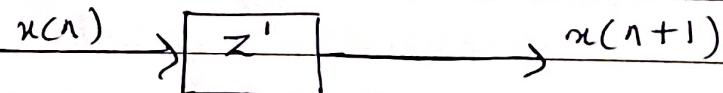
OR



3) Unit Delay Element

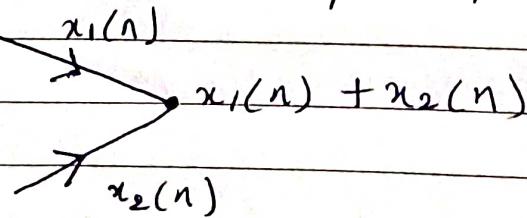


4) Unit Advance Element



Signal Flow Graph Representation

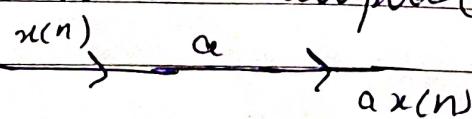
1)



Adder

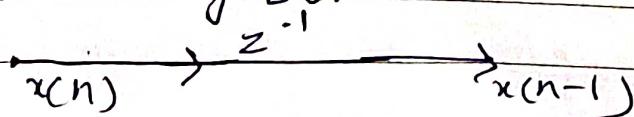
2)

Constant Multiplier



3)

Unit Delay Element

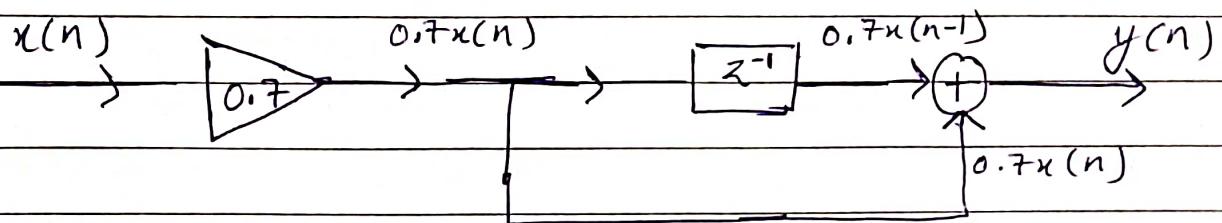


4) Unit Advance Element

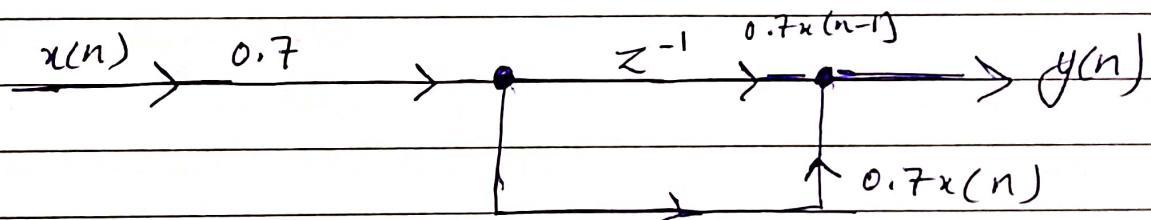
$$x(n) \xrightarrow{z} u(n+1)$$

Given $y(n) = 0.7 x(n) + 0.7x(n-1)$

Any Block Diagram Representation



Signal Flow Graph Representation



Infinite Impulse Response: [IIR] filter

- $y(n)$ depends → $x(n)$ & $x(n-1)$ also on $y(n-1)$ → smaller filter size.
- Difference eqn → linear phase is not easy
- $$y(n) = b_0 x(n) + b_1 x(n-1) + \dots + b_M x(n-M) - a_1 y(n-1) - \dots - a_N y(n-N)$$
- Transfer fun → objective → determine the filter numerator & denominator → satisfy filter specifications
- $$H(z) = \frac{Y(z)}{X(z)} = \frac{b_0 + b_1 z^{-1} + \dots + b_M z^{-M}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}}$$
- $b_i \rightarrow (M+1)$ numerator
- $a_i \rightarrow N$ denominator.
- $Y(z) \neq X(z) \rightarrow Z\text{-Transform of } x(n) \neq y(n)$
- Poles (s) → inside the unit circle → STABLE

Advantages

- Easy to design & easy to implement

Disadvantages

- Non Linear
- non-stable.
- Infinite Impulse response.



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Direct Form I Realization of IIR

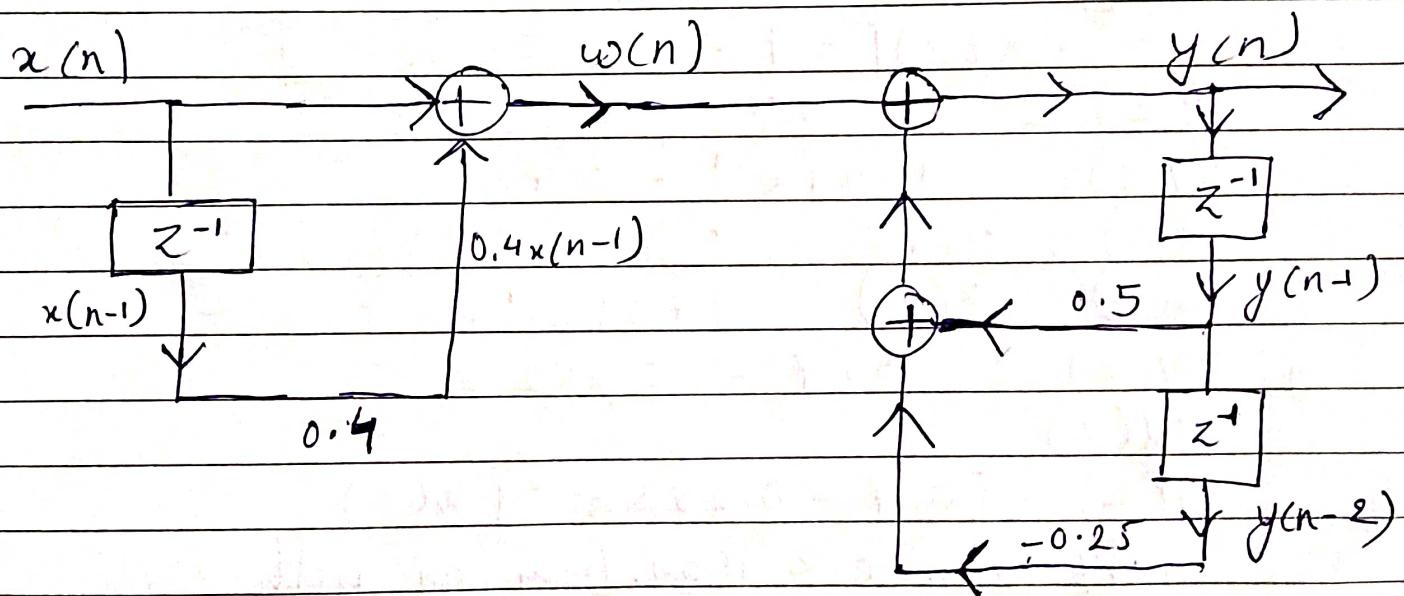
$$y(n) = 0.5 y(n-1) - 0.25 y(n-2) + x(n) + 0.4x(n-1)$$

Am) Take x terms together

$$x(n) + 0.4x(n-1) = w(n)$$

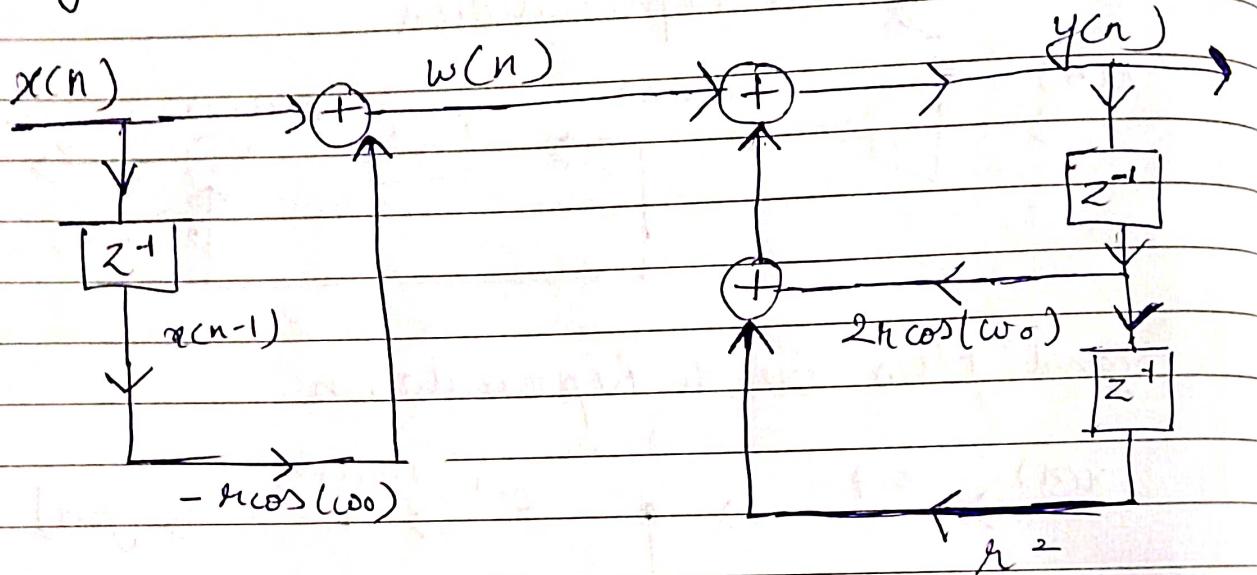
$$\text{So, } y(n) = 0.5y(n-1) - 0.25y(n-2) + w(n)$$

Now Direct form Realization



ques) $y(n) = 2r \cos(\omega_0) y(n-1) + r^2 y(n-2) + x(n)$
 $- r \cos(\omega_0) x(n-1)$

Ans) $w(n) = r \cos(\omega_0) x(n-1) = w(n)$
 $y(n) = 2r \cos(\omega_0) y(n-1) + r^2 y(n-2) + w(n)$



Direct Form 2 Realization of IIR Filter

ques) $y(n) = -0.1 y(n-1) + 0.72 y(n-2) + 0.7 x(n)$
 $- 0.252 x(n-2)$

Ans) Take Z Transform on both sides

$$Y(z) = -0.1 z^{-1} Y(z) + 0.72 z^{-2} Y(z) \\ + 0.7 X(z) - 0.252 z^{-2} X(z)$$

Take $Y(z)$ on one side and $X(z)$ on other

$$Y(z) [1 + 0.1 z^{-1} - 0.72 z^{-2}] \\ = X(z) [0.7 - 0.252 z^{-2}]$$

$$\frac{Y(z)}{X(z)} = \frac{0.7 - 0.252 z^{-2}}{1 + 0.1 z^{-1} - 0.72 z^{-2}}$$

$$\frac{Y(z)}{X(z)} \times \frac{W(z)}{X(z)} = \frac{0.7 - 0.252 z^{-2}}{1 + 0.1 z^{-1} - 0.72 z^{-2}}$$

$$\frac{Y(z)}{W(z)} = 0.7 - 0.252 z^{-2}$$

$$Y(z) = [0.7 - 0.252 z^{-2}] W(z)$$

Take inverse Z Transform on both sides

$$y(n) = [0.7 w(n) - 0.252 w(n-2)] \quad \text{--- (1)}$$

$$\frac{W(z)}{X(z)} = \frac{1}{1 + 0.1z^{-1} - 0.72z^{-2}}$$

$$X(z) = [1 + 0.1z^{-1} - 0.72z^{-2}] W(z)$$

Take Inverse Z Transform on both sides

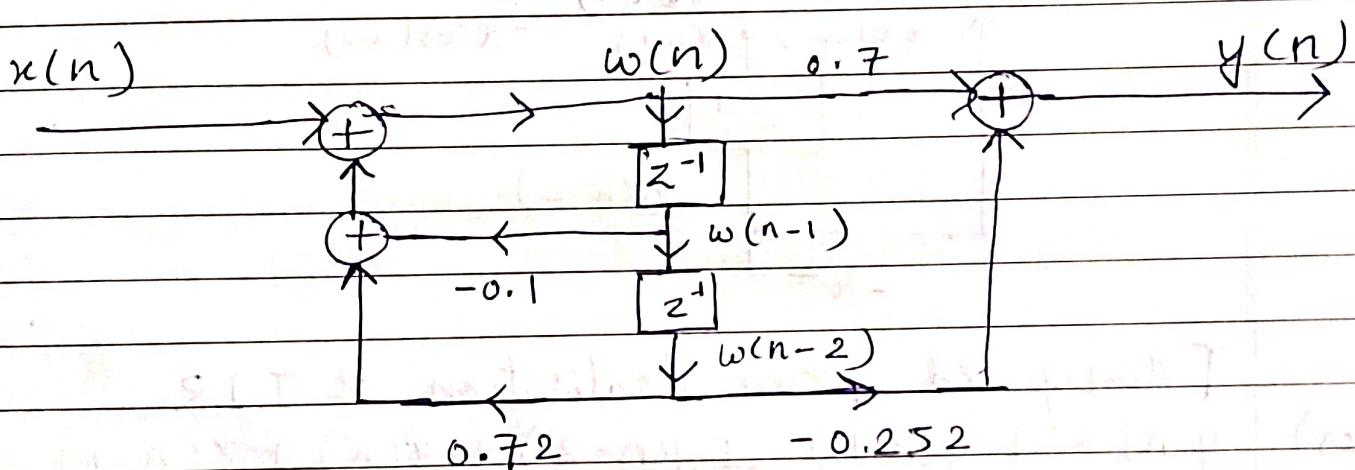
$$x(n) = w(n) + 0.1 w(n-1) - 0.72 w(n-2)$$

$$\Rightarrow w(n) = x(n) - 0.1 w(n-1) + 0.72 w(n-2) \quad \text{--- (2)}$$

$$y(n) = 0.7 w(n) - 0.252 w(n-2) \quad \text{--- (1)}$$

$x(n) = w(n) + 0.1 w(n-1) - 0.72 w(n-2)$

$$w(n) = x(n) - 0.1 w(n-1) + 0.72 w(n-2) \quad \text{--- (2)}$$



ques) $y(n) = 2r \cos(\omega_0) y(n-1) - r^2 y(n-2) + x(n) - r \cos(\omega_0) x(n-1)$

Ans) $Y(z) = 2r \cos(\omega_0) z^{-1} Y(z) - r^2 z^{-2} Y(z) + X(z) - r \cos(\omega_0) z^{-1} X(z)$

$$\Rightarrow Y(z) [1 - 2r \cos(\omega_0) z^{-1} + r^2 z^{-2}] = [1 - r \cos(\omega_0) z^{-1}] X(z)$$

$$\frac{Y(z)}{X(z)} = \frac{1 - r \cos(\omega_0) z^{-1}}{1 - 2r \cos(\omega_0) z^{-1} + r^2 z^{-2}} = \frac{Y(z)}{W(z)} \times \frac{W(z)}{X(z)}$$

$$\underline{Y(z)} = \underline{1 - r \cos(\omega_0) z^{-1}}$$

$$\underline{W(z)}$$

$$\underline{y(n)} = \underline{w(n) - r \cos(\omega_0) w(n-1)} \quad \text{--- (1)}$$

$$\underline{\frac{W(z)}{X(z)}} = \frac{1}{1 - 2r \cos(\omega_0) z^{-1} + r^2 z^{-2}}$$

$$X(z) = W(z) \left[1 - 2r \cos(\omega_0) z^{-1} + r^2 z^{-2} \right]$$

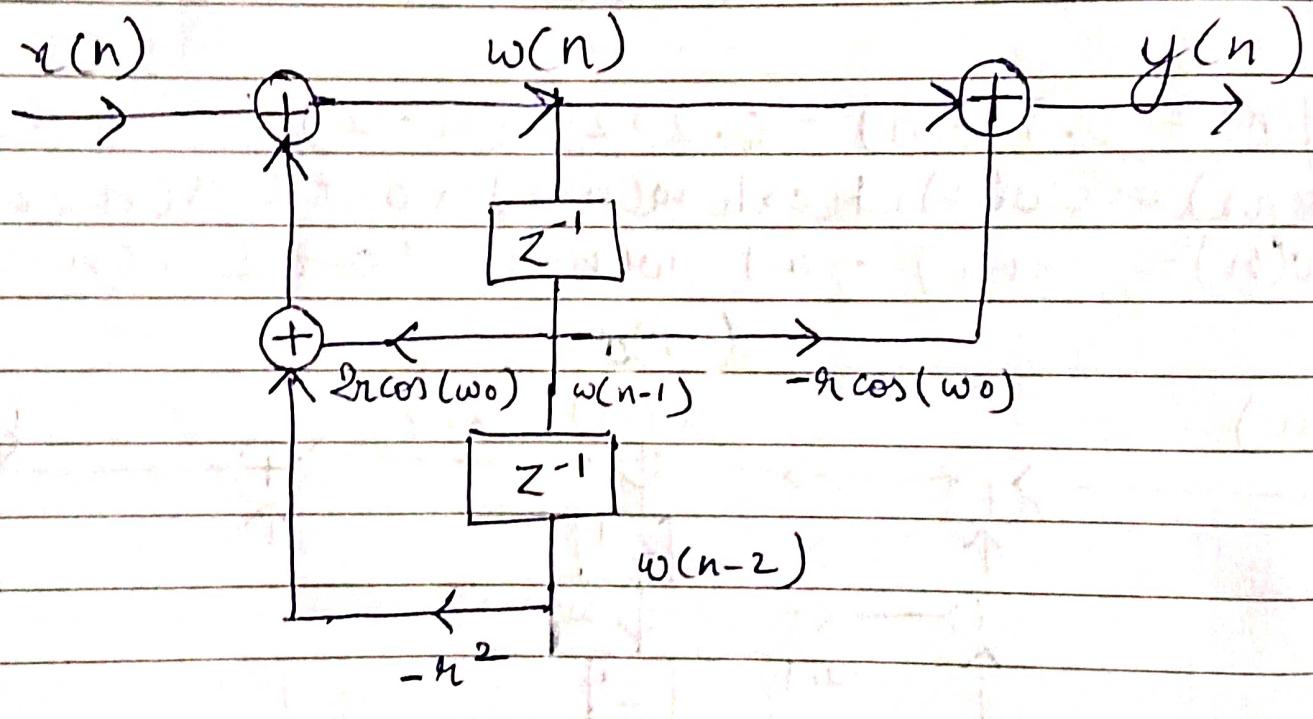
$$x(n) = w(n) - 2r \cos(\omega_0) w(n-1) + r^2 w(n-2)$$

$$w(n) = x(n) + 2r \cos(\omega_0) w(n-1) - r^2 w(n-2)$$

\rightarrow

$$y(n) = w(n) - r \cos(\omega_0) w(n-1)$$

$$w(n) = x(n) + 2r \cos(\omega_0) w(n-1) - r^2 w(n-2)$$



Transposed Form Realization

$$y(n) = \frac{1}{2} y(n-1) - \frac{1}{4} y(n-2) + x(n) + x(n-1)$$

Steps

- First Draw the Direct Form II, form Signal Flow Graphs.
- Interchange Input and Output
- Reverse the direction of All Branches
- summing points become branching points
- Branching points become summing points

$-n^2$

Transposed Form Realisation of IIR

ques) $y(n) = \frac{1}{2}y(n-1) - \frac{1}{4}y(n-2) + x(n) + x(n-1)$

Ans) ① Draw the direct form 2 diagram

$$Y(z) = \frac{1}{2}z^{-1}Y(z) - \frac{1}{4}z^{-2}Y(z) + X(z) + z^{-1}X(z)$$

$$Y(z) \left[1 - \frac{z^{-1}}{2} + \frac{z^{-2}}{4} \right] = X(z) \left[1 + z^{-1} \right]$$

$$\frac{Y(z)}{X(z)} = \frac{1 + z^{-1}}{1 - \frac{z^{-1}}{2} + \frac{z^{-2}}{4}} = \frac{Y(z)}{W(z)} \times \frac{W(z)}{X(z)}$$

$$\frac{Y(z)}{W(z)} = 1 + z^{-1}$$

$$Y(z) = [1 + z^{-1}]W(z)$$

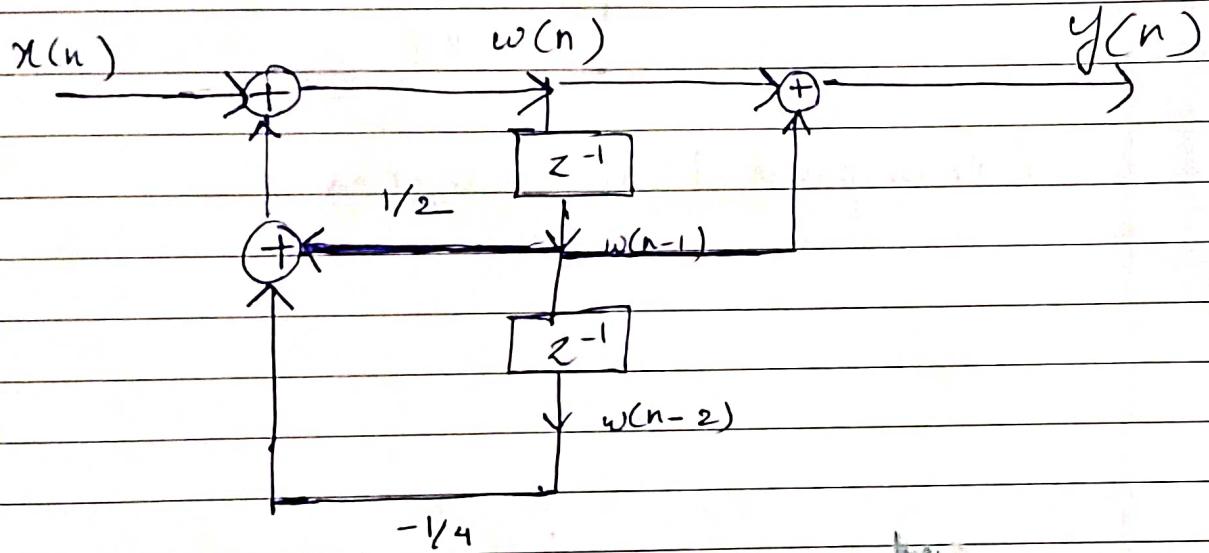
$$y(n) = w(n) + w(n-1) \quad - \textcircled{1}$$

$$\frac{W(z)}{X(z)} = \frac{1}{1 - \frac{z^{-1}}{2} + \frac{z^{-2}}{4}}$$

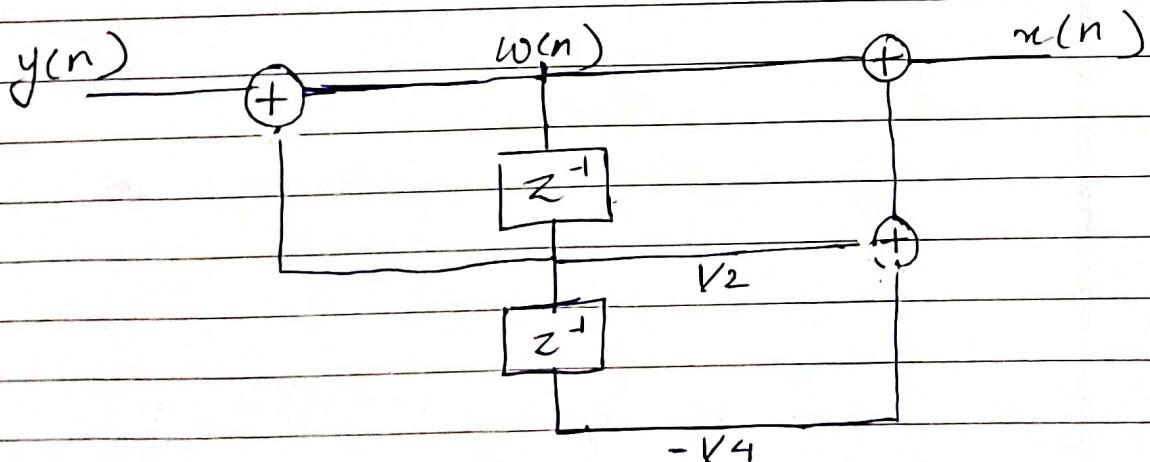
$$X(z) = W(z) \left[1 - \frac{z^{-1}}{2} + \frac{z^{-2}}{4} \right]$$

$$x(n) = w(n) - \frac{1}{2}w(n-1) + \frac{1}{4}w(n-2)$$

$$w(n) = x(n) + \frac{1}{2}w(n-1) - \frac{1}{4}w(n-2) \quad - \textcircled{2}$$

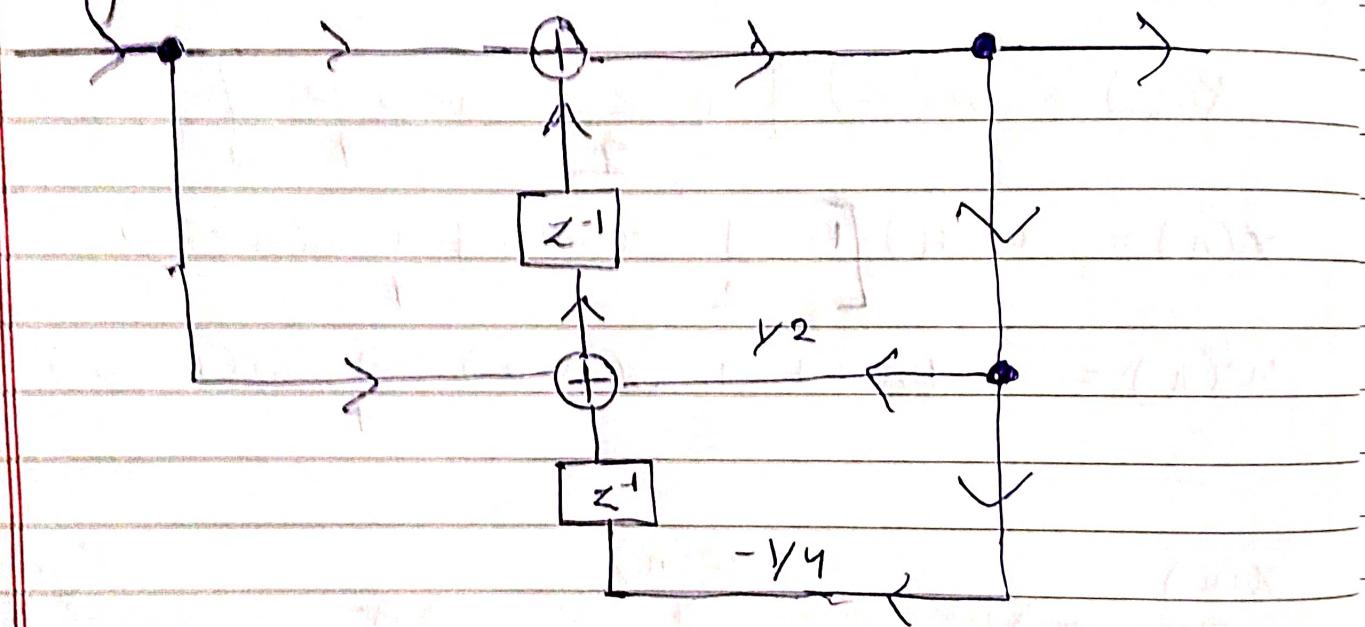


(2) Interchange the input and output



③

Convert summing points to branching points
 and branching points to summing points
 and reverse the direction of arrows

 $y(n)$ $w(n)$ $u(n)$ 

CTransposed Form Realization

Cascade Form Realization of IIR Filters

ques) $y(n) = \frac{3}{4}y(n-1) - \frac{1}{8}y(n-2) + x(n) + \frac{1}{3}x(n-1)$

Ans) $Y(z) = \frac{3}{4}z^{-1}Y(z) - \frac{1}{8}z^{-2}Y(z) + X(z) + \frac{1}{3}z^{-1}X(z)$

$$Y(z) \left[1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2} \right] = X(z) \left[1 + \frac{1}{3}z^{-1} \right]$$

$$\frac{Y(z)}{X(z)} = \frac{1 + z^{-1}}{1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}}$$

$$H(z) = \frac{1 + z^{-1}}{1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}}$$

Split denominator into two terms

$$H(z) = \frac{1+z^{-1}}{3} \overline{\left(1-\frac{z^{-1}}{2}\right)\left(1-\frac{z^{-1}}{4}\right)}$$

$$H(z) = H_1(z) H_2(z)$$

$$H_1(z) = \frac{1+z^{-1}}{3} \overline{\left(1-\frac{z^{-1}}{2}\right)} \quad H_2(z) = \frac{1}{\left(1-\frac{z^{-1}}{4}\right)}$$

~~Now we realize~~ Now we realize $H_1(z)$ and $H_2(z)$ separately using direct form 2 realization and combine them.

$$h_1(z) = \frac{1+z^{-1}}{3}$$

$$\frac{1-z^{-1}}{4}$$

$$\frac{y_1(z)}{w_1(z)} \times \frac{w_1(z)}{x_1(z)} = \frac{1+z^{-1}}{3} \cdot \left(\frac{1-z^{-1}}{4} \right)$$

$$\frac{y_1(z)}{w_1(z)} = \frac{1+z^{-1}}{3}$$

$$y_1(z) = w_1(z) + \frac{z^{-1} w_1(z)}{3}$$

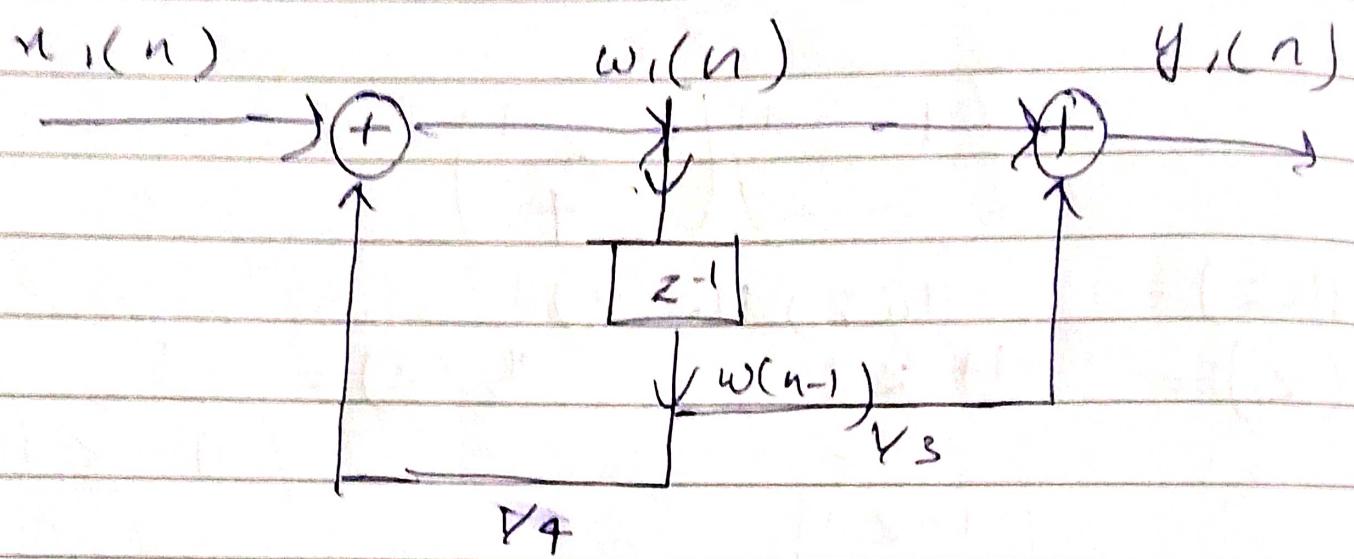
$$y_1(n) = w_1(n) + \frac{1}{3} w_1(n-1)$$

$$\frac{w_1(z)}{x_1(z)} = \frac{1}{1-\frac{z^{-1}}{4}}$$

$$x_1(z) = w_1(z) - \frac{1}{4} z^{-1} w_1(z)$$

$$x(n) = w_1(n) - \frac{1}{4} w_1(n-1)$$

$$w(n) = x(n) + \frac{1}{4} w_1(n-1)$$



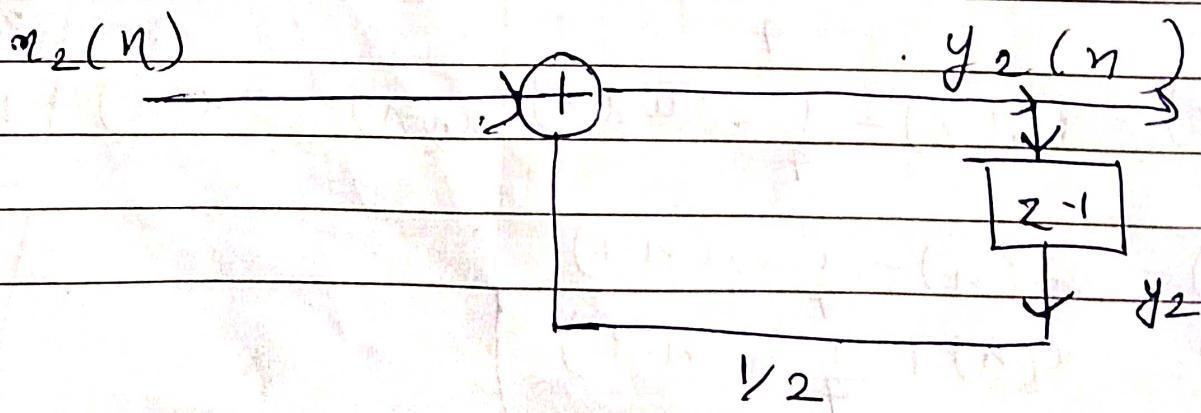
Direct form realization 2 for $H_1(z)$

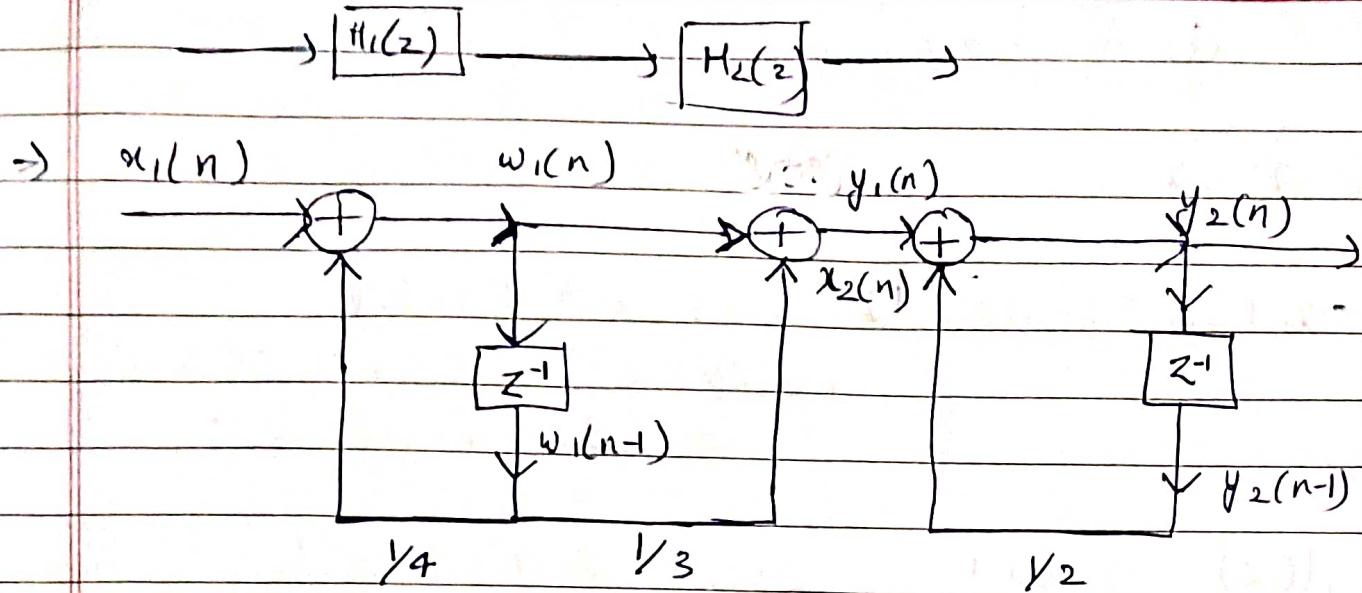
$$\frac{Y_2(z)}{X_2(z)} = \frac{1}{(1-z^{-1})^2} \quad \left[\begin{array}{l} \text{There is no} \\ \text{numerator so, no} \\ \text{need of } W_2(z) \end{array} \right]$$

$$Y_2(z) = \left[1 - \frac{z^{-1}}{2} \right] = X_2(z)$$

$$y_2(n) - \frac{1}{2} y_2(n-1) = x_2(n)$$

$$y_2(n) = \frac{1}{2} y_2(n-1) + x_2(n)$$





[Cascade Form Realization]

Parallel Form Realization of IIR Filter

$$\begin{aligned}
 y(n) &= -0.1y(n-1) + 0.72y(n-2) + 0.7x(n) - \\
 &\quad 0.252x(n-2) \\
 Y(z) &= -0.1z^{-1}Y(z) + 0.72z^{-2}Y(z) + 0.7X(z) - \\
 &\quad 0.252z^{-2}X(z) \\
 \Rightarrow Y(z)[1 + 0.1z^{-1} - 0.72z^{-2}] &= X(z)[0.7 - 0.252z^{-2}] \\
 \Rightarrow \frac{Y(z)}{X(z)} &= \frac{0.7 - 0.252z^{-2}}{1 + 0.1z^{-1} - 0.72z^{-2}} = H(z) \\
 H(z) &= \frac{0.7 - 0.252z^{-2}}{1 + 0.1z^{-1} - 0.72z^{-2}}
 \end{aligned}$$

We need to represent $H(z)$ as

$$H(z) = C + H_1(z) + H_2(z) + \dots$$

$$-0.72z^{-2} + 0.12z^{-1} + 1 \quad \boxed{0.35} \quad -0.252z^{-2} + 0.70 \\ \boxed{-0.252z^{-2} + 0.35 + 0.035z^{-1}} \\ 0.35 = 0.035z^{-1}$$

$$H(z) = 0.35 + \frac{0.35 - 0.035z^{-1}}{-0.72z^{-2} + 0.12z^{-1} + 1} \\ \frac{0.35 - 0.035z^{-1}}{-0.72z^{-2} + 0.12z^{-1} + 1} \quad \text{=} \quad \frac{A}{1+0.9z^{-1}} + \frac{B}{1-0.8z^{-1}}$$

$$\Rightarrow A(1-0.8z^{-1}) + B(1+0.9z^{-1}) \\ = 0.35 - 0.035z^{-1}$$

$$\Rightarrow A + B = 0.35 \\ -A \times (0.8) + B(0.9) = -0.035$$

$$\Rightarrow A = (0.35 - B) \\ \star (-0.35 + B)(0.8) + B(0.9) = -0.035$$

$$\Rightarrow B(0.1) = 0.35 \\ \Rightarrow B = 0.35$$

$$(1.7) B = -0.035 + 0.35 \times 0.8$$

$$1.7 B = 0.35(-0.1 + 0.8)$$

$$\boxed{B = 0.144} \quad \boxed{A = 0.206}$$

$$\Rightarrow H(z) = C + H_1(z) + H_2(z)$$

$$H(z) = 0.35 + \frac{0.206}{1+0.9z^{-1}} + \frac{0.144}{1-0.8z^{-1}}$$

$$-0.72z^{-2} + 0.1z^{-1} + 1 \boxed{-0.252z^{-2} + 0.70}$$

$$\underline{+ 0.252z^{-2} + 0.35 + 0.035z^{-1}}$$

$$0.35 - 0.035z^{-1}$$

$$H(z) = 0.35 + \frac{0.35 - 0.035z^{-1}}{-0.72z^{-2} + 0.1z^{-1} + 1}$$

$$\frac{0.35 - 0.035z^{-1}}{-0.72z^{-2} + 0.1z^{-1} + 1} = \frac{A}{1+0.9z^{-1}} + \frac{B}{1-0.8z^{-1}}$$

$$\Rightarrow A(1-0.8z^{-1}) + B(1+0.9z^{-1}) \\ = 0.35 - 0.035z^{-1}$$

$$\Rightarrow A + B = 0.35 \\ -A \times (0.8) + B(0.9) = -0.035$$

$$\rightarrow A = (0.35 - B) \\ (-0.35 + B)(0.8) + B(0.9) = -0.035$$

B (engg)

$$\rightarrow B(1.7) = 0.35 + 0.035$$

B = 0.206

$$(1.7) B = -0.035 + 0.35 \times 0.8$$

$$1.7 B = 0.35(-0.1 + 0.8)$$

$$\boxed{B = 0.144} \quad \boxed{A = 0.206}$$

$$\text{so, } H(z) = C + H_1(z) + H_2(z)$$

$$H(z) = 0.35 + \frac{0.206}{1+0.9z^{-1}} + \frac{0.144}{1-0.8z^{-1}}$$

$$\frac{Y_1(z)}{X_1(z)} = \frac{0.206}{1 + 0.9z^{-1}}$$

No need to take 0.206 as we can multiply it later in Direct Form 2 output

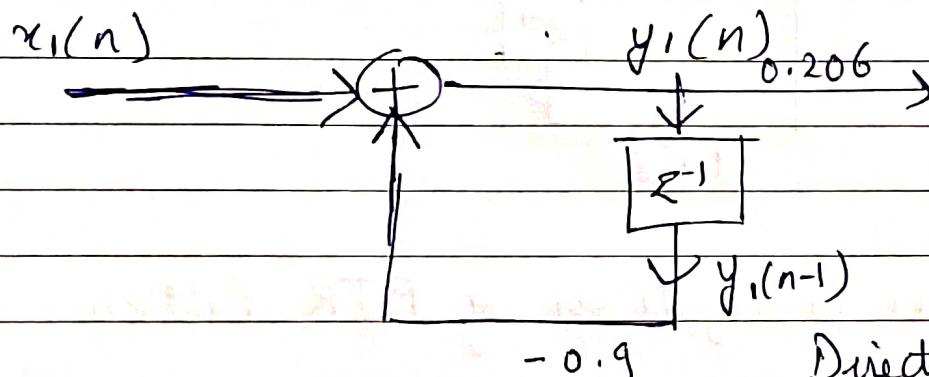
$$Y_1(z) = 1$$

$$X_1(z) = (0.9z^{-1} + 1)$$

$$X_1(z) = (1 + 0.9z^{-1}) Y_1(z)$$

$$x_1(n) = y_1(n) + 0.9 y_1(n-1)$$

$$y_1(n) = x_1(n) - 0.9 y_1(n-1)$$

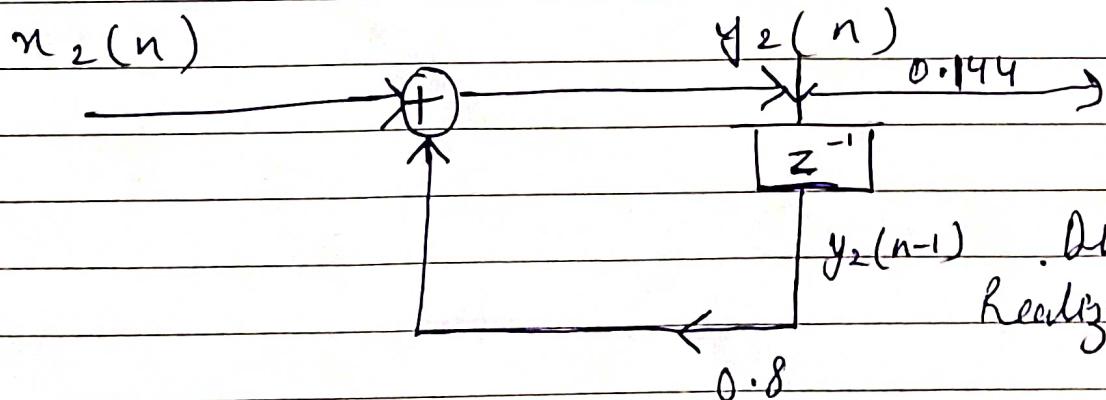


Direct Form 2 Realization
of $H_1(z)$

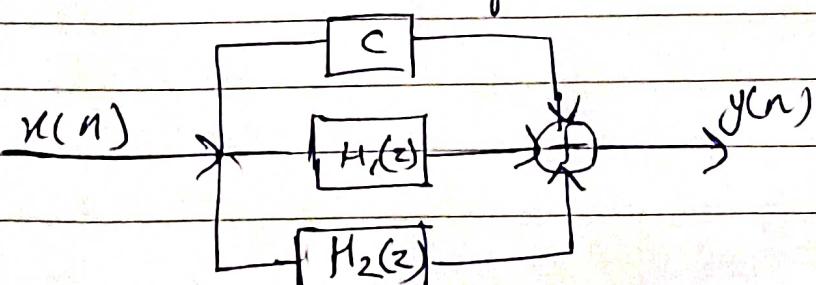
$$\frac{Y_2(z)}{X_2(z)} = \frac{1}{1 - 0.8z^{-1}}$$

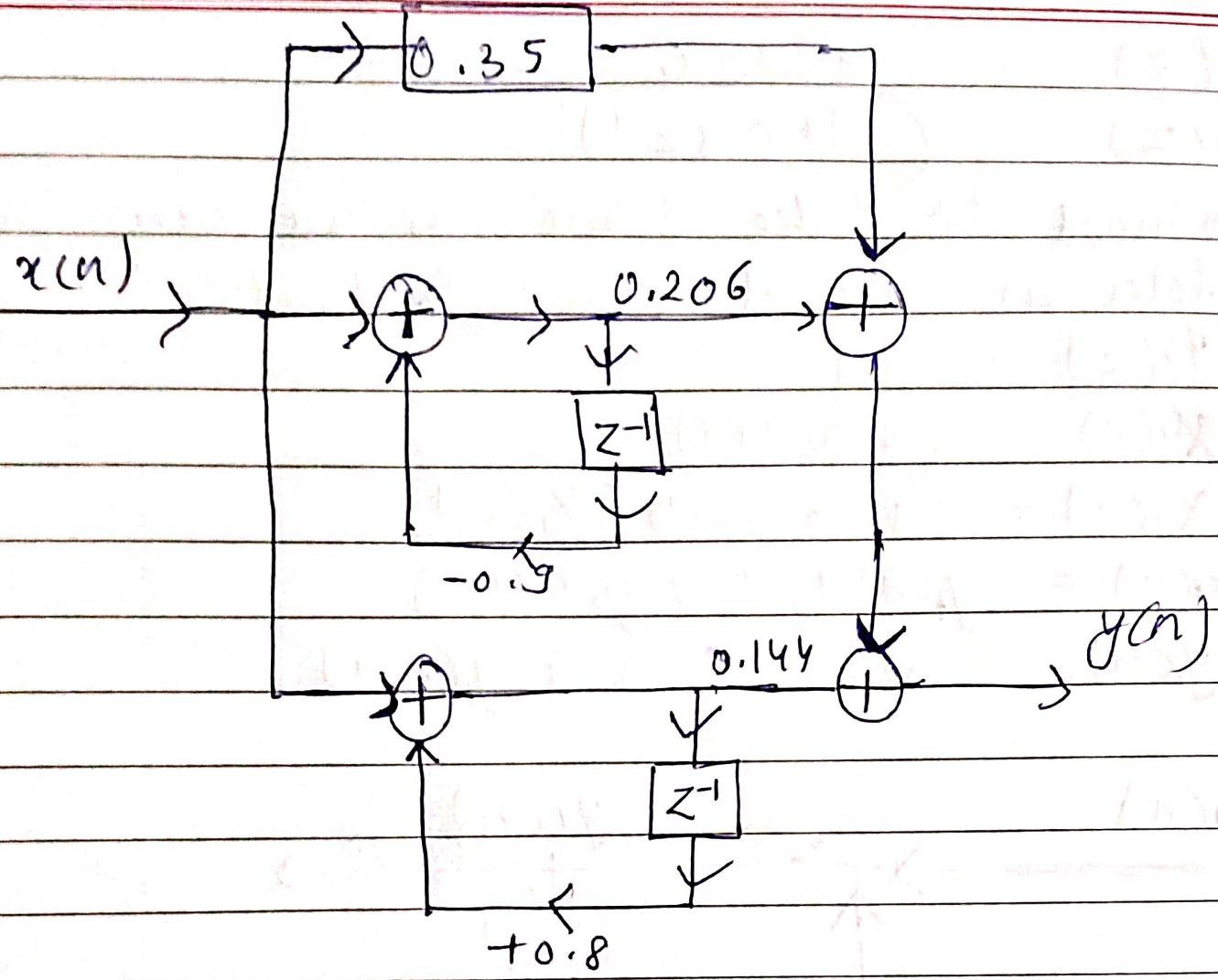
$$y_2(n) - 0.8 y_2(n-1) = x_2(n)$$

$$y_2(n) = 0.8 y_2(n-1) + x_2(n)$$



Structure of Parallel Form is





Introduction - Design of FIR Filter

- Filter → Impulse response is finite.
- Output → depends only on present and past values.
- Applications → where linear phase is important.
Ex:- Data transmission, Speech processing, Correlation processing, Interpolation.

Characteristics:

- (i) Impulse response → Finite length.
- (ii) non-recursive FIR filter → Stable.
- (iii) Phase distortion of freq response can be eliminated by FIR filter.
- (iv) Implement a recursive FIR Filters
- (v) Effect of Start-up transient have small duration.
- (vi) Quantization noise can be made negligible

Advantages:

- Stable
- Can be realized in both recursive & non-recursive.
- exact linear phase.
- Flexible.
- low sensitive to Quantization noise.
- Efficiently realized in H/W.

Disadvantages:

- Complex
- requires more filter co-efficients to be stored.
- long duration impulse response require large amount of processing.
- narrow transition band FIR filter requires more arithmetic operations & H/W components
 ↳ Costly.

Direct Form Realization of FIR Filter

ques)

$$H(z) = 1 + 2z^{-1} - 3z^{-2} - 4z^{-3} + 5z^{-4}$$

Ans)

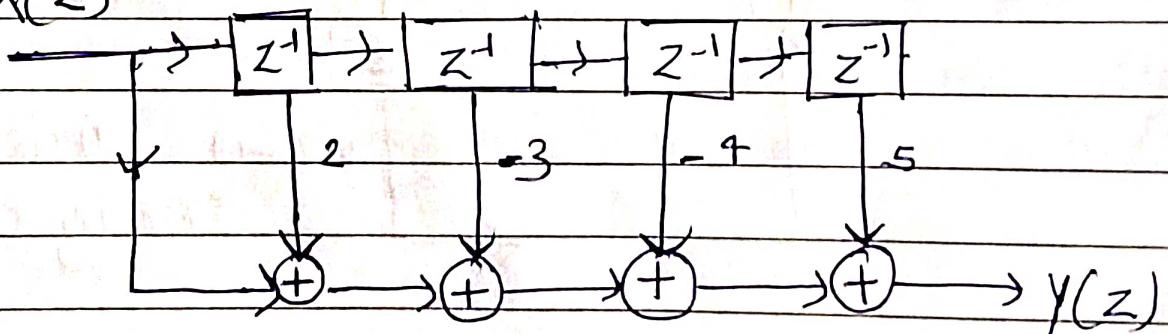
$$Y(z) = 1 + 2z^{-1} - 3z^{-2} - 4z^{-3} + 5z^{-4}$$

$X(z)$

$$Y(z) = X(z)[1 + 2z^{-1} - 3z^{-2} - 4z^{-3} + 5z^{-4}]$$

$$Y(z) = X(z) + 2z^{-1}X(z) - 3z^{-2}X(z) \\ - 4z^{-3}X(z) + 5z^{-4}X(z)$$

$X(z)$



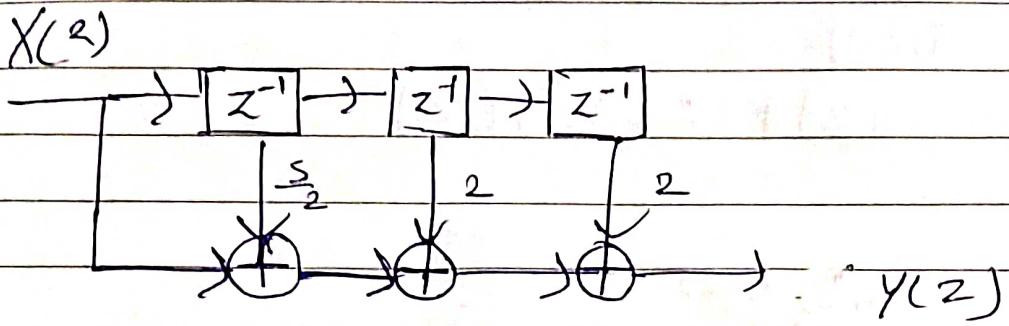
ques)

$$H(z) = \frac{1 + 5z^{-1} + 2z^{-2} + 2z^{-3}}{2}$$

Ans)

$$\frac{Y(z)}{X(z)} = 1 + 5z^{-1} + 2z^{-2} + 2z^{-3}$$

$$Y(z) = X(z) + \frac{5z^{-1}X(z)}{2} + 2z^{-2}X(z) + 2z^{-3}X(z)$$



Cascade Form Realization of FIR Filter

In cascade form realization question, transfer function must be in the form of product of smaller transfer function.

$$H(z) = \frac{(1+2z^{-1}-z^{-2})}{H_1(z)} \cdot \frac{(1+z^{-1}-z^{-2})}{H_2(z)}$$

$$\underline{Y_1(z)} = (1+2z^{-1}-z^{-2})$$

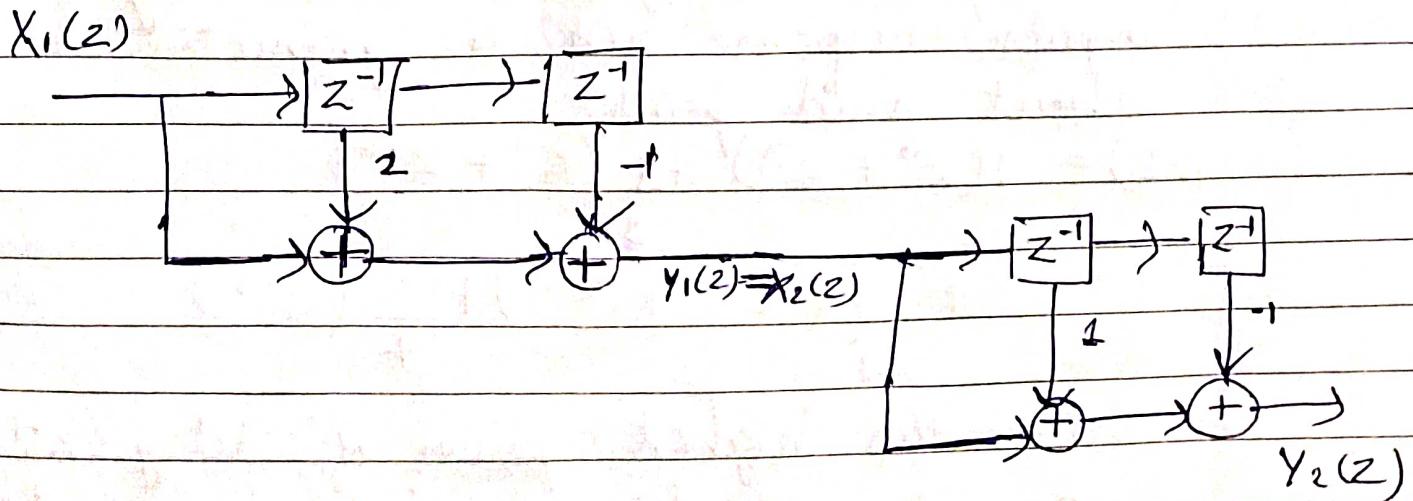
$$Y_1(z) = X_1(z) + 2z^{-1}X(z) - z^{-2}X_1(z) \quad \text{--- (1)}$$

$$\underline{Y_2(z)} = (1+z^{-1}-z^{-2})$$

$$Y_2(z) = X_2(z) + z^{-1}X_2(z) - z^{-2}X_2(z) \quad \text{--- (2)}$$

General structure of Cascade Form is

$$X_1(z) \rightarrow Y_1(z) = X_2(z) \longrightarrow Y_2(z)$$

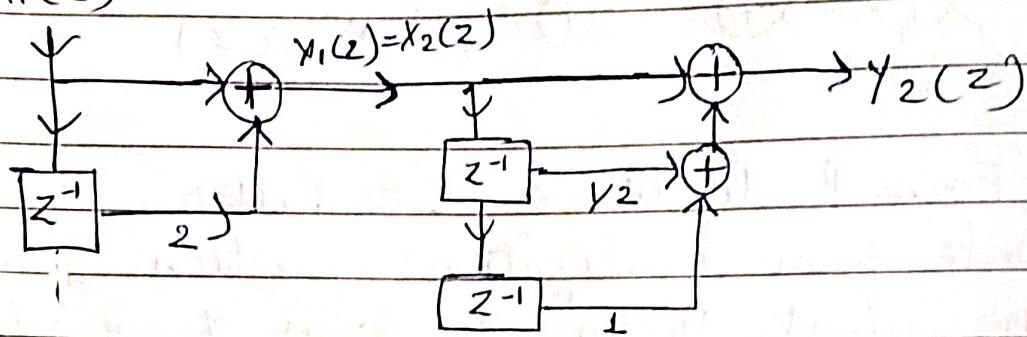


$$Ques) H(z) = (1 + 2z^{-1}) \left(1 + \frac{1}{2}z^{-1} + z^{-2} \right)$$

$$H_1(z) = \frac{Y_1(z)}{X_1(z)} = 1 + 2z^{-1}$$

$$Y_1(z) = X_1(z) + 2z^{-1}X_1(z)$$

$X_1(z)$



$$\frac{Y_2(z)}{X_2(z)} = 1 + z^{-1} + z^{-2}$$

$$Y_2(z) = X_2(z) + \frac{1}{z}z^{-1}X_2(z) + \frac{1}{z^2}z^{-2}X_2(z)$$

Linear Phase Realization of FIR Filter

Advantage: Number of multipliers is reduced

$$Ques) H(z) = 1 + \underbrace{z^{-1}}_3 + \underbrace{z^{-2}}_8 + \underbrace{z^{-3}}_4 + \underbrace{z^{-4}}_8 + \underbrace{z^{-5}}_3 + \underbrace{z^{-6}}_1$$

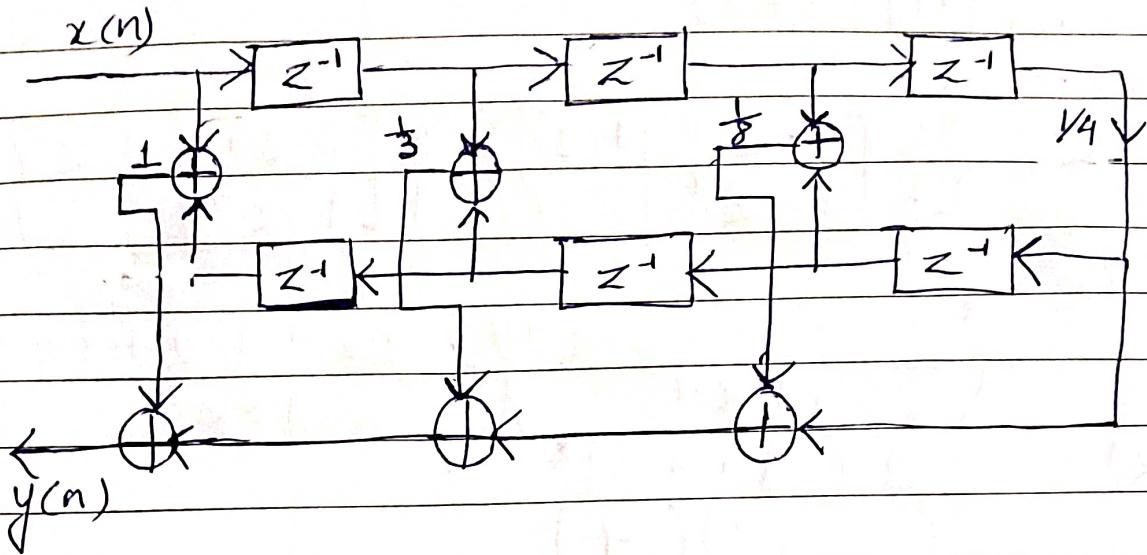
$$Ans) h(n) = \left\{ 1, \frac{1}{3}, \frac{1}{8}, \frac{1}{4}, \frac{1}{8}, \frac{1}{3}, 1 \right\}$$

Linear phase realization exists only when impulse response $h(n)$ is symmetrical about mid point

$$H(z) = 1(z^0 + z^0) + \frac{1}{3}(z^{-1} + z^{-5})$$

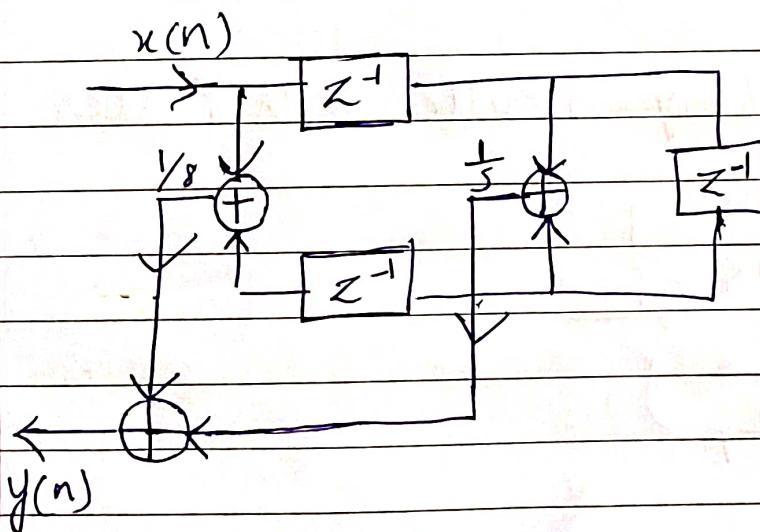
$$+ \frac{1}{8}(z^{-2} + z^{-4}) + \frac{1}{4}(z^{-3})$$

Since the highest power of delay (z^{-1}) is 6. So we use 6 delay elements.



$$(Ans) H(z) = \frac{1}{8} + \frac{1}{5}z^{-1} + \frac{1}{5}z^{-2} + \frac{1}{8}z^{-3}$$

$$H(z) = \frac{1}{8}(z^0 + z^{-3}) + \frac{1}{5}(z^{-1} + z^{-2})$$



Bilinear Transformation

Used to convert transfer function from analog domain to digital domain.

$$H(s) \rightarrow H(z)$$

Procedure : Replace s with $\frac{2}{T} \left[\frac{1-z^{-1}}{1+z^{-1}} \right]$

$$s \rightarrow \frac{2}{T} \left[\frac{1-z^{-1}}{1+z^{-1}} \right]$$

Ques) $H(s) = \frac{2}{(s+1)(s+2)}$, with $T = 1$ second

Ans) $H(z) = \frac{2}{\left\{ \frac{z-1}{1+z^{-1}} + 1 \right\} \left\{ \frac{2}{1} \left[\frac{1-z^{-1}}{1+2^{-1}} \right] + 2 \right\}}$

$$H(z) = \frac{2}{\left(\frac{2 - 2z^{-1} + 1 + z^{-1}}{1 + z^{-1}} \right) \left(\frac{2 - 2z^{-1} + 2 + 2z^{-1}}{1 + z^{-1}} \right)}$$

$$H(z) = \frac{2(1+z^{-1})^2}{(3-z^{-1})(4)}$$

$$H(z) = \frac{1}{2} \left(\frac{1+z^{-1}}{3-z^{-1}} \right)^2$$

$$H(z) = \frac{1}{6} \left(\frac{1+z^{-1}}{1-z^{-1}} \right)^2$$

Finding Order of Lowpass Butterworth Filter

$$N \geq \log \sqrt{\frac{10^{0.1x_s} - 1}{10^{0.1x_p} - 1}} \log \left(\frac{\Omega_s}{\Omega_p} \right)$$

Ques) Given $x_p = 1 \text{ dB}$ $x_s = 30 \text{ dB}$

$$\Omega_p = 200 \text{ rad/sec}$$

$$\Omega_s = 600 \text{ rad/sec. Find order}$$

Ans) $N \geq \log \sqrt{\frac{10^{0.1 \times 30} - 1}{10^{0.1 \times 1} - 1}} \log \left(\frac{600}{200} \right)$

$$N \geq \log \sqrt{\frac{10^3 - 1}{10^{0.1} - 1}}$$

$$\log(3)$$

$$N \geq 3.758$$

⇒ $N = 4$

α_p = passband attenuation

α_s = stopband attenuation

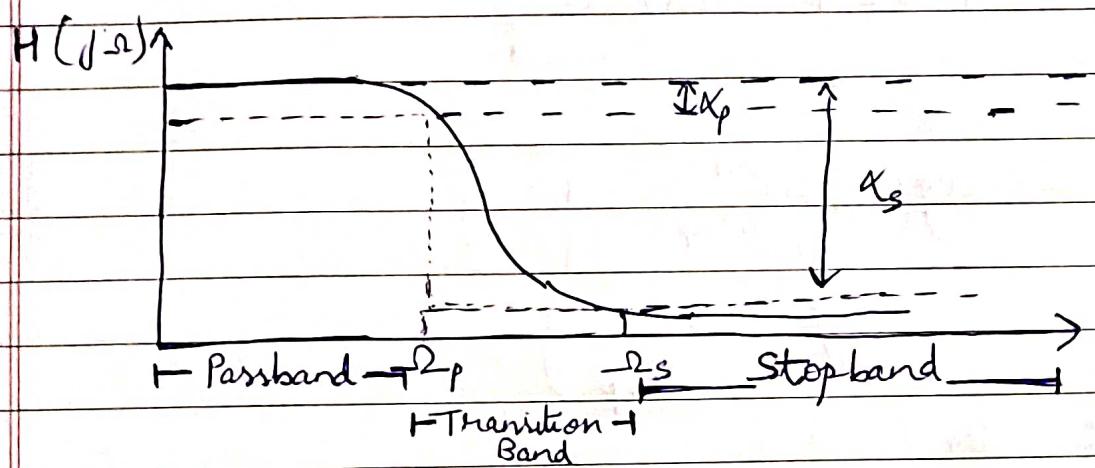
ω_s = stopband end edge frequency in analog domain

ω_p = passband edge frequency in analog domain

ω_s = stopband edge frequency in digital domain

ω_p = passband edge frequency in digital domain

In analog domain,

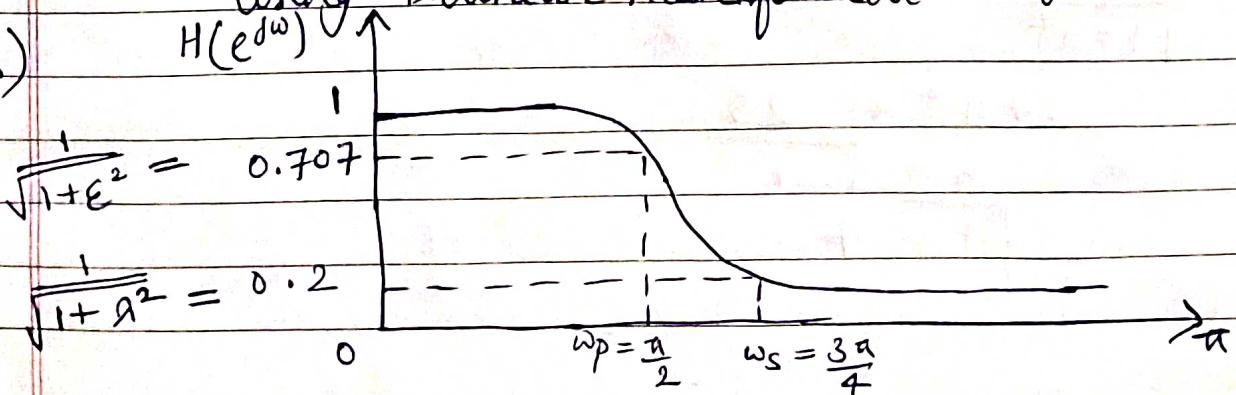


Butterworth Filter Design using Bilinear Transformation

Ques) Design a butterworth filter satisfying the condition $0.707 \leq |H(e^{j\omega})| \leq 1$ }
for $0 \leq \omega \leq \frac{\pi}{2}$ }

and $|H(e^{j\omega})| \leq 0.2$ for $\frac{3\pi}{4} \leq \omega \leq \pi$ }

Ans) Using Bilinear Transformation with $T=1$ second



$$\Omega_p = \frac{\omega}{T} \tan\left(\frac{\omega_p}{2}\right)$$

$$\Omega_s = \frac{\omega}{T} \tan\left(\frac{\omega_s}{2}\right)$$

$$\Omega_p = \frac{2}{T} \tan\left(\frac{\pi}{4}\right) = 2 \text{ rad/sec}$$

$$\Omega_s = \frac{2}{T} \tan\left(\frac{3\pi}{8}\right) = 2 \tan\left(\frac{3\pi}{8}\right)$$

$$\boxed{\Omega_s = 4.824 \text{ rad/sec}}$$

$$N \geq \log\left(\frac{\sqrt{10^{0.1\alpha_s}} - 1}{\sqrt{10^{0.1\alpha_p}} - 1}\right)$$

$$\log\left(\frac{\Omega_s}{\Omega_p}\right)$$

$$N \geq \log\left(\frac{\lambda}{E}\right)$$

$$\log\left(\frac{\Omega_s}{\Omega_p}\right)$$

$$\frac{1}{\sqrt{1+\varepsilon^2}} = 0.707 = \frac{\sqrt{2}}{2}$$

$$\frac{1}{1+\varepsilon^2} = \frac{2}{4} = \frac{1}{2}$$

$$1 + \varepsilon^2 = 2$$

$$\boxed{\varepsilon = 1}$$

$$\frac{1}{\sqrt{1+\lambda^2}} = 0.2 = \frac{1}{5}$$

$$1 + \lambda^2 = 25$$

$$\lambda = \sqrt{24}$$

$$\boxed{\lambda = 4.89}$$

$$N = \frac{\log\left(\frac{4.89}{1}\right)}{\log\left(\frac{4.824}{2}\right)}$$

$$N \geq \frac{\log(4.89)}{\log(2.412)}$$

$$N = 1.8 \Rightarrow N=2$$

Order(N)

1

 $s+1$

2

 $s^2 + \sqrt{2}s + 1$

3

 $(s+1)(s^2 + s + 1)$

4

 $(s^2 + 0.765s + 1)(s^2 + 1.847s + 1)$ Denominator of $H(s)$ Here $N=2$

$$\text{So, } H(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$$

Replace s with $\frac{s}{\Omega_c}$

$$\text{where } \Omega_c = \frac{\Omega_p}{\epsilon_{T/N}}$$

Here $\Omega_p = 2$ and $\epsilon = 1$

$$\text{So } s \rightarrow \frac{s}{2}$$

$$H(s) = \frac{1}{\left(\frac{s}{2}\right)^2 + \sqrt{2}\left(\frac{s}{2}\right) + 1}$$

$$H(s) = \frac{1}{\frac{s^2}{4} + \frac{s}{\sqrt{2}} + 1}$$

Now, we apply bilinear transformation, to convert it into digital domain

$$S \rightarrow \frac{2}{T} \left[\frac{1-z^{-1}}{1+z^{-1}} \right]$$

$$S \rightarrow \frac{2}{1} \left[\frac{1-z^{-1}}{1+z^{-1}} \right]$$

$$H(z) = \frac{1}{\frac{1}{4} \left[2 \left(\frac{1-z^{-1}}{1+z^{-1}} \right) \right]^2 + \frac{1}{\sqrt{2}} \left[2 \left(\frac{1-z^{-1}}{1+z^{-1}} \right) \right] + 1}$$

$$H(z) = \frac{1}{\frac{1}{4} \left[4 \left(\frac{1-z^{-1}}{1+z^{-1}} \right)^2 \right] + \frac{1}{\sqrt{2}} \cdot 2 \left(\frac{1-z^{-1}}{1+z^{-1}} \right) + 1}$$

$$= \frac{(1+z^{-1})^2}{(1-z^{-1})^2 + \sqrt{2}(1-z^{-2}) + (1+z^{-1})^2}$$

$$= \frac{(1+z^{-1})^2}{2 + 2z^{-2} + \sqrt{2} - \sqrt{2}z^{-2}}$$

$$= \frac{(1+z^{-1})^2}{2(1+z^{-2}) + \sqrt{2}(1-z^{-2})}$$

Impulse Invariance Method to design IIR Filter (Analog Filter to Digital Filter)

① Find $H_a(s)$ - Analog Filter Transfer Function

② Select sampling period (T)

③ $H_a(s) = \sum_{k=1}^N \frac{C_k}{s - P_k}$

(Sum of single pole filters)

④ $H(z) = \prod_{k=1}^N \frac{C_k}{1 - e^{P_k T} z^{-1}}$

ques) Find analog $H(z)$ using impulse invariance method
($T = 1$ second)

$$H(s) = \frac{2}{(s+1)(s+2)}$$

Ans) $\frac{2}{(s+1)(s+2)} = \frac{A}{(s+1)} + \frac{B}{(s+2)}$
 $= \frac{(A+B)s + (A+B)}{(s+1)(s+2)}$

$$A+B=0 \quad 2A+B=2$$

$$2A - A = 2$$

$A = 2$	$B = -2$
---------	----------

$$H(s) = \frac{2}{(s+1)} + \frac{(-2)}{(s+2)}$$

$$\rho_k = -1, -2$$

$$\text{So, } H(s) = \frac{2}{1-e^{-1}z^{-1}} + \frac{(-2)}{1-e^{-2}z^{-1}}$$

Chebyshev Filter Design

ques) Given the specification $A_p = 3 \text{ dB}$, $A_s = 16 \text{ dB}$

$f_p = 1 \text{ kHz}$ and $f_s = 2 \text{ kHz}$. Determine the order of filter using Chebyshev Approximation.

Find $H(z)$

Ans) $A_p = 3 \text{ dB}$ $A_s = 16 \text{ dB}$

$$f_p = 1 \text{ kHz}$$
 $f_s = 2 \text{ kHz}$

$$\Omega_p = 2\pi \times 1000 = 2000\pi \text{ rad/sec}$$

$$\Omega_s = 2\pi \times 2000 = 4000\pi \text{ rad/sec}$$

$$N = \cosh^{-1} \left(\frac{\frac{10^{0.1 A_s}}{1} - 1}{\frac{10^{0.1 A_p}}{1} - 1} \right) = \cosh^{-1} \left(\frac{10^{1.6} - 1}{10^{0.3} - 1} \right)$$

$$\cosh^{-1} \left(\frac{\Omega_s}{\Omega_p} \right) = \cosh^{-1}(2)$$

$$\cosh^{-1} x = \ln \left(x + \sqrt{x^2 - 1} \right)$$

$$N = 1.91$$

∴ $N = 2$

$$\epsilon = \sqrt{10^{0.1\alpha_p}} - 1$$

$$\lambda = \sqrt{10^{0.1\alpha_s}} - 1$$

$$u = \epsilon^{-1} + \sqrt{\epsilon^{-2} + 1}$$

$$N = \cosh^{-1}\left(\frac{2}{\epsilon}\right)$$

$$\cosh^{-1}\left(\frac{\alpha_s}{\alpha_p}\right)$$

$$u = 2.414$$

$$a = \alpha_p \left[\frac{u^{VN} - u^{-VN}}{2} \right]$$

$$b = \alpha_p \left[\frac{u^{VN} + u^{-VN}}{2} \right]$$

$$a = 910 \text{ a}$$

$$b = 2197 \text{ a}$$

Poles

$$s_K = a \cos \phi_K + j b \sin \phi_K$$

$$K = 1, 2, \dots, N$$

$$\phi_K = \frac{\pi}{2} + \left[\frac{2K-1}{2N} \right] \pi \quad K = 1, 2, \dots, N$$

$$\phi_1 = \frac{\pi}{2} + \frac{\pi}{4} = 135^\circ$$

$$\phi_2 = \frac{\pi}{2} + \frac{3\pi}{4} = 225^\circ$$

~~$$s_K = a \cos \phi_K + j b \sin \phi_K$$~~

$$s_1 = 910 \text{ a} \cos(135^\circ) + j(2197 \text{ a}) \sin(135^\circ)$$

$$s_1 = -643.46 \text{ a} + j 1554 \text{ a}$$

$$S_2 = \frac{a \cos \phi_2 + j b \sin \phi_2}{(910\pi) \cos(225) + j \sin(225)}$$

$$S_2 = -643.46\pi - j 1554\pi$$

$$H(s) = \frac{\text{Numerator}}{\text{Denominator}}$$

$$\text{Denominator} = (s - s_1)(s - s_2) \dots (s - s_N)$$

$$H(s) = \frac{\text{Numerator}}{(s + 643.46\pi - j 1554\pi)(s + 643.46\pi + j 1554\pi)}$$

To find numerator

~~Put~~ ① If N is even

Put $s=0$ in denominator and then divide that value by $\sqrt{1+\varepsilon^2}$

~~For even N~~

② If N is odd

Put $s=0$ in denominator to get the numerator value.

Here $N=2$ is even

$$\text{Numerator} \neq \sqrt{1+\varepsilon^2} = \sqrt{2} = 1.414$$

$$\text{Numerator} = \frac{(643.46\pi - j 1554\pi)(643.46\pi + j 1554\pi)}{\sqrt{2}}$$

$$H(s) = \frac{(643.46\pi - j 1554\pi)(643.46\pi + j 1554\pi)}{(s + 643.46\pi - j 1554\pi)(s + 643.46\pi + j 1554\pi)}$$

Impulse Response of Linear phase FIR Filter:

Symmetric:

$$h(n) = h(M-1-n); 0 \leq n \leq M-1$$

↓
order

Let $M=8$ → even

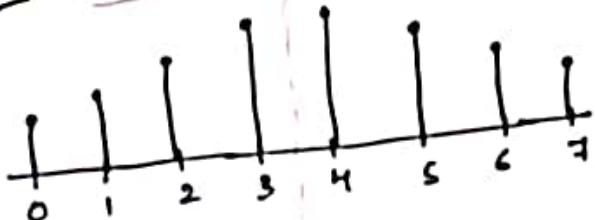
$$\therefore h(n) = h(8-1-n); 0 \leq n \leq 7$$

$$n=0 \quad h(0) = h(8-1-0) = h(7)$$

$$n=1 \quad h(1) = h(8-1-1) = h(6)$$

$$n=2 \quad h(2) = h(8-1-2) = h(5)$$

$$n=3 \quad h(3) = h(8-1-3) = h(4)$$



$M=9$



Anti-Symmetric:

$$h(n) = -h(M-1-n); 0 \leq n \leq M-1$$

$$\text{Let } M=8$$

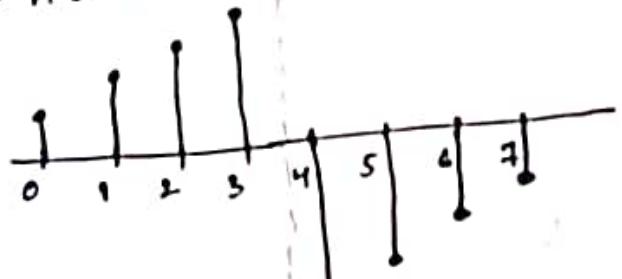
$$\therefore h(n) = -h(8-1-n); 0 \leq n \leq 7$$

$$n=0 \quad h(0) = -h(8-1-0) = -h(7)$$

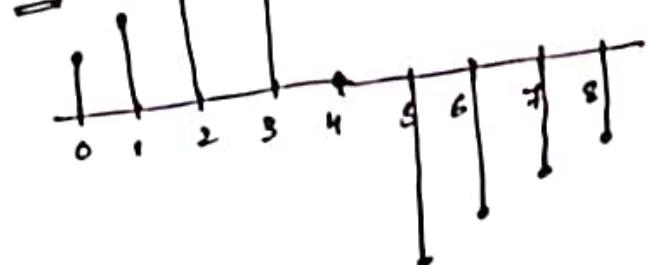
$$n=1 \quad h(1) = -h(8-1-1) = -h(6)$$

$$n=2 \quad h(2) = -h(8-1-2) = -h(5)$$

$$n=3 \quad h(3) = -h(8-1-3) = -h(4)$$



$M=9$



Frequency Response of Linear phase FIR Filter

$$h(n) \xrightarrow{\text{DTFT}} H(\omega)$$

Freq response of FIR filter.

$$H(\omega) = \underbrace{H_r(\omega)}_{\text{real part of } H(\omega)} e^{j\theta(\omega)}$$

(i) Symmetric Impulse response with M is even:

$$H_r(\omega) = \sum_{n=0}^{\frac{M}{2}-1} 2h(n) \cos\left[\omega\left(n - \frac{M-1}{2}\right)\right]$$

$$\theta(\omega) = \begin{cases} -\omega\left(\frac{M-1}{2}\right); & H_r(\omega) > 0 \\ -\omega\left(\frac{M-1}{2}\right) + \pi; & H_r(\omega) < 0 \end{cases}$$

(ii) Symmetric Impulse response with M is odd:

~~$$H_r(\omega) = h\left(\frac{M-1}{2}\right) + \sum_{n=0}^{\frac{M-3}{2}} 2h(n) \cos\left(\omega\left[n - \frac{M-1}{2}\right]\right)$$~~

$$H_r(\omega) = h\left(\frac{M-1}{2}\right) + \sum_{n=0}^{\frac{M-3}{2}} 2h(n) \cos\left(\omega\left[n - \frac{M-1}{2}\right]\right)$$

$$\theta(\omega) = \begin{cases} -\omega\left(\frac{M-1}{2}\right); & H_r(\omega) > 0 \\ -\omega\left(\frac{M-1}{2}\right) + \pi; & H_r(\omega) < 0 \end{cases}$$

(iii) Anti-Symmetric Impulse response with M is even:

$$H_r(\omega) = 2 \sum_{n=0}^{\frac{M}{2}-1} h(n) \sin\left(\omega\left[\frac{M-1}{2} - n\right]\right)$$

$$\theta(\omega) = \begin{cases} \frac{\pi}{2} - \omega\left(\frac{M-1}{2}\right); & H_r(\omega) > 0 \\ \frac{3\pi}{2} - \omega\left(\frac{M-1}{2}\right); & H_r(\omega) < 0 \end{cases}$$

(iv) Anti-Symmetric Impulse response with M is odd:

$$H_r(\omega) = 2 \sum_{n=0}^{\frac{M-3}{2}} h(n) \sin\left(\omega\left[\frac{M-1}{2} - n\right]\right)$$

$$\theta(\omega) = \begin{cases} \frac{\pi}{2} - \omega\left(\frac{M-1}{2}\right); & H_r(\omega) > 0 \\ \frac{3\pi}{2} - \omega\left(\frac{M-1}{2}\right); & H_r(\omega) < 0 \end{cases}$$