

Project Report On

AXI4-Lite to SRAM Bridge with UVM based Verification



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TABLE OF CONTENTS

1. Introduction

1. Introduction
2. Literature Survey
3. Aim of Project
4. Scope and Objective

2. THEORETICAL DESCRIPTION OF PROJECT

1. Introduction to AMBA
2. Features of AXI4 Lite
3. Channel Handshake
4. AXI4 Lite Channels
5. Channel Transfer Example
6. Data size, Length and Burst type

3. SYSTEM DESIGN AND OPTIMIZATION

1. Design Information
2. Basic Block Diagram
3. Implementation Considerations

5. RESULTS AND TOOLS USED

1. Simulation Result
2. Synthesis Result
3. Xilinx Vivado and EDA Playground

6. VERIFICATION

1. Verification Technology – UVM

7. CONCLUSION

8. FUTURE SCOPE

9. REFERENCES

Abstract

In modern digital systems, the efficient and reliable transfer of data between processing elements and memory subsystems is crucial for achieving high performance. The AXI4 (Advanced eXtensible Interface 4) protocol has emerged as a standard for interconnecting components within System-on-Chip (SoC) designs, offering a flexible and scalable solution for memory access. This abstract presents a comprehensive approach to the design and verification of a high-performance AXI4 memory interface, ensuring robustness, efficiency, and compatibility within complex system architectures.

The design phase encompasses several critical stages, including architecture definition, protocol selection and interface configuration for designing AXI4 master and slave interfacing with memory. The memory interface architecture is tailored to meet the stringent requirements of modern computing systems.

Verification of the AXI4 memory interface involves exhaustive testing to ensure functional correctness, protocol compliance, and interoperability with diverse system components. Utilizing industry-standard verification methodologies such as UVM (Universal Verification Methodology) and formal verification techniques, the design undergoes rigorous validation across various scenarios and corner cases.

The proposed design and verification methodology yield a high-performance AXI4 memory interface capable of seamlessly integrating into complex SoC designs while meeting the demands of modern computing applications. By leveraging a combination of advanced design techniques and rigorous verification methodologies, the memory interface architecture achieves optimal performance, reliability, and scalability, thereby facilitating the development of next-generation computing systems.

Keywords: AXI4, Memory Interface, Design, Verification, UVM.

INTRODUCTION

In the realm of modern computing systems, the quest for high-performance memory interfaces stands as a crucial frontier. With the relentless pursuit of faster data processing and seamless interaction between various components, the demand for efficient and reliable memory interfaces has escalated. Among the plethora of protocols available, the Advanced eXtensible Interface 4 (AXI4) emerges as a cornerstone, offering a robust framework for connecting components within a system-on-chip (SoC) architecture.

This document delves into the intricate world of designing and verifying high-performance AXI4-lite memory interfaces. It embarks on a journey through the fundamental principles, design methodologies, challenges, and verification strategies essential for crafting robust and efficient AXI4 memory interfaces.

Fundamentals of AXI4 Protocol Here, we provide a comprehensive overview of the AXI4 protocol, elucidating its key features, transaction types, signaling mechanisms, and protocol layers. Understanding the intricacies of AXI4 forms the bedrock for designing efficient memory interfaces that harness its full potential.

Design Considerations This section navigates through the crucial design considerations when architecting high-performance AXI4 memory interfaces. From optimizing data throughput and minimizing latency to ensuring compatibility with diverse memory devices, each aspect is meticulously examined to unveil the underlying principles guiding optimal design decisions.

Implementation Strategies Armed with a profound understanding of AXI4 fundamentals and design considerations, this section delves into implementation strategies tailored to unleash the full performance potential of AXI4 memory interfaces. From pipelining and parallelism to advanced arbitration techniques, a myriad of strategies are explored to craft interfaces that seamlessly integrate with the broader SoC ecosystem.

Verification Methodologies The reliability and correctness of high-performance AXI4 memory interfaces hinge on robust verification methodologies. In this section, we elucidate various verification strategies, including simulation-based testing, formal verification, and hardware emulation, essential for rigorously validating the functionality and performance of AXI4 memory interfaces across diverse usage scenarios.

LITERATURE SURVEY

The Advanced Microcontroller Bus Architecture (AMBA) is an open-standard, on-chip interconnect specification for the connection and management of functional blocks in system-on-a-chip (SoC) designs. The literature on AXI4 Memory Interface enclose diverse perspectives, addressing performance optimization, security considerations, and adaptability in various computing environments.

Performance Optimization:

Research often delves into enhancing AXI4 Memory Interface performance. Studies explore methods to boost data transfer rates, minimize latency, and optimize overall system efficiency. Novel techniques, such as parallel processing and advanced buffering strategies, are proposed to achieve high-throughput and low-latency communication within the AXI4 framework.

Energy Efficiency in AXI4:

With a growing focus on energy-aware computing, researchers investigate strategies for energy-efficient AXI4 Memory Interface access. This involves the development of power-saving mechanisms and trade-offs to balance performance requirements with the stringent power constraints of devices, particularly in the context of Internet of Things (IoT) applications.

Security Challenges:

Security considerations in AXI4-based memory systems are a critical area of study. Papers examine potential vulnerabilities and propose countermeasures to ensure secure data transfers. Topics include access control mechanisms, data integrity verification, and protection against unauthorized access, contributing insights into safeguarding AXI4 Memory Interfaces from security threats

Scalability in Multi-Core Architectures:

As multi-core processors become prevalent, research addresses scalability challenges in AXI4 interconnects. Investigations focus on identifying and mitigating bottlenecks to accommodate increasing core counts. Proposed scalable AXI4 Memory Interface architectures aim to optimize memory access in the context of evolving multi-core

systems, balancing performance and scalability

Adaptive AXI4 Interfaces:

Adaptive AXI4 Memory Interface designs are explored for heterogeneous computing platforms. Researchers investigate dynamic adjustments to memory access patterns based on varying workloads, optimizing resource utilization. This adaptability is crucial in environments with diverse computing tasks, showcasing the flexibility of AXI4 interfaces in meeting the demands of heterogeneous computing.

Real-time Monitoring and Fault Tolerance:

Some studies introduce real-time monitoring systems for AXI4 transactions to enhance system reliability. Additionally, research addresses fault-tolerant AXI4 Memory Interface designs, particularly for critical applications like aerospace systems. These mechanisms aim to detect and mitigate memory errors induced by environmental conditions or radiation, ensuring data integrity and system reliability in challenging contexts.

Machine Learning Integration:

Emerging research explores the integration of machine learning techniques to optimize AXI4 Memory Interfaces. This involves developing models that learn and adapt to application-specific access patterns, dynamically adjusting interface parameters. Machine learning-driven optimizations aim to enhance overall system performance by predicting and responding to the varying demands of different workloads efficiently.

Cross-Layer Analysis in Cyber-Physical Systems (CPS):

Some studies conduct cross-layer analyses of AXI4 interconnects within the context of cyber-physical systems (CPS). This approach examines the interactions between hardware and software layers, identifying challenges and opportunities for improving AXI4 Memory Interface design within CPS architectures. The research contributes to a holistic understanding of system performance, essential for the integration of AXI4 interfaces in CPS applications.

Mobile Device Considerations:

Tailoring AXI4 Memory Interface design to mobile devices is a specific focus area. Research explores power-aware optimization strategies, dynamically adjusting interface parameters based on the device's power state. The goal is to achieve energy-efficient

AXI4 Memory Interfaces without compromising performance, addressing the unique power constraints of mobile computing platforms.

Application in Automotive Electronics:

Another niche area of investigation involves the application of AXI4 Memory Interfaces in automotive electronics. Research in this domain explores the specific requirements and challenges in integrating AXI4 interfaces for efficient data communication within automotive systems. This includes considerations for real-time data transfer, reliability, and safety-critical functionalities in the context of modern automotive electronics architectures.

AIM OF PROJECT

The aim for the project "AXI4-Lite to SRAM Bridge with UVM-based Verification" expressed in a complete, coherent sentence:

The aim of this project is to design and implement an efficient AXI4-Lite slave interface that converts AXI4-Lite protocol transactions into synchronous SRAM memory accesses, enabling a master device to reliably read and write data to SRAM, while developing a comprehensive UVM-based verification environment that simulates and validates the bridge's protocol compliance, data integrity, and timing accuracy through constrained-random testing, scoreboarding, and functional coverage, ultimately delivering a scalable and reusable hardware and verification solution suitable for integration into system-on-chip designs.

SCOPE AND OBJECTIVE

- RTL design of AXI4 Lite Slave
- RTL design of FIFOs
- RTL design of SRAM controller including SRAM
- Integrating AXI4 lite Slave to perform write in and read from memory in fixed and increment mode following proper handshake as per the AXI protocol.
- Verification of AXI4 lite design using UVM involving list of monitor checks for analyzing protocol violations.

The scope of the AXI4 lite memory interface is broad, encompassing various aspects of system-level communication and memory access within digital systems, key dimensions that define the scope of AXI4-Lite:

Interconnect Standard:

AXI4-Lite serves as a widely adopted interconnect standard in System-on-Chip (SoC) designs for simple memory-mapped communication. Its scope includes facilitating communication and data transfer between IP blocks, processors, and peripherals, but specifically for low-throughput control and status accesses within an integrated circuit.

High Performance and Scalability:

AXI4-Lite is designed to meet simpler performance requirements compared to AXI4. Its scope focuses on providing an efficient and easy-to-implement interface suitable for control registers and small data transfers. Unlike AXI4, it does not support bursts or multiple parallel channels, meaning scalability and throughput are limited.

Flexibility and Adaptability:

The scope of AXI4-Lite includes flexibility to be tailored for simple control interfaces. While it does not support diverse burst lengths or complex transaction types like full AXI4, its fixed, lightweight protocol makes it adaptable for many peripherals needing straightforward register read/writes.

Memory-Mapped Communication:

AXI4-Lite is specifically used for memory-mapped communication, enabling access to memory-mapped registers with a simplified signaling protocol. Its scope ensures processors and peripherals can interact with control and status registers in a standardized and efficient manner, usually for low bandwidth data exchange.

Cross-Platform Integration:

AXI4-Lite extends beyond individual chip designs to facilitate cross-platform integration, often appearing in FPGA implementations to connect simple peripherals or control modules. Its standardized interface allows seamless communication between programmable logic and processors in diverse environments.

Security Considerations:

Although AXI4-Lite's simpler protocol structure inherently reduces complexity, the scope of its security considerations includes standard mechanisms for access control and data integrity within the simpler control communication domain, helping protect against unauthorized register accesses.

Application in Various Domains:

AXI4-Lite finds application primarily in domains where simple, low-throughput control and status communication is needed, such as embedded systems, consumer electronics, automotive, and industrial control. Its scope emphasizes ease of use and reliability over raw throughput, supporting the needs of diverse applications with minimal complexity. It also can find its application in Low power memory communication protocols.

THEORETICAL DESCRIPTION OF PROJECT

1. Introduction to AMBA

The Advanced microcontroller bus architecture (AMBA) family enables extensive testing of intellectual property (IPs) such as from ARM and other IP suppliers and system-on-chip (SoC) design through metric-driven protocol compliance verification. It delivers high- frequency operation using sophisticated bridges and supports tremendous performance and high-frequency. It is appropriate for high-bandwidth and low latency designs. The Advanced eXtensible Interface 4 (AXI4) bus family, defined as part of the ARM - AMBA standard's fourth version. The AMBA – AXI4-lite bus protocol is a subset of the AXI4 bus protocol with a simpler interface than the full-featured AXI-4 bus protocol. It only supports one ID thread per master, therefore it's best for an endpoint that only has to connect with one master at a time. There are five channels in the AXI4-Lite interface: read data, read address, write data, write address, and write response. Burst lengths up to 256 bits are supported by the AXI4 family.

The AXI protocol is burst-based. Every transaction has address and control information on the address channel that describes the nature of the data to be transferred. The data is transferred between master and slave using a write data channel to the slave or a read data channel to the master. In write transactions, in which all the data flows from the master to the slave, the AXI protocol has an additional write response channel to allow the slave to signal to the master the completion of the write transaction.

The objectives of the latest generation AMBA interface are to:

- be suitable for high-bandwidth and low-latency designs
- enable high-frequency operation without using complex bridges
- meet the interface requirements of a wide range of components
- be suitable for memory controllers with high initial access latency
- provide flexibility in the implementation of interconnect architectures
- be backward-compatible with existing AHB and APB interfaces.

The key features of the AXI protocol are:

- separate address/control and data phases
- support for unaligned data transfers using byte strobes
- burst-based transactions with only start address issued
- separate read and write data channels to enable low-cost Direct Memory Access (DMA)
- ability to issue multiple outstanding addresses
- out-of-order transaction completion
- easy addition of register stages to provide timing closure.

2. Features of AXI

The AXI protocol has several key features that are designed to improve bandwidth and latency of data transfers and transactions, as you can see here:

Independent read and write channels

AXI supports two different sets of channels, one for write operations, and one for read operations. Having two independent sets of channel helps to improve the bandwidth performances of the interfaces. This is because read and write operations can happen at the same time.

Multiple outstanding addresses

AXI allows for multiple outstanding addresses. This means that a master can issue transactions without waiting for earlier transactions to complete. This can improve system performance because it enables parallel processing of transactions.

No strict timing relationship between address and data operations

With AXI, there is no strict timing relationship between the address and data operations. This means that, for example, a master could issue a write address on the **Write Address** channel, but there is no time requirement for when the master has to provide the corresponding data to write on the **Write Data** channel.

Support for unaligned data transfers

For any burst that is made up of data transfers wider than one byte, the first bytes accessed can be unaligned with the natural address boundary. For example, a 32-bit data packet that starts at a byte address of 0x1002 is not aligned to the natural 32-bit address boundary.

Out-of-order transaction completion

Out-of-order transaction completion is possible with AXI. The AXI protocol includes transaction identifiers, and there is no restriction on the completion of transactions with different ID values.

This means that a single physical port can support out-of-order transactions by acting as several logical ports, each of which handles its transactions in order.

Burst transactions based on start address

AXI masters only issue the starting address for the first transfer. For any following transfers, the

slave will calculate the next transfer address based on the burst type.

3. Channel Handshake

Handshake process

All five channels use the same VALID/READY handshake to transfer data and control information. This two-way flow control mechanism enables both the master and slave to control the rate at which the data and control information moves. The source generates the VALID signal to indicate when the data or control information is available. The destination generates the READY signal to indicate that it accepts the data or control information. Transfer occurs only when both the VALID and READY signals are HIGH.

There must be no combinatorial paths between input and output signals on both master and slave interfaces.

Figure 1 to Figure 3 show examples of the handshake sequence. In Figure 1, the source presents the data or control information and drives the VALID signal HIGH. The data or control information from the source remains stable until the destination drives the READY signal HIGH, indicating that it accepts the data or control information. The arrow shows when the transfer occurs.

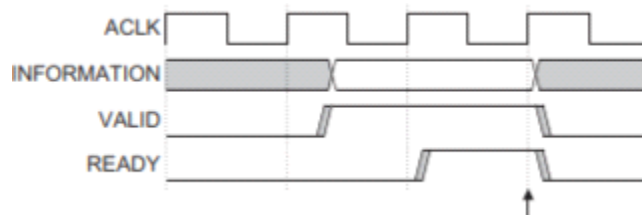


Figure 1 - VALID before READY handshake

In Figure 2 the destination drives READY HIGH before the data or control information is valid. This indicates that the destination can accept the data or control information in a single cycle as soon as it becomes valid. The arrow shows when the transfer occurs.

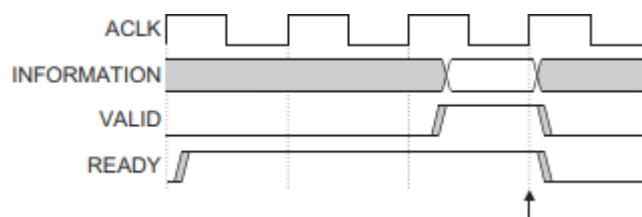


Figure 2 READY before VALID handshake

In Figure 3, both the source and destination happen to indicate in the same cycle that they can transfer the data or control information. In this case the transfer occurs immediately. The arrow shows when the transfer occurs.

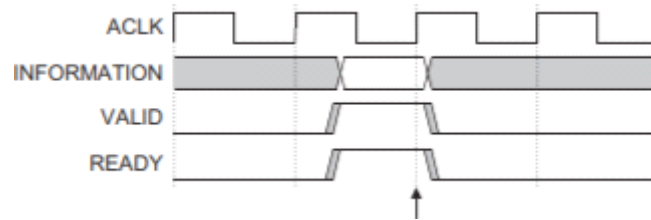


Figure 3 VALID with READY handshake

The individual AXI protocol channel handshake mechanisms are described in:

- Write address channel
- Write data channel
- Write response channel
- Read address channel
- Read data channel

Write address channel

The master can assert the AWVALID signal only when it drives valid address and control information. It must remain asserted until the slave accepts the address and control information and asserts the associated AWREADY signal.

The default value of AWREADY can be either HIGH or LOW. The recommended default value is HIGH, although if AWREADY is HIGH then the slave must be able to accept any valid address that is presented to it.

A default AWREADY value of LOW is possible but not recommended, because it implies that the transfer takes at least two cycles, one to assert AWVALID and another to assert AWREADY.

Write data channel

During a write burst, the master can assert the WVALID signal only when it drives valid write data. WVALID must remain asserted until the slave accepts the write data and asserts the WREADY signal.

The default value of WREADY can be HIGH, but only if the slave can always accept write data in a single cycle. The master must assert the WLAST signal when it drives the final write transfer in the burst. When WVALID is LOW, the WSTRB[3:0] signals can take any value, although it is recommended that they are either driven LOW or held at their previous value.

Write response channel

The slave can assert the BVALID signal only when it drives a valid write response. BVALID must remain asserted until the master accepts the write response and asserts BREADY. The default value of BREADY can be HIGH, but only if the master can always accept a write response in a single cycle.

Read address channel

The master can assert the ARVALID signal only when it drives valid address and control information. It must remain asserted until the slave accepts the address and control information and asserts the associated ARREADY signal.

The default value of ARREADY can be either HIGH or LOW. The recommended default value is HIGH, although if ARREADY is HIGH then the slave must be able to accept any valid address that is presented to it.

A default ARREADY value of LOW is possible but not recommended, because it implies that the transfer takes at least two cycles, one to assert ARVALID and another to assert ARREADY.

Read data channel

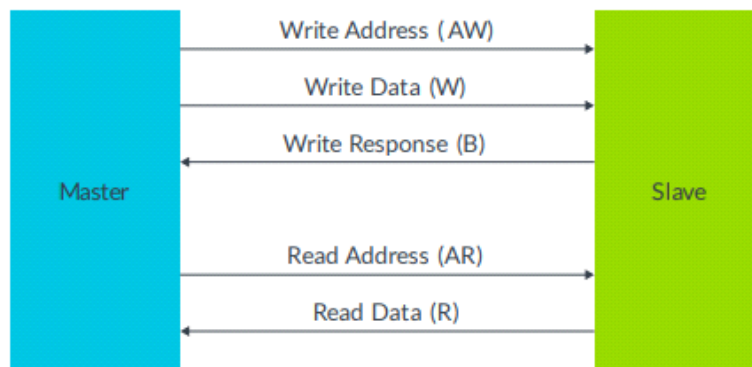
The slave can assert the RVALID signal only when it drives valid read data. RVALID must remain asserted until the master accepts the data and asserts the RREADY signal. Even if a slave has only one source of read data, it must assert the RVALID signal only in response to a request for the data.

The master interface uses the RREADY signal to indicate that it accepts the data. The default value of RREADY can be HIGH, but only if the master is able to accept read data immediately, whenever it performs a read transaction. The slave must assert the RLAST signal when it drives the final read transfer in the burst.

4. AXI4 Channels

The AXI specification describes a point-to-point protocol between two interfaces: a master and slave.

The following diagram shows the five main channels that each AXI interface uses for communication:



Write operations use the following channels:

- The master sends an address on the Write Address (AW) channel and transfers data on the Write Data (W) channel to the slave.
- The slave writes the received data to the specified address. Once the slave has completed the write operation, it responds with a message to the master on the Write Response (B) channel.

Read operations use the following channels:

- The master sends the address it wants to read on the Read Address (AR) channel.
- The slave sends the data from the requested address to the master on the Read Data (R) channel.

The slave can also return an error message on the Read Data (R) channel. An error occurs if, for example, the address is not valid, or the data is corrupted, or the access does not have the right security permission.

Using separate address and data channels for read and write transfers helps to maximize the bandwidth of the interface. There is no timing relationship between the groups of read and write channels. This means that a read sequence can happen at the same time as a write sequence.

Each of these five channels contains several signals, and all these signals in each channel have the prefix as follows:

- AW for signals on the Write Address channel
- AR for signals on the Read Address channel
- W for signals on the Write Data channel
- R for signals on the Read Data channel
- B for signals on the Write Response channel

5. Channel Transfer Examples

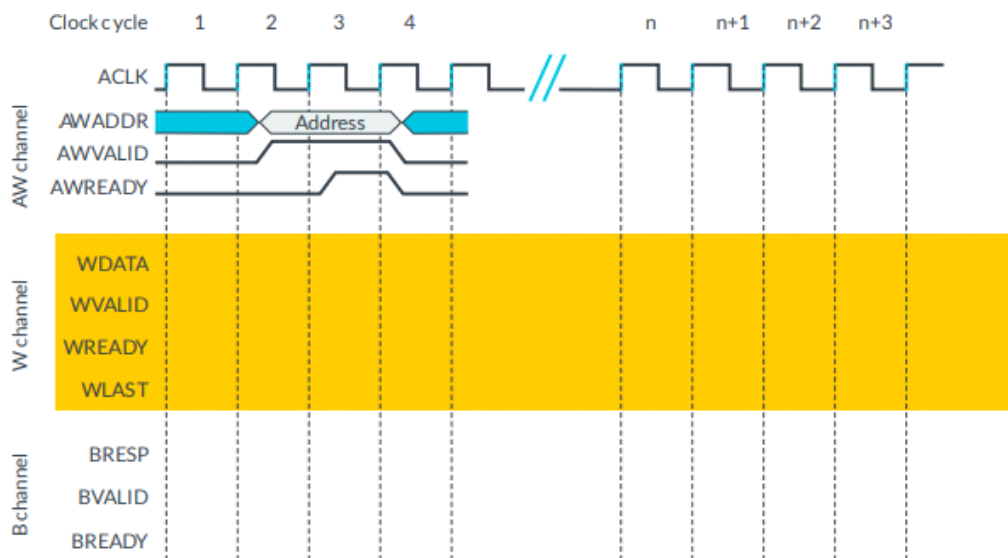
Write transaction: single data item

This section describes the process of a write transaction for a single data item, and the different channels that are used to complete the transaction.

This write transaction involves the following channels:

- Write Address (AW)
- Write (W)
- Write Response (B)

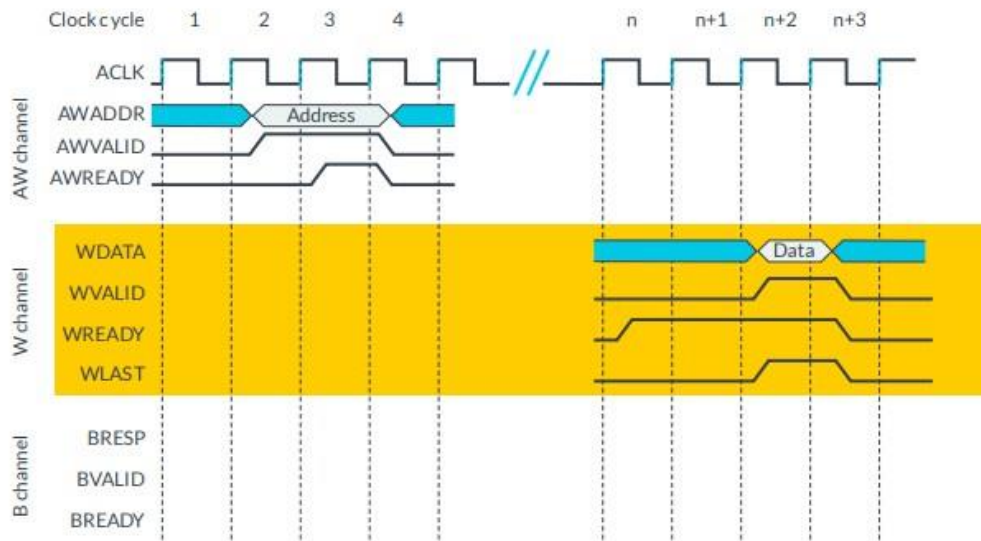
First, there is a handshake on the Write Address (AW) channel, as shown in the following diagram:



This handshake is where the master communicates the address of the write to the slave. The handshake has the following sequence of events:

1. The master puts the address on AWADDR and asserts AWVALID in clock cycle 2.
2. The slave asserts AWREADY in clock cycle 3 to indicate its ability to receive the address value.
3. The handshake completes on the rising edge of clock cycle 4.

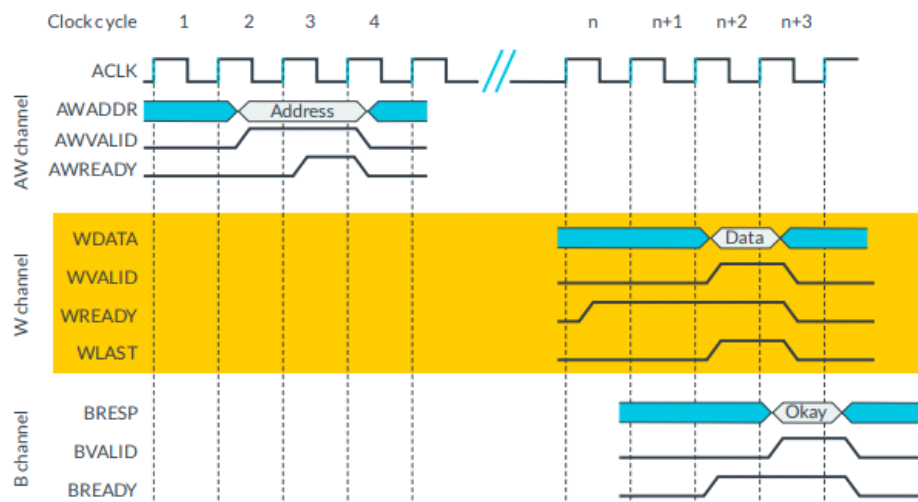
After this first handshake, the master transfers the data to the slave on the Write (W) channel, as shown in the following diagram:



The data transfer has the following sequence of events:

1. The slave is waiting for data with WREADY set to high in clock cycle n.
2. The master puts the data on the WDATA bus and asserts WVALID in clock cycle n+2.
3. The handshake completes on the rising edge of clock cycle n+3

Finally, the slave uses the Write Response (B) channel, to confirm that the write transaction has completed once all WDATA has been received. This response is shown in the following diagram:



The write response has the following sequence of events:

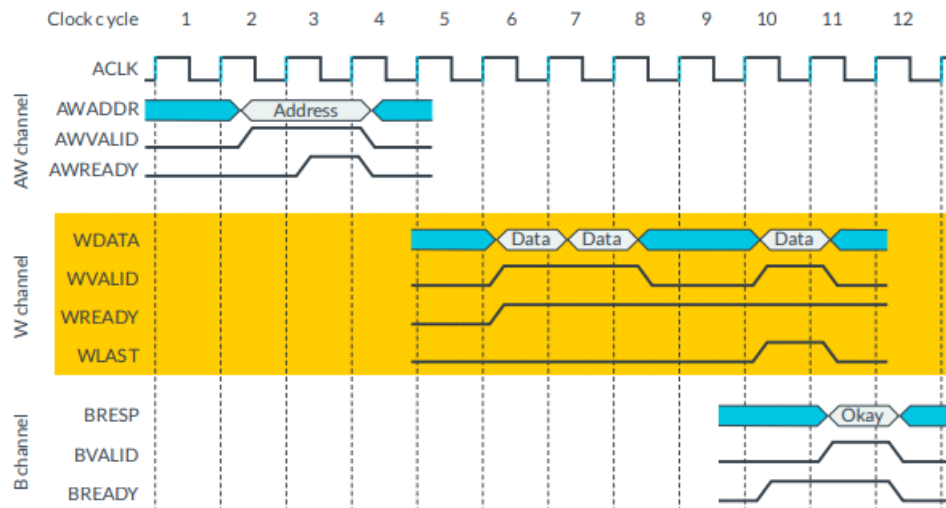
1. The master asserts BREADY.
2. The slave drives BRESP to indicate success or failure of the write transaction, and asserts BVALID.

The handshake completes on the rising edge of clock cycle n+3.

Write transaction: multiple data items

AXI is a burst-based protocol, which means that it is possible to transfer multiple data in a single transaction. We can transfer a single address on the AW channel to transfer multiple data, with associated burst width and length information.

The following diagram shows an example of a multiple data transfer:



In this case, the AW channel indicates a sequence of three transfers, and on the W channel, we see three data transfers.

The master drives the WLAST high to indicate the final WDATA. This means that the slave can either count the data transfers or just monitor WLAST.

Once all WDATA transfers are received, the slave gives a single BRESP value on the B channel. One single BRESP covers the entire burst. If the slave decides that any of the transfers contain an error, it must wait until the entire burst has completed before it informs the master that an error occurred.

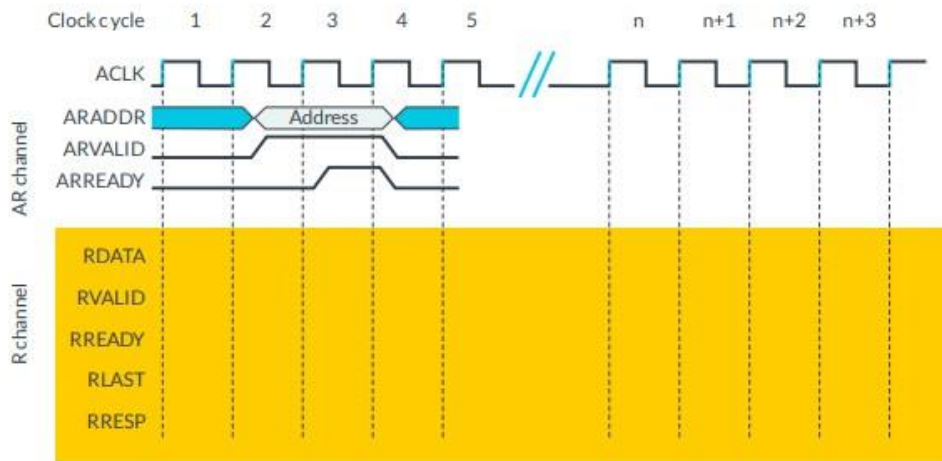
Read transaction: single data item

This section looks in detail at the process of a read transaction for a single data item, and the different channels used to complete the transaction.

This write transaction involves the following channels:

- Read Address (AR)
- Read (R)

First, there is a handshake on the Read Address (AR) channel, as shown in the following diagram:

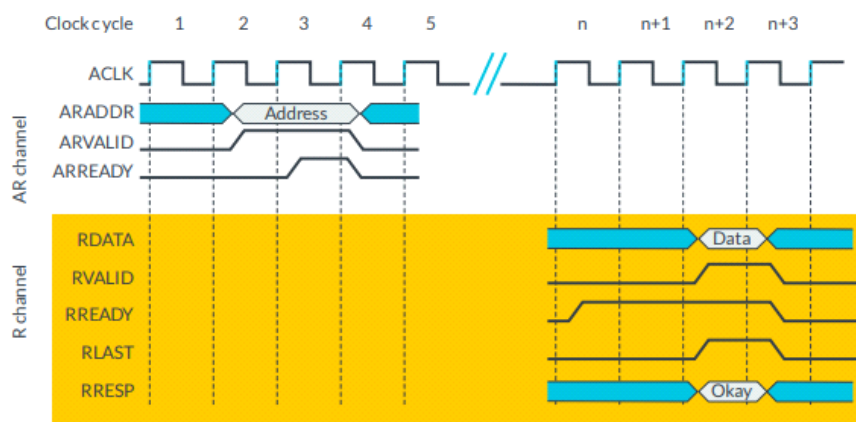


The handshake has the following sequence of events:

1. In clock cycle 2, the master communicates the address of the read to the slave on ARADDR and asserts ARVALID.
2. In clock cycle 3, the slave asserts ARREADY to indicate that it is ready to receive the address value.

The handshake completes on the rising edge of clock cycle 4.

Next, on the Read (R) channel, the slave transfers the data to the master. The following diagram shows the data transfer process:



The data transfer handshake has the following sequence of events:

1. In clock cycle n, the master indicates that it is waiting to receive the data by asserting RREADY.
2. The slave retrieves the data and places it on RDATA in clock cycle n+2. In this case, because this is a single data transaction, the slave also sets the RLAST signal to high. At the same time, the slave uses RRESP to indicate the success or failure of the read transaction

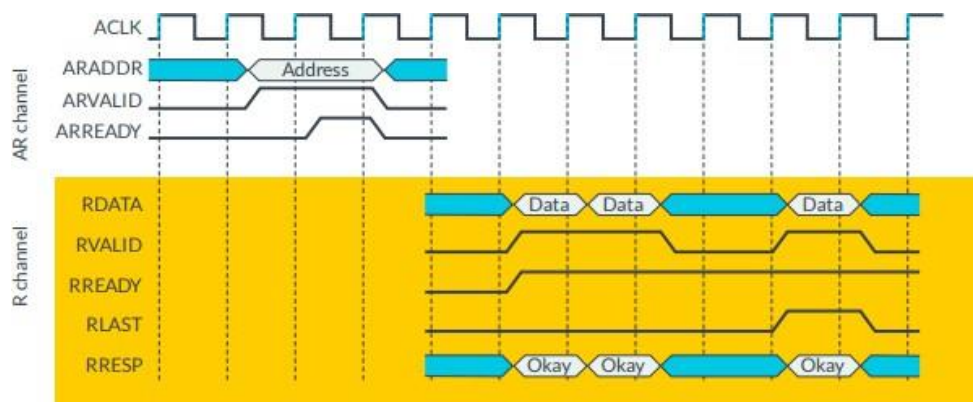
to the master, and asserts RVALID.

3. Because RREADY is already asserted by the master, the handshake completes on the rising edge of clock cycle $n+3$.

Read transaction: multiple data items

The AXI protocol also allows a read burst of multiple data transfer in the same transaction. This is similar to the write burst that is described in Write transaction: multiple data items.

The following diagram shows an example of a burst read transfer



In this example, we transfer a single address on the AR channel to transfer multiple data items, with associated burst width and length information. Here, the AR channel indicates a sequence of three transfers, therefore on the R channel, we see three data transfers from the slave to the master.

On the R channel, the slave transfers the data to the master. In this example, the master is waiting for data as shown by RREADY set to high. The slave drives valid RDATA and asserts RVALID for each transfer.

One difference between a read transaction and a write transaction is that for a read transaction there is an RRESP response for every transfer in the transaction. This is because, in the write transaction, the slave has to send the response as a separate transfer on the B channel. In the read transaction, the slave uses the same channel to send the data back to the master and to indicate the status of the read operation.

If an error is indicated for any of the transfers in the transaction, the full indicated length of the transaction must still be completed. There is no such thing as early burst termination.

6. Data size, Length and Burst type

Each read and write transaction has attributes that specify the data length, size, and the burst signal attributes for that transaction.

In the following list of attributes, x stands for write and read, so they apply to both the Write

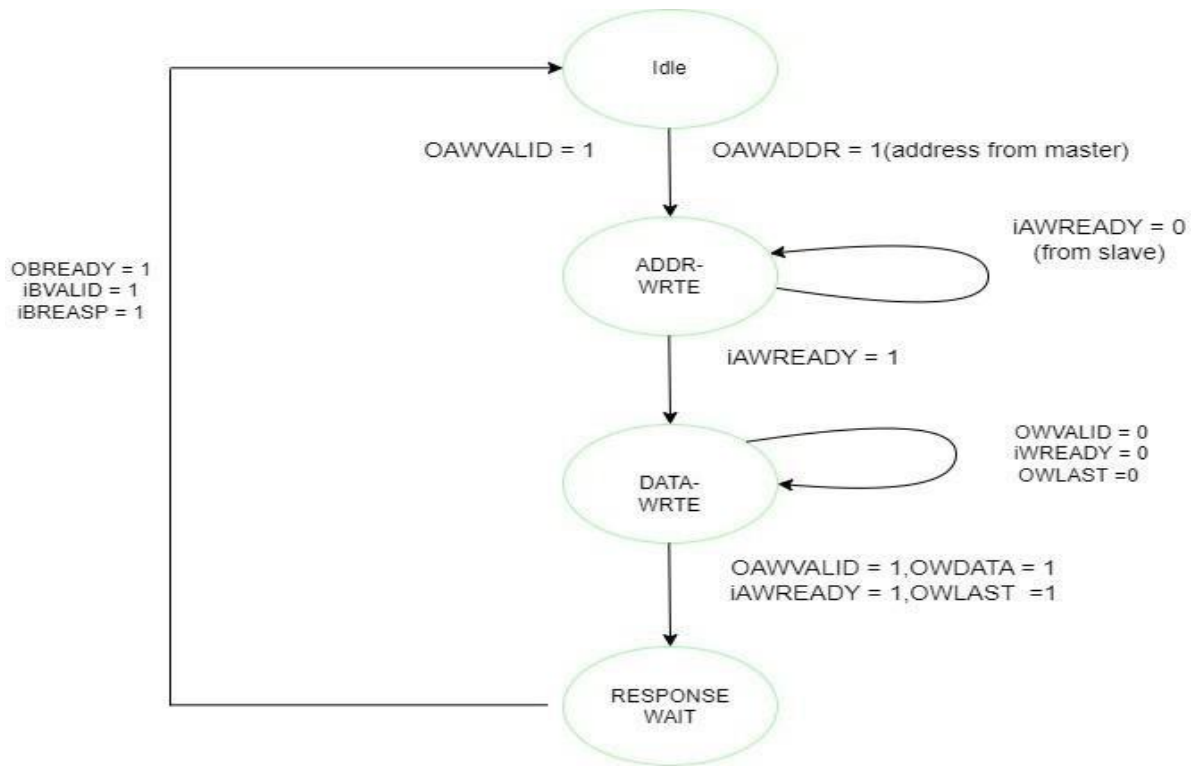
Address channel and the Read Address channel:

- **AxLEN** describes the length of the transaction in the number of transfers.
 - o For AXI4, AxLEN[7:0] has 8 bits, which specifies a range of 1-256 data transfers in a transaction.
- **AxSize[2:0]** describes the maximum number of bytes to transfer in each data transfer. Three bits of encoding indicate 1, 2, 4, 8, 16, 32, 64, or 128 bytes per transfer.
- **AxBURST[1:0]** describes the burst type of the transaction: fixed, incrementing, or wrapping

SYSTEM DESIGN AND OPTIMIZATION

1. Design Information

- Write Channel FSM for AXI4 Master



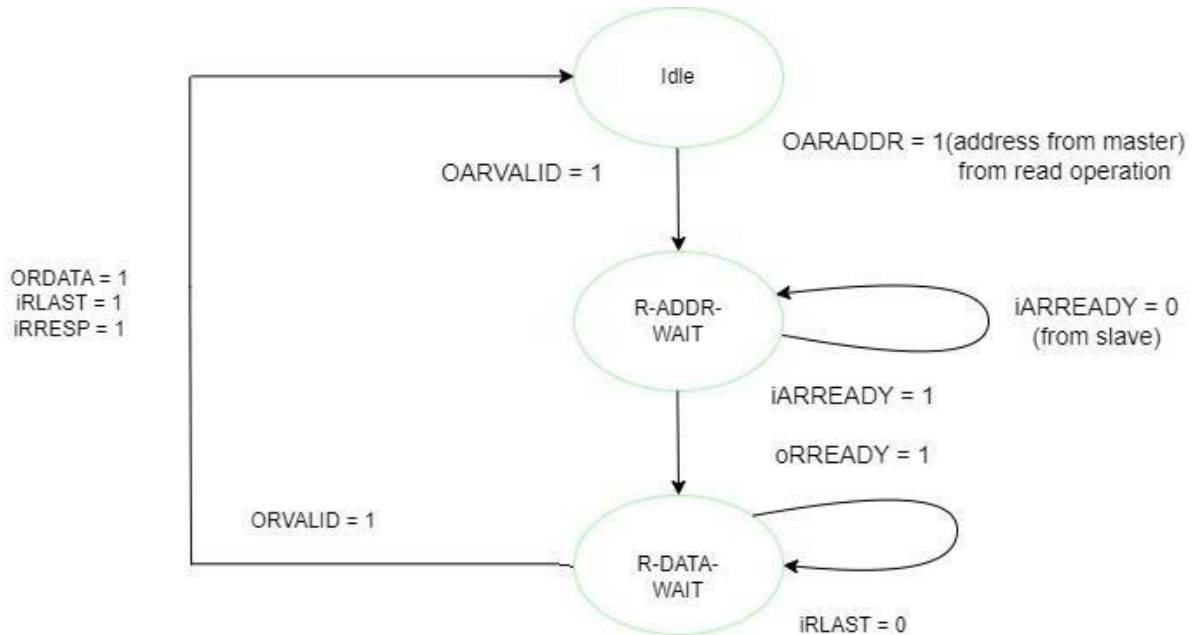
IDLE STATE : In this state all the outputs from the master in write channel and all internal variable are initialized to zero under reset condition and when reset is deasserted next state becomes ADDR_WAIT.

ADDR_WAIT : In this state the address, length, size , burst type, id coming to the master from the driver through dummy interface are sampled and stored inside internal variables as the valid and ready handshake happens and next state becomes DATA_WAIT, otherwise same state is maintained till the handshake occurs.

DATA_WAIT : In this state the data coming from the driver through dummy interface is sampled and passed on to the wdata bus which goes to the slave. The data packets are transferred according to the burst length specified till then same state is maintained and once all packets are transferred next state becomes RESPONSE_WAIT.

RESPONSE_WAIT : In this state once all the data packets are received by the slave , it sends the response.

- Read Channel FSM for AXI4 Master

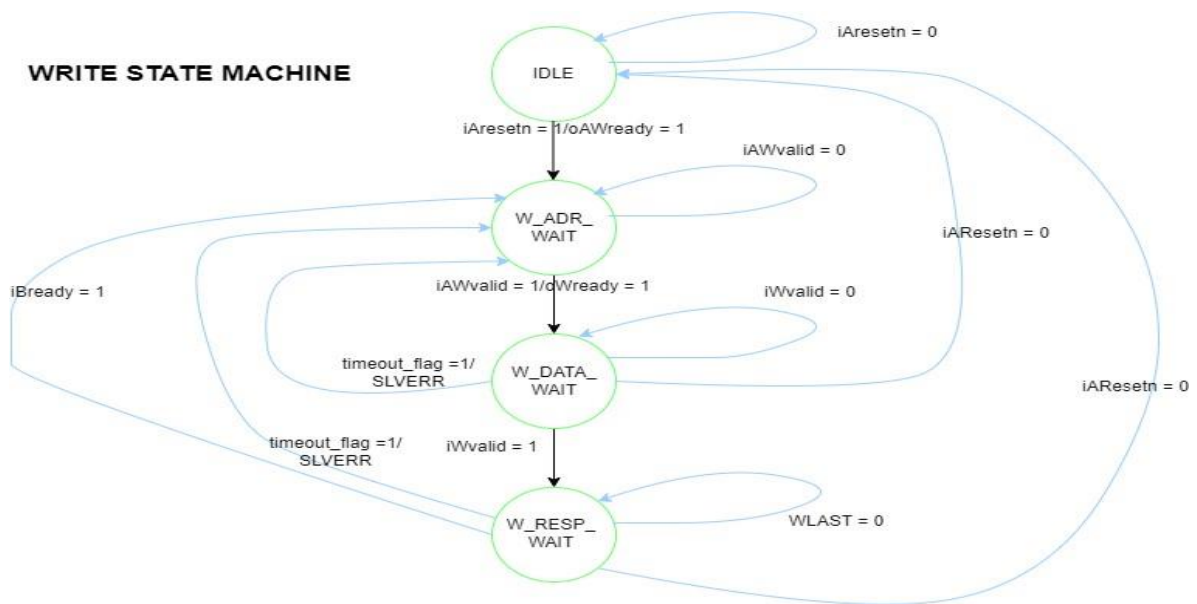


IDLE : In this state all the outputs from the master in read channel and all internal variable are initialized to zero under reset condition and when reset is deasserted next state becomes R_ADDR_WAIT.

R_ADDR_WAIT : In this state the address, length, size , burst type, id coming to the master from the driver through dummy interface are sampled and stored inside internal variables as the valid and ready handshake happens and next state becomes R_DATA_WAIT, otherwise same state is maintained till the handshake occurs.

R_DATA_WAIT : In this state once the rvalid and rready handshake happens the data to be read from the address requested by the master could be observed on the rdata bus and along with each data response is also trasferred.

- Write Channel FSM for AXI4 Slave



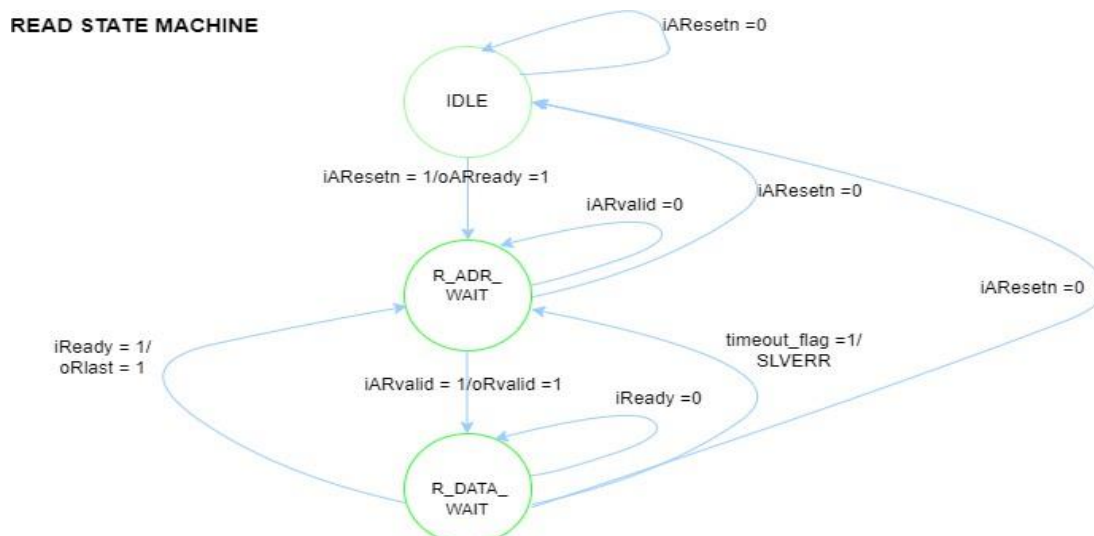
IDLE : The reset state is the initial state. The state machine abandons all other functions and reverts to this state if the reset signal is asserted.

W_ADDR_WAIT : . In the address wait state, the slave awaits the address and control information from the Master for the write transaction.

W_DATA_WAIT : The data wait state follows the address handshake and continues with the data transfer for write. The data coming on the wdata bus is written inside the memory on the address specified by the master.

W_RESP_WAIT : In the response wait state the slave awaits for the last data and then handshake via the response channel and confirms the data transaction with a response signal.

- Read Channel FSM for AXI4 Slave



IDLE : The reset state is the initial state. The state machine abandons all other functions and reverts to this state if the reset signal is asserted.

R_ADDR_WAIT : . In the address wait state, the slave awaits the address and control information from the Master for the read transaction.

R_DATA_WAIT : The data wait state follows the address handshake and continues with the data transfer for the read. The data from the specified memory location is fetched and transferred on to the rdata bus. The read transaction does not involve a separate channel for response hence it provides a response signal for every data transfer instead of the last data transfer over the read data channel itself.

2. Basic Block Diagram

Block diagram of AXI4-Lite Slave with SRAM controller including SRAM is shown below:

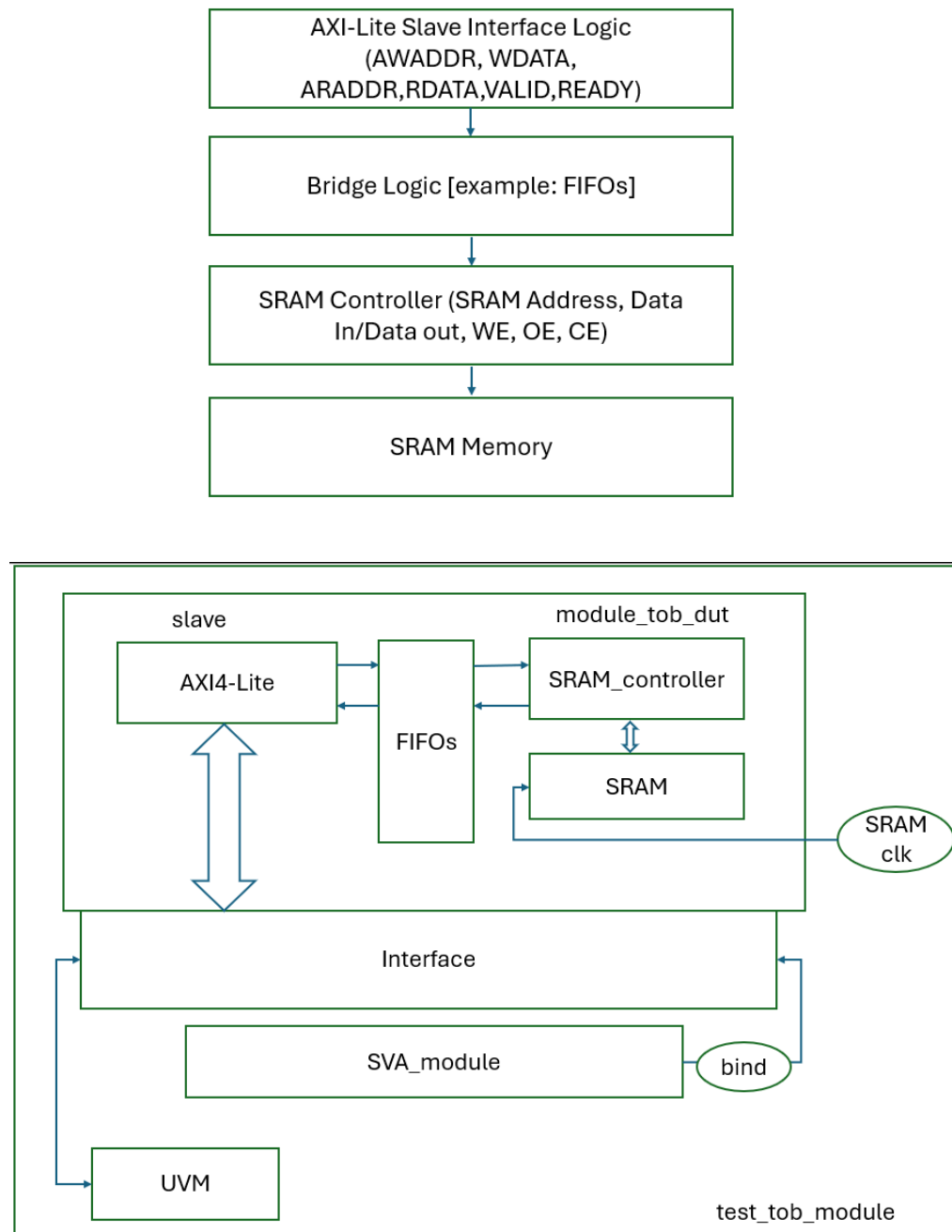


Fig: UVM verification environment block diagram

UVM: elaborated

Write Operation:

Data is generated using dummy Interface and send it to master. Master sends address to slave using AW channel and data to write in the memory using W channel. Depending on address sent by master, slave writes the data in memory. Overall response is sent to master after successfully completion of data using channel B.

Read Operation

Master sends the address from where it wants to read the data to slave using channel RW. Slave sends the data and response at that particular address using channel R. Monitor and scoreboard is used to check data and functionality correctness.

3. Implementation Considerations

• Signals Specification

Channels	Signals	Spcification
Write Address (AW):	AWVALID	1 bit
	AWREADY	1 bit
	AWADDR[7:0]	8 bits
	AWSIZE[2:0]	3 bits
	AWBURST	1 bit(fixed 0, incr 1)
	AWID[3:0]	4 bits
	AWLEN[7:0]	8 bits
Write Data (W)	WVALID	1 bit
	WREADY	1 bit
	WLAST	1 bit
	WDATA[31:0]	32 bits
	WID[3:0]	4 bits
	WSTRB[3:0]	4 bits
Write Response (B)	BVALID	1 bit
	BREADY	1 bit
	BRESP[1:0]	00: OKAY ; 01: EXOKAY; 10: SLVERR; 11: DECERR
	BID[3:0]	4 bits
Read Address (AR)	ARVALID	1 bit
	AREADY	1 bit
	ARADDR[7:0]	8 bits
	ARSIZE[2:0]	3 bits
	ARBURST	1 bit(fixed 0, incr 1)
	ARID[3:0]	4 bits
	ARLEN[7:0]	8 bits
Read Data (R)	RVALID	1 bit
	READY	1 bit
	RLAST	1 bit
	RDATA[31:0]	32 bits
	RRESP[1:0]	00: OKAY ; 01: EXOKAY; 10: SLVERR; 11: DECERR
	RID[3:0]	4 bits

TOOL USED AND RESULT

The following tools are used-

1. **XILINX VIVADO 2019**
2. **EDA playground**

ELABORATED DESIGN

Elaborated Design of AXI4 Lite Memory Interface is as follows:

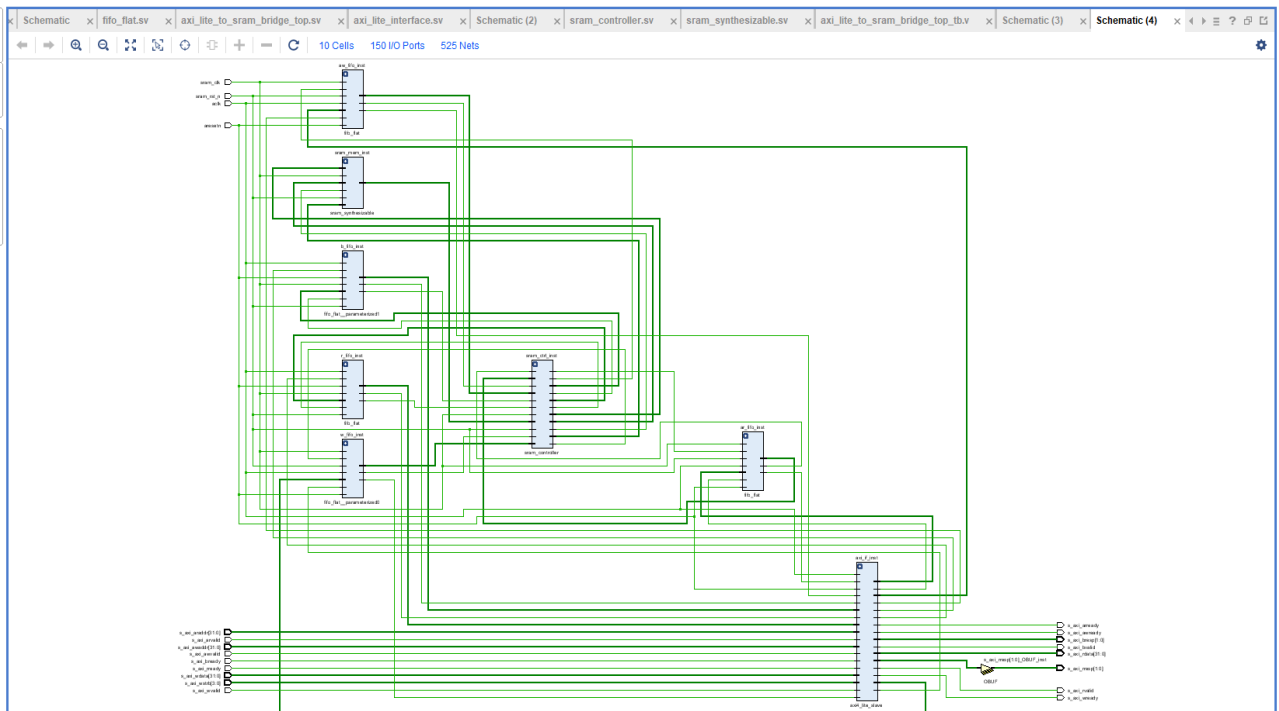


Fig: Schematic of AXI4-Lite Slave with SRAM controller including SRAM

AXI4 Testcase

```

Tcl Console x Messages Log
[Icons] [Find] [Next] [Previous] [Highlight] [Match Case] [Whole Words]
Built simulation snapshot axi_lite_to_sram_bridge_top_tb_behav
INFO: [USF-XSim-69] 'elaborate' step finished in '1' seconds
INFO: [USF-XSim-4] XSim:Simulate design
INFO: [USF-XSim-61] Executing 'SIMULATE' step in 'D:/projects/final_top_sayv/final_top_sayv.sim/sim_1/behav/xsim'
INFO: [USF-XSim-98] *** Running xsim
with args "axi_lite_to_sram_bridge_top_tb_behav -key {Behavioral:sim_1:Functional:axi_lite_to_sram_bridge_top_tb} -tclbatch {axi_lite_to_sram_bridge_top_tb.tcl} -log {simulate.log}"
INFO: [USF-XSim-8] Loading simulator feature
Vivado Simulator 2019.1
Time resolution is 1 ps
source axi_lite_to_sram_bridge_top_tb.tcl
# set curr_wave [current_wave_config]
# if { [string length $curr_wave] == 0 } {
#   if { [llength [get_objects]] > 0 } {
#     add_wave /
#     set_property needs_save false [current_wave_config]
#   } else {
#     send_msg_id AddWave-1 WARNING "No top level signals found. Simulator will start without a wave window. If you want to open a wave window go to 'File->New Waveform Configuration' or type 'create_wave_config' in the TCL console."
#   }
# }
# run 1000ns
Write transaction completed at time      295000: ADDR = 00000000, DATA = deadbeef, STRB = 1111
Read transaction completed at time      475000: ADDR = 00000000, DATA = deadbeef
Write transaction completed at time      655000: ADDR = 00000004, DATA = cafebabe, STRB = 1100
Read transaction completed at time      835000: ADDR = 00000004, DATA = cafexxxx
INFO: [USF-XSim-96] XSim completed. Design snapshot 'axi_lite_to_sram_bridge_top_tb_behav' loaded.
INFO: [USF-XSim-97] XSim simulation ran for 1000ns
launch_simulation: Time (s): cpu = 00:00:03 ; elapsed = 00:00:07 . Memory (MB): peak = 4079.367 ; gain = 0.000
Type a Tcl command here

```

SIMULATION RESULTS

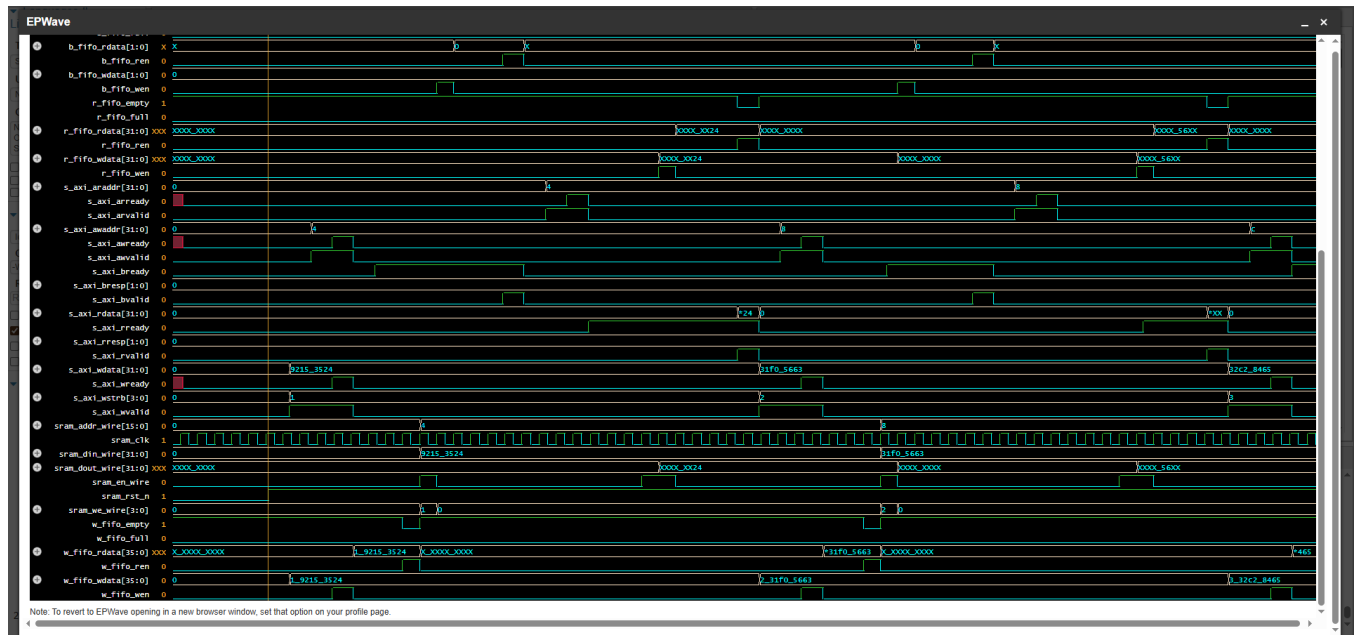
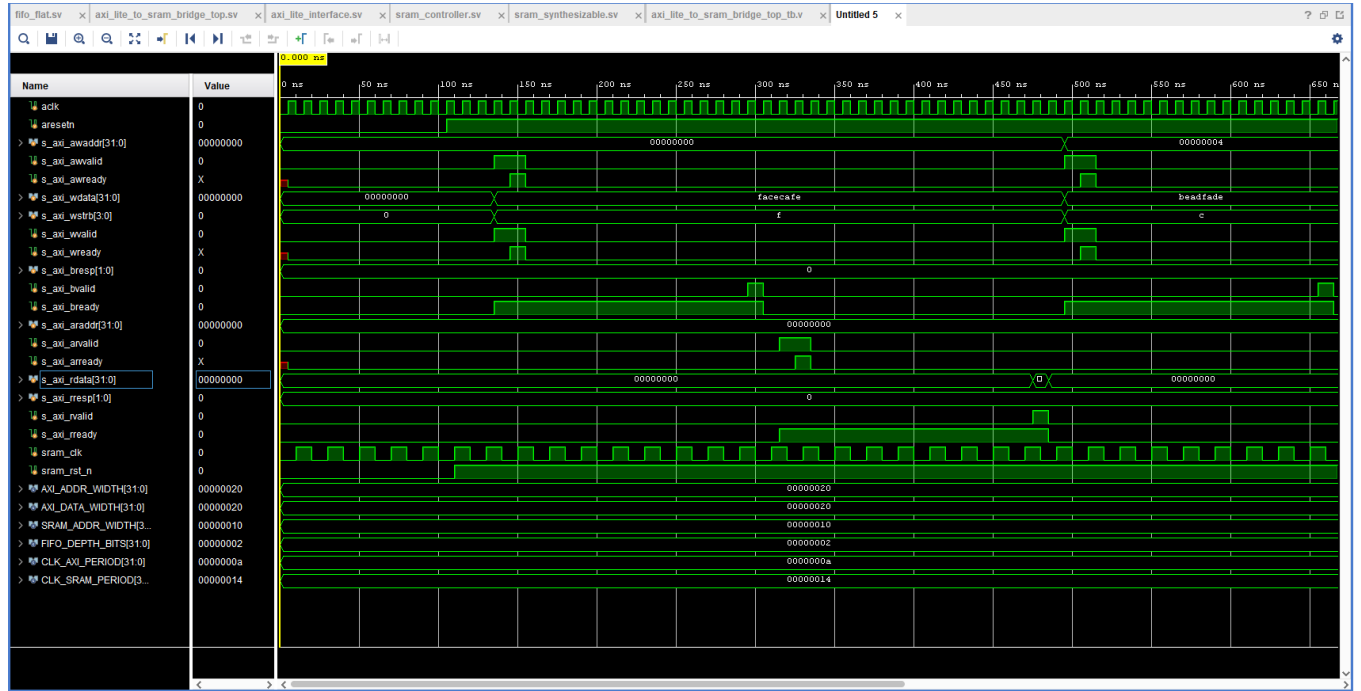


Fig: AXI4 Lite Slave to SRAM controller (including SRAM) write transaction simulated on Vivado and EDA playground

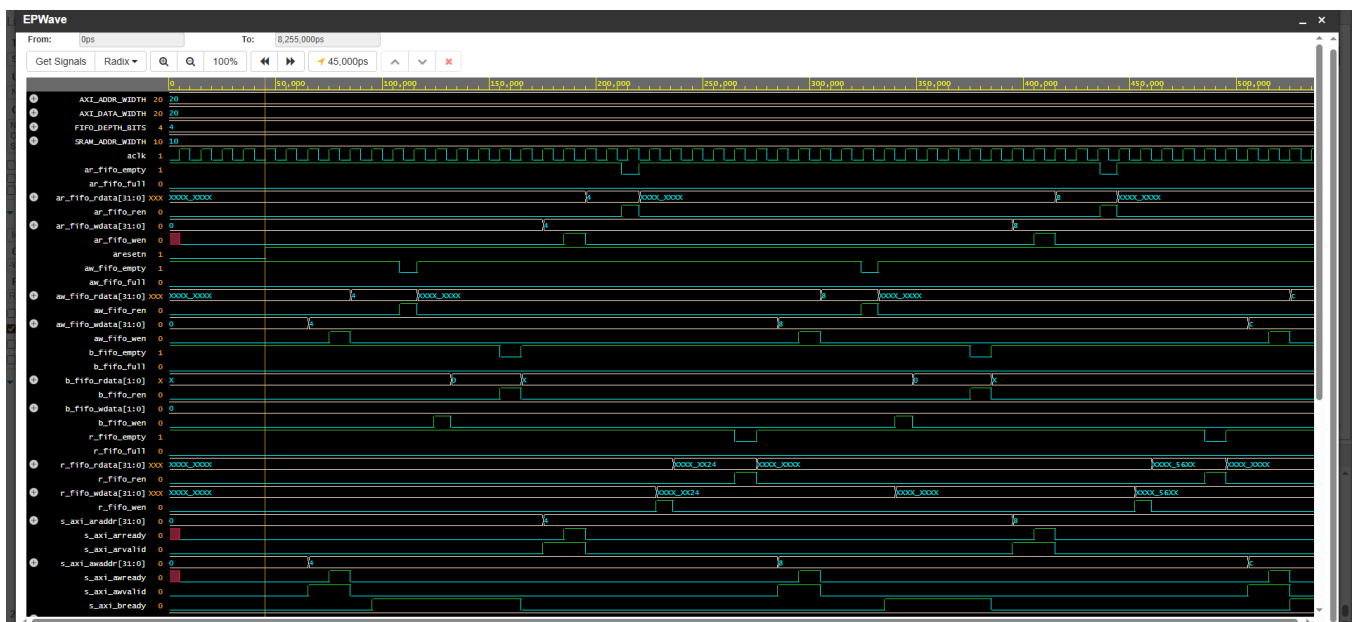
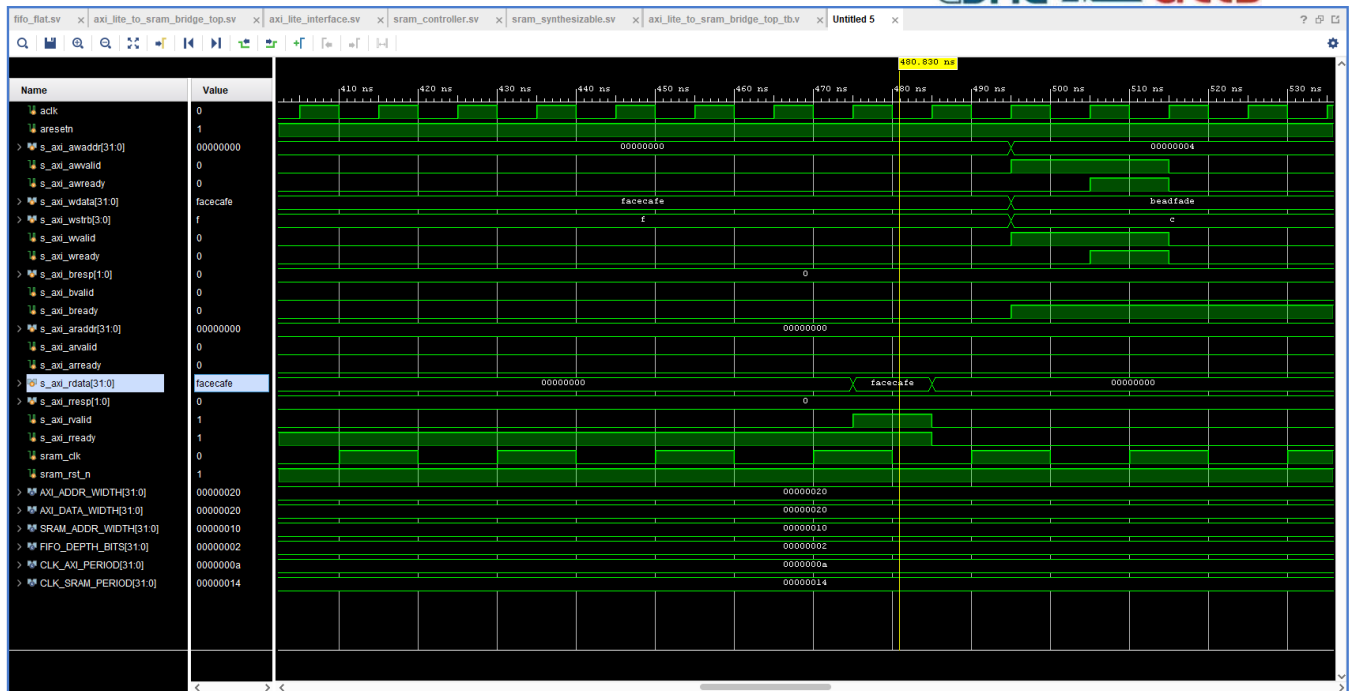


Fig: AXI4 Lite Slave to SRAM controller (including SRAM) read transactions simulated on Vivado and EDA Playground

Log

Share

```

TB INFO: Finished READ Transaction #58
TB INFO: Starting READ Transaction #59 from Addr=0x00001020
TB INFO: Scoreboard MATCH. Addr: 0x00001020, Data: 0x8aaa4b15
TB INFO: Finished READ Transaction #59
TB INFO: Starting READ Transaction #60 from Addr=0x00001024
TB INFO: Scoreboard MATCH. Addr: 0x00001024, Data: 0xb1230762
TB INFO: Finished READ Transaction #60
TB INFO: Starting READ Transaction #61 from Addr=0x00001028
TB INFO: Scoreboard MATCH. Addr: 0x00001028, Data: 0xc7b9a18f
TB INFO: Finished READ Transaction #61
TB INFO: Starting READ Transaction #62 from Addr=0x0000102c
TB INFO: Scoreboard MATCH. Addr: 0x0000102c, Data: 0x4fc4569f
TB INFO: Finished READ Transaction #62
TB INFO: Starting READ Transaction #63 from Addr=0x00001030
TB INFO: Scoreboard MATCH. Addr: 0x00001030, Data: 0xc4de3789
TB INFO: Finished READ Transaction #63
TB INFO: Starting READ Transaction #64 from Addr=0x00001034
TB INFO: Scoreboard MATCH. Addr: 0x00001034, Data: 0x6bfec0d7
TB INFO: Finished READ Transaction #64
TB INFO: Starting READ Transaction #65 from Addr=0x00001038
TB INFO: Scoreboard MATCH. Addr: 0x00001038, Data: 0x861d7f0c
TB INFO: Finished READ Transaction #65
TB INFO: Starting READ Transaction #66 from Addr=0x0000103c
TB INFO: Scoreboard MATCH. Addr: 0x0000103c, Data: 0x3b825a77
TB INFO: Finished READ Transaction #66
TB INFO: Starting READ Transaction #67 from Addr=0x00001040
TB INFO: Scoreboard MATCH. Addr: 0x00001040, Data: 0x3f05007e
TB INFO: Finished READ Transaction #67
TB INFO: Starting READ Transaction #68 from Addr=0x00001044
TB INFO: Scoreboard MATCH. Addr: 0x00001044, Data: 0x8fd28f1f
TB INFO: Finished READ Transaction #68
TB INFO: Starting READ Transaction #69 from Addr=0x00001048
TB INFO: Scoreboard MATCH. Addr: 0x00001048, Data: 0x3c148878
TB INFO: Finished READ Transaction #69
TB INFO: Starting READ Transaction #70 from Addr=0x0000104c
TB INFO: Scoreboard MATCH. Addr: 0x0000104c, Data: 0x1ff2ae3f
TB INFO: Finished READ Transaction #70

TB INFO: =====
TB INFO:          *** TEST PASSED ***
TB INFO: =====

TB INFO: =====
TB INFO:          AXI Bridge Test Scenario Started
TB INFO: =====

TB INFO: --- Test 1: Verifying all 15 byte strobe combinations ---

TB INFO: Starting WRITE Transaction #1 to Addr=0x00000004
TB INFO: Finished WRITE Transaction #1
TB INFO: Starting READ Transaction #2 from Addr=0x00000004
TB INFO: Scoreboard MATCH. Addr: 0x00000004, Data: 0xxxxxx24
TB INFO: Finished READ Transaction #2
TB INFO: Starting WRITE Transaction #3 to Addr=0x00000008
TB INFO: Finished WRITE Transaction #3
TB INFO: Starting READ Transaction #4 from Addr=0x00000008
TB INFO: Scoreboard MATCH. Addr: 0x00000008, Data: 0xxxxx56xx
TB INFO: Finished READ Transaction #4
TB INFO: Starting WRITE Transaction #5 to Addr=0x0000000c
TB INFO: Finished WRITE Transaction #5
TB INFO: Starting READ Transaction #6 from Addr=0x0000000c
TB INFO: Scoreboard MATCH. Addr: 0x0000000c, Data: 0xxxxx8465
TB INFO: Finished READ Transaction #6
TB INFO: Starting WRITE Transaction #7 to Addr=0x00000010
TB INFO: Finished WRITE Transaction #7

```

Fig: Screenshot of test cases and test success output for AXI4 Lite Slave to SRAM controller (including SRAM) read transactions simulated on Vivado and EDA Playground.

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Double does not endorse training material
from other suppliers or EDA Playground.

▼ Languages & Libraries

Testbench • Design

SystemVerilog/Verilog

UVM / OVM

UVM 1.2

Other Libraries

None
OVL
SVUnit

☐ Enable TL-Verilog

☐ Enable Easier UVM

☐ Enable VUnit

▼ Tools & Simulators

Aldec Riviera Pro 2023.04

Compile Options

-timescale 1ns/1ns

Run Options

+access+r

Run Time: 10 ms

☐ Use run.do Tcl file

☐ Use run.bash shell script

☒ Open EPWave after run

☐ Show output file after run

☐ Download files after run

▼ Examples

using EDA Playground

VHDL

Verilog/SystemVerilog

UVM

EasierUVM

SVUnit

VUnit (Verilog/SV)

VUnit (VHDL)

T1_Marlinon

```

# Log
# Kernel: wstrb integral 4 'bxxxx
# Kernel: rdata integral 32 'hxxbxx93
# Kernel: resp integral 2 'h0
# Kernel: -----
# Kernel: , RDATA00xxbxx93
# Kernel: UVM_INFO /home/runner/my_scoreboard.sv(41) @ 2105000: uvm_test_top.env.scb [scoreboard] Checking model for READ @ 0x9b27002b
# Kernel: UVM_INFO /home/runner/my_scoreboard.sv(58) @ 2105000: uvm_test_top.env.scb [scoreboard] SCOREBOARD MATCH!
# Kernel: Address: 9b27002b
# Kernel: Expected: xxbxx93
# Kernel: Actual:xxbxx93
# Kernel: UVM_INFO /home/runner/my_sequence.sv(30) @ 2105000: uvm_test_top.env.agent.sqr#8seq [base_sequence] Sequence body finished
# Kernel: UVM_INFO /home/build/v1bl/v1lb/uvvm-1.2/src/base/uvvm_objection.svh(1271) @ 2125000: reporter [TEST_DONE] 'run' phase is ready to proceed to the 'extract' phase
# Kernel: UVM_INFO /home/runner/my_scoreboard.sv(67) @ 2125000: uvm_test_top.env.scb [scoreboard] TEST PASSED
# Kernel: UVM_INFO /home/build/v1bl/v1lb/uvvm-1.2/src/base/uvvm_report_server.svh(869) @ 2125000: reporter [UVM/REPORT/SERVER]
# Kernel: --- UVM Report Summary ---
# Kernel:
# Kernel: ** Report counts by severity
# Kernel: UVM_INFO : 179
# Kernel: UVM_WARNING : 0
# Kernel: UVM_ERROR : 0
# Kernel: UVM_FATAL : 0
# Kernel: ** Report counts by id
# Kernel: [RNTST] 1
# Kernel: [TEST_DONE] 1
# Kernel: [UVM/RELNOTES] 1
# Kernel: [VIF] 1
# Kernel: [W1] 11
# Kernel: [W2] 11
# Kernel: [W3] 70
# Kernel: [axi_driver] 20
# Kernel: [axi_monitor] 20
# Kernel: [base_sequence] 2
# Kernel: [rest while in driver] 10
# Kernel: [scoreboard] 31
# Kernel:
# RUNTIME: Info: RUNTIME_0068 uvm_root.svh (531): ifinish called.
# Kernel: Time: 2125 ns, Iteration: 57, Instance: /tb_top, Process: @INITIAL#96_28.
# Kernel: stopped at time: 2125 ns
# VSDM: Simulation has finished. There are no more test vectors to simulate.
# VSDM: Simulation has finished.
Finding VCD File...
./dump.vcd
[2023-08-07 15:11:27 UTC] Opening EPWave...
Done

```

Fig: UVM verification output.

SYNTHESIS RESULT

TIMING SUMMARY

IMPLEMENTED DESIGN - impl_2 | xc7z020dgd484-1

Tcl Console Messages Log Reports Design Runs Timing x Power Methodology DRC Package Pins I/O Ports

Design Timing Summary

Setup	Hold	Pulse Width
Worst Negative Slack (WNS): NA	Worst Hold Slack (WHS): NA	Worst Pulse Width Slack (WPWS): NA
Total Negative Slack (TNS): NA	Total Hold Slack (THS): NA	Total Pulse Width Negative Slack (TPWS): NA
Number of Failing Endpoints: NA	Number of Failing Endpoints: NA	Number of Failing Endpoints: NA
Total Number of Endpoints: NA	Total Number of Endpoints: NA	Total Number of Endpoints: NA

There are no user specified timing constraints.

Timing Summary - impl_2 (saved)

POWER

IMPLEMENTED DESIGN - impl_2 | xc7z020dgd484-1

Tcl Console Messages Log Reports Design Runs Timing Power x Methodology DRC Package Pins I/O Ports

Summary

Power analysis from Implemented netlist. Activity derived from constraints files, simulation files or vectorless analysis.

Total On-Chip Power: 23.924 W (Junction temp exceeded!)

Design Power Budget: Not Specified

Power Budget Margin: N/A

Junction Temperature: 125.0°C

Thermal Margin: -215.9°C (-17.9 W)

Effective θ_{JA} : 11.5°C/W

Power supplied to off-chip devices: 0 W

Confidence level: Low

[Launch Power Constraint Advisor](#) to find and fix invalid switching activity

On-Chip Power

Dynamic: 22.773 W (95%)

5% Device Static: 1.151 W (5%)

18% Signals: 4.049 W (18%)

13% Logic: 1.290 W (6%)

63% BRAM: 2.941 W (13%)

IO: 14.493 W (63%)

impl_2 (saved)

VERIFICATION USING UVM

This report provides an overview of the verification plan designed for an AXI4-Lite interface, utilizing a UVM- based environment. It outlines the key components, strategies, and goals of the verification effort. The following components are present in the proposed verification environment:

- i. TEST
- ii. VIRTUAL SEQUENCE
- iii. TRANSACTION
- iv. DRIVER
- v. AXI-MONITOR
- vi. AGENT
- vii. ENVIRONMENT
- viii. SCOREBOARD.

➤ Transaction Class:

The transaction class plays a crucial role in generating, representing, and manipulating AXI4-Lite transactions, with randomized variables providing variability and non-randomized variables ensuring adherence to the AXI4-Lite protocol specifications.

Purpose: To encapsulate input signals for the DUT, ensuring organized and reusable test cases.

Randomized Variables:

- Addr: Addresses for memory access, ensuring coverage of different memory regions.
- Data: Data for write operations, testing various data patterns.
- Size: Burst size, verifying behavior with varying data bursts.

Non-Randomized Variables:

- awvalid, wvalid, arvalid: Control signals, likely driven deterministically for specific test scenarios.
- id: Transaction ID, potentially used for tracking specific transactions.
- strb: Byte strobes, controlling individual byte writes, likely set based on data patterns.
- Burst: Burst type (fixed or increment), testing different burst modes.
- cmd: Command type (read or write), dictated by test scenarios.

➤ Sequence-

Purpose: To coordinate the generation of transactions in a structured manner, forming test sequences.

Created Sequences:

- **Reset Sequence:** The reset sequence ensures that the DUT is properly initialized before the main verification sequences are executed, establishing a known and predictable starting point for the verification process.
- **Write-Read in Fixed Burst Mode Sequence:** Generates write-read transactions with a fixed burst size, testing specific burst behavior. This sequence is designed to generate transactions that perform write and read operations in fixed burst mode, adhering to the AXI4 protocol specifications.
- **Write-Read in Increment Burst Mode Sequence:** Generates write-read transactions with incrementing burst sizes, verifying handling of different burst lengths.

Similar to the previous sequence, this sequence focuses on generating transactions for write and read operations but specifically in increment burst mode.

The sequence creates transactions with attributes suitable for increment burst mode, ensuring that addresses are incremented correctly and transactions are aligned according to the protocol requirements.

Like the fixed burst mode sequence, this sequence manages the generation and execution of transactions in a systematic manner, guaranteeing compliance with the increment burst mode rules and constraints.

- **Driver-**We are driving input variables from sequence to DUT with the help of Dummy interface. Acts as a bridge, enabling communication between the UVM testbench and the DUT under verification.

FEATURES:

- **Transaction Generation:**

The driver receives transactions from sequences.

These transactions represent various AXI4 operations such as reads, writes, or other control operations.

- **Signal Translation and Driving:**

This translation involves mapping the transaction attributes (e.g., addresses, data) to the corresponding AXI4 signals (e.g., AWADDR, WDATA) and controlling the timing and sequencing of these signals according to the AXI4 protocol specifications.

The driver ensures that signals are driven onto the interface with the correct timing and sequencing to emulate the behavior of an AXI4 master initiating transactions with the DUT.

- **Interface Communication:**

The driver communicates with the DUT through a dummy interface, which abstracts the actual physical interface of the DUT.

This dummy interface provides an interface between the driver and the DUT, allowing the driver to drive signals onto the AXI4 interface of the DUT without directly interacting with the DUT's internal logic.

- **Monitor-** Monitor is a critical component responsible for observing transactions on the main interface and performing various checks to ensure protocol compliance and proper functionality.

- **Passive Monitoring of Data:**

The monitor passively observes transactions on the main AXI4 interface between the testbench and the DUT. It typically interfaces with the main AXI4 interface through analysis ports or TLM (Transaction Level Modeling) interfaces provided by UVM.

The monitor captures relevant information from AXI4 transactions, including addresses, data, control signals, and timing information, without actively driving or modifying the signals.

- **Protocol Violation Checks:**

The monitor performs a series of checks to ensure that the observed transactions adhere to the AXI4 protocol specifications and to detect any protocol violations.

Examples of protocol violation checks include:

Write-Read Handshake Violation: Verifying that write and read transactions follow the proper handshake protocol, ensuring that read data is valid only after a corresponding write transaction.

Signal Stability: Ensuring that no signal on the interface is driving an 'X' value, indicating undefined or unknown behavior.

Burst Violation: Checking that burst transactions conform to the specified burst type and alignment rules defined by the AXI4 protocol.

Protocol violation checks are implemented as methods or functions within the monitor component, allowing for modular and reusable verification code.

If a protocol violation is detected during monitoring, the monitor may raise appropriate flags.

Reporting and Error Handling:

Error messages, warnings, or informative logs generated by the monitor help identify areas of concern and guide the debugging process.

Overall, the monitor component serves as a watchdog for observing AXI4 transactions and ensuring protocol compliance through a series of checks. By detecting and reporting protocol violations, the monitor helps validate the correct behavior of the DUT and ensures the robustness of AXI4- based designs.

- **Scoreboard-** In a UVM-based verification environment, the scoreboard plays a critical role in verifying the correctness of transactions and ensuring the consistency of data between the DUT (Design Under Test) and the testbench.

scoreboard functionality described within the context of such an environment:

Storage of Write Data:

- The scoreboard component includes a queue to store the write data received from the driver through the dummy interface.
- Whenever the driver sends a write transaction to the DUT, the data associated with that transaction is stored in the scoreboard for later comparison.

Verification of Read Data:

As read transactions are issued to the DUT, the scoreboard compares the data received from the DUT with the data stored in its internal storage.

- If the data received from the DUT matches the corresponding write data stored in the scoreboard, the test case is considered to have passed.
- Conversely, if there is a mismatch between the read data from the DUT and the expected data stored in the scoreboard, the test case fails, indicating a potential issue in the DUT's behavior.

- Agent- The agent plays a pivotal role in the AXI4 verification ecosystem by harmonizing the functions of the driver, sequencer, and monitor components. It oversees the generation, sequencing, and monitoring of AXI4 transactions, thereby enhancing the integrity of AXI4-based design verification.
- Environment- The env class, extending uvm_env, oversees the entirety of the verification process. It comprises an instance of the agent class and the scoreboard component. During the build phase, env instantiates both the agent and scoreboard. The agent orchestrates AXI4 transaction generation, sequencing, and monitoring. Meanwhile, the scoreboard ensures transaction correctness and protocol adherence.

In summary, env plays a crucial role in ensuring thorough verification of AXI4-based designs by coordinating the activities of the agent and scoreboard.

- Test- The test class oversees the verification of the AXI4 protocol. It initializes environment and validation components, handles system reset, and verifies write-read transactions. During the run phase, it raises an objection, performs reset and validation tasks, and drops the objection upon completion, ensuring thorough testing for protocol compliance.

Structure:

- Extends uvm_test, inheriting features for test execution.
- Includes instances of env, valid_wrrd_fixed, valid_wrrd_incr, and rst_dut components.
- Build phase: Creates and connects these components.
- Run phase: Resets DUT, executes fixed-burst write-read validation, and signals test completion.

- Tb_Top- The SystemVerilog testbench ensures AXI4 protocol compliance of the DUT through the following elements:

Key Components:

- DUT: axi4_top instance connects to interfaces for testing.
- Interfaces:
 - dummy_interface_master: Provides control signals.
 - main_interface_master: Carries data signals.
- UVM Environment:
 - agent: Generates and sequences AXI4 transactions.
 - env: Orchestrates overall verification process.
 - sequence: Defines specific test scenarios.
 - driver: Converts transactions to AXI4 signals.
 - monitor: Captures and analyzes DUT responses.
 - scoreboard: Verifies transaction correctness and coverage.

Test Execution:

- ➔ Initializes components.
- ➔ Manages system reset.
- ➔ Starts transaction validation using run_test().
- ➔ Simulation Setup:
 - ➔ Generates clock signal.
 - ➔ Instantiates DUT and interfaces.
- ➔ Configuration: Uses uvm_config_db to connect interfaces to UVM components.
- ➔ Simulation Control: Enables waveform analysis with \$dumpfile and \$dumpvars.

Benefits:

- Structured UVM-based verification for comprehensive coverage.
- Flexible interface configuration for different test scenarios.
- Easy integration with VCD tools for signal debugging.

CONCLUSION

In this project we designed AXI4 Lite Slave with SRAM controller including synthesizable SRAM memory in system Verilog HDL and integrated them to perform read and write operations on memory. These read and write operations were performed as per the AXI4-Lite protocol following the handshake of valid and ready signals.

The design was tested for variable addresses and variable data along with different response signals.

The verification of above design was done incorporating verification plan designed for an AXI4-lite Slave interface, utilizing a UVM-based environment. With an automated UVM Based testbench protocol violations could be analyzed in accordance with the checks written inside the monitor classes. The scoreboard played a crucial role in verifying the correctness of transactions and ensuring the consistency of data between the design under test and testbench. The UVM verification platform built for the AXI4-Lite to SRAM bridge design meets UVM specification requirements by providing a reusable and portable verification environment. This includes reusing UVM components (UVCs) that generate constrained-random AXI4-Lite transactions, monitor signals, and verify SRAM read/write responses.

The verification process effectively demonstrates the correctness of the design under test (DUT) by comparing outputs of the DUT against a reference model through scoreboarding. Functional and code coverage metrics confirm thorough validation of AXI4-Lite transactions and SRAM accesses in various test scenarios including reads, writes, and error conditions.

The use of UVM methodology enhances verification productivity by enabling automation, modular architecture, and systematic stimulus generation. This approach increases confidence that the bridge design meets timing, protocol compliance, data integrity, and functional requirements.

Overall, the project achieves a highly reusable, portable, and scalable verification environment that can be adapted to similar AMBA protocol bridges. This results in robust, well-covered verification of the AXI4-Lite to SRAM bridge, shortening time-to-market and improving design quality.

FUTURE SCOPE

The future scope of this project can be strategically expanded to include the following key areas:

Enhanced Data Validity and Protection Level Support:

Extend the project to incorporate more sophisticated data validity and protection level support in the AXI4 Memory Interface. This entails implementing mechanisms to distinguish valid and invalid data within lanes, ensuring more granular control over data integrity and security.

Cache Support Integration:

Incorporate cache support mechanisms into the AXI4 Memory Interface design. This can involve optimizing data transfers to and from caches, implementing cache coherence protocols, and exploring ways to enhance overall system performance through effective cache utilization.

Wrap Mode Implementation:

Future development should focus on implementing wrap modes in the AXI4 Memory Interface. This involves incorporating mechanisms to handle circular addressing or sequential wrapping of data, which can be particularly beneficial in applications with circular buffers or streaming data.

Atomic Access with Lock Signal:

Enhance the AXI4 Memory Interface by implementing atomic access with a lock signal. This includes introducing mechanisms to ensure atomicity of specific memory operations, preventing interference from concurrent accesses, and improving support for critical sections in multi-threaded or multi-processor systems.

Power Management and Energy Efficiency:

Explore future developments in power management and energy efficiency within the AXI4 Memory Interface. Investigate techniques for dynamic power gating, clock gating, or other power-saving mechanisms to optimize energy consumption, especially in scenarios where power efficiency is paramount, such as in battery-powered devices or IoT applications.

Integration with Emerging Memory Technologies:

Future efforts should consider integrating the AXI4 Memory Interface with emerging memory technologies. Evaluate its compatibility with non-volatile memory, resistive RAM, or other emerging memory types, and optimize the interface to leverage the unique characteristics of these technologies for improved performance and reliability.

Comprehensive Verification Strategies:

Strengthen the verification methodologies by incorporating comprehensive testing scenarios for the newly introduced features. This includes designing test cases that specifically target wrap modes, protection levels, cache interactions, atomic access with lock signals, and any other enhancements, ensuring robust verification of the extended AXI4 Memory Interface.

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