Deep Learning - Theory and Practice

IE 643 Lectures 10, 11

Sep 3 & 11, 2024.

Recap

- MLP for multi-class classification
 - Cross-entropy
 - Training MLP for multi-class classification

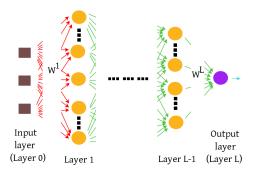
MLP for multi-label classification



- Input: Training Data $D = \{(x^i, y^i)\}_{i=1}^S, x^i \in \mathcal{X} \subseteq \mathbb{R}^d, y^i \in \mathcal{Y}, \ \forall i \in \{1, \dots, S\}$ and MLP architecture parametrized by weights w.
- New Task: $\mathcal{Y} = \{1, ..., C\}, C \ge 2$.
- Corresponds to multi-class classification.

Question 1: What is a suitable architecture for the MLP's last (or output) layer?

Question 2: What is a suitable loss (or error) function?



Question 1: Can the same MLP architecture with single output neuron used in binary classification be used for multi-class classification?

Question 2: Can the same logistic sigmoidal activation function for the output neuron used in binary classification be used for multi-class classification?

We will use the following approach for multi-class classification:

- Input: Training Data $D = \{(x^i, y^i)\}_{i=1}^S, x^i \in \mathcal{X} \subseteq \mathbb{R}^d, y^i \in \mathcal{Y}, \ \forall i \in \{1, \dots, S\}$ and MLP architecture parametrized by weights w.
- New Task: $\mathcal{Y} = \{1, \dots, C\}, C \geq 2$ corresponds to multi-class classification.

• Transform
$$y = c$$
 to $y^{onehotenc} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$.

- Note: $y^{onehotenc} \in \{0,1\}^C$ corresponding to $y=c \in \mathcal{Y}$ has a 1 at c-th coordinate, and other entries as zeros.
- y^{onehotenc} is called the one-hot encoding of y.

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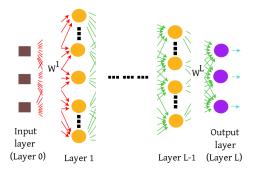
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- $y^{onehotenc}$ is called the one-hot encoding of y.
- $y^{onehotenc}$ for y = c corresponds to a discrete probability distribution with its entire mass concentrated at the c-th coordinate.

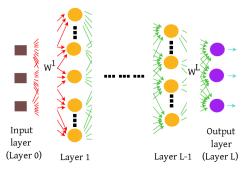
What change can be made to the network architecture so that the MLP outputs a discrete probability distribution?

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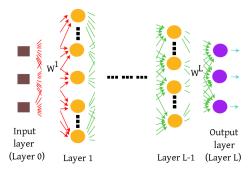
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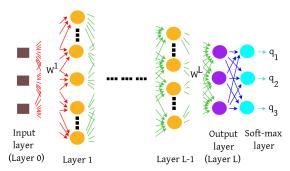


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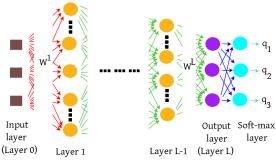
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- Given arbitrary activations $a_1^L, a_2^L, \ldots, a_C^L$ from an output layer (*L*-th layer), how do we get probabilities?
- Perform the following transformation:

$$q_j = \frac{\exp(a_j^L)}{\sum_{r=1}^C \exp(a_r^L)}, \ \forall j = 1, \dots, C.$$

• q_1, \ldots, q_C form a discrete probability distribution. (Verify this claim!)

The transformation used to obtain the probabilities q_j is called the soft-max function.

Now that the MLP outputs a discrete probability distribution, how do we compare the one-hot encoding and the output distribution?

- We will use the popular divergence measure called Kullback-Liebler divergence (or KL-divergence).
- Given two discrete probability distributions $p = (p_1, \ldots, p_C)$ and $q = (q_1, \ldots, q_C)$, where $q_j > 0 \ \forall j = 1, \ldots, C$, KL-divergence between p and q is defined as:

$$\mathit{KL}(p||q) = \sum_{j=1}^{C} p_j \log rac{p_j}{q_j}.$$

- **Note:** The distribution *p* is usually called the true distribution and the distribution *q* is called the predicted distribution.
- Does the soft-max function give predictions $q_j > 0, j = 1, \dots, C$?

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 - ▶ d(x,x) = 0, $\forall x \in X$ (identity of indistinguishables)
 - ▶ $d(x, y) = d(y, x), \forall x, y \in X$ (Symmetry)
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- KL-divergence does not obey symmetry property.
 - Simple example: compute KL(p||q) and KL(q||p) for p = (1/4, 3/4) and q = (1/2, 1/2).

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- Does KL-divergence obey triangle inequality?

Some useful properties of KL-divergence:

• For two discrete probability distributions $p = (p_1, p_2, ..., p_C)$ and $q = (q_1, q_2, ..., q_C)$, $q_j > 0$, $\forall j = 1, ..., C$, $KL(p||q) \ge 0$.

KL-Divergence: Equivalent Representation

• Given two discrete probability distributions $p = (p_1, \ldots, p_C)$ and $q = (q_1, \ldots, q_C)$, where $q_j > 0 \ \forall j = 1, \ldots, C$, KL-divergence between p and q is defined as:

$$\mathit{KL}(p||q) = \sum_{j=1}^{C} p_j \log \frac{p_j}{q_j} = \sum_{j=1}^{C} p_j \log p_j - \sum_{j=1}^{C} p_j \log q_j.$$

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Note: $\sum_{j=1}^{C} p_j \log p_j$ is called negative entropy associated with distribution p (denoted by NE(p)) and $-\sum_{j=1}^{C} p_j \log q_j$ is called cross-entropy between p and q (denoted by CE(p,q)).

• Hence KL(p||q) = NE(p) + CE(p,q).

Question:

• Why should we transform $y \in \mathcal{Y}$ taking an integer value, to a $y^{onehotenc}$ which represents a discrete probability distribution?

One possible answer:

- If the prediction \hat{y} made by MLP is also a discrete probability distribution, then the comparison between \hat{y} and $y^{onehotenc}$ becomes a comparison between two discrete probability distributions.
- Multiple ways to compare two probability distributions.
- Loss function design becomes possibly simpler?

Loss function using KL-Divergence:

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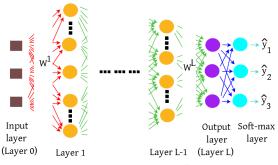
- Our aim is to minimize the error measured using KL-divergence between the true distribution p and the predicted distribution q.
- However, minimizing KL-divergence between p and q is equivalent to minimizing cross-entropy between p and q. (why?)
- Hence we will consider the cross-entropy between p and q as our loss function.

Cross-entropy loss function:

• Given two discrete probability distributions $p = (p_1, \ldots, p_C)$ and $q = (q_1, \ldots, q_C)$, where $q_j > 0 \ \forall j = 1, \ldots, C$, cross-entropy between p and q is defined as:

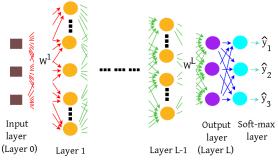
$$CE(p,q) = -\sum_{j=1}^{C} p_j \log q_j.$$

- Input: Training Data $D = \{(x^i, y^i)\}_{i=1}^S$, $x^i \in \mathcal{X} \subseteq \mathbb{R}^d$, $y^i \in \tilde{\mathcal{Y}}$, $\forall i \in \{1, ..., S\}$ and MLP architecture parametrized by weights w.
- Without loss of generality, assume $\tilde{\mathcal{Y}} = \{0,1\}^C$ corresponding to the output space $\mathcal{Y} = \{1,\ldots,C\}, C \geq 2$ and y^i are one-hot encoded vectors.



- Input: Training Data $D = \{(x^i, y^i)\}_{i=1}^S, x^i \in \mathcal{X} \subseteq \mathbb{R}^d, y^i \in \tilde{\mathcal{Y}}, \ \forall i \in \{1, \dots, S\}$ and MLP architecture parametrized by weights w.
- Aim of training MLP: To learn a parametrized map $h_w: \mathcal{X} \to \tilde{\mathcal{Y}}$ such that for the training data D, we have $y^i = h_w(x^i)$, $\forall i \in \{1, \dots, S\}$.
- Aim of using the trained MLP model: For an unseen sample $\hat{x} \in \mathcal{X}$, predict $\hat{y} = h_w(\hat{x}) = MLP(\hat{x}; w)$; to find integer label use $\operatorname{argmax}_{\hat{j}} \hat{y_j}$.

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Methodology for training MLP

- Design a suitable loss (or error) function $e: \tilde{\mathcal{Y}} \times \tilde{\mathcal{Y}} \to [0, +\infty)$ to compare the actual label y^i and the prediction \hat{y}^i made by MLP using $e(y^i, \hat{y}^i)$, $\forall i\{1, \ldots, S\}$.
- recall: $e(y^i, \hat{y}^i) = CE(y^i, \hat{y}^i)$, the cross-entropy loss function.
- Usually the error is parametrized by the weights w of the MLP and is denoted by $e(\hat{y}^i, y^i; w)$.
- Use Gradient descent/SGD/mini-batch SGD to minimize the total error:

 $E = \sum_{i=1}^{S} e(\hat{y}^i, y^i; w) =: \sum_{i=1}^{S} e^i(w).$

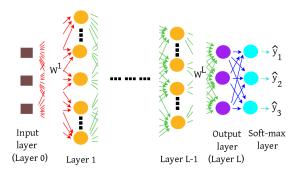
P. Balamurugan

Deep Learning - Theory and Practice

SGD for training MLP for multi-class classification

SGD Algorithm to train MLP

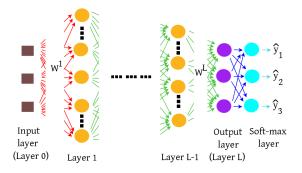
- Input: Training Data $D = \{(x^i, y^i)\}_{i=1}^S$, $x^i \in \mathcal{X} \subseteq \mathbb{R}^d$, $y^i \in \tilde{\mathcal{Y}}$, $\forall i$; MLP architecture, max epochs K, learning rates γ_k , $\forall k \in \{1, \ldots, K\}$.
- Start with $w^0 \in \mathbb{R}^d$.
- For $k = 0, 1, 2, \dots, K$
 - ▶ Choose a sample $j_k \in \{1, ..., S\}$.
 - Find $\hat{y}^{j_k} = \mathsf{MLP}(x^{j_k}; w^k)$. (forward pass)
 - Compute error $e^{j_k}(w^k)$ using cross-entropy loss function.
 - Compute error gradient $\nabla_w e^{j_k}(w^k)$ using backpropagation.
 - ▶ Update: $w^{k+1} \leftarrow w^k \gamma_k \nabla_w e^{j_k} (w^k)$.
- **Output:** $w^* = w^{K+1}$.



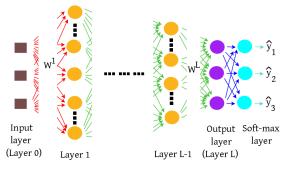
Recall forward pass: For an arbitrary sample (x, y) from training data D, and the MLP with weights $w = (W^1, W^2, \dots, W^L)$, the prediction \hat{y} is computed using forward pass as:

$$\hat{y} = \mathsf{MLP}(x; w) = \mathsf{softmax}(\phi(W^L \phi(W^{L-1} \dots \phi(W^1 x) \dots))).$$

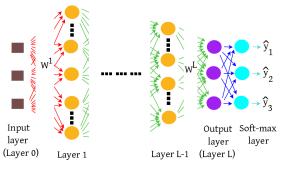
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Backpropagation: For an arbitrary sample (x, y) from training data D, and the MLP with weights $w = (W^1, W^2, \dots, W^L)$, how do we compute the error gradient?



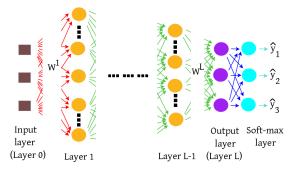
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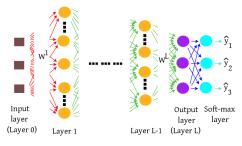
$$abla_{W^\ell} e = \mathsf{Diag}(\phi^{\ell'}) \delta^\ell (a^{\ell-1})^{ op}$$

$$\text{where } \mathsf{Diag}(\phi^{\ell'}) = \begin{bmatrix} \phi'(z_1^\ell) & & & \\ & \ddots & & \\ & & \phi'(z_{N_\ell}^\ell) \end{bmatrix}, \ \delta^\ell = \begin{bmatrix} \frac{\partial e}{\partial z_1^\ell} \\ \vdots \\ \frac{\partial e}{\partial z_N^\ell} \end{bmatrix} \text{ and } \mathbf{a}^{\ell-1} = \begin{bmatrix} \mathbf{a}_1^{\ell-1} \\ \vdots \\ \mathbf{a}_{N_{\ell-1}}^{\ell-1} \end{bmatrix}.$$



Backpropagation: Indeed, the error gradients are very similar to the binary classification setup. For an arbitrary sample (x,y) from training data D, and the MLP with weights $w=(W^1,W^2\ldots,W^L)$, the error gradient with respect to weights W^ℓ in ℓ -th layer is:

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 where $V^{\ell+1} = (W^{\ell+1})^\top \mathsf{Diag}(\phi^{\ell+1'})$.



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The main difference arises in the procedure to find $\delta^L = \begin{bmatrix} \frac{\partial e}{\partial a_1^L} \\ \vdots \\ \frac{\partial e}{\partial a_n^L} \end{bmatrix}$.

Training MLP for multi-class classification: Finding error gradients at the output layer

Recall: For an arbitrary sample (x, y) from training data D, and the prediction \hat{y} from the MLP, we know the following:

• y is in one-hot encoded form: $y = \begin{bmatrix} y_1 \\ \vdots \\ y_C \end{bmatrix}$ with some particular y_c taking value 1 (corresponding to the label c) and $y_j = 0, j \neq c$.

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$$\bullet \hat{y} = \begin{bmatrix} y_1 \\ \vdots \\ \hat{y}_C \end{bmatrix}.$$

• $e(\hat{y}, y)$ is the cross-entropy error function: $e(\hat{y}, y) = \sum_{j=1}^{C} e^{j} = -\sum_{j=1}^{C} y_{j} \log \hat{y}_{j}$.

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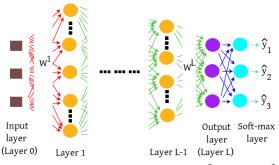
Recall: For an arbitrary sample (x, y) from training data D, and the prediction \hat{y} from the MLP, we know the following:

- y is in one-hot encoded form: $y = \begin{bmatrix} y_1 \\ \vdots \\ y_C \end{bmatrix}$ with some particular y_c taking value 1 (corresponding to the label c) and $y_j = 0, j \neq c$.
- ullet y and \hat{y} are discrete probability distributions.

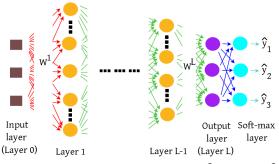
$$\hat{y} = \begin{bmatrix} \hat{y}_1 \\ \vdots \\ \hat{y}_C \end{bmatrix}.$$

- $e(\hat{y}, y)$ is the cross-entropy error function: $e(\hat{y}, y) = \sum_{j=1}^{C} e^{j} = -\sum_{j=1}^{C} y_j \log \hat{y}_j$.
- Note: $\hat{y}_j = \frac{\exp(a_j^L)}{\sum_{r=1}^C \exp(a_r^L)}, \ \forall j = 1, \dots, C.$





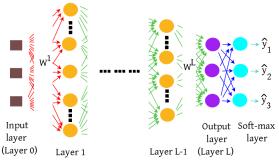
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Aim: To find $\delta^L = \begin{bmatrix} \frac{\partial e}{\partial a_1^L} & \cdots & \frac{\partial e}{\partial a_C^L} \end{bmatrix}^{\top}$.

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Aim: To find
$$\delta^L = \begin{bmatrix} \frac{\partial e}{\partial a_1^L} & \cdots & \frac{\partial e}{\partial a_L^L} \end{bmatrix}^\top$$
.

• We have $\frac{\partial e}{\partial a_i^L} = \sum_{m=1}^C \frac{\partial e^m}{\partial \hat{y}_m} \frac{\partial \hat{y}_m}{\partial a_i^L}$, $\forall j$.

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- $e(\hat{y}, y)$ is the cross-entropy error function: $e(\hat{y}, y) = \sum_{j=1}^{C} e^{j} = -\sum_{j=1}^{C} y_{j} \log \hat{y}_{j}$, with $\hat{y}_{j} = \frac{\exp(a_{j}^{l})}{\sum_{i}^{C} e^{i}\exp(a_{j}^{l})}$, $\forall j$.
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- We have $\frac{\partial e}{\partial a_j^L} = \sum_{m=1}^C \frac{\partial e^m}{\partial \hat{y}_m} \frac{\partial \hat{y}_m}{\partial a_j^L}$.
- $\bullet \ \frac{\partial e^m}{\partial \hat{y}_m} = -\frac{y_m}{\hat{y}_m}.$
- $\bullet \ \frac{\partial \hat{y}_m}{\partial a_j^L} = \frac{\partial}{\partial a_j^L} \left(\frac{\exp\left(a_m^L\right)}{\sum_{r=1}^C \exp\left(a_r^L\right)} \right).$

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- We have $\frac{\partial e}{\partial a_j^L} = \sum_{m=1}^C \frac{\partial e^m}{\partial \hat{y}_m} \frac{\partial \hat{y}_m}{\partial a_j^L}$.
- $\bullet \quad \frac{\partial \hat{y}_m}{\partial s_j^L} = \frac{\partial}{\partial s_j^L} \left(\frac{\exp\left(s_m^L\right)}{\sum_{r=1}^C \exp\left(s_r^L\right)} \right) = \begin{cases} \hat{y}_j (1 \hat{y}_j) & \text{if } j = m \\ -\hat{y}_m \hat{y}_j & \text{otherwise.} \end{cases}$ (Homework!)



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- Hence by substitution, $\frac{\partial e}{\partial a_j^L} = \sum_{\substack{m=1 \ m \neq j}}^C y_m \hat{y}_j y_j (1 \hat{y}_j) = \hat{y}_j y_j.$



• **Recall:** We wanted to find
$$\delta^L = \begin{bmatrix} \frac{\partial a_L^L}{\partial a_C^L} \\ \vdots \\ \frac{\partial e}{\partial a_C^L} \end{bmatrix}$$
.

• We have $\frac{\partial e^m}{\partial a_j^L} = \hat{y}_j - y_j$.

• Hence
$$\delta^L = \begin{bmatrix} \hat{y}_1 - y_1 \\ \vdots \\ \hat{y}_C - y_C \end{bmatrix}$$
.

Training MLP for multi-class classification

Since the backpropagation for multi-class classification is essentially similar to that of binary classification, it suffers from

- Exploding gradient problem and
- Vanishing gradient problem.

MLP for multi-label classification

- Input: Training Data $D = \{(x^i, y^i)\}_{i=1}^S$, $x^i \in \mathcal{X} \subseteq \mathbb{R}^d$, $\forall i \in \{1, ..., S\}$ and MLP architecture parametrized by weights w.
- New Task: $y^i \subseteq \mathcal{Y} = \{1, \dots, C\}, C \ge 2$.
- Corresponds to multi-label classification.

Question 1: What is a suitable architecture for the MLP's last (or output) layer?

Question 2: What is a suitable loss (or error) function?

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