A Project Report on

"Parametric design and analysis of Machine Elements using Python"

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Parametric Design And Analysis Of Machine Elements Using Python

Abstract:

The idea behind this project was to minimize the efforts and hard work of Engineers behind their designing process. As they are the one's who are bringing automation all over the globe, and so with the flow we also decided to make the designing process automated, so an Engineer will only give the parameters or conditions like Power, Load, Tensile Stress of material, etc which he think best for situation and our program will give the safest calculation. We had implemented the 3 machine elements in our project for simplification and easy to understand to everyone.

Introduction:

As everything is moving towards Automation, we got idea to automate our design works, our design calculations to solve them with in just matter of time. With the help of Python programming language and some awesome tools we are trying to make the tired and time-consuming work of designing, easy and fast to finish within just some few seconds. We also had added functionality to plot the Shear Force and Bending Moment diagram or to save it as an image as user want which could be used to further analyze.

Our program will not only give the designed calculations but to ensure the design is safe for the given parameters it will also try to check its safety under various loads and if the design is not safe it will again design the elements for given parameters by increasing the FOS 0.5 until user doesn't get the safest design.

We also wanted to know how do the CNC machine plots the code so accurately so we also tried to make a simple CNC code plotting Program which could be used for getting the error and solve them before going to the CNC machine.

Thus, reducing the error which occurs during machining the products. By our CNC plotting program user could also realize how to fix some issue and also will be able to experiment the different codes output.

We also had implemented small program to draw the 2D design in AutoCAD by connecting it to through an API (Application Programming Interface) where after designing shaft the AutoCAD will draw the simple 2D drawing of the Shaft with designed parameters thus helping user to analyze it practically as well.

Problem Statement:

To develop a software which will recursively design safest dimension for the selected elements for given parameters, load conditions and to plot the given CNC code for testing to see for any error.

Objectives:

- > To save the time and efforts of Designing calculations.
- > To reduce tired work of smart Engineers/Students so they could have time for their productivity.
- > To automate the designing and drawing process in AutoCAD.
- > To improve efficiency by designing the safest element.
- > To see for and solve the error before going to CNC machine.

Methodology:

The main aim of our project is to design the safest dimension for given elements.

For it we have to gather all the design formulae and their failure condition of the following 3 elements.

- Cotter Pin
- Kunkle Pin
- Shaft

We had designed all our algorithm on basis of torsional theory and bending theory.

We had given how we had arranged the formulae and made our own algorithm so the computer can understand it and we also optimize the code so it would do the work even more quickly with less power and less time consuming.

We had to take consider of the failures of elements in different circumstances and we also made an algorithm for same so the program will design the safest possible dimensions.

Design Procedure for Shaft:

```
For Shaft subjected to twisting Moment
             tau G 0
                             → Torsional Theory
             d/2
      T = Twisting Moment --- >> unit N-mm
       Power = 2 * \pi * N * T / 60
          where P = Power = Watt
                N = Rpm
                T = N-m
       In case of belt drives the twisting moment (T) is given by
               T = (T1-T2)*R
               where
                   T1 = Tension in tight side --->> unit Newton
                   T2 = Tension in slack side --->> unit Newton
                   R = Radius of the Pulley --->> unit meter
      tau = Shear stress ---->> unit N / mm^2
      r = Distance From Neutral Axis to the outer mo Syt fibre.
       J = Polar Moment of Inertia
      For Solid Shaft J = \pi/32 * d^4 ---> unit mm<sup>4</sup>
       For Hollow Shaft J = \pi/32 * (D^4 - d^4)
     Thus
                              T = \pi/16 * tau * d^3
           For solid shaft
          For Hollow Shaft T = \pi/16 * tau * D^3 * (1 - k^4)
          where k = d / D (ratio of inner dia to outer dia)
```

```
therefore
           For solid Shaft d = cuberoot ((T * 16) / (tau*\pi))
                              &
       For Hollow Shaft D = cuberoot ((T * 16) / (tau * \pi * (1 - k^4))
For Bending Moment
        M sigma B
        M = Bending Moment --->> unit N-m
           For Solid Shaft M = \pi/32 * sigma B * d^3
           For Hollow Shaft M = \pi/32 * sigma B * D^3 (1 - k^4)
           where k = d/D
        For Solid Shaft I = \pi/64 * d^4
           For Hollow Shaft I = \pi/64 * (D^4 - d^4)
       sigma B = Bending stress --->> unit N/mm^2
           sigma B = (32 * M) / (\pi * d^3)
           tau = (16 * T) / (\pi * d^3)
       y = Distance from neutral axis to the outer mo Syt fibre
           y = d/2 --->> unit mm
   If Numerical requires both twisting and bending moment following will be
the procedure
     tau max = 0.5 * sqrt (sigma B^2 + 4 * tau^2)
       By Simplifying
     tau max = 16 * sqrt[ M^2 + T^2 ] / ( \pi * d^3 )
```

```
The Twisting Moment due to maximum Syt shear Stress on surface of
      Shaft is known as equivalent Twisting moment i.e., Te
       Te = sqrt[M^2 + T^2]
   i.e. Te = \pi/16 * tau max * d^3 . . . eqn
      Te = Equivalent Twisting Moment
      Me = Equivalent Bending Moment
      Me = 0.5 * [ M^2 + Te^2]
Calculating by
                 T G 0
                      L
    T J= ((Te*16)/(tau*pi) ... eqn
      As We know
        Tmax = \pi /16 * tau * (D^4 - d^4)/D
        (D^4 - d^4)/D = (Tmax*16) / (\pi * tau) ... eqn 1
    i.e., T J = (D^4 - d^4)/D
           From this eqn J = (Te * L) / (G * 0)
           J = \pi /32 * (D^4 - d^4)
thus--->
          (D^4 - d^4) = J * 32 / pi ... eqn 2
          Let consider d1 d2 = J * 32 /pi
          Therefore d1 d2 = D^4 - d^4
          And
                       T J = (D^4 - d^4)/D
            i.e.
            d1 d2 / D = T J
            i.e.
            D = d1 d2 / T J
```

The max() is a function which takes maximum from given two values

| Power to be Transmitted P | 20000 |
|---|-------|
| Total to be mailerance. | , |
| Load on Shaft W | 0 |
| Enter Rpm . If you don't know please leave it blank or type 0 | 200 |
| Enter Length . If you don't know please leave it blank or type 0 | О |
| Enter Faactor of Safety. If you don't know please leave it blank or type 0 | 1 |
| Enter Bending Stress . If not applicable please leave it blank or type 0 | |
| Enter Shear Stress Strength of material. If you don't know please leave it blank or type 0 | 60 |
| Enter Torque excedence %. If you don't know please leave it blank or type 0 | |
| Design the Shaft for above parameters | |

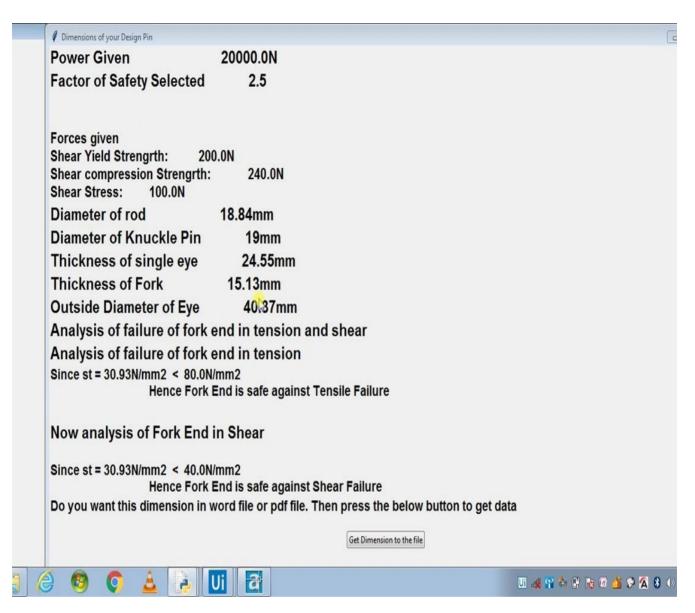
Solid Shaft Problem

| Dimensions of | f your Design Shaft | - | | ø | × |
|-----------------|-------------------------------------|--|---------------------------|--------|-----|
| * Surrensions o | , you wang man | | |) (FE) | 5.3 |
| | | | | | |
| | Torque Ratio given | 0.0% | | | |
| | Power Given | 20000 Watt | | | |
| | Load Given | N | | | |
| | Factor of Safety Given | 1 | | | |
| | Rotation / minute (Rpm) | 200rpm | | | |
| | Max Twisting Moment | 954.929658551372 - 9 | 954.929658551372 N-m | | |
| | Max Bending Moment | 0.0 - 0.0 N-m | | | |
| | Shear Stress considered | 60.0N/mm^2 | | | |
| | Bending Stress considere | d 0.0N/mm^2 | | | |
| | Diameter of Shaft | 45mm | | | |
| | Mass of Cylinder for 1 m l | ength 1162.1 g | | | |
| Do you wa | nt this dimension in word file or p | odf file. Then press the below button to | get data | | |
| | | | Get Dimension to the file | | |
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And It's solution

Design Procedure for Knuckle Pin:

```
P = Power to Be Transmitted
     Syt = Shear Strength of Material
     Syc = Compression Strength of Material
     tau = Shear Stress of material
    ## Diameter of rod
    a_1 = Syt*\pi/4 #a1 => area affecting
    Diameter of Rod (d) = \sqrt{\frac{P}{a_1}}
    ## Diameter of Knuckle Pin
    a_2 = 2*\pi*tau/4 \#a2 \Rightarrow area affecting
    Diameter of pin (Dp) = \max_{d} (\sqrt{\frac{P}{a_2}}, d)
    ## Thickness of Single Eye
    t1 = \max(1.25*d, P/(Syc*Dp))
    ## Thickness of Fork
    t = \max(0.75*d, P/(Syc*Dp*2))
    ## Diameter
    a5 = P/(tau*t)
    D = \max_{a} (a5+Dp, 2*d)
    ## Analysis of Fork end in Tension failure
    a6 = 2*t*(D-Dp)
    Syt1 = P / a6
    ## Analysis of Fork end in shear
    a7 = 2*t*(D-Dp)
    tau1 = P / a7
     If Syt1 < Syt and tau1 < tau then design is safe for the given
parameters
```



Design of Knuckle Pin problem

Design of Cotter Pin:

```
Design of rod under tension:
        Diameter of rod (d) = sqrt(P * p4 / Syt)
Design of spigot end tensile:
       d2 = sqrt(P/(p4-0.25) * Syt))
        t = (d2/4)
Design of spigot considering crushing:
       d2 = sqrt (P * 4 / Syc)
        t = d2 / 4
Shearing failure of spigot:
        a = (P/(tau*d2*2))
Crushing of spigot end:
        Syc1 = P / (d2*t)
        If the Syc1 < Syc then design is safe up to this point
Design of spigot collar:
       t1 = (P/(tau*pi*d2))
Design of socket under tension:
       A = P/Syt
       o = A+(p4*(d2**2) - (d2*t))
       Solving the Quadratic Eqn we get the D
       D1 = solve quadra (p4, -1*t, -o)
        d1 = D1^0.25
Design of socket in crushing failure:
       d4 = P / ((Syc * t) + d2)
Design of socket in shearing failure:
       c = (P/(2*tau*(d4-d2)))
Design of cotter considering shearing failure:
       b = (P/(tau*2*t))
       Length of Pin (L) = (4*d)
        e = (1.2*d)
Bending of cotter:
       z = (t*(b**2))/6
        Moment of inertia (M) = (P / 2) * ((d4/6) + (d2/12))
        sb = (M/z)
      If sb > Syc then design is unsafe up to this point
```

CNC Programming:

We had developed a small program of plotting the diagram of CNC machine code. In this we had implemented Absolute Programming Method.

Absolute Programming Method:

In Absolute Programming Method each point or location on the workpiece is set at a certain distance from the zero or reference point. All of coordinates and movements values are consider from Origin (0,0).

Means in our Program the each and every input point or coordinates mu Syt be given as reference from the origin only.

We implemented this because we thought in determining each and every point with reference to same fix point (in our case it's origin (0,0)), it will be easy for user to determine each point.

Input in Our Program:

Let draw a square of 200 x 200 unit in our program.

The input mu Syt be in following format.

Xpx Ypy

Where px = point refer to X axis

py = point refer to Y axis

X & Y => for referring which axis the points are referring.

We could also give input as \rightarrow Yp Xc

Where p = point refer to Y axis

And c = point refer to x axis.

So code to draw rectangle will be

 $X200 Y0 \rightarrow drawing the base of rectangle$

 $X200 Y200 \rightarrow$ the right most side of rectangle

 $X0 Y200 \rightarrow Drawing the top line of rectangle.$

 $XO\ YO \rightarrow$ Again coming to origin to close the rectangle.

Circle:

Let's add the circle in our centre of our rectangle which have diameter of 100 unit.

To add circle user must specify the centre of the circle and then radius in following way.

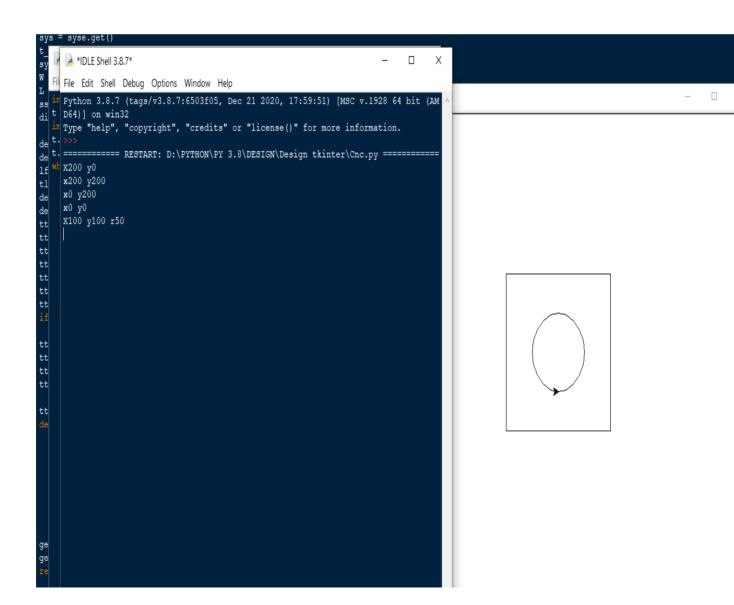
X100 Y100 R50

In above line X100 Y100is centre point of our rectangle as

$$200/2 = 100 \& 200/2 = 100.$$

R50 represents radius of circle which 100/2 = 50 as the diameter was 100.

So, in this way we could add a circle to our Rectangle.



Advantages:

Our program has better efficiency to calculate the safe dimension fastly and better productivity to design the specified elements with calculated dimension.

- Easy to use.
- Easy to implement.
- Save time.
- Quick and correct analysis.
- Wide range of applications.
- Program is portable.
- No need of training.
- No cost or power consuming.
- Easy to detect errors.

Applications:

- Could be use by Professor's to explain students about parametric design.
- Could be use by students to experiment and also to verify or do their calculations.
- Could be use in industry in small scale for designing the small elements and if the software is upgraded it could be used for all design elements.
- Our CNC plotting could be used in industry before going to actual CNC machine thus reducing the errors and also waste.

Conclusion:

In this semester we have successfully developed the software for parametric design and analysis of machine elements. We also developed the small program for CNC code plotting.

We had connected to AutoCAD through an API by which we could draw the 2D drawing of the designed dimension just within few seconds.

References:

o www.python.org/docs.com:

For solving the and learning about Python errors.

o www.github.com

To manage our Project code

o https://pypi.org/project/pyautocad

As manual for using pyautocad API

o https://pyautocad.readthedocs.io

For referring to different failures of pyautocad api and designing 2D elements in AutoCAD

o https://www.youtube.com

For referencing the different errors and their solutions occurred while calculating the dimensions