

Tutorial - 3

Q1. Write a linear search pseudo code to search an element in a sorted array with minimum comparison

```

→ Int linear search (int A[], int n, int t) {
    if (abs(A[0] - t) > abs(A[n-1] - t))
        for (i = n-2 to 0; i--)
            if (A[i] == t) { return i; }
        else
            for (i = 0 to n-1; i++)
                if (A[i] == t)
                    return i;
}

```

Q2. Iterative Insertion Sort

```

void insertion (int A[], int n)
{
    for (i = 1 to n)
        { t = A[i];
          j = i
          while (j > 0 && t < A[j])
          {
              A[j+1] = A[j];
              j = j - 1;
          }
          A[j+1] = t;
        }
}

```

Recursive Insertion Sort

```
void insertion (int A[], int n)
{
    if (n <= 1)
        return;
    insertion (A, n-1);
    int last = A[n-1];
    int j = n-2;
    while (j >= 0 && A[j] > last)
    {
        A[j+1] = A[j];
        j--;
    }
    A[j+1] = last;
}
```

Insertion sort is also called online sorting algorithm it will if the elements to be sorted are provided one at a time with the understanding that the algorithm must keep the sequence sorted as more elements are added as other sorting algorithms like bubble sort, insertion sort, heap sort etc are considered external sorting technique as they need the data to be sorted in advance.

Q3 Complexity of all sorting algorithms

Sorting	Best Case	Worst Case
Bubble sort	$O(n^2)$	$O(n^2)$
Selection sort	$O(n^2)$	$O(n^2)$
Insertion sort	$O(n)$	$O(n^2)$
Count sort	$O(n)$	$O(n+k)$
Quick sort	$O(n \log n)$	$O(n^2)$
Merge sort	$O(n \log n)$	$O(n \log n)$
Heap sort	$O(n \log n)$	$O(n \log n)$

Sort	Inplace	Stable	Online
Bubble	✓	✓	x
Selection	✓	x	x
Insertion	✓	✓	✓
Count	x	✓	x
Quick	✓	x	x
Merge	x	✓	x
Heap	✓	x	x

Q6 Recursive / Iterative pseudo code for binary search

Iterative

```

int binary search (int arr[], int x)
{
    int l = 0, r = arr.length - 1;
    while (l <= r)
    {

```

```

int m = l + (r - l) / 2;
if (arr[m] == x)
    return m;
if (arr[m] < x)
    l = m + 1;
else
    r = m - 1;
}
return -1;
}

```

Recursive

```

int binarySearch(int arr[], int l,
int r, int x)
{
    if (l >= r)
    {
        int mid = l + (r - l) / 2;
        if (arr[mid] == x)
            return mid;
        else if (arr[mid] > x)
            return binarySearch(arr, l, mid - 1, x);
        else
            return binarySearch(arr, mid + 1, r, x);
    }
    return (-1);
}

```

Linear Search;

Iterative:- Time complexity = $O(n)$
 space complexity = $O(1)$

Recursive: Time complexity = $O(n)$
 space complexity = $O(n)$

Binary search:

Iterative: Time complexity = $O(n \log n)$
 space complexity = $O(\log n)$

Q6. $T(n)$
 \downarrow
 $T(n/2)$
 \downarrow
 $T(n/4)$
 \vdots
 \downarrow
 $T(n/2^R)$

Recurrence relation = $T(n/2) + O(1)$

Q7.

```
int n;
int A[n];
int key;
int l = 0, j = n-1;
while (l < j)
{
    if (A[l] + A[j] == key)
        break;
    else if (A[l] + A[j] > key)
        j--;
    else if (A[l] + A[j] < key)
        l++;
}
```

use $j--;$

$i++;$

}

Count $< i < "$ $" < j;$

Time complexity = $O(n \log n)$

Q9. i) run time

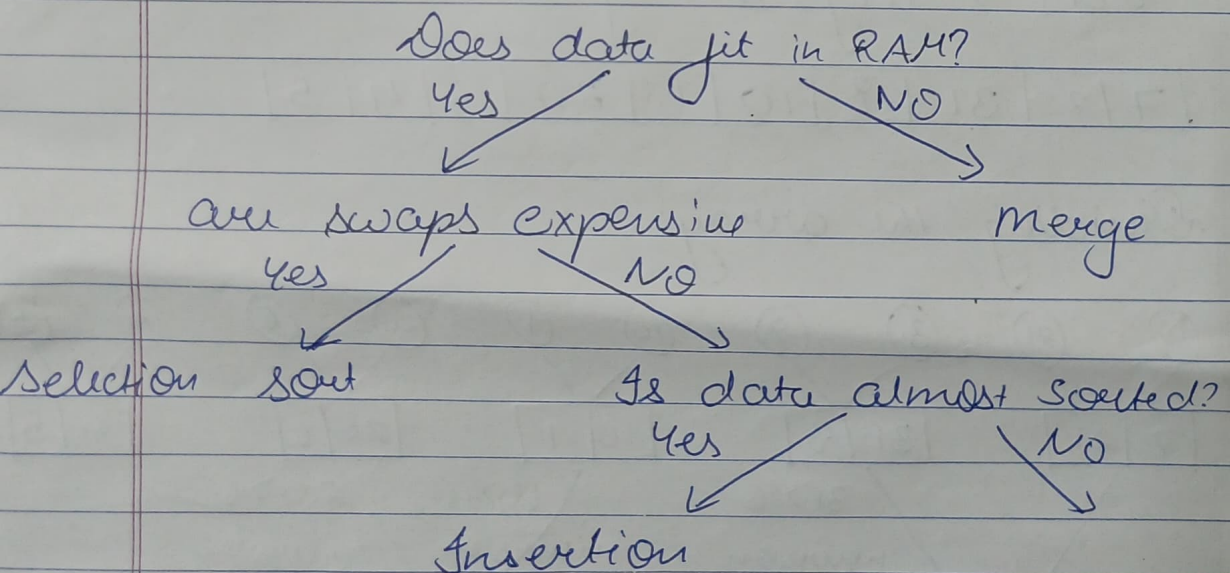
ii) space

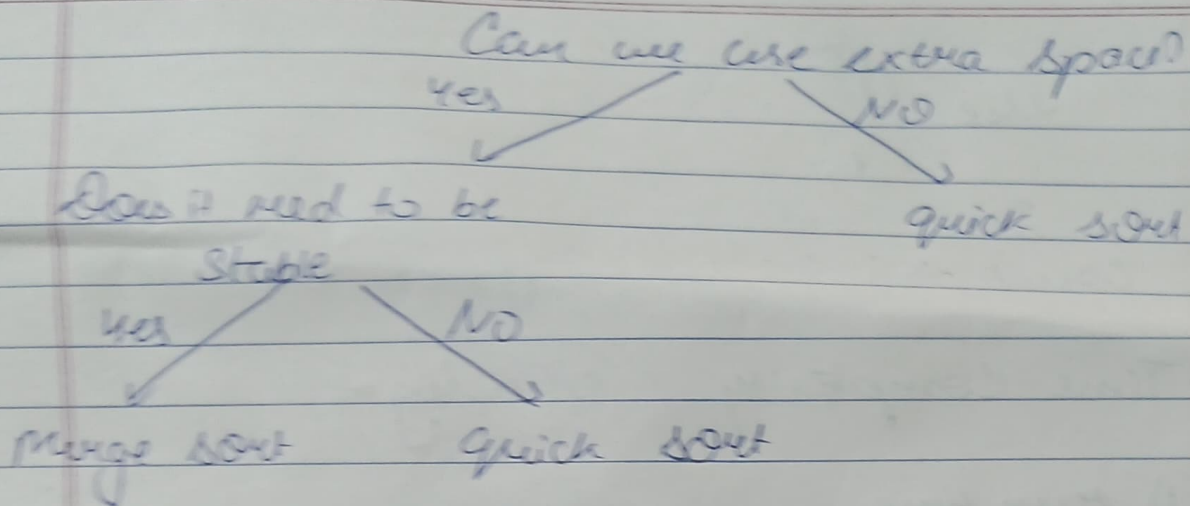
iii) stable

iv) No. of swaps

v) will the data fit in the RAM

→ There is no best sorting algorithms. It depends on the situation or the type of array provided



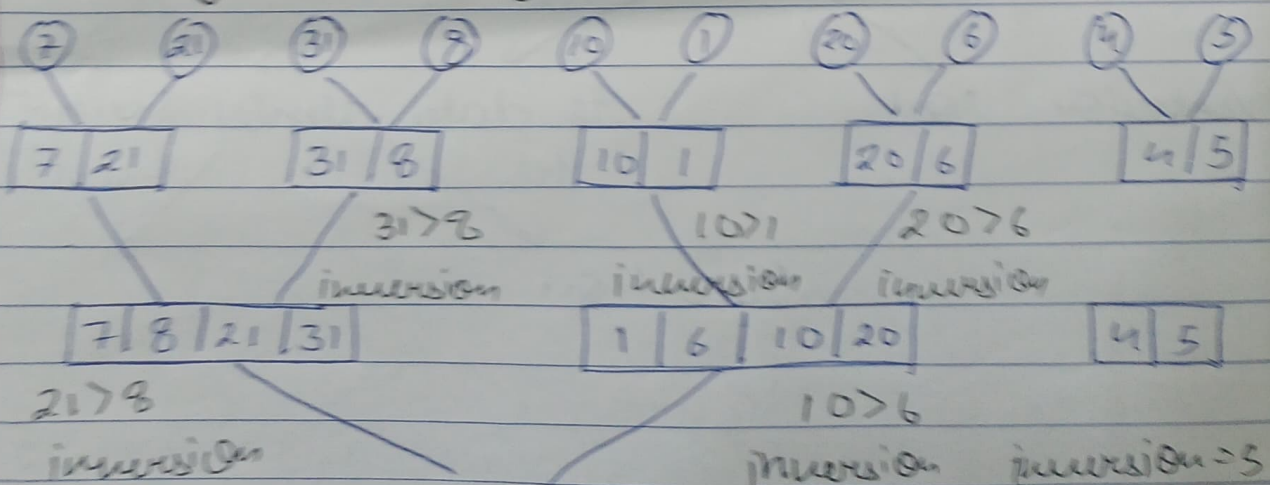


Q9. Inversion in an array indicates how far the array is from being sorted. If the array is already sorted, the inversion count is 0, but if the array is sorted in reverse order, then the inversion count is maximum.

Condition for inversion
 $a[i] > a[j] \text{ \& } i < j$

[7 | 2 | 3 | 8 | 10 | 1 | 20 | 6 | 4 | 5]

Dividing the array:



1	6	7	8	10	20	21	31	4	5
---	---	---	---	----	----	----	----	---	---

$7 > 1$, $7 > 6$, $8 > 1$, $8 > 6$, $21 > 10$, $21 > 20$,
 $31 > 6$, $31 > 7$, $31 > 20$, $21 > 1$, $21 > 6$

Total inversion in this step = 12

1	4	5	6	7	8	10	20	21	31
---	---	---	---	---	---	----	----	----	----

inv count = 0

$6 > 4$, $6 > 5$, $7 > 4$, $7 > 5$, $8 > 4$, $8 > 5$, $10 > 4$,
 $10 > 5$, $20 > 4$, $20 > 5$, $21 > 4$, $21 > 5$, $31 > 4$,
 $31 > 5$

→ Total inversion in this step = 14

inversion count = 31

Q10 Best Case:

Time Complexity = $O(n \log n)$

The best Case occurs when the partition process always picks the middle elements as pivot

Worst Case:

Time complexity = $O(n^2)$

When the array is sorted in ascending and descending order

Q11 Best Case:

Merge Sort: $2T(n/2) + n$

Quick Sort: $2T(n/2) + n$

Worst Case:

Merge Sort: $2T(n/2) + n$

Quick Sort: $T(n-1) + n$

Similarities: They both work on the concept of divide & conquer algorithms. Both have best case complexity of $O(n \log n)$

Differences:

Merge Sort

i) The array is divided into just 2 half

ii) Worst case complexity is $O(n \log n)$

iii) It requires extra space i.e NOT inplace

iv) It is external sorting algorithm & it is stable

v) works consistently on

Quick Sort

i) The array is divided in any ratio

ii) Worst case complexity $O(n^2)$

iii) It does not require extra space i.e inplace

iv) It is internal sorting algorithm & not stable

v) works fast on small

any size of data set set

Q12. Selection sort is not stable by default but you can write a version of stable selection sort

```
void selection (int A[], int n)
{
    for (int i=0, i<n-1; i++)
    {
        int min = i;
        for (int j = i+1; j<n; j++)
        {
            if (A[i] > A[j])
                min = j;
        }
        int key = A[min];
        while (min > i)
        {
            A[min] = A[min-1];
            min--;
        }
        A[i] = key;
    }
}
```

Q13. void bubble sort (int A[], int n)

```
{
    int i, j;
    int j = 0;
    for (i=0; i<n; i++)
    {
        for (j=0; j<n-1; j++)
```



```

    }
    if (A[j] > A[j+1])
        swap (A[j], A[j+1])
    j = j + 1;
}

if (j == 0)
    break;
}

```

Q14 When the data set is large enough to fit inside RAM, we ought to use merge sort because it uses the divide & conquer approach in which it keeps dividing the array into smaller parts until it can no longer be split, it then merge the array divided in n parts. Therefore, at the time only a part of array is taken in RAM.

External Sorting

It is used to sort maximum amount of data. It is required when the data doesn't fit inside the RAM & instead they must be inside in the slower external memory.

During sorting, chunks of small data that can fit in main memory read & written out to a temporary file

During merging, the sorted subfiles are combined into a single large file

Internal sorting

It is a type of sorting which is used when the entire collection of data is small enough to reside within RAM. Then there is no need of external memory for program execution. It is used when input is small

Eg - Insertion sort, quick sort, heap sort etc.