BDA Individual Assignment

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Q1. PageRank

Steps:

- 1. Read the text file and create an RDD.
- 2. Pass this RDD into a parsing function and the edges node wise
- 3. Count the number of linkages
- 4. Create ranks
- 5. Iterating until the distance get conversed, assuming that the comparing distance(delta) is 0.1

Outputs:

```
1 # Passing the text through the parser function and grouping it as per the nodes as key and values being the connections the
   2 txt_lnk = text.map(lambda x: passed(x)).distinct().groupByKey().mapValues(lambda x: list(x)).cache()
   3 txt_lnk.collect()
 [('1', ['1', '2']), ('2', ['1', '3']), ('3', ['2'])]
   1 # Counting the number of nodes.
   2 X = txt_lnk.count()
   3 print(X)
 3
   1 # Generating ranks for each node
   2 rank = txt_lnk.map(lambda node: (node[0],1.0/N))
   3 print(rank.collect())
 [('1', 0.33333333333333), ('2', 0.333333333333), ('3', 0.3333333333333)]
In [28]: 1 old_rank = rank.collect()
                2 while True:
                      nile True:
    print("Old Rank - {0}".format(old_rank))
    ranks = txt_lnk.join(rank).flatMap(lambda x : [(i, float(x[1][1])/len(x[1][0])) for i in x[1][0]])
    ranks = ranks.reduceByKey(lambda x,y: x+y)
    new_rank = ranks.sortByKey().collect()
    print("Mew_rank - {0}".format(new_rank))
    if check_conv(old_rank, new_rank):
        print("Page ranking is completed.")
        break
              9
                              break
                       old_rank = new_rank
            Old Rank - [('1', 0.333333333333333), ('2', 0.3333333333333), ('3', 0.33333333333333)]

New_rank - [('1', 0.3333333333333), ('2', 0.5), ('3', 0.16666666666666666)]

Old Rank - [('1', 0.3333333333333), ('2', 0.5), ('3', 0.1666666666666666)]

New_rank - [('1', 0.3333333333333), ('2', 0.5), ('3', 0.1666666666666666)]
             Page ranking is completed.
```

Q2. Inverted Index

Steps:

- 1. Read the text file and create RDD.
- 2. Parsing the content to get key value pairs (tuples within a tuple). This contains word and the corresponding document.
- 3. Generating frequency of each using mapper
- 4. Formatting the RDD to get desired result
- 5. Grouping the result by Key
- 6. Sorting the output by keys
- 7. Formatting the result to get the desired format

Outputs:

```
In [32]: 1
    Kep_pair1 = textFile.flatMap(lambda x: map_out(x)).cache()
    Kep_pair1.collect()
    # From the output below, we are getting key value pairs(tuples within a tuple). This contains we define the contains we have seen that the contains we have seen that the contains we define th
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```
new4 = new3.map(lambda x: new_data(x)).cache()
 Out[37]: ['a#d1:4;d2:2;d3:5;d4:5;d5:3;d6:3;d7:6;',
            'about#d4:1;',
'across#d5:2;'
             'actors#d4:1:'
             'addition#d2:1;'
             'administrative#d1:1;',
            'affect#d4:1;',
            'afghanistan#d4:1;',
'after#d3:2;d7:1;',
             'agenda#d7:1;',
            'agree#d7:1;',
            'air#d7:1;'
            'air#d7:1;',
'aircraft#d7:1;',
            'airlines#d7:1;'
             'alaska#d5:1;d6:1;',
            'all#d3:1;',
```

Q3. Kmeans

Steps:

- 1. First step to read the info files.
- 2. Then parse the info.
- 3. Initialize the K clusters.
- 4. Now perform iteration until converse.
- 5. Get nearest points mapper.
- 6. Combined the mapper results using reducer.
- 7. Update the centroids.
- 8. Check the space between points and centroid.
- 9. After converse results as follows.

Outputs:

```
2 text = sc.textFile("C:/Users/ysrivastava/BDA/Assignment/KMeans/points.txt")
              3 text.collect()
  Out[2]: ['3.023\t5.138'
              3.075\t4.989'
             '2.321\t5.350',
             '3.328\t4.944'
'3.195\t5.186'
             '3.034\t4.656',
             '3.484\t4.877'
             '3.023\t4.951',
             '2.707\t4.871',
             '2.894\t5.031'
             '2.880\t5.207',
             '2.780\t5.196',
             '2.941\t4.951'
             '3.213\t5.123',
             '2.972\t4.941',
              3.138\t5.460'.
             '3.247\t5.185',
             '3.602\t5.405'
             '2.857\t4.686',
  In [6]: 1 # Passing the data points to remove the tabs
              2 def parse(points):
                     var = points.split('\t')
                    result = []
for x in var:
                        value = float(x)
                        result.append(value)
                    return np.array(result)
  In [7]: 1 #Calling the parsing function
2 arr = text.map(lambda m: parse(m)).cache()
             3 arr.collect()
  Out[7]: [array([3.023, 5.138]),
             array([3.075, 4.989]),
array([2.321, 5.35]),
             array([3.328, 4.944]),
             array([3.195, 5.186]),
             array([3.034, 4.656]),
             array([3.484, 4.877]),
array([3.023, 4.951]),
             array([2.707, 4.871]),
In [18]:
           1 Dist = float(0.1)
              kp = [np.array([float(2)\ ,\ float(5)]),\ np.array([float(6),\ float(2)]),\ np.array([float(1),\ float(1)])]
            3 dist2 = 1.0
            4 type(kp)
           5 print(kp)
          [array([2., 5.]), array([6., 2.]), array([1., 1.])]
In [21]: 1 nearest = arr.map(lambda p: process_map(p, kp))
           print(nearest.take(5))
           [(0, (array([3.023, 5.138]), 1)), (0, (array([3.075, 4.989]), 1)), (0, (array([2.321, 5.35]), 1)), (0, (array([3.195, 5.186]), 1))] 
In [23]: 1 Status = nearest.reduceByKey(lambda pointer1 , pointer2: pairs(pointer1 , pointer2))
           print(Status.take(4))
          [(0, (array([1496.991, 2502.065]), 500)), (2, (array([1016.494, 501.689]), 500)), (1, (array([2496.329, 995.104]), 500))]
In [24]: 1 new_points = Status.map(lambda map_object: mapper(map_object)).collect()
           print(new_points)
           [(0, \operatorname{array}([2.993982, 5.00413\ ])), (2, \operatorname{array}([2.032988, 1.003378])), (1, \operatorname{array}([4.992658, 1.990208]))] ] 
In [25]: 1 updated_distance = all_points_dist(new_points)
           print(updated_distance)
          51,92141868048006
In [27]:
           1 def change points(new points, kp):
                   for (cluster_number, point) in new_points:
                      kp[cluster_number] = point
                   return kp
           6 change_points(new_points, kp)
7 print(kp)
```

 $[\mathsf{array}([2.993982, \, 5.00413 \,]), \, \mathsf{array}([4.992658, \, 1.990208]), \, \mathsf{array}([2.032988, \, 1.003378])]$

In [2]: 1 # Reading the text file

```
In [30]: 1 while dist2 > Dist:
                       print(dist2)
                       near = arr.map(lambda p: process_map(p, kp))
             3
                      point_Stats = nearest.reduceByKey(lambda pointer1 , pointer2: pairs(pointer1 , pointer2))
new_Points = point_Stats.map(lambda map_object: mapper(map_object)).collect()
              5
                      print(new_Points)
                      dist2 = sum(np.sum((kp[iK] - p) ** 2) for (iK, p) in new_Points)
              8
                      for (iK, p) in new_Points:
    kp[iK] = p
             9
             10
             11
             12 results(kp)
            1.0
            1.0
[(0, array([2.993982, 5.00413])), (2, array([2.032988, 1.003378])), (1, array([4.992658, 1.990208]))]
2.99398#5.00413
4.99266#1.99021
2.03299#1.00338
```